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This book documents version 0.13.35-644c of the GNU Astronomy Utilities (Gnuastro).
Gnuastro provides various programs and libraries for astronomical data manipulation and
analysis.

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For myself, I am interested in science and in philosophy only because I want to learn something about the riddle of the world in which we live, and the riddle of man’s knowledge of that world. And I believe that only a revival of interest in these riddles can save the sciences and philosophy from narrow specialization and from an obscurantist faith in the expert’s special skill, and in his personal knowledge and authority; a faith that so well fits our ‘post-rationalist’ and ‘post-critical’ age, proudly dedicated to the destruction of the tradition of rational philosophy, and of rational thought itself.

Short Contents

1 Introduction .............................................. 1
2 Tutorials .................................................. 16
3 Installation ................................................. 74
4 Common program behavior ............................... 105
5 Data containers .......................................... 146
6 Data manipulation ........................................ 188
7 Data analysis ............................................... 248
8 Modeling and fitting ..................................... 332
9 High-level calculations .................................. 359
10 Library ....................................................... 372
11 Developing ................................................ 516
A Gnuastro programs list .................................. 538
B Other useful software ..................................... 540
C GNU Free Doc. License ................................... 545
D GNU Gen. Pub. License v3 .............................. 553
Index: Macros, structures and functions .................. 564
Index .......................................................... 570
# Table of Contents

## 1 Introduction ................................................................. 1  
1.1 Quick start ........................................................................ 1  
1.2 Science and its tools ........................................................ 2  
1.3 Your rights ........................................................................ 6  
1.4 Naming convention .......................................................... 7  
1.5 Version numbering ........................................................... 7  
1.5.1 GNU Astronomy Utilities 1.0 ........................................... 8  
1.6 New to GNU/Linux? ............................................................ 8  
1.6.1 Command-line interface ............................................... 9  
1.7 Report a bug ....................................................................... 11  
1.8 Suggest new feature .......................................................... 12  
1.9 Announcements .................................................................. 13  
1.10 Conventions ...................................................................... 13  
1.11 Acknowledgments ............................................................. 14

## 2 Tutorials .......................................................................... 16  
2.1 Sufi simulates a detection ................................................. 17  
2.2 General program usage tutorial ........................................ 24  
2.2.1 Calling Gnuastro’s programs ........................................ 25  
2.2.2 Accessing documentation .............................................. 25  
2.2.3 Setup and data download .............................................. 27  
2.2.4 Dataset inspection and cropping .................................. 27  
2.2.5 Angular coverage on the sky ........................................ 29  
2.2.6 Cosmological coverage ............................................... 31  
2.2.7 Building custom programs with the library .................... 32  
2.2.8 Option management and configuration files .................... 34  
2.2.9 Warping to a new pixel grid ........................................ 36  
2.2.10 NoiseChisel and Multitemension FITS files .................... 37  
2.2.11 NoiseChisel optimization for detection ......................... 39  
2.2.12 NoiseChisel optimization for storage ............................ 43  
2.2.13 Segmentation and making a catalog .............................. 44  
2.2.14 Working with catalogs (estimating colors) ..................... 46  
2.2.15 Aperture photometry .................................................. 51  
2.2.16 Matching catalogs ...................................................... 52  
2.2.17 Finding reddest clumps and visual inspection ............... 53  
2.2.18 Writing scripts to automate the steps ......................... 55  
2.2.19 Citing and acknowledging Gnuastro ............................. 61  
2.3 Detecting large extended targets ....................................... 61  
2.3.1 NoiseChisel optimization ........................................... 62  
2.3.2 Achieved surface brightness level ................................. 68

## 3 Installation ................................................................. 74  
3.1 Dependencies ................................................................. 74
3.1.1 Mandatory dependencies ........................................ 75
  3.1.1.1 GNU Scientific library .................................. 75
  3.1.1.2 CFITSIO .............................................. 75
  3.1.1.3 WCSLIB .................................................. 76
3.1.2 Optional dependencies ........................................ 77
3.1.3 Bootstrapping dependencies .................................. 79
3.1.4 Dependencies from package managers ....................... 81
3.2 Downloading the source ........................................ 84
  3.2.1 Release tarball ........................................... 84
  3.2.2 Version controlled source .................................. 85
    3.2.2.1 Bootstrapping ....................................... 86
    3.2.2.2 Synchronizing ........................................ 88
3.3 Build and install ............................................. 89
  3.3.1 Configuring ................................................ 90
    3.3.1.1 Guastro configure options .......................... 90
    3.3.1.2 Installation directory ............................... 92
    3.3.1.3 Executable names .................................... 97
    3.3.1.4 Configure and build in RAM .......................... 98
  3.3.2 Separate build and source directories .................... 98
  3.3.3 Tests ..................................................... 101
  3.3.4 A4 print book ............................................ 102
  3.3.5 Known issues ............................................... 102
4 Common program behavior ......................................... 105
  4.1 Command-line ................................................ 105
    4.1.1 Arguments and options .................................. 106
      4.1.1.1 Arguments .......................................... 107
      4.1.1.2 Options ............................................. 107
    4.1.2 Common options ......................................... 109
      4.1.2.1 Input/Output options ............................... 109
      4.1.2.2 Processing options .................................. 112
      4.1.2.3 Operating mode options ............................ 114
    4.1.3 Standard input .......................................... 118
  4.2 Configuration files ........................................... 120
    4.2.1 Configuration file format ................................ 120
    4.2.2 Configuration file precedence ........................... 121
    4.2.3 Current directory and User wide ........................ 122
    4.2.4 System wide ............................................. 122
  4.3 Getting help .................................................. 123
    4.3.1 --usage .................................................. 123
    4.3.2 --help ................................................... 124
    4.3.3 Man pages ............................................... 125
    4.3.4 Info ..................................................... 125
    4.3.5 help-guastro mailing list ................................ 126
  4.4 Installed scripts ............................................. 126
  4.5 Multi-threaded operations .................................... 127
    4.5.1 A note on threads ....................................... 128
    4.5.2 How to run simultaneous operations ..................... 128
4.6 Numeric data types ........................................ 130
4.7 Memory management ....................................... 132
4.8 Tables ......................................................... 135
  4.8.1 Recognized table formats .............................. 136
  4.8.2 Gnuastro text table format ........................... 137
  4.8.3 Selecting table columns .............................. 140
4.9 Tessellation ................................................ 141
4.10 Automatic output ......................................... 142
4.11 Output FITS files ......................................... 143

5 Data containers .............................................. 146
  5.1 Fits .......................................................... 146
    5.1.1 Invoking Fits .......................................... 148
      5.1.1.1 HDU information and manipulation .......... 149
      5.1.1.2 Keyword manipulation ......................... 152
  5.2 Sort FITS files by night .................................. 158
    5.2.1 Invoking astscript-sort-by-night ................. 159
  5.3 ConvertType ................................................ 162
    5.3.1 Recognized file formats ............................ 162
    5.3.2 Color ................................................... 165
    5.3.3 Invoking ConvertType .............................. 166
  5.4 Table ........................................................ 171
    5.4.1 Column arithmetic ................................. 172
    5.4.2 Invoking Table ...................................... 176
  5.5 Query ........................................................ 183
    5.5.1 Invoking Query ..................................... 184

6 Data manipulation ............................................ 188
  6.1 Crop ........................................................ 188
    6.1.1 Crop modes ........................................... 188
    6.1.2 Crop section syntax ............................... 191
    6.1.3 Blank pixels ....................................... 191
    6.1.4 Invoking Crop ....................................... 192
      6.1.4.1 Crop options .................................. 193
      6.1.4.2 Crop output ................................... 198
  6.2 Arithmetic .................................................. 199
    6.2.1 Reverse polish notation ............................ 199
    6.2.2 Arithmetic operators ............................... 200
    6.2.3 Invoking Arithmetic ............................... 212
  6.3 Convolve ..................................................... 216
    6.3.1 Spatial domain convolution ........................ 217
      6.3.1.1 Convolution process .......................... 217
      6.3.1.2 Edges in the spatial domain ................. 218
    6.3.2 Frequency domain and Fourier operations ....... 219
      6.3.2.1 Fourier series historical background ....... 219
      6.3.2.2 Circles and the complex plane ............... 221
      6.3.2.3 Fourier series ............................... 223
6.3.2.4 Fourier transform .................................. 224
6.3.2.5 Dirac delta and comb ......................... 225
6.3.2.6 Convolution theorem ......................... 227
6.3.2.7 Sampling theorem ............................. 228
6.3.2.8 Discrete Fourier transform ................. 231
6.3.2.9 Fourier operations in two dimensions .... 232
6.3.2.10 Edges in the frequency domain .......... 233
6.3.3 Spatial vs. Frequency domain .................. 234
6.3.4 Convolution kernel ................................ 235
6.3.5 Invoking Convolve ............................... 236
6.4 Warp ................................................... 238
6.4.1 Warping basics ................................... 239
6.4.2 Merging multiple warpings .................... 241
6.4.3 Resampling ........................................ 242
6.4.4 Invoking Warp .................................... 243

7 Data analysis ........................................... 248
7.1 Statistics .............................................. 248
7.1.1 Histogram and Cumulative Frequency Plot .... 248
7.1.2 2D Histograms .................................... 249
7.1.3 Sigma clipping ..................................... 251
7.1.4 Sky value ........................................... 252
7.1.4.1 Sky value definition .......................... 253
7.1.4.2 Sky value misconceptions .................... 254
7.1.4.3 Quantifying signal in a tile .................. 255
7.1.5 Invoking Statistics ............................... 257
7.2 NoiseChisel ........................................... 269
7.2.1 Invoking NoiseChisel ............................. 271
7.2.1.1 NoiseChisel input ............................. 273
7.2.1.2 Detection options ............................. 275
7.2.1.3 NoiseChisel output ............................ 282
7.3 Segment ............................................... 284
7.3.1 Invoking Segment .................................. 286
7.3.1.1 Segment input ................................ 287
7.3.1.2 Segmentation options ......................... 290
7.3.1.3 Segment output ................................ 293
7.4 MakeCatalog .......................................... 295
7.4.1 Detection and catalog production ............ 297
7.4.2 Quantifying measurement limits ............... 298
7.4.3 Measuring elliptical parameters ............... 302
7.4.4 Adding new columns to MakeCatalog .......... 305
7.4.5 Invoking MakeCatalog ............................ 307
7.4.5.1 MakeCatalog inputs and basic settings ...... 307
7.4.5.2 Upper-limit settings ........................... 311
7.4.5.3 MakeCatalog measurements .................. 313
7.4.5.4 MakeCatalog output ........................... 324
7.5 Match ................................................... 326
7.5.1 Invoking Match .................................... 326
8 Modeling and fitting .......................................................... 332
  8.1 MakeProfiles ............................................................. 332
     8.1.1 Modeling basics .................................................. 332
        8.1.1.1 Defining an ellipse and ellipsoid ..................... 332
        8.1.1.2 Point spread function .................................. 334
        8.1.1.3 Stars ...................................................... 336
        8.1.1.4 Galaxies ................................................... 336
        8.1.1.5 Sampling from a function ............................... 336
        8.1.1.6 Oversampling ............................................. 337
     8.1.2 If convolving afterwards ..................................... 338
     8.1.3 Brightness, Flux, Magnitude and Surface brightness .... 338
     8.1.4 Profile magnitude ............................................ 340
     8.1.5 Invoking MakeProfiles ......................................... 340
        8.1.5.1 MakeProfiles catalog ................................... 342
        8.1.5.2 MakeProfiles profile settings .......................... 345
        8.1.5.3 MakeProfiles output dataset ............................ 348
        8.1.5.4 MakeProfiles log file .................................... 352
  8.2 MakeNoise .............................................................. 352
     8.2.1 Noise basics .................................................... 352
        8.2.1.1 Photon counting noise .................................. 353
        8.2.1.2 Instrumental noise ...................................... 354
        8.2.1.3 Final noised pixel value ............................... 354
        8.2.1.4 Generating random numbers ............................. 355
     8.2.2 Invoking MakeNoise ............................................ 356

9 High-level calculations .................................................. 359
  9.1 CosmicCalculator ..................................................... 359
     9.1.1 Distance on a 2D curved space ............................... 359
     9.1.2 Extending distance concepts to 3D ........................... 364
     9.1.3 Invoking CosmicCalculator .................................... 364
        9.1.3.1 CosmicCalculator input options ........................ 365
        9.1.3.2 CosmicCalculator basic cosmology calculations ...... 368
        9.1.3.3 CosmicCalculator spectral line calculations ........ 370

10 Library ................................................................. 372
  10.1 Review of library fundamentals ................................... 372
     10.1.1 Headers ......................................................... 373
     10.1.2 Linking .......................................................... 376
     10.1.3 Summary and example on libraries ........................... 379
  10.2 BuildProgram ......................................................... 380
     10.2.1 Invoking BuildProgram ....................................... 381
  10.3 Gnuastro library ..................................................... 384
     10.3.1 Configuration information (config.h) .................... 385
     10.3.2 Multithreaded programming (threads.h) .................... 386
        10.3.2.1 Implementation of pthread_barrier .................... 387
        10.3.2.2 Gnuastro’s thread related functions ................. 388
     10.3.3 Library data types (type.h) ............................... 390
<table>
<thead>
<tr>
<th>Section</th>
<th>Description</th>
<th>Page</th>
</tr>
</thead>
<tbody>
<tr>
<td>10.3.4</td>
<td>Pointers (pointer.h)</td>
<td>394</td>
</tr>
<tr>
<td>10.3.5</td>
<td>Library blank values (blank.h)</td>
<td>396</td>
</tr>
<tr>
<td>10.3.6</td>
<td>Data container (data.h)</td>
<td>400</td>
</tr>
<tr>
<td>10.3.6.1</td>
<td>Generic data container (gal_data_t)</td>
<td>400</td>
</tr>
<tr>
<td>10.3.6.2</td>
<td>Dataset allocation</td>
<td>405</td>
</tr>
<tr>
<td>10.3.6.3</td>
<td>Arrays of datasets</td>
<td>406</td>
</tr>
<tr>
<td>10.3.6.4</td>
<td>Copying datasets</td>
<td>407</td>
</tr>
<tr>
<td>10.3.7</td>
<td>Dimensions (dimension.h)</td>
<td>408</td>
</tr>
<tr>
<td>10.3.8</td>
<td>Linked lists (list.h)</td>
<td>411</td>
</tr>
<tr>
<td>10.3.8.1</td>
<td>List of strings</td>
<td>413</td>
</tr>
<tr>
<td>10.3.8.2</td>
<td>List of int32_t</td>
<td>414</td>
</tr>
<tr>
<td>10.3.8.3</td>
<td>List of size_t</td>
<td>415</td>
</tr>
<tr>
<td>10.3.8.4</td>
<td>List of float</td>
<td>417</td>
</tr>
<tr>
<td>10.3.8.5</td>
<td>List of double</td>
<td>418</td>
</tr>
<tr>
<td>10.3.8.6</td>
<td>List of void *</td>
<td>420</td>
</tr>
<tr>
<td>10.3.8.7</td>
<td>Ordered list of size_t</td>
<td>421</td>
</tr>
<tr>
<td>10.3.8.8</td>
<td>Doubly linked ordered list of size_t</td>
<td>422</td>
</tr>
<tr>
<td>10.3.8.9</td>
<td>List of gal_data_t</td>
<td>423</td>
</tr>
<tr>
<td>10.3.9</td>
<td>Array input output</td>
<td>424</td>
</tr>
<tr>
<td>10.3.10</td>
<td>Table input output (table.h)</td>
<td>426</td>
</tr>
<tr>
<td>10.3.11</td>
<td>FITS files (fits.h)</td>
<td>430</td>
</tr>
<tr>
<td>10.3.11.1</td>
<td>FITS Macros, errors and filenames</td>
<td>430</td>
</tr>
<tr>
<td>10.3.11.2</td>
<td>CFITSIO and Gnuastro types</td>
<td>431</td>
</tr>
<tr>
<td>10.3.11.3</td>
<td>FITS HDUs</td>
<td>431</td>
</tr>
<tr>
<td>10.3.11.4</td>
<td>FITS header keywords</td>
<td>432</td>
</tr>
<tr>
<td>10.3.11.5</td>
<td>FITS arrays (images)</td>
<td>439</td>
</tr>
<tr>
<td>10.3.11.6</td>
<td>FITS tables</td>
<td>441</td>
</tr>
<tr>
<td>10.3.12</td>
<td>File input output</td>
<td>442</td>
</tr>
<tr>
<td>10.3.12.1</td>
<td>Text files (txt.h)</td>
<td>442</td>
</tr>
<tr>
<td>10.3.12.2</td>
<td>TIFF files (tiff.h)</td>
<td>445</td>
</tr>
<tr>
<td>10.3.12.3</td>
<td>JPEG files (jpeg.h)</td>
<td>446</td>
</tr>
<tr>
<td>10.3.12.4</td>
<td>EPS files (eps.h)</td>
<td>447</td>
</tr>
<tr>
<td>10.3.12.5</td>
<td>PDF files (pdf.h)</td>
<td>448</td>
</tr>
<tr>
<td>10.3.13</td>
<td>World Coordinate System (wcs.h)</td>
<td>449</td>
</tr>
<tr>
<td>10.3.14</td>
<td>Arithmetic on datasets (arithmetic.h)</td>
<td>454</td>
</tr>
<tr>
<td>10.3.15</td>
<td>Tessellation library (tile.h)</td>
<td>460</td>
</tr>
<tr>
<td>10.3.15.1</td>
<td>Independent tiles</td>
<td>461</td>
</tr>
<tr>
<td>10.3.15.2</td>
<td>Tile grid</td>
<td>466</td>
</tr>
<tr>
<td>10.3.16</td>
<td>Bounding box (box.h)</td>
<td>470</td>
</tr>
<tr>
<td>10.3.17</td>
<td>Polygons (polygon.h)</td>
<td>471</td>
</tr>
<tr>
<td>10.3.18</td>
<td>Qsort functions (qsort.h)</td>
<td>474</td>
</tr>
<tr>
<td>10.3.19</td>
<td>K-d tree (kdtree.h)</td>
<td>476</td>
</tr>
<tr>
<td>10.3.20</td>
<td>Permutations (permutation.h)</td>
<td>479</td>
</tr>
<tr>
<td>10.3.21</td>
<td>Matching (match.h)</td>
<td>480</td>
</tr>
<tr>
<td>10.3.22</td>
<td>Statistical operations (statistics.h)</td>
<td>482</td>
</tr>
<tr>
<td>10.3.23</td>
<td>Binary datasets (binary.h)</td>
<td>489</td>
</tr>
<tr>
<td>10.3.24</td>
<td>Labeled datasets (label.h)</td>
<td>492</td>
</tr>
<tr>
<td>10.3.25</td>
<td>Convolution functions (convolve.h)</td>
<td>497</td>
</tr>
</tbody>
</table>
1 Introduction

GNU Astronomy Utilities (Gnuastro) is an official GNU package consisting of separate programs and libraries for the manipulation and analysis of astronomical data. All the programs share the same basic command-line user interface for the comfort of both the users and developers. Gnuastro is written to comply fully with the GNU coding standards so it integrates finely with the GNU/Linux operating system. This also enables astronomers to expect a fully familiar experience in the source code, building, installing and command-line user interaction that they have seen in all the other GNU software that they use. The official and always up to date version of this book (or manual) is freely available under Appendix C [GNU Free Doc. License], page 545, in various formats (PDF, HTML, plain text, info, and as its Texinfo source) at http://www.gnu.org/software/gnuastro/manual/.

For users who are new to the GNU/Linux environment, unless otherwise specified most of the topics in Chapter 3 [Installation], page 74, and Chapter 4 [Common program behavior], page 105, are common to all GNU software, for example installation, managing command-line options or getting help (also see Section 1.6 [New to GNU/Linux?], page 8). So if you are new to this empowering environment, we encourage you to go through these chapters carefully. They can be a starting point from which you can continue to learn more from each program’s own manual and fully benefit from and enjoy this wonderful environment. Gnuastro also comes with a large set of libraries, so you can write your own programs using Gnuastro’s building blocks, see Section 10.1 [Review of library fundamentals], page 372, for an introduction.

In Gnuastro, no change to any program or library will be committed to its history, before it has been fully documented here first. As discussed in Section 1.2 [Science and its tools], page 2, this is a founding principle of the Gnuastro.

1.1 Quick start

The latest official release tarball is always available as gnuastro-latest.tar.gz (ftp://ftp.gnu.org/gnu/gnuastro/gnuastro-latest.tar.gz). For better compression (faster download), and robust archival features, an Lzip (http://www.nongnu.org/lzip/lzip.html) compressed tarball is also available at gnuastro-latest.tar.lz (ftp://ftp.gnu.org/gnu/gnuastro/gnuastro-latest.tar.lz), see Section 3.2.1 [Release tarball], page 84, for more details on the tarball release.

Let’s assume the downloaded tarball is in the TOPGNUASTRO directory. The first two commands below can be used to decompress the source. If you download tar.lz and your Tar implementation doesn’t recognize Lzip (the second command fails), run the third and fourth lines. Note that lines starting with ## don’t need to be typed.

## Go into the download directory.

1 The Gzip library and program are commonly available on most systems. However, Gnuastro recommends Lzip as described above and the beta-releases are also only distributed in tar.lz. You can download and install Lzip’s source (in .tar.gz format) from its webpage and follow the same process as below: Lzip has no dependencies, so simply decompress, then run ./configure, make, sudo make install.

2 In case Tar doesn’t directly decompress your .tar.lz tarball, you can merge the separate calls to Lzip and Tar (shown in the main body of text) into one command by directly piping the output of Lzip into Tar with a command like this: $ lzip -cd gnuastro-0.5.tar.lz | tar -xf -
$ cd TOPGNUASTRO

## Also works on ‘tar.gz’. GNU Tar recognizes both formats.
$ tar xf gnuastro-latest.tar.lz

## Only when previous command fails.
$ lzip -d gnuastro-latest.tar.lz
$ tar xf gnuastro-latest.tar

Gnuastro has three mandatory dependencies and some optional dependencies for extra functionality, see Section 3.1 [Dependencies], page 74, for the full list. In Section 3.1.4 [Dependencies from package managers], page 81, we have prepared the command to easily install Gnuastro’s dependencies using the package manager of some operating systems. When the mandatory dependencies are ready, you can configure, compile, check and install Gnuastro on your system with the following commands.

$ cd gnuastro-X.X  # Replace X.X with version number.
$ ./configure
$ make -j8          # Replace 8 with no. CPU threads.
$ make check
$ sudo make install

See Section 3.3.5 [Known issues], page 102, if you confront any complications. For each program there is an ‘Invoke ProgramName’ sub-section in this book which explains how the programs should be run on the command-line (for example Section 5.4.2 [Invoking Table], page 176). You can read the same section on the command-line by running $ info astprogname (for example info asttable). The ‘Invoke ProgramName’ sub-section starts with a few examples of each program and goes on to explain the invocation details. See Section 4.3 [Getting help], page 123, for all the options you have to get help. In Chapter 2 [Tutorials], page 16, some real life examples of how these programs might be used are given.

### 1.2 Science and its tools

History of science indicates that there are always inevitably unseen faults, hidden assumptions, simplifications and approximations in all our theoretical models, data acquisition and analysis techniques. It is precisely these that will ultimately allow future generations to advance the existing experimental and theoretical knowledge through their new solutions and corrections.

In the past, scientists would gather data and process them individually to achieve an analysis thus having a much more intricate knowledge of the data and analysis. The theoretical models also required little (if any) simulations to compare with the data. Today both methods are becoming increasingly more dependent on pre-written software. Scientists are dissociating themselves from the intricacies of reducing raw observational data in experimentation or from bringing the theoretical models to life in simulations. These ‘intricacies’ are precisely those unseen faults, hidden assumptions, simplifications and approximations that define scientific progress.

Unfortunately, most persons who have recourse to a computer for statistical analysis of data are not much interested either in computer programming or in statistical method, being primarily concerned with their own proper business.
Hence the common use of library programs and various statistical packages. ... It’s time that was changed.


Anscombe’s quartet (http://en.wikipedia.org/wiki/Anscombe%27s_quartet) demonstrates how four data sets with widely different shapes (when plotted) give nearly identical output from standard regression techniques. Anscombe uses this (now famous) quartet, which was introduced in the paper quoted above, to argue that “Good statistical analysis is not a purely routine matter, and generally calls for more than one pass through the computer”. Echoing Anscombe’s concern after 44 years, some of the highly recognized statisticians of our time (Leek, McShane, Gelman, Colquhoun, Nuijten and Goodman), wrote in Nature that:

We need to appreciate that data analysis is not purely computational and algorithmic – it is a human behaviour....Researchers who hunt hard enough will turn up a result that fits statistical criteria – but their discovery will probably be a false positive.


Users of statistical (scientific) methods (software) are therefore not passive (objective) agents in their result. Therefore, it is necessary to actually understand the method, not just use it as a black box. The subjective experience gained by frequently using a method/software is not sufficient to claim an understanding of how the tool/method works and how relevant it is to the data and analysis. This kind of subjective experience is prone to serious misunderstandings about the data, what the software/statistical-method really does (especially as it gets more complicated), and thus the scientific interpretation of the result. This attitude is further encouraged through non-free software³, poorly written (or non-existent) scientific software manuals, and non-reproducible papers⁴. This approach to scientific software and methods only helps in producing dogmas and an “obscurantist faith in the expert’s special skill, and in his personal knowledge and authority”⁵.

Program or be programmed. Choose the former, and you gain access to the control panel of civilization. Choose the latter, and it could be the last real choice you get to make.


It is obviously impractical for any one human being to gain the intricate knowledge explained above for every step of an analysis. On the other hand, scientific data can be large and numerous, for example images produced by telescopes in astronomy. This requires efficient algorithms. To make things worse, natural scientists have generally not been trained in the advanced software techniques, paradigms and architecture that are taught in computer science or engineering courses and thus used in most software. The GNU Astronomy Utilities are an effort to tackle this issue.

³ https://www.gnu.org/philosophy/free-sw.html
⁴ Where the authors omit many of the analysis/processing “details” from the paper by arguing that they would make the paper too long/unreadable. However, software engineers have been dealing with such issues for a long time. There are thus software management solutions that allow us to supplement papers with all the details necessary to exactly reproduce the result. For example see zenodo.1163746 (https://doi.org/10.5281/zenodo.1163746) and zenodo.1164774 (https://doi.org/10.5281/zenodo.1164774) and this general discussion (http://akhlaghi.org/reproducible-science.html).
⁵ Karl Popper. The logic of scientific discovery. 1959. Larger quote is given at the start of the PDF (for print) version of this book.
Gnuastro is not just a software, this book is as important to the idea behind Gnuastro as the source code (software). This book has tried to learn from the success of the “Numerical Recipes” book in educating those who are not software engineers and computer scientists but still heavy users of computational algorithms, like astronomers. There are two major differences.

The first difference is that Gnuastro’s code and the background information are segregated: the code is moved within the actual Gnuastro software source code and the underlying explanations are given here in this book. In the source code, every non-trivial step is heavily commented and correlated with this book, it follows the same logic of this book, and all the programs follow a similar internal data, function and file structure, see Section 11.4 [Program source], page 522. Complementing the code, this book focuses on thoroughly explaining the concepts behind those codes (history, mathematics, science, software and usage advise when necessary) along with detailed instructions on how to run the programs. At the expense of frustrating “professionals” or “experts”, this book and the comments in the code also intentionally avoid jargon and abbreviations. The source code and this book are thus intimately linked, and when considered as a single entity can be thought of as a real (an actual software accompanying the algorithms) “Numerical Recipes” for astronomy.

The second major, and arguably more important, difference is that “Numerical Recipes” does not allow you to distribute any code that you have learned from it. In other words, it does not allow you to release your software’s source code if you have used their codes, you can only publicly release binaries (a black box) to the community. Therefore, while it empowers the privileged individual who has access to it, it exacerbates social ignorance. Exactly at the opposite end of the spectrum, Gnuastro’s source code is released under the GNU general public license (GPL) and this book is released under the GNU free documentation license. You are therefore free to distribute any software you create using parts of Gnuastro’s source code or text, or figures from this book, see Section 1.3 [Your rights], page 6.

With these principles in mind, Gnuastro’s developers aim to impose the minimum requirements on you (in computer science, engineering and even the mathematics behind the tools) to understand and modify any step of Gnuastro if you feel the need to do so, see Section 11.1 [Why C programming language?], page 516, and Section 11.2 [Program design philosophy], page 518.

Without prior familiarity and experience with optics, it is hard to imagine how, Galileo could have come up with the idea of modifying the Dutch military telescope optics to use in astronomy. Astronomical objects could not be seen with the Dutch military design of the telescope. In other words, it is unlikely that Galileo could have asked a random optician to make modifications (not understood by Galileo) to the Dutch design, to do something no astronomer of the time took seriously. In the paradigm of the day, what could be the purpose of enlarging geometric spheres (planets) or points (stars)? In that paradigm only the position and movement of the heavenly bodies was important, and that had already been accurately studied (recently by Tycho Brahe).

In the beginning of his “The Sidereal Messenger” (published in 1610) he cautions the readers on this issue and before describing his results/observations, Galileo instructs us on how to build a suitable instrument. Without a detailed description of how he made his tools and done his observations, no reasonable person would believe his results. Before he actually
saw the moons of Jupiter, the mountains on the Moon or the crescent of Venus, Galileo was “evasive” to Kepler. Science is defined by its tools/methods, not its raw results.

The same is true today: science cannot progress with a black box, or poorly released code. The source code of a research is the new (abstractified) communication language in science, understandable by humans and computers. Source code (in any programming language) is a language/notation designed to express all the details that would be too tedious/long/frustrating to report in spoken languages like English, similar to mathematic notation.

Today, the quality of the source code that goes into a scientific result (and the distribution of that code) is as critical to scientific vitality and integrity, as the quality of its written language/English used in publishing/distributing its paper. A scientific paper will not even be reviewed by any respectable journal if its written in a poor language/English. A similar level of quality assessment is thus increasingly becoming necessary regarding the codes/methods used to derive the results of a scientific paper.

Bjarne Stroustrup (creator of the C++ language) says: “Without understanding software, you are reduced to believing in magic”. Ken Thomson (the designer or the Unix operating system) says “I abhor a system designed for the ‘user’ if that word is a coded pejorative meaning ‘stupid and unsophisticated’.” Certainly no scientist (user of a scientific software) would want to be considered a believer in magic, or stupid and unsophisticated.

This can happen when scientists get too distant from the raw data and methods, and are mainly discussing results. In other words, when they feel they have tamed Nature into their own high-level (abstract) models (creations), and are mainly concerned with scaling up, or industrializing those results. Roughly five years before special relativity, and about two decades before quantum mechanics fundamentally changed Physics, Lord Kelvin is quoted as saying:

There is nothing new to be discovered in physics now. All that remains is more and more precise measurement.
—William Thomson (Lord Kelvin), 1900

A few years earlier Albert. A. Michelson made the following statement:

The more important fundamental laws and facts of physical science have all been discovered, and these are now so firmly established that the possibility of their ever being supplanted in consequence of new discoveries is exceedingly remote....
Our future discoveries must be looked for in the sixth place of decimals.
—Albert. A. Michelson, dedication of Ryerson Physics Lab, U. Chicago 1894

If scientists are considered to be more than mere “puzzle” solvers (simply adding to the decimals of existing values or observing a feature in 10, 100, or 100000 more galaxies or stars, as Kelvin and Michelson clearly believed), they cannot just passively sit back and

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7 For example, take the following two results on the age of the universe: roughly 14 billion years (suggested by the current consensus of the standard model of cosmology) and less than 10,000 years (suggested from some interpretations of the Bible). Both these numbers are results. What distinguishes these two results, is the tools/methods that were used to derive them. Therefore, as the term “Scientific method” also signifies, a scientific statement it defined by its method, not its result.
uncritically repeat the previous (observational or theoretical) methods/tools on new data. Today there is a wealth of raw telescope images ready (mostly for free) at the finger tips of anyone who is interested with a fast enough internet connection to download them. The only thing lacking is new ways to analyze this data and dig out the treasure that is lying hidden in them to existing methods and techniques.

New data that we insist on analyzing in terms of old ideas (that is, old models which are not questioned) cannot lead us out of the old ideas. However many data we record and analyze, we may just keep repeating the same old errors, missing the same crucially important things that the experiment was competent to find.


1.3 Your rights

The paragraphs below, in this section, belong to the GNU Texinfo\(^9\) manual and are not written by us! The name “Texinfo” is just changed to “GNU Astronomy Utilities” or “Gnuastro” because they are released under the same licenses and it is beautifully written to inform you of your rights.

GNU Astronomy Utilities is “free software”; this means that everyone is free to use it and free to redistribute it on certain conditions. Gnuastro is not in the public domain; it is copyrighted and there are restrictions on its distribution, but these restrictions are designed to permit everything that a good cooperating citizen would want to do. What is not allowed is to try to prevent others from further sharing any version of Gnuastro that they might get from you.

Specifically, we want to make sure that you have the right to give away copies of the programs that relate to Gnuastro, that you receive the source code or else can get it if you want it, that you can change these programs or use pieces of them in new free programs, and that you know you can do these things.

To make sure that everyone has such rights, we have to forbid you to deprive anyone else of these rights. For example, if you distribute copies of the Gnuastro related programs, you must give the recipients all the rights that you have. You must make sure that they, too, receive or can get the source code. And you must tell them their rights.

Also, for our own protection, we must make certain that everyone finds out that there is no warranty for the programs that relate to Gnuastro. If these programs are modified by someone else and passed on, we want their recipients to know that what they have is not what we distributed, so that any problems introduced by others will not reflect on our reputation.

The full text of the licenses for the Gnuastro book and software can be respectively found in Appendix D [GNU Gen. Pub. License v3], page 553\(^{10}\) and Appendix C [GNU Free Doc. License], page 545\(^{11}\).

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\(^{9}\) Texinfo is the GNU documentation system. It is used to create this book in all the various formats.

\(^{10}\) Also available in http://www.gnu.org/copyleft/gpl.html

\(^{11}\) Also available in http://www.gnu.org/copyleft/fdl.html
1.4 Naming convention

Gnuastro is a package of independent programs and a collection of libraries, here we are mainly concerned with the programs. Each program has an official name which consists of one or two words, describing what they do. The latter are printed with no space, for example NoiseChisel or Crop. On the command-line, you can run them with their executable names which start with an `ast` and might be an abbreviation of the official name, for example `astnoisechisel` or `astcrop`, see Section 3.3.1.3 [Executable names], page 97.

We will use “ProgramName” for a generic official program name and `astprogname` for a generic executable name. In this book, the programs are classified based on what they do and thoroughly explained. An alphabetical list of the programs that are installed on your system with this installation are given in Appendix A [Gnuastro programs list], page 538. That list also contains the executable names and version numbers along with a one line description.

1.5 Version numbering

Gnuastro can have two formats of version numbers, for official and unofficial releases. Official Gnuastro releases are announced on the `info-gnuastro` mailing list, they have a version control tag in Gnuastro’s development history, and their version numbers are formatted like “A.B”. A is a major version number, marking a significant planned achievement (for example see Section 1.5.1 [GNU Astronomy Utilities 1.0], page 8), while B is a minor version number, see below for more on the distinction. Note that the numbers are not decimals, so version 2.34 is much more recent than version 2.5, which is not equal to 2.50.

Gnuastro also allows a unique version number for unofficial releases. Unofficial releases can mark any point in Gnuastro’s development history. This is done to allow astronomers to easily use any point in the version controlled history for their data-analysis and research publication. See Section 3.2.2 [Version controlled source], page 85, for a complete introduction. This section is not just for developers and is intended to straightforward and easy to read, so please have a look if you are interested in the cutting-edge. This unofficial version number is a meaningful and easy to read string of characters, unique to that particular point of history. With this feature, users can easily stay up to date with the most recent bug fixes and additions that are committed between official releases.

The unofficial version number is formatted like: A.B.C-D. A and B are the most recent official version number. C is the number of commits that have been made after version A.B. D is the first 4 or 5 characters of the commit hash number\(^\text{12}\). Therefore, the unofficial version number ‘3.92.8-29c8’, corresponds to the 8th commit after the official version 3.92 and its commit hash begins with 29c8. The unofficial version number is sort-able (unlike the raw hash) and as shown above is descriptive of the state of the unofficial release. Of course an official release is preferred for publication (since its tarballs are easily available and it has gone through more tests, making it more stable), so if an official release is announced prior to your publication’s final review, please consider updating to the official release.

The major version number is set by a major goal which is defined by the developers and user community before hand, for example see Section 1.5.1 [GNU Astronomy Utilities

\(^{12}\) Each point in Gnuastro’s history is uniquely identified with a 40 character long hash which is created from its contents and previous history for example: 5b17501d8f29ba3cd610673261e6e2229c846d35. So the string D in the version for this commit could be 5b17, or 5b175.
The incremental work done in minor releases are commonly small steps in achieving the major goal. Therefore, there is no limit on the number of minor releases and the difference between the (hypothetical) versions 2.927 and 3.0 can be a small (negligible to the user) improvement that finalizes the defined goals.

1.5.1 GNU Astronomy Utilities 1.0

Currently (prior to Gnuastro 1.0), the aim of Gnuastro is to have a complete system for data manipulation and analysis at least similar to IRAF\(^\text{13}\). So an astronomer can take all the standard data analysis steps (starting from raw data to the final reduced product and standard post-reduction tools) with the various programs in Gnuastro.

The maintainers of each camera or detector on a telescope can provide a completely transparent shell script or Makefile to the observer for data analysis. This script can set configuration files for all the required programs to work with that particular camera. The script can then run the proper programs in the proper sequence. The user/observer can easily follow the standard shell script to understand (and modify) each step and the parameters used easily. Bash (or other modern GNU/Linux shell scripts) is powerful and made for this gluing job. This will simultaneously improve performance and transparency. Shell scripting (or Makefiles) are also basic constructs that are easy to learn and readily available as part of the Unix-like operating systems. If there is no program to do a desired step, Gnuastro’s libraries can be used to build specific programs.

The main factor is that all observatories or projects can freely contribute to Gnuastro and all simultaneously benefit from it (since it doesn’t belong to any particular one of them), much like how for-profit organizations (for example RedHat, or Intel and many others) are major contributors to free and open source software for their shared benefit. Gnuastro’s copyright has been fully awarded to GNU, so it doesn’t belong to any particular astronomer or astronomical facility or project.

1.6 New to GNU/Linux?

Some astronomers initially install and use a GNU/Linux operating system because their necessary tools can only be installed in this environment. However, the transition is not necessarily easy. To encourage you in investing the patience and time to make this transition, and actually enjoy it, we will first start with a basic introduction to GNU/Linux operating systems. Afterwards, in Section 1.6.1 [Command-line interface], page 9, we’ll discuss the wonderful benefits of the command-line interface, how it beautifully complements the graphic user interface, and why it is worth the (apparently steep) learning curve. Finally a complete chapter (Chapter 2 [Tutorials], page 16) is devoted to real world scenarios of using Gnuastro (on the command-line). Therefore if you don’t yet feel comfortable with the command-line we strongly recommend going through that chapter after finishing this section.

You might have already noticed that we are not using the name “Linux”, but “GNU/Linux”. Please take the time to have a look at the following essays and FAQs for a complete understanding of this very important distinction.


\(^\text{13}\) http://iraf.noao.edu/
In short, the Linux kernel\(^\text{14}\) is built using the GNU C library (glibc) and GNU compiler collection (gcc). The Linux kernel software alone is just a means for other software to access the hardware resources, it is useless alone: to say “running Linux”, is like saying “driving your carburetor”.

To have an operating system, you need lower-level (to build the kernel), and higher-level (to use it) software packages. The majority of such software in most Unix-like operating systems are GNU software: “the whole system is basically GNU with Linux loaded”. Therefore to acknowledge GNU’s instrumental role in the creation and usage of the Linux kernel and the operating systems that use it, we should call these operating systems “GNU/Linux”.

1.6.1 Command-line interface

One aspect of Gnuastro that might be a little troubling to new GNU/Linux users is that (at least for the time being) it only has a command-line user interface (CLI). This might be contrary to the mostly graphical user interface (GUI) experience with proprietary operating systems. Since the various actions available aren’t always on the screen, the command-line interface can be complicated, intimidating, and frustrating for a first-time user. This is understandable and also experienced by anyone who started using the computer (from childhood) in a graphical user interface (this includes most of Gnuastro’s authors). Here we hope to convince you of the unique benefits of this interface which can greatly enhance your productivity while complementing your GUI experience.

Through GNOME \(^\text{15}\), most GNU/Linux based operating systems now have an advanced and useful GUI. Since the GUI was created long after the command-line, some wrongly consider the command line to be obsolete. Both interfaces are useful for different tasks. For example you can’t view an image, video, pdf document or web page on the command-line. On the other hand you can’t reproduce your results easily in the GUI. Therefore they should not be regarded as rivals but as complementary user interfaces, here we will outline how the CLI can be useful in scientific programs.

You can think of the GUI as a veneer over the CLI to facilitate a small subset of all the possible CLI operations. Each click you do on the GUI, can be thought of as internally running a different CLI command. So asymptotically (if a good designer can design a GUI which is able to show you all the possibilities to click on) the GUI is only as powerful as the command-line. In practice, such graphical designers are very hard to find for every program, so the GUI operations are always a subset of the internal CLI commands. For programs that are only made for the GUI, this results in not including lots of potentially useful operations. It also results in ‘interface design’ to be a crucially important part of any GUI program. Scientists don’t usually have enough resources to hire a graphical designer, also the complexity of the GUI code is far more than CLI code, which is harmful for a scientific software, see Section 1.2 [Science and its tools], page 2.

For programs that have a GUI, one action on the GUI (moving and clicking a mouse, or tapping a touchscreen) might be more efficient and easier than its CLI counterpart (typing

\(^{14}\) In Unix-like operating systems, the kernel connects software and hardware worlds.

\(^{15}\) http://www.gnome.org/
the program name and your desired configuration). However, if you have to repeat that same action more than once, the GUI will soon become frustrating and prone to errors. Unless the designers of a particular program decided to design such a system for a particular GUI action, there is no general way to run any possible series of actions automatically on the GUI.

On the command-line, you can run any series of actions which can come from various CLI capable programs you have decided yourself in any possible permutation with one command\textsuperscript{16}. This allows for much more creativity and exact reproducibility that is not possible to a GUI user. For technical and scientific operations, where the same operation (using various programs) has to be done on a large set of data files, this is crucially important. It also allows exact reproducibility which is a foundation principle for scientific results. The most common CLI (which is also known as a shell) in GNU/Linux is GNU Bash, we strongly encourage you to put aside several hours and go through this beautifully explained webpage: \url{https://flossmanuals.net/command-line/}. You don’t need to read or even fully understand the whole thing, only a general knowledge of the first few chapters are enough to get you going.

Since the operations in the GUI are limited and they are visible, reading a manual is not that important in the GUI (most programs don’t even have any!). However, to give you the creative power explained above, with a CLI program, it is best if you first read the manual of any program you are using. You don’t need to memorize any details, only an understanding of the generalities is needed. Once you start working, there are more easier ways to remember a particular option or operation detail, see Section 4.3 [Getting help], page 123.

To experience the command-line in its full glory and not in the GUI terminal emulator, press the following keys together: \texttt{CTRL+ALT+F4}\textsuperscript{17} to access the virtual console. To return back to your GUI, press the same keys above replacing F4 with F7 (or F1, or F2, depending on your GNU/Linux distribution). In the virtual console, the GUI, with all its distracting colors and information, is gone. Enabling you to focus entirely on your actual work.

For operations that use a lot of your system’s resources (processing a large number of large astronomical images for example), the virtual console is the place to run them. This is because the GUI is not competing with your research work for your system’s RAM and CPU. Since the virtual consoles are completely independent, you can even log out of your GUI environment to give even more of your hardware resources to the programs you are running and thus reduce the operating time.

Since it uses far less system resources, the CLI is also convenient for remote access to your computer. Using secure shell (SSH) you can log in securely to your system (similar to the virtual console) from anywhere even if the connection speeds are low. There are apps for smart phones and tablets which allow you to do this.

\textsuperscript{16} By writing a shell script and running it, for example see the tutorials in Chapter 2 [Tutorials], page 16.
\textsuperscript{17} Instead of F4, you can use any of the keys from F1 to F6 for different virtual consoles depending on your GNU/Linux distribution, try them all out. You can also run a separate GUI from within this console if you want to.
1.7 Report a bug

According to Wikipedia “a software bug is an error, flaw, failure, or fault in a computer program or system that causes it to produce an incorrect or unexpected result, or to behave in unintended ways”. So when you see that a program is crashing, not reading your input correctly, giving the wrong results, or not writing your output correctly, you have found a bug. In such cases, it is best if you report the bug to the developers. The programs will also inform you if known impossible situations occur (which are caused by something unexpected) and will ask the users to report the bug issue.

Prior to actually filing a bug report, it is best to search previous reports. The issue might have already been found and even solved. The best place to check if your bug has already been discussed is the bugs tracker on Section 11.9 [Gnuastro project webpage], page 530, at https://savannah.gnu.org/bugs/?group=gnuastro. In the top search fields (under “Display Criteria”) set the “Open/Closed” drop-down menu to “Any” and choose the respective program or general category of the bug in “Category” and click the “Apply” button. The results colored green have already been solved and the status of those colored in red is shown in the table.

Recently corrected bugs are probably not yet publicly released because they are scheduled for the next Gnuastro stable release. If the bug is solved but not yet released and it is an urgent issue for you, you can get the version controlled source and compile that, see Section 3.2.2 [Version controlled source], page 85.

To solve the issue as readily as possible, please follow the following to guidelines in your bug report. The How to Report Bugs Effectively (http://www.chiark.greenend.org.uk/~sgtatham/bugs.html) and How To Ask Questions The Smart Way (http://catb.org/~esr/faqs/smart-questions.html) essays also provide some good generic advice for all software (don’t contact their authors for Gnuastro’s problems). Mastering the art of giving good bug reports (like asking good questions) can greatly enhance your experience with any free and open source software. So investing the time to read through these essays will greatly reduce your frustration after you see something doesn’t work the way you feel it is supposed to for a large range of software, not just Gnuastro.

Be descriptive

Please provide as many details as possible and be very descriptive. Explain what you expected and what the output was: it might be that your expectation was wrong. Also please clearly state which sections of the Gnuastro book (this book), or other references you have studied to understand the problem. This can be useful in correcting the book (adding links to likely places where users will check). But more importantly, it will be encouraging for the developers, since you are showing how serious you are about the problem and that you have actually put some thought into it. “To be able to ask a question clearly is two-thirds of the way to getting it answered.” – John Ruskin (1819-1900).

Individual and independent bug reports

If you have found multiple bugs, please send them as separate (and independent) bugs (as much as possible). This will significantly help us in managing and resolving them sooner.
Reproducible bug reports

If we cannot exactly reproduce your bug, then it is very hard to resolve it. So please send us a Minimal working example\(^{18}\) along with the description. For example in running a program, please send us the full command-line text and the output with the `-P` option, see Section 4.1.2.3 [Operating mode options], page 114. If it is caused only for a certain input, also send us that input file. In case the input FITS is large, please use Crop to only crop the problematic section and make it as small as possible so it can easily be uploaded and downloaded and not waste the archive’s storage, see Section 6.1 [Crop], page 188.

There are generally two ways to inform us of bugs:

- **Send a mail to** bug-gnuastro@gnu.org. Any mail you send to this address will be distributed through the bug-gnuastro mailing list\(^{19}\). This is the simplest way to send us bug reports. The developers will then register the bug into the project webpage (next choice) for you.

- **Use the Gnuastro project webpage at** https://savannah.gnu.org/projects/gnuastro/: There are two ways to get to the submission page as listed below. Fill in the form as described below and submit it (see Section 11.9 [Gnuastro project webpage], page 530, for more on the project webpage).
  - Using the top horizontal menu items, immediately under the top page title. Hovering your mouse on “Support” will open a drop-down list. Select “Submit new”.
  - In the main body of the page, under the “Communication tools” section, click on “Submit new item”.

Once the items have been registered in the mailing list or webpage, the developers will add it to either the “Bug Tracker” or “Task Manager” trackers of the Gnuastro project webpage. These two trackers can only be edited by the Gnuastro project developers, but they can be browsed by anyone, so you can follow the progress on your bug. You are most welcome to join us in developing Gnuastro and fixing the bug you have found maybe a good starting point. Gnuastro is designed to be easy for anyone to develop (see Section 1.2 [Science and its tools], page 2) and there is a full chapter devoted to developing it: Chapter 11 [Developing], page 516.

### 1.8 Suggest new feature

We would always be happy to hear of suggested new features. For every program there are already lists of features that we are planning to add. You can see the current list of plans from the Gnuastro project webpage at https://savannah.gnu.org/projects/gnuastro/ and following “Tasks”→“Browse” on the horizontal menu at the top of the page immediately under the title, see Section 11.9 [Gnuastro project webpage], page 530. If you want to request a feature to an existing program, click on the “Display Criteria” above the list and under “Category”, choose that particular program. Under “Category” you can also see the existing suggestions for new programs or other cases like installation, documentation or libraries. Also be sure to set the “Open/Closed” value to “Any”.

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\(^{19}\) [https://lists.gnu.org/mailman/listinfo/bug-gnuastro](https://lists.gnu.org/mailman/listinfo/bug-gnuastro)
If the feature you want to suggest is not already listed in the task manager, then follow the steps that are fully described in Section 1.7 [Report a bug], page 11. Please have in mind that the developers are all busy with their own astronomical research, and implementing existing “task”s to add or resolving bugs. Gnuastro is a volunteer effort and none of the developers are paid for their hard work. So, although we will try our best, please don’t not expect that your suggested feature be immediately included (with the next release of Gnuastro).

The best person to apply the exciting new feature you have in mind is you, since you have the motivation and need. In fact Gnuastro is designed for making it as easy as possible for you to hack into it (add new features, change existing ones and so on), see Section 1.2 [Science and its tools], page 2. Please have a look at the chapter devoted to developing (Chapter 11 [Developing], page 516) and start applying your desired feature. Once you have added it, you can use it for your own work and if you feel you want others to benefit from your work, you can request for it to become part of Gnuastro. You can then join the developers and start maintaining your own part of Gnuastro. If you choose to take this path of action please contact us before hand (Section 1.7 [Report a bug], page 11) so we can avoid possible duplicate activities and get interested people in contact.

**Gnuastro is a collection of low level programs:** As described in Section 11.2 [Program design philosophy], page 518, a founding principle of Gnuastro is that each library or program should be basic and low-level. High level jobs should be done by running the separate programs or using separate functions in succession through a shell script or calling the libraries by higher level functions, see the examples in Chapter 2 [Tutorials], page 16. So when making the suggestions please consider how your desired job can best be broken into separate steps and modularized.

1.9 Announcements

Gnuastro has a dedicated mailing list for making announcements (info-gnuastro). Anyone can subscribe to this mailing list. Anytime there is a new stable or test release, an email will be circulated there. The email contains a summary of the overall changes along with a detailed list (from the NEWS file). This mailing list is thus the best way to stay up to date with new releases, easily learn about the updated/new features, or dependencies (see Section 3.1 [Dependencies], page 74).

To subscribe to this list, please visit [https://lists.gnu.org/mailman/listinfo/info-gnuastro](https://lists.gnu.org/mailman/listinfo/info-gnuastro). Traffic (number of mails per unit time) in this list is designed to be low: only a handful of mails per year. Previous announcements are available on its archive ([http://lists.gnu.org/archive/html/info-gnuastro/](http://lists.gnu.org/archive/html/info-gnuastro/)).

1.10 Conventions

In this book we have the following conventions:

- All commands that are to be run on the shell (command-line) prompt as the user start with a `. In case they must be run as a super-user or system administrator, they will start with a single `. If the command is in a separate line and next line is also in the code type face, but doesn’t have any of the ` or ` signs, then it is the output of
the command after it is run. As a user, you don’t need to type those lines. A line that
starts with ## is just a comment for explaining the command to a human reader and
must not be typed.

- If the command becomes larger than the page width a \ is inserted in the code. If
  you are typing the code by hand on the command-line, you don’t need to use multiple
  lines or add the extra space characters, so you can omit them. If you want to copy and
  paste these examples (highly discouraged!) then the \ should stay.

The \ character is a shell escape character which is used commonly to make characters
which have special meaning for the shell loose that special place (the shell will not treat
them specially if there is a \ behind them). When it is a last character in a line (the
next character is a new-line character) the new-line character looses its meaning an the
shell sees it as a simple white-space character, enabling you to use multiple lines to
write your commands.

1.11 Acknowledgments

Gnuastro would not have been possible without scholarships and grants from several funding
institutions. We thus ask that if you used Gnuastro in any of your papers/reports, please
add the proper citation and acknowledge the funding agencies/projects. For details of which
papers to cite (may be different for different programs) and get the acknowledgment state-
ment to include in your paper, please run the relevant programs with the common --cite
option like the example commands below (for more on --cite, please see Section 4.1.2.3
[Operating mode options], page 114).

   $ astnoisechisel --cite
   $ astmkcatalog --cite

Here, we’ll acknowledge all the institutions (and their grants) along with the people who
helped make Gnuastro possible. The full list of Gnuastro authors is available at the start of
this book and the AUTHORS file in the source code (both are generated automatically from
the version controlled history). The plain text file THANKS, which is also distributed along
with the source code, contains the list of people and institutions who played an indirect role
in Gnuastro (not committed any code in the Gnuastro version controlled history).

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of Gnuastro. Working with Roland at the Centre de Recherche Astrophysique de Lyon
(CRAL), enabled a thorough re-write of the core functionality of all libraries and programs,
turning Gnuastro into the large collection of generic programs and libraries it is today. Work
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All work on Gnuastro has been voluntary, but the authors are most grateful to the following institutions (in chronological order) for hosting/supporting us in our research. Where necessary, these institutions have disclaimed any ownership of the parts of Gnuastro that were developed there, thus insuring the freedom of Gnuastro for the future (see Section 11.11.1 [Copyright assignment], page 533). We highly appreciate their support for free software, and thus free science, and therefore a free society.

Tohoku University Astronomical Institute, Sendai, Japan.
University of Salento, Lecce, Italy.
Centre de Recherche Astrophysique de Lyon (CRAL), Lyon, France.
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Google Summer of Code 2020
2 Tutorials

To help new users have a smooth and easy start with Gnuastro, in this chapter several thoroughly elaborated tutorials, or cookbooks, are provided. These tutorials demonstrate the capabilities of different Gnuastro programs and libraries, along with tips and guidelines for the best practices of using them in various realistic situations.

We strongly recommend going through these tutorials to get a good feeling of how the programs are related (built in a modular design to be used together in a pipeline), very similar to the core Unix-based programs that they were modeled on. Therefore these tutorials will greatly help in optimally using Gnuastro’s programs (and generally, the Unix-like command-line environment) effectively for your research.

In Section 2.1 [Sufi simulates a detection], page 17, we’ll start with a fictional1 tutorial explaining how Abd al-rahman Sufi (903 – 986 A.D., the first recorded description of “nebulous” objects in the heavens is attributed to him) could have used some of Gnuastro’s programs for a realistic simulation of his observations and see if his detection of nebulous objects was trust-able. Because all conditions are under control in a simulated/mock environment/dataset, mock datasets can be a valuable tool to inspect the limitations of your data analysis and processing. But they need to be as realistic as possible, so the first tutorial is dedicated to this important step of an analysis.

The next two tutorials (Section 2.2 [General program usage tutorial], page 24, and Section 2.3 [Detecting large extended targets], page 61) use real input datasets from some of the deep Hubble Space Telescope (HST) images and the Sloan Digital Sky Survey (SDSS) respectively. Their aim is to demonstrate some real-world problems that many astronomers often face and how they can be be solved with Gnuastro’s programs.

The ultimate aim of Section 2.2 [General program usage tutorial], page 24, is to detect galaxies in a deep HST image, measure their positions and brightness and select those with the strongest colors. In the process, it takes many detours to introduce you to the useful capabilities of many of the programs. So please be patient in reading it. If you don’t have much time and can only try one of the tutorials, we recommend this one.

Section 2.3 [Detecting large extended targets], page 61, deals with a major problem in astronomy: effectively detecting the faint outer wings of bright (and large) nearby galaxies to extremely low surface brightness levels (roughly one quarter of the local noise level in the example discussed). Besides the interesting scientific questions in these low-surface brightness features, failure to properly detect them will bias the measurements of the background objects and the survey’s noise estimates. This is an important issue, especially in wide surveys. Because bright/large galaxies and stars2, cover a significant fraction of the survey area.

---

1 The two historically motivated tutorials (Section 2.1 [Sufi simulates a detection], page 17, is not intended to be a historical reference (the historical facts of this fictional tutorial used Wikipedia as a reference). This form of presenting a tutorial was influenced by the PGF/TikZ and Beamer manuals. They are both packages in in \TeX and \LaTeX, the first is a high-level vector graphic programming environment, while with the second you can make presentation slides. On a similar topic, there are also some nice words of wisdom for Unix-like systems called Rootless Root (http://catb.org/esr/writings/unix-koans). These also have a similar style but they use a mythical figure named Master Foo. If you already have some experience in Unix-like systems, you will definitely find these Unix Koans entertaining/educative.

2 Stars also have similarly large and extended wings due to the point spread function, see Section 8.1.1.2 [Point spread function], page 334.
In these tutorials, we have intentionally avoided too many cross references to make it more easy to read. For more information about a particular program, you can visit the section with the same name as the program in this book. Each program section in the subsequent chapters starts by explaining the general concepts behind what it does, for example see Section 6.3 [Convolve], page 216. If you only want practical information on running a program, for example its options/configuration, input(s) and output(s), please consult the subsection titled “Invoking ProgramName”, for example see Section 7.2.1 [Invoking NoiseChisel], page 271. For an explanation of the conventions we use in the example codes through the book, please see Section 1.10 [Conventions], page 13.

2.1 Sufi simulates a detection

It is the year 953 A.D. and Abd al-rahman Sufi (903 – 986 A.D.)\(^3\) is in Shiraz as a guest astronomer. He had come there to use the advanced 123 centimeter astrolabe for his studies on the Ecliptic. However, something was bothering him for a long time. While mapping the constellations, there were several non-stellar objects that he had detected in the sky, one of them was in the Andromeda constellation. During a trip he had to Yemen, Sufi had seen another such object in the southern skies looking over the Indian ocean. He wasn’t sure if such cloud-like non-stellar objects (which he was the first to call ‘Sahābi’ in Arabic or ‘nebulous’) were real astronomical objects or if they were only the result of some bias in his observations. Could such diffuse objects actually be detected at all with his detection technique?

He still had a few hours left until nightfall (when he would continue his studies on the ecliptic) so he decided to find an answer to this question. He had thoroughly studied Claudius Ptolemy’s (90 – 168 A.D) Almagest and had made lots of corrections to it, in particular in measuring the brightness. Using his same experience, he was able to measure a magnitude for the objects and wanted to simulate his observation to see if a simulated object with the same brightness and size could be detected in a simulated noise with the same detection technique. The general outline of the steps he wants to take are:

1. Make some mock profiles in an over-sampled image. The initial mock image has to be over-sampled prior to convolution or other forms of transformation in the image. Through his experiences, Sufi knew that this is because the image of heavenly bodies is actually transformed by the atmosphere or other sources outside the atmosphere (for example gravitational lenses) prior to being sampled on an image. Since that transformation occurs on a continuous grid, to best approximate it, he should do all the work on a finer pixel grid. In the end he can re-sample the result to the initially desired grid size.

2. Convolve the image with a point spread function (PSF, see Section 8.1.1.2 [Point spread function], page 334) that is over-sampled to the same resolution as the mock image. Since he wants to finish in a reasonable time and the PSF kernel will be very large due to oversampling, he has to use frequency domain convolution which has the side effect of dimming the edges of the image. So in the first step above he also has to build the

---

\(^3\) In Latin Sufi is known as Azophi. He was an Iranian astronomer. His manuscript “Book of fixed stars” contains the first recorded observations of the Andromeda galaxy, the Large Magellanic Cloud and seven other non-stellar or ‘nebulous’ objects.
image to be larger by at least half the width of the PSF convolution kernel on each edge.

3. With all the transformations complete, the image should be re-sampled to the same size of the pixels in his detector.

4. He should remove those extra pixels on all edges to remove frequency domain convolution artifacts in the final product.

5. He should add noise to the (until now, noise-less) mock image. After all, all observations have noise associated with them.

Fortunately Sufi had heard of GNU Astronomy Utilities from a colleague in Isfahan (where he worked) and had installed it on his computer a year before. It had tools to do all the steps above. He had used MakeProfiles before, but wasn’t sure which columns he had chosen in his user or system wide configuration files for which parameters, see Section 4.2 [Configuration files], page 120. So to start his simulation, Sufi runs MakeProfiles with the -P option to make sure what columns in a catalog MakeProfiles currently recognizes and the output image parameters. In particular, Sufi is interested in the recognized columns (shown below).

```
$ astmkprof -P
```

[[[ ... Truncated lines ... ]]]

# Output:

type float32 # Type of output: e.g., int16, float32, etc...
mergedsize 1000,1000 # Number of pixels along first FITS axis.
oversample 5 # Scale of oversampling (>0 and odd).

[[[ ... Truncated lines ... ]]]

# Columns, by info (see '--searchin'), or number (starting from 1):
ccol 2 # Center along first FITS axis (horizontal).
ccol 3 # Center along second FITS axis (vertical).
fcol 4 # sersic (1), moffat (2), gaussian (3),
       # point (4), flat (5), circumference (6).
rcol 5 # Effective radius or FWHM in pixels.
ncol 6 # Sersic index or Moffat beta.
pcol 7 # Position angle.
qcol 8 # Axis ratio.
mcol 9 # Magnitude.
tcol 10 # Truncation in units of radius or pixels.

[[[ ... Truncated lines ... ]]]

In Gnuastro, column counting starts from 1, so the columns are ordered such that the first column (number 1) can be an ID he specifies for each object (and MakeProfiles ignores), each subsequent column is used for another property of the profile. It is also possible to use column names for the values of these options and change these defaults, but Sufi preferred
to stick to the defaults. Fortunately MakeProfiles has the capability to also make the PSF which is to be used on the mock image and using the \texttt{--prepforconv} option, he can also make the mock image to be larger by the correct amount and all the sources to be shifted by the correct amount.

For his initial check he decides to simulate the nebula in the Andromeda constellation. The night he was observing, the PSF had roughly a FWHM of about 5 pixels, so as the first row (profile), he defines the PSF parameters and sets the radius column (\texttt{rcol1} above, fifth column) to 5.000, he also chooses a Moffat function for its functional form. Remembering how diffuse the nebula in the Andromeda constellation was, he decides to simulate it with a mock Sérsic index 1.0 profile. He wants the output to be 499 pixels by 499 pixels, so he can put the center of the mock profile in the central pixel of the image (note that an even number doesn’t have a central element).

Looking at his drawings of it, he decides a reasonable effective radius for it would be 40 pixels on this image pixel scale, he sets the axis ratio and position angle to approximately correct values too and finally he sets the total magnitude of the profile to 3.44 which he had accurately measured. Sufi also decides to truncate both the mock profile and PSF at 5 times the respective radius parameters. In the end he decides to put four stars on the four corners of the image at very low magnitudes as a visual scale. While he was preparing the catalog, one of his students approached him and was also following the steps.

Using all the information above, he creates the catalog of mock profiles he wants in a file named \texttt{cat.txt} (short for catalog) using his favorite text editor and stores it in a directory named \texttt{simulationtest} in his home directory. [The \texttt{cat} command prints the contents of a file, short for “concatenation”. So please copy-paste the lines after “\texttt{cat cat.txt}” into \texttt{cat.txt} when the editor opens in the steps above it, note that there are 7 lines, first one starting with \#. Also be careful when copying from the PDF format, the Info, web, or text formats shouldn’t have any problem]:

```bash
$ mkdir ~/simulationtest
$ cd ~/simulationtest
$ pwd
/home/rahman/simulationtest
$ emacs cat.txt
$ ls
  cat.txt
$ cat cat.txt

# Column 4: PROFILE_NAME [,str6] Radial profile's functional name
1 0.0000 0.0000 moffat 5.000 4.765 0.0000 1.000 30.000 5.000
2 250.00 250.00 sersic 40.00 1.000 -25.00 0.400 3.4400 5.000
3 50.000 50.000 point 0.000 0.000 0.0000 0.000 6.0000 0.000
4 450.00 50.000 point 0.000 0.000 0.0000 0.000 6.5000 0.000
5 50.000 450.00 point 0.000 0.000 0.0000 0.000 7.0000 0.000
6 450.00 450.00 point 0.000 0.000 0.0000 0.000 7.5000 0.000
```

The zero point magnitude for his observation was 18. Now he has all the necessary parameters and runs MakeProfiles with the following command:

```bash
$ astmkprof --prepforconv --mergedsize=499,499 --zeropoint=18.0 cat.txt
```
MakeProfiles started on Sat Oct  6 16:26:56 953
  - 6 profiles read from cat.txt
  - Random number generator (RNG) type: mt19937
  - Using 8 threads.
  ---- row 2 complete, 5 left to go
  ---- row 3 complete, 4 left to go
  ---- row 4 complete, 3 left to go
  ---- row 5 complete, 2 left to go
  ---- ./0_cat.fits created.
  ---- row 0 complete, 1 left to go
  ---- row 1 complete, 0 left to go
  - ./cat.fits created. 0.041651 seconds
MakeProfiles finished in 0.267234 seconds

$ls
0_cat.fits  cat.fits  cat.txt

The file 0_cat.fits is the PSF Sufi had asked for, and cat.fits is the image containing the main objects in the catalog. The size of cat.fits was surprising for the student, instead of 499 by 499 (as we had requested), it was 2615 by 2615 pixels (from the command below):

$ astfits cat.fits -h1 | grep NAXIS

So Sufi explained why oversampling is important in modeling, especially for parts of the image where the flux change is significant over a pixel. Recall that when you oversample the model (for example by 5 times), for every desired pixel, you get 25 pixels (5 \times 5). Sufi then explained that after convolving (next step below) we will down-sample the image to get our originally desired size/resolution.

Sufi then opened cat.fits [you can use any FITS viewer, for example, ds9]. After seeing the image, the student complained that only the large elliptical model for the Andromeda nebula can be seen in the center. He couldn’t see the four stars that we had also requested in the catalog. So Sufi had to explain that the stars are there in the image, but the reason that they aren’t visible when looking at the whole image at once, is that they only cover a single pixel! To prove it, he centered the image around the coordinates 2308 and 2308, where one of the stars is located in the over-sampled image [you can do this in ds9 by selecting “Pan” in the “Edit” menu, then clicking around that position]. Sufi then zoomed in to that region and soon, the star’s non-zero pixel could be clearly seen.

Sufi explained that the stars will take the shape of the PSF (cover an area of more than one pixel) after convolution. If we didn’t have an atmosphere and we didn’t need an aperture, then stars would only cover a single pixel with normal CCD resolutions. So Sufi convolved the image with this command:

$ astconvolve --kernel=0_cat.fits cat.fits
Convolve started on Mon Apr  6 16:35:32 953
  - Using 8 CPU threads.
  - Input: cat.fits (hdu: 1)
  - Kernel: 0_cat.fits (hdu: 1)
  - Input and Kernel images padded. 0.075541 seconds
  - Images converted to frequency domain. 6.728407 seconds
- Multiplied in the frequency domain. 0.040659 seconds
- Converted back to the spatial domain. 3.465344 seconds
- Padded parts removed. 0.016767 seconds
- Output: cat_convolved.fits
Convolve finished in: 10.422161 seconds

$ ls
0_cat.fits cat_convolved.fits cat.fits cat.txt
When convolution finished, Sufi opened cat_convolved.fits and the four stars could be easily seen now. It was interesting for the student that all the flux in that single pixel is now distributed over so many pixels (the sum of all the pixels in each convolved star is actually equal to the value of the single pixel before convolution). Sufi explained how a PSF with a larger FWHM would make the points even wider than this (distributing their flux in a larger area). With the convolved image ready, they were prepared to re-sample it to the original pixel scale Sufi had planned [from the $ astmkprof -P command above, recall that MakeProfiles had over-sampled the image by 5 times]. Sufi explained the basic concepts of warping the image to his student and ran Warp with the following command:

$ astwarp --scale=1/5 --centeroncorner cat_convolved.fits
Warp started on Mon Apr  6 16:51:59 953
Using 8 CPU threads.
Input: cat_convolved.fits (hdu: 1)
matrix:
0.2000 0.0000 0.4000
0.0000 0.2000 0.4000
0.0000 0.0000 1.0000

$ ls
0_cat.fits cat_convolved_scaled.fits cat.txt
cat_convolved.fits cat.fits

$ astfits -p cat_convolved_scaled.fits | grep NAXIS
NAXIS = 2 / number of data axes
NAXIS1 = 523 / length of data axis 1
NAXIS2 = 523 / length of data axis 2
cat_convolved_scaled.fits now has the correct pixel scale. However, the image is still larger than what we had wanted, it is 523 \((499 + 12 + 12)\) by 523 pixels. The student is slightly confused, so Sufi also re-samples the PSF with the same scale by running

$ astwarp --scale=1/5 --centeroncorner 0_cat.fits
$ astfits -p 0_cat_scaled.fits | grep NAXIS
NAXIS = 2 / number of data axes
NAXIS1 = 25 / length of data axis 1
NAXIS2 = 25 / length of data axis 2
Sufi notes that 25 = \((2 \times 12) + 1\) and goes on to explain how frequency space convolution will dim the edges and that is why he added the --prepforconv option to MakeProfiles, see Section 8.1.2 [If convolving afterwards], page 338. Now that convolution is done, Sufi can remove those extra pixels using Crop with the command below. Crop’s --section option
accepts coordinates inclusively and counting from 1 (according to the FITS standard), so the crop region’s first pixel has to be 13, not 12.

```
$ astcrop cat_convolved_scaled.fits --section=13:*-12,13:*-12  \
   --mode=img --zeroisnotblank
Crop started on Sat Oct 6 17:03:24 953
- Read metadata of 1 image. 0.001304 seconds
---- ...nvolved_scaled_cropped.fits created: 1 input.
Crop finished in: 0.027204 seconds
```

Finally, `cat_convolved_scaled_cropped.fits` is 499 × 499 pixels and the mock Andromeda galaxy is centered on the central pixel (open the image in a FITS viewer and confirm this by zooming into the center, note that an even-width image wouldn’t have a central pixel). This is the same dimensions as Sufi had desired in the beginning. All this trouble was certainly worth it because now there is no dimming on the edges of the image and the profile centers are more accurately sampled.

The final step to simulate a real observation would be to add noise to the image. Sufi set the zero point magnitude to the same value that he set when making the mock profiles and looking again at his observation log, he had measured the background flux near the nebula had a magnitude of 7 that night. So using these values he ran MakeNoise:

```
$ astmknoise --zeropoint=18 --background=7 --output=out.fits  \
     cat_convolved_scaled_cropped.fits
MakeNoise started on Mon Apr 6 17:05:06 953
- Generator type: ranlxs1
- Generator seed: 1428318100
MakeNoise finished in: 0.033491 (seconds)
```

The `out.fits` file now contains the noised image of the mock catalog Sufi had asked for. Seeing how the `--output` option allows the user to specify the name of the output file, the student was confused and wanted to know why Sufi hadn’t used it before? Sufi then explained to him that for intermediate steps it is best to rely on the automatic output, see Section 4.10 [Automatic output], page 142. Doing so will give all the intermediate files the same basic name structure, so in the end you can simply remove them all with the Shell’s capabilities. So Sufi decided to show this to the student by making a shell script from the commands he had used before.

The command-line shell has the capability to read all the separate input commands from a file. This is useful when you want to do the same thing multiple times, with only the names of the files or minor parameters changing between the different instances. Using the shell’s history (by pressing the up keyboard key) Sufi reviewed all the commands and then he retrieved the last 5 commands with the `$ history 5` command. He selected all those
lines he had input and put them in a text file named `mymock.sh`. Then he defined the `edge` and `base` shell variables for easier customization later. Finally, before every command, he added some comments (lines starting with `#`) for future readability.

```bash
edge=12
base=cat

# Stop running next commands if one fails.
set -e

# Remove any (possibly) existing output (from previous runs)
# before starting.
rm -f out.fits

# Run MakeProfiles to create an oversampled FITS image.
astmkprof --prepforconv --mergedsize=499,499 --zeropoint=18.0 "$base".txt

# Convolve the created image with the kernel.
astconvolve --kernel=0_"$base".fits "$base".fits

# Scale the image back to the intended resolution.
astwarp --scale=1/5 --centeroncorner "$base"_convolved.fits

# Crop the edges out (dimmed during convolution). `--section` accepts
# inclusive coordinates, so the start of start of the section must be
# one pixel larger than its end.
st_edge=$(( edge + 1 ))
astcrop "$base"_convolved_scaled.fits --zeroisnotblank
    --mode=img --section=$st_edge:*-$edge,$st_edge:*-$edge

# Add noise to the image.
astmknoise --zeropoint=18 --background=7 --output=out.fits "$
    base"_convolved_scaled_cropped.fits

# Remove all the temporary files.
rm 0*.fits "$base"*.fits
```

He used this chance to remind the student of the importance of comments in code or shell scripts: when writing the code, you have a good mental picture of what you are doing, so writing comments might seem superfluous and excessive. However, in one month when you want to re-use the script, you have lost that mental picture and remembering it can be time-consuming and frustrating. The importance of comments is further amplified when you want to share the script with a friend/colleague. So it is good to accompany any script/code with useful comments while you are writing it (create a good mental picture of what/why you are doing something).

Sufi then explained to the eager student that you define a variable by giving it a name, followed by an `=` sign and the value you want. Then you can reference that variable from
anywhere in the script by calling its name with a \$ prefix. So in the script whenever you see $base, the value we defined for it above is used. If you use advanced editors like GNU Emacs or even simpler ones like Gedit (part of the GNOME graphical user interface) the variables will become a different color which can really help in understanding the script. We have put all the $base variables in double quotation marks ("), so the variable name and the following text do not get mixed, the shell is going to ignore the " after replacing the variable value. To make the script executable, Sufi ran the following command:

```
$ chmod +x mymock.sh
```

Then finally, Sufi ran the script, simply by calling its file name:

```
$ ./mymock.sh
```

After the script finished, the only file remaining is the out.fits file that Sufi had wanted in the beginning. Sufi then explained to the student how he could run this script anywhere that he has a catalog if the script is in the same directory. The only thing the student had to modify in the script was the name of the catalog (the value of the base variable in the start of the script) and the value to the edge variable if he changed the PSF size. The student was also happy to hear that he won’t need to make it executable again when he makes changes later, it will remain executable unless he explicitly changes the executable flag with chmod.

The student was really excited, since now, through simple shell scripting, he could really speed up his work and run any command in any fashion he likes allowing him to be much more creative in his works. Until now he was using the graphical user interface which doesn’t have such a facility and doing repetitive things on it was really frustrating and some times he would make mistakes. So he left to go and try scripting on his own computer.

Sufi could now get back to his own work and see if the simulated nebula which resembled the one in the Andromeda constellation could be detected or not. Although it was extremely faint\(^4\), fortunately it passed his detection tests and he wrote it in the draft manuscript that would later become “Book of fixed stars”. He still had to check the other nebula he saw from Yemen and several other such objects, but they could wait until tomorrow (thanks to the shell script, he only has to define a new catalog). It was nearly sunset and they had to begin preparing for the night’s measurements on the ecliptic.

### 2.2 General program usage tutorial

Measuring colors of astronomical objects in broad-band or narrow-band images is one of the most basic and common steps in astronomical analysis. Here, we will use Gnuastro’s programs to get a physical scale (area at certain redshifts) of the field we are studying, detect objects in a Hubble Space Telescope (HST) image, measure their colors and identify the ones with the strongest colors, do a visual inspection of these objects and inspect spatial position in the image. After this tutorial, you can also try the Section 2.3 [Detecting large extended targets], page 61, tutorial which goes into a little more detail on detecting very low surface brightness signal.

---

\(^4\) The brightness of a diffuse object is added over all its pixels to give its final magnitude, see Section 8.1.3 [Brightness, Flux, Magnitude and Surface brightness], page 338. So although the magnitude 3.44 (of the mock nebula) is orders of magnitude brighter than 6 (of the stars), the central galaxy is much fainter. Put another way, the brightness is distributed over a large area in the case of a nebula.
During the tutorial, we will take many detours to explain, and practically demonstrate, the many capabilities of Gnuastro’s programs. In the end you will see that the things you learned during this tutorial are much more generic than this particular problem and can be used in solving a wide variety of problems involving the analysis of data (images or tables). So please don’t rush, and go through the steps patiently to optimally master Gnuastro.

In this tutorial, we’ll use the HSTeXtreme Deep Field (https://archive.stsci.edu/prepds/xdf) dataset. Like almost all astronomical surveys, this dataset is free for download and usable by the public. You will need the following tools in this tutorial: Gnuastro, SAO DS9\(^5\), GNU Wget\(^6\), and AWK (most common implementation is GNU AWK\(^7\)).

This tutorial was first prepared for the “Exploring the Ultra-Low Surface Brightness Universe” workshop (November 2017) at the ISSI in Bern, Switzerland. It was further extended in the “4th Indo-French Astronomy School” (July 2018) organized by LIO, CRAL CNRS UMR5574, UCBL, and IUCAA in Lyon, France. We are very grateful to the organizers of these workshops and the attendees for the very fruitful discussions and suggestions that made this tutorial possible.

Write the example commands manually: Try to type the example commands on your terminal manually and use the history feature of your command-line (by pressing the “up” button to retrieve previous commands). Don’t simply copy and paste the commands shown here. This will help simulate future situations when you are processing your own datasets.

2.2.1 Calling Gnuastro’s programs

A handy feature of Gnuastro is that all program names start with ast. This will allow your command-line processor to easily list and auto-complete Gnuastro’s programs for you. Try typing the following command (press \texttt{TAB} key when you see \texttt{<TAB>}) to see the list:

\begin{verbatim}
$ ast<TAB><TAB>
\end{verbatim}

Any program that starts with ast (including all Gnuastro programs) will be shown. By choosing the subsequent characters of your desired program and pressing \texttt{<TAB><TAB>}, the list will narrow down and the program name will auto-complete once your input characters are unambiguous. In short, you often don’t need to type the full name of the program you want to run.

2.2.2 Accessing documentation

Gnuastro contains a large number of programs and it is natural to forget the details of each program’s options or inputs and outputs. Therefore, before starting the analysis steps of this tutorial, let’s review how you can access this book to refresh your memory any time you want, without having to take your hands off the keyboard.

When you install Gnuastro, this book is also installed on your system along with all the programs and libraries, so you don’t need an internet connection to to access/read it. Also, by accessing this book as described below, you can be sure that it corresponds to your installed version of Gnuastro.

\(^5\) See Section B.1 [SAO ds9], page 540, available at http://ds9.si.edu/site/Home.html

\(^6\) https://www.gnu.org/software/wget

\(^7\) https://www.gnu.org/software/gawk
GNU Info\(^8\) is the program in charge of displaying the manual on the command-line (for more, see Section 4.3.4 [Info], page 125). To see this whole book on your command-line, please run the following command and press subsequent keys. Info has its own mini-environment, therefore we’ll show the keys that must be pressed in the mini-environment after a \(\rightarrow\) sign. You can also ignore anything after the # sign in the middle of the line, they are only for your information.

\[
\begin{align*}
$\text{info}\ gnuastro & \quad \#\ \text{Open the top of the manual.} \\
\rightarrow\ <\text{SPACE}> & \quad \#\ \text{All the book chapters.} \\
\rightarrow\ <\text{SPACE}> & \quad \#\ \text{Continue down: show sections.} \\
\rightarrow\ <\text{SPACE}>\ldots & \quad \#\ \text{Keep pressing space to go down.} \\
\rightarrow\ q & \quad \#\ \text{Quit Info, return to the command-line.}
\end{align*}
\]

The thing that greatly simplifies navigation in Info is the links (regions with an under- line). You can immediately go to the next link in the page with the <TAB> key and press <ENTER> on it to go into that part of the manual. Try the commands above again, but this time also use <TAB> to go to the links and press <ENTER> on them to go to the respective section of the book. Then follow a few more links and go deeper into the book. To return to the previous page, press 1 (small L). If you are searching for a specific phrase in the whole book (for example an option name), press s and type your search phrase and end it with an <ENTER>.

You don’t need to start from the top of the manual every time. For example, to get to Section 7.2.1 [Invoking NoiseChisel], page 271, run the following command. In general, all programs have such an “Invoking ProgramName” section in this book. These sections are specifically for the description of inputs, outputs and configuration options of each program. You can access them directly for each program by giving its executable name to Info.

\[
\$\text{info}\ astnoisechisel
\]

The other sections don’t have such shortcuts. To directly access them from the command-line, you need to tell Info to look into Gnuastro’s manual, then look for the specific section (an unambiguous title is necessary). For example, if you only want to review/remember NoiseChisel’s Section 7.2.1.2 [Detection options], page 275), just run the following command. Note how case is irrelevant for Info when calling a title in this manner.

\[
\$\text{info}\ gnuastro\ "Detection options"
\]

In general, Info is a powerful and convenient way to access this whole book with detailed information about the programs you are running. If you are not already familiar with it, please run the following command and just read along and do what it says to learn it. Don’t stop until you feel sufficiently fluent in it. Please invest the half an hour’s time necessary to start using Info comfortably. It will greatly improve your productivity and you will start reaping the rewards of this investment very soon.

\[
\$\text{info}\ info
\]

As a good scientist you need to feel comfortable to play with the features/options and avoid (be critical to) using default values as much as possible. On the other hand, our human memory is limited, so it is important to be able to easily access any part of this book fast and remember the option names, what they do and their acceptable values.

---

\(^8\) GNU Info is already available on almost all Unix-like operating systems.
If you just want the option names and a short description, calling the program with the `--help` option might also be a good solution like the first example below. If you know a few characters of the option name, you can feed the output to `grep` like the second or third example commands.

```
$ astnoisechisel --help
$ astnoisechisel --help | grep quant
$ astnoisechisel --help | grep check
```

### 2.2.3 Setup and data download

The first step in the analysis of the tutorial is to download the necessary input datasets. First, to keep things clean, let’s create a `gnuastro-tutorial` directory and continue all future steps in it:

```
$ mkdir gnuastro-tutorial
$ cd gnuastro-tutorial
```

We will be using the near infra-red Wide Field Camera (http://www.stsci.edu/hst/wfc3) dataset. If you already have them in another directory (for example `XDFDIR`, with the same FITS file names), you can set the download directory to be a symbolic link to `XDFDIR` with a command like this:

```
$ ln -s XDFDIR download
```

Otherwise, when the following images aren’t already present on your system, you can make a `download` directory and download them there.

```
$ mkdir download
$ cd download
$ xdfurl=http://archive.stsci.edu/pub/hlsp/xdf
$ wget $xdfurl/hlsp_xdf_hst_wfc3ir-60mas_hudf_f105w_v1_sci.fits
$ wget $xdfurl/hlsp_xdf_hst_wfc3ir-60mas_hudf_f125w_v1_sci.fits
$ wget $xdfurl/hlsp_xdf_hst_wfc3ir-60mas_hudf_f160w_v1_sci.fits
$ cd..
```

In this tutorial, we’ll just use these three filters. Later, you may need to download more filters. To do that, you can use the shell’s `for` loop to download them all in series (one after the other⁹) with one command like the one below for the WFC3 filters. Put this command instead of the three `wget` commands above. Recall that all the extra spaces, back-slashes (\), and new lines can be ignored if you are typing on the lines on the terminal.

```
$ for f in f105w f125w f140w f160w; do \
    wget $xdfurl/hlsp_xdf_hst_wfc3ir-60mas_hudf_"$f"_v1_sci.fits; \
    done
```

### 2.2.4 Dataset inspection and cropping

First, let’s visually inspect the datasets we downloaded in Section 2.2.3 [Setup and data download], page 27. Let’s take F160W image as an example. Do the steps below with the other image(s) too (and later with any dataset that you want to work on). It is very important to get a good visual feeling of the dataset you intend to use. Also, note how

---

⁹ Note that you only have one port to the internet, so downloading in parallel will actually be slower than downloading in series.
SAO DS9 (used here for visual inspection of FITS images) doesn’t follow the GNU style of options where “long” and “short” options are preceded by -- and - respectively (for example --width and -w, see Section 4.1.1.2 [Options], page 107).

Run the command below to see the F160W image with DS9. Ds9’s -zscale scaling is good to visually highlight the low surface brightness regions, and as the name suggests, -zoom to fit will fit the whole dataset in the window. If the window is too small, expand it with your mouse, then press the “zoom” button on the top row of buttons above the image. Afterwards, in the bottom row of buttons, press “zoom fit”. You can also zoom in and out by scrolling your mouse or the respective operation on your touch-pad when your cursor/pointer is over the image.

```
$ ds9 download/hlsp_xdf_hst_wfc3ir-60mas_hudf_f160w_v1_sci.fits -zscale -zoom to fit
```

As you hover your mouse over the image, notice how the “Value” and positional fields on the top of the ds9 window get updated. The first thing you might notice is that when you hover the mouse over the regions with no data, they have a value of zero. The next thing might be that the dataset actually has two “depth”s (see Section 7.4.2 [Quantifying measurement limits], page 298). Recall that this is a combined/reduced image of many exposures, and the parts that have more exposures are deeper. In particular, the exposure time of the deep inner region is larger than 4 times of the outer (more shallower) parts.

To simplify the analysis in this tutorial, we’ll only be working on the deep field, so let’s crop it out of the full dataset. Fortunately the XDF survey webpage (above) contains the vertices of the deep flat WFC3-IR field. With Gnuastro’s Crop program\(^\text{10}\), you can use those vertices to cutout this deep region from the larger image. But before that, to keep things organized, let’s make a directory called flat-ir and keep the flat (single-depth) regions in that directory (with a ‘xdf-’ suffix for a shorter and easier filename).

```
$ mkdir flat-ir
$ astcrop --mode=wcs -h0 --output=flat-ir/xdf-f105w.fits --polygon="53.187414,-27.779152 : 53.159507,-27.759633 : \
53.134517,-27.787144 : 53.161906,-27.807208" download/hlsp_xdf_hst_wfc3ir-60mas_hudf_f105w_v1_sci.fits 
```

```
$ astcrop --mode=wcs -h0 --output=flat-ir/xdf-f125w.fits --polygon="53.187414,-27.779152 : 53.159507,-27.759633 : \
53.134517,-27.787144 : 53.161906,-27.807208" download/hlsp_xdf_hst_wfc3ir-60mas_hudf_f125w_v1_sci.fits 
```

```
$ astcrop --mode=wcs -h0 --output=flat-ir/xdf-f160w.fits --polygon="53.187414,-27.779152 : 53.159507,-27.759633 : \
53.134517,-27.787144 : 53.161906,-27.807208" download/hlsp_xdf_hst_wfc3ir-60mas_hudf_f160w_v1_sci.fits 
```

The only thing varying in the three calls to Gnuastro’s Crop program is the filter name! Note how everything else is the same. In such cases, you should generally avoid repeating a command manually, it is prone to many bugs, and as you see, it is very hard to read (didn’t you suddenly write a 7 as an 8?). To simplify the command, and later allow work

\(^{10}\) To learn more about the crop program see Section 6.1 [Crop], page 188.
on more filters, we can use the shell’s for loop as shown below. Notice how the place where the filter names (\texttt{f105w}, \texttt{f125w} and \texttt{f160w}) are used above, have been replaced with \texttt{$f$} (the shell variable that \texttt{for} will update in every loop) below.

```bash
$ rm flat-ir/*.fits
$ for f in f105w f125w f160w; do \
  astcrop --mode=wcs -h0 --output=flat-ir/xdf-$f.fits \
  --polygon="53.187414,-27.779152 : 53.159507,-27.759633 : \
  53.134517,-27.787144 : 53.161906,-27.807208" \
  download/hlsp_xdf_hst_wfc3ir-60mas_hudf_"$f"_v1_sci.fits; \
done
```

Please open these images and inspect them with the same \texttt{ds9} command you used above. You will see how it is nicely flat now and doesn’t have varying depths. Another important result of this crop is that regions with no data now have a NaN (Not-a-Number, or a blank value) value. In the downloaded files, such regions had a value of zero. However, zero is a number, and is thus meaningful, especially when you later want to NoiseChisel\textsuperscript{11}. Generally, when you want to ignore some pixels in a dataset, and avoid higher-level ambiguities or complications, it is always best to give them blank values (not zero, or some other absurdly large or small number). Gnuastro has the Arithmetic program for such cases, and we’ll introduce it later in this tutorial.

### 2.2.5 Angular coverage on the sky

This is the deepest image we currently have of the sky. The first thing that comes to mind may be this: “How large is this field on the sky?”. The FITS world coordinate system (WCS) meta data standard contains the key to answering this question. Run the following command to see all the FITS keywords (metadata) for one of the images (mostly the same with the other filters because they were are scaled to the same region of Sky):

```bash
astfits flat-ir/xdf-f160w.fits -h1
```

Look into the keywords grouped under the ‘World Coordinate System (WCS)’ title. These keywords define how the image relates to the outside world. In particular, the \texttt{CDELT*} keywords (or \texttt{CDELT1} and \texttt{CDELT2} in this 2D image) contain the “Coordinate DELTa” (or change in coordinate units) with a change in one pixel. But what is the units of each “world” coordinate? The \texttt{CUNIT*} keywords (for “Coordinate UNIT”) have the answer. In this case, both \texttt{CUNIT1} and \texttt{CUNIT1} have a value of \texttt{deg}, so both “world” coordinates are in units of degrees. We can thus conclude that the value of \texttt{CDELT*} is in units of degrees-per-pixel\textsuperscript{12}.

\textsuperscript{11} As you will see below, unlike most other detection algorithms, NoiseChisel detects the objects from their faintest parts, it doesn’t start with their high signal-to-noise ratio peaks. Since the Sky is already subtracted in many images and noise fluctuates around zero, zero is commonly higher than the initial threshold applied. Therefore not ignoring zero-valued pixels in this image, will cause them to part of the detections!

\textsuperscript{12} With the FITS \texttt{CDELT} convention, rotation (\texttt{PC} or \texttt{CD} keywords) and scales (\texttt{CDELT}) are separated. In the FITS standard the \texttt{CDELT} keywords are optional. When \texttt{CDELT} keywords aren’t present, the \texttt{PC} matrix is assumed to contain both the coordinate rotation and scales. Note that not all FITS writers use the \texttt{CDELT} convention. So you might not find the \texttt{CDELT} keywords in the WCS meta data of some FITS files. However, all Gnuastro programs (which use the default FITS keyword writing format of WCSLIB) write their output WCS with the \texttt{CDELT} convention, even if the input doesn’t have it. If your dataset doesn’t use the \texttt{CDELT} convention, you can feed it to any (simple) Gnuastro program (for example Arithmetic) and the output will have the \texttt{CDELT} keyword. See Section 8 of the FITS standard (\url{https://fits.gsfc.nasa.gov/standard40/fits_standard40aa-le.pdf}) for more
With the commands below, we’ll use CDELT (along with the image size) to find the answer of our initial question: “how much of the sky does this image cover?”. The lines starting with ## are just comments for you to read and understand each command. Don’t type them on the terminal. The commands are intentionally repetitive in some places to better understand each step and also to demonstrate the beauty of command-line features like history, variables, pipes and loops (which you will commonly use as you master the command-line).

Use shell history: Don’t forget to make effective use of your shell’s history: you don’t have to re-type previous command to add something to them. This is especially convenient when you just want to make a small change to your previous command. Press the “up” key on your keyboard (possibly multiple times) to see your previous command(s) and modify them accordingly.

```
## See the general statistics of non-blank pixel values.
$ aststatistics flat-ir/xdf-f160w.fits

## We only want the number of non-blank pixels.
$ aststatistics flat-ir/xdf-f160w.fits --number

## Keep the result of the command above in the shell variable ‘n’.
$ n=$(aststatistics flat-ir/xdf-f160w.fits --number)

## See what is stored the shell variable ‘n’.
$ echo $n

## Show all the FITS keywords of this image.
$ astfits flat-ir/xdf-f160w.fits -h1

## The resolution (in degrees/pixel) is in the ‘CDELT’ keywords.
## Only show lines that contain these characters, by feeding
## the output of the previous command to the ‘grep’ program.
$ astfits flat-ir/xdf-f160w.fits -h1 | grep CDELT

## Since the resolution of both dimensions is (approximately) equal,
## we’ll only use one of them (CDELT1).
$ astfits flat-ir/xdf-f160w.fits -h1 | grep CDELT1

## To extract the value (third token in the line above), we’ll
## feed the output to AWK. Note that the first two tokens are
## ‘CDELT1’ and ‘=’.
$ astfits flat-ir/xdf-f160w.fits -h1 | grep CDELT1 | awk '{print $3}'

## Save it as the shell variable ‘r’.
$ r=$(astfits flat-ir/xdf-f160w.fits -h1 | grep CDELT1 \ 
   | awk '{print $3}')
```
## Print the values of ‘n’ and ‘r’.
```
$ echo $n $r
```

## Use the number of pixels (first number passed to AWK) and
## length of each pixel’s edge (second number passed to AWK)
## to estimate the area of the field in arc-minutes squared.
```
$ echo $n $r | awk '{print $1 * ($2^2) * 3600}'
```

The output of the last command (area of this field) is 4.03817 (or approximately 4.04) arc-minutes squared. Just for comparison, this is roughly 175 times smaller than the average moon’s angular area (with a diameter of 30arc-minutes or half a degree).

AWK for table/value processing: As you saw above AWK is a powerful and simple tool for text processing. You will see it often in shell scripts. GNU AWK (the most common implementation) comes with a free and wonderful book ([https://www.gnu.org/software/gawk/manual/](https://www.gnu.org/software/gawk/manual/)) in the same format as this book which will allow you to master it nicely. Just like this manual, you can also access GNU AWK’s manual on the command-line whenever necessary without taking your hands off the keyboard. Just run `info awk`.

### 2.2.6 Cosmological coverage

Having found the angular coverage of the dataset in Section 2.2.5 [Angular coverage on the sky], page 29, we can now use Gnuastro to answer a more physically motivated question: “How large is this area at different redshifts?”. To get a feeling of the tangential area that this field covers at redshift 2, you can use Gnuastro’s CosmicCalculator program (Section 9.1 [CosmicCalculator], page 359). In particular, you need the tangential distance covered by 1 arc-second as raw output. Combined with the field’s area that was measured before, we can calculate the tangential distance in Mega Parsecs squared (Mpc²).

```
## Print general cosmological properties at redshift 2 (for example).
$ astcosmiccal -z2
```

```
## When given a "Specific calculation" option, CosmicCalculator
## will just print that particular calculation. To see all such
## calculations, add a ‘--help’ token to the previous command
## (under the same title). Note that with ‘--help’, no processing
## is done, so you can always simply append it to remember
## something without modifying the command you want to run.
$ astcosmiccal -z2 --help
```

```
## Only print the "Tangential dist. covered by 1arcsec at z (kpc)".
## in units of kpc/arc-seconds.
$ astcosmiccal -z2 --arcsectandist
```

```
## But its easier to use the short version of this option (which
## can be appended to other short options.
$ astcosmiccal -sz2
```
## Convert this distance to kpc^2/arcmin^2 and save in 'k'.
\[
\$ k=$(astcosmiccal -sz2 | awk '{print ($1*60)^2}')
\]

## Re-calculate the area of the dataset in arcmin^2.
\[
\$ n=$(aststatistics flat-ir/xdf-f160w.fits --number)
\$ r=$(astfits flat-ir/xdf-f160w.fits -h1 | grep CDELT1 | awk '{print $3}')
\$ a=$(echo $n $r | awk '{print $1 * ($2^2) * 3600}')
\]

## Multiply 'k' and 'a' and divide by 10^6 for value in Mpc^2.
\[
\$ echo $k $a | awk '{print $1 * $2 / 1e6}'
\]

At redshift 2, this field therefore covers approximately 1.07 Mpc^2. If you would like to see how this tangential area changes with redshift, you can use a shell loop like below.
\[
\$ for z in 0.5 1.0 1.5 2.0 2.5 3.0 3.5 4.0 4.5 5.0; do
\$ k=$(astcosmiccal -sz$z); echo $z $k $a | awk '{print $1, ($2*60)^2 * $3 / 1e6}';
\done
\]

Fortunately, the shell has a useful tool/program to print a sequence of numbers that is nicely called seq. You can use it instead of typing all the different redshifts in this example. For example the loop below will calculate and print the tangential coverage of this field across a larger range of redshifts (0.1 to 5) and with finer increments of 0.1.
\[
\$ for z in $(seq 0.1 0.1 5); do
\$ k=$(astcosmiccal -z$z --arcsectandist); echo $z $k $area | awk '{print $1, ($2*60)^2 * $3 / 1e6}';
\done
\]

### 2.2.7 Building custom programs with the library

In Section 2.2.6 [Cosmological coverage], page 31, we repeated a certain calculation/output of a program multiple times using the shell’s for loop. This simple way repeating a calculation is great when it is only necessary once. However, if you commonly need this calculation and possibly for a larger number of redshifts at higher precision, the command above can be slow (try it out to see).

This slowness of the repeated calls to a generic program (like CosmicCalculator), is because it can have a lot of overhead on each call. To be generic and easy to operate, it has to parse the command-line and all configuration files (see Section 2.2.8 [Option management and configuration files], page 34) which contain human-readable characters and need a lot of pre-processing to be ready for processing by the computer. Afterwards, CosmicCalculator has to check the sanity of its inputs and check which of its many options you have asked for. All the this pre-processing takes as much time as the high-level calculation you are requesting, and it has to re-do all of these for every redshift in your loop.

To greatly speed up the processing, you can directly access the core work-horse of CosmicCalculator without all that overhead by designing your custom program for this job. Using Gnaastro’s library, you can write your own tiny program particularly designed for this exact calculation (and nothing else!). To do that, copy and paste the following C program in a file called myprogram.c.
#include <math.h>
#include <stdio.h>
#include <stdlib.h>
#include <gnuastro/cosmology.h>

int main(void)
{
    double area=4.03817; /* Area of field (arcmin^2). */
    double z, adist, tandist; /* Temporary variables. */

    /* Constants from Plank 2018 (arXiv:1807.06209, Table 2) */
    double H0=67.66, olambda=0.6889, omatter=0.3111, oradiation=0;

    /* Do the same thing for all redshifts (z) between 0.1 and 5. */
    for(z=0.1; z<5; z+=0.1)
    {
        /* Calculate the angular diameter distance. */
        adist=gal_cosmology_angular_distance(z, H0, olambda,
                                            omatter, oradiation);

        /* Calculate the tangential distance of one arcsecond. */
        tandist = adist * 1000 * M_PI / 3600 / 180;

        /* Print the redshift and area. */
        printf("%.5.2f %g
", z, pow(tandist * 60,2) * area / 1e6);
    }

    /* Tell the system that everything finished successfully. */
    return EXIT_SUCCESS;
}

Then run the following command to compile your program and run it.

$ astbuildprog myprogram.c

In the command above, you used Gnuastro’s BuildProgram program. Its job is to greatly simplify the compilation, linking and running of simple C programs that use Gnuastro’s library (like this one). BuildProgram is designed to manage Gnuastro’s dependencies, compile and link your custom program and then run it.

Did you notice how your custom program was much faster than the repeated calls to CosmicCalculator in the previous section? You might have noticed that a new file called myprogram is also created in the directory. This is the compiled program that was created and run by the command above (its in binary machine code format, not human-readable any more). You can run it again to get the same results with a command like this:

$ ./myprogram

The efficiency of your custom myprogram compared to repeated calls to CosmicCalculator is because in the latter, the requested processing is comparable to the necessary overheads.
For other programs that take large input datasets and do complicated processing on them, the overhead is usually negligible compared to the processing. In such cases, the libraries are only useful if you want a different/new processing compared to the functionalities in Gnuastro’s existing programs.

Gnuastro has a large library which is used extensively by all the programs. In other words, the library is like the skeleton of Gnuastro. For the full list of available functions classified by context, please see Section 10.3 [Gnuastro library], page 384. Gnuastro’s library and BuildProgram are created to make it easy for you to use these powerful features as you like. This gives you a high level of creativity, while also providing efficiency and robustness. Several other complete working examples (involving images and tables) of Gnuastro’s libraries can be see in Section 10.4 [Library demo programs], page 507.

But for this tutorial, let’s stop discussing the libraries at this point in and get back to Gnuastro’s already built programs which don’t need any programming. But before continuing, let’s clean up the files we don’t need any more:

$ rm myprogram*

2.2.8 Option management and configuration files

None of Gnuastro’s programs keep a default value internally within their code. However, when you ran CosmicCalculator only with the -z2 option (not specifying the cosmological parameters) in Section 2.2.6 [Cosmological coverage], page 31, it completed its processing and printed results. Where did the necessary cosmological parameters (like the matter density, etc) that are necessary for its calculations come from? Fast reply: the values come from a configuration file (see Section 4.2.2 [Configuration file precedence], page 121).

CosmicCalculator is a small program with a limited set of parameters/options. Therefore, let’s use it to discuss configuration files in Gnuastro (for more, you can always see Section 4.2 [Configuration files], page 120). Configuration files are an important part of all Gnuastro’s programs, especially the ones with a large number of options, so it’s important to understand this part well.

Once you get comfortable with configuration files here, you can make good use of them in all Gnuastro programs (for example, NoiseChisel). For example, to do optimal detection on various datasets, you can have configuration files for different noise properties. The configuration of each program (besides its version) is vital for the reproducibility of your results, so it’s important to manage them properly.

As we saw above, the full list of the options in all Gnuastro programs can be seen with the --help option. Try calling it with CosmicCalculator as shown below. Note how options are grouped by context to make it easier to find your desired option. However, in each group, options are ordered alphabetically.

$ astcosmiccal --help

The options that need a value have an = sign after their long version and FLT, INT or STR for floating point numbers, integer numbers, and strings (filenames for example) respectively. All options have a long format and some have a short format (a single character), for more see Section 4.1.1.2 [Options], page 107.

When you are using a program, it is often necessary to check the value the option has just before the program starts its processing. In other words, after it has parsed the command-line options and all configuration files. You can see the values of all options that need one
Chapter 2: Tutorials

with the --printparams or -P option. --printparams is common to all programs (see Section 4.1.2 [Common options], page 109). In the command below, try replacing -P with --printparams to see how both do the same operation.

$ astcosmiccal -P

Let’s say you want a different Hubble constant. Try running the following command (just adding --H0=70 after the command above) to see how the Hubble constant in the output of the command above has changed.

$ astcosmiccal -P --H0=70

Afterwards, delete the -P and add a -z2 to see the calculations with the new cosmology (or configuration).

$ astcosmiccal --H0=70 -z2

From the output of the --help option, note how the option for Hubble constant has both short (-H) and long (--H0) formats. One final note is that the equal (=) sign is not mandatory. In the short format, the value can stick to the actual option (the short option name is just one character after-all, thus easily identifiable) and in the long format, a white-space character is also enough.

$ astcosmiccal -H70 -z2
$ astcosmiccal --H0 70 -z2 --arcsectandist

When an option doesn’t need a value, and has a short format (like --arcsectandist), you can easily append it before other short options. So the last command above can also be written as:

$ astcosmiccal --H0 70 -sz2

Let’s assume that in one project, you want to only use rounded cosmological parameters (H0 of 70km/s/Mpc and matter density of 0.3). You should therefore run CosmicCalculator like this:

$ astcosmiccal --H0=70 --olambda=0.7 --omatter=0.3 -z2

But having to type these extra options every time you run CosmicCalculator will be prone to errors (typos in particular), frustrating and slow. Therefore in Gnuastro, you can put all the options and their values in a “Configuration file” and tell the programs to read the option values from there.

Let’s create a configuration file... With your favorite text editor, make a file named my-cosmology.conf (or my-cosmology.txt, the suffix doesn’t matter, but a more descriptive suffix like .conf is recommended). Then put the following lines inside of it. One space between the option value and name is enough, the values are just under each other to help in readability. Also note that you can only use long option names in configuration files.

H0  70
olambda  0.7
omatter  0.3

You can now tell CosmicCalculator to read this file for option values immediately using the --config option as shown below. Do you see how the output of the following command corresponds to the option values in my-cosmology.conf, and is therefore identical to the previous command?

$ astcosmiccal --config=my-cosmology.conf -z2
But still, having to type `--config=my-cosmology.conf` every time is annoying, isn’t it? If you need this cosmology every time you are working in a specific directory, you can use Gnuastro’s default configuration file names and avoid having to type it manually.

The default configuration files (that are checked if they exist) must be placed in the hidden `.gnuastro` sub-directory (in the same directory you are running the program). Their file name (within `.gnuastro`) must also be the same as the program’s executable name. So in the case of CosmicCalculator, the default configuration file in a given directory is `.gnuastro/astcosmiccal.conf`.

Let’s do this. We’ll first make a directory for our custom cosmology, then build a `.gnuastro` within it. Finally, we’ll copy the custom configuration file there:

```
$ mkdir my-cosmology
$ mkdir my-cosmology/.gnuastro
$ mv my-cosmology.conf my-cosmology/.gnuastro/astcosmiccal.conf
```

Once you run CosmicCalculator within `my-cosmology` (as shown below), you will see how your custom cosmology has been implemented without having to type anything extra on the command-line.

```
$ cd my-cosmology
$ astcosmiccal -P
$ cd ..
```

To further simplify the process, you can use the `--setdirconf` option. If you are already in your desired working directory, calling this option with the others will automatically write the final values (along with descriptions) in `.gnuastro/astcosmiccal.conf`. For example, try the commands below:

```
$ mkdir my-cosmology2
$ cd my-cosmology2
$ astcosmiccal -P
$ astcosmiccal --H0 70 --olambda=0.7 --omatter=0.3 --setdirconf
$ astcosmiccal -P
$ cd ..
```

Gnuastro’s programs also have default configuration files for a specific user (when run in any directory). This allows you to set a special behavior every time a program is run by a specific user. Only the directory and filename differ from the above, the rest of the process is similar to before. Finally, there are also system-wide configuration files that can be used to define the option values for all users on a system. See Section 4.2.2 [Configuration file precedence], page 121, for a more detailed discussion.

We’ll stop the discussion on configuration files here, but you can always read about them in Section 4.2 [Configuration files], page 120. Before continuing the tutorial, let’s delete the two extra directories that we don’t need any more:

```
$ rm -rf my-cosmology*
```

### 2.2.9 Warping to a new pixel grid

We are now ready to start processing the downloaded images. The XDF datasets we are using here are already aligned to the same pixel grid. However, warping to a different/matched pixel grid is commonly needed before higher-level analysis when you are using datasets from different instruments. So let’s have a look at Gnuastro’s features warping features here.
Gnuastro’s Warp program should be used for warping the pixel-grid (see Section 6.4 [Warp], page 238). For example, try rotating one of the images by 20 degrees:

$ astwarp flat-ir/xdf-f160w.fits --rotate=20

Open the output (xdf-f160w_rotated.fits) and see how it is rotated. If your final image is already aligned with RA and Dec, you can simply use the --align option and let Warp calculate the necessary rotation and apply it. For example, try aligning the rotated image back to the standard orientation (just note that because of the two rotations, the NaN parts of the image are larger now):

$ astwarp xdf-f160w_rotated.fits --align

Warp can generally be used for many kinds of pixel grid manipulation (warping), not just rotations. For example the outputs of the commands below will respectively have larger pixels (new resolution being one quarter the original resolution), get shifted by 2.8 (by sub-pixel), get a shear of 2, and be tilted (projected). Run each of them and open the output file to see the effect, they will become handy for you in the future.

$ astwarp flat-ir/xdf-f160w.fits --scale=0.25
$ astwarp flat-ir/xdf-f160w.fits --translate=2.8
$ astwarp flat-ir/xdf-f160w.fits --shear=0.2
$ astwarp flat-ir/xdf-f160w.fits --project=0.001,0.0005

If you need to do multiple warps, you can combine them in one call to Warp. For example to first rotate the image, then scale it, run this command:

$ astwarp flat-ir/xdf-f160w.fits --rotate=20 --scale=0.25

If you have multiple warps, do them all in one command. Don’t warp them in separate commands because the correlated noise will become too strong. As you see in the matrix that is printed when you run Warp, it merges all the warps into a single warping matrix (see Section 6.4.2 [Merging multiple warpings], page 241) and simply applies that (mixes the pixel values) just once. However, if you run Warp multiple times, the pixels will be mixed multiple times, creating a strong artificial blur/smoothing, or stronger correlated noise.

Recall that the merging of multiple warps is done through matrix multiplication, therefore order matters in the separate operations. At a lower level, through Warp’s --matrix option, you can directly request your desired final warp and don’t have to break it up into different warps like above (see Section 6.4.4 [Invoking Warp], page 243).

Fortunately these datasets are already aligned to the same pixel grid, so you don’t actually need the files that were just generated. You can safely delete them all with the following command. Here, you see why we put the processed outputs that we need later into a separate directory. In this way, the top directory can be used for temporary files for testing that you can simply delete with a generic command like below.

$ rm *.fits

2.2.10 NoiseChisel and Multiextension FITS files

Having completed a review of the basics in the previous sections, we are now ready to separate the signal (galaxies or stars) from the background noise in the image. We will be using the results of Section 2.2.4 [Dataset inspection and cropping], page 27, so be sure you already have them. Gnuastro has NoiseChisel for this job. But NoiseChisel’s output is a multi-extension FITS file, therefore to better understand how to use NoiseChisel, let’s take a look at multi-extension FITS files and how you can interact with them.
In the FITS format, each extension contains a separate dataset (image in this case). You can get basic information about the extensions in a FITS file with Gnuastro’s Fits program (see Section 5.1 [Fits], page 146). To start with, let’s run NoiseChisel without any options, then use Gnuastro’s FITS program to inspect the number of extensions in this file.

```bash
$ astnoisechisel flat-ir/xdf-f160w.fits
$ astfits xdf-f160w_detected.fits
```

From the output list, we see that NoiseChisel’s output contains 5 extensions and the first (counting from zero, with name NOISECHISEL-CONFIG) is empty: it has value of 0 in the last column (which shows its size). The first extension in all the outputs of Gnuastro’s programs only contains meta-data: data about/descriving the datasets within (all) the output’s extensions. This is recommended by the FITS standard, see Section 5.1 [Fits], page 146, for more. In the case of Gnuastro’s programs, this generic zero-th/meta-data extension (for the whole file) contains all the configuration options of the program that created the file.

The second extension of NoiseChisel’s output (numbered 1, named INPUT-NO-SKY) is the Sky-subtracted input that you provided. The third (DETECTIONS) is NoiseChisel’s main output which is a binary image with only two possible values for all pixels: 0 for noise and 1 for signal. Since it only has two values, to avoid taking too much space on your computer, its numeric datatype an unsigned 8-bit integer (or uint8)\(^{13}\). The fourth and fifth (SKY and SKY_STD) extensions, have the Sky and its standard deviation values for the input on a tile grid and were calculated over the undetected regions (for more on the importance of the Sky value, see Section 7.1.4 [Sky value], page 252).

Metadata regarding how the analysis was done (or a dataset was created) is very important for higher-level analysis and reproducibility. Therefore, Let’s first take a closer look at the NOISECHISEL-CONFIG extension. If you specify a special header in the FITS file, Gnuastro’s Fits program will print the header keywords (metadata) of that extension. You can either specify the HDU/extension counter (starting from 0), or name. Therefore, the two commands below are identical for this file:

```bash
$ astfits xdf-f160w_detected.fits -h0
$ astfits xdf-f160w_detected.fits -hNOISECHISEL-CONFIG
```

The first group of FITS header keywords are standard keywords (containing the SIMPLE and BITPIX keywords the first empty line). They are required by the FITS standard and must be present in any FITS extension. The second group contains the input file and all the options with their values in that run of NoiseChisel. Finally, the last group contains the date and version information of Gnuastro and its dependencies. The “versions and date” group of keywords are present in all Gnuastro’s FITS extension outputs, for more see Section 4.11 [Output FITS files], page 143.

Note that if a keyword name is larger than 8 characters, it is preceded by a HIERARCH keyword and that all keyword names are in capital letters. Therefore, if you want to see only one keyword’s value by feeding the output to Grep, you should ask Grep to ignore case with its -i option (short name for --ignore-case). For example, below we’ll check the value to the --sminarea option, note how we don’t need Grep’s -i option when it is fed with astnoisechisel -P since it is already in small-caps there. The extra white spaces in the first command are only to help in readability, you can ignore them when typing.

---

\(^{13}\) To learn more about numeric data types see Section 4.6 [Numeric data types], page 130.
$ astnoisechisel -P | grep snminarea
$ astfits xdf-f160w_detected.fits -h0 | grep -i snminarea

The metadata (that is stored in the output) can later be used to exactly reproduce/understand your result, even if you have lost/forgot the command you used to create the file. This feature is present in all of Gnuastro’s programs, not just NoiseChisel.

Let’s continue with the extensions in NoiseChisel’s output that contain a dataset by visually inspecting them (here, we’ll use SAO DS9). Since the file contains multiple related extensions, the easiest way to view all of them in DS9 is to open the file as a “Multi-extension data cube” with the `-mecube` option as shown below.\(^\text{14}\)

$ ds9 -mecube xdf-f160w_detected.fits -zscale -zoom to fit

A “cube” window opens along with DS9’s main window. The buttons and horizontal scroll bar in this small new window can be used to navigate between the extensions. In this mode, all DS9’s settings (for example zoom or color-bar) will be identical between the extensions. Try zooming into one part and flipping through the extensions to see how the galaxies were detected along with the Sky and Sky standard deviation values for that region. Just have in mind that NoiseChisel’s job is only detection (separating signal from noise). We’ll do segmentation on this result later to find the individual galaxies/peaks over the detected pixels.

Each HDU/extension in a FITS file is an independent dataset (image or table) which you can delete from the FITS file, or copy/cut to another file. For example, with the command below, you can copy NoiseChisel’s DETECTIONS HDU/extension to another file:

$ astfits xdf-f160w_detected.fits --copy=DETECTIONS -odetections.fits

There are similar options to conveniently cut (`--cut`, copy, then remove from the input) or delete (`--remove`) HDUs from a FITS file also. See Section 5.1.1.1 [HDU information and manipulation], page 149, for more.

### 2.2.11 NoiseChisel optimization for detection

In Section 2.2.10 [NoiseChisel and Multiextension FITS files], page 37, we ran NoiseChisel and reviewed NoiseChisel’s output format. Now that you have a better feeling for multi-extension FITS files, let’s optimize NoiseChisel for this particular dataset.

One good way to see if you have missed any signal (small galaxies, or the wings of brighter galaxies) is to mask all the detected pixels and inspect the noise pixels. For this, you can use Gnuastro’s Arithmetic program (in particular its `where` operator, see Section 6.2.2 [Arithmetic operators], page 200). The command below will produce `mask-det.fits`. In it, all the pixels in the `INPUT-NO-SKY` extension that are flagged 1 in the `DETECTIONS` extension (dominated by signal, not noise) will be set to NaN.

Since the various extensions are in the same file, for each dataset we need the file and extension name. To make the command easier to read/write/understand, let’s use shell variables: `in` will be used for the Sky-subtracted input image and `det` will be used for the detection map. Recall that a shell variable’s value can be retrieved by adding a `$` before

---

\(^\text{14}\) You can configure your graphic user interface to open DS9 in multi-extension cube mode by default when using the GUI (double clicking on the file). If your graphic user interface is GNOME (another GNU software, it is most common in GNU/Linux operating systems), a full description is given in Section B.1.1 [Viewing multiextension FITS images], page 540.
its name, also note that the double quotations are necessary when we have white-space characters in a variable name (like this case).

```bash
$ in="xdf-f160w_detected.fits -hINPUT-NO-SKY"
$ det="xdf-f160w_detected.fits -hDETECTIONS"
$ astarithmetic $in $det nan where --output=mask-det.fits
```

To invert the result (only keep the detected pixels), you can flip the detection map (from 0 to 1 and vice-versa) by adding a 'not' after the second $det:

```bash
$ astarithmetic $in $det not nan where --output=mask-sky.fits
```

Looking again at the detected pixels, we see that there are thin connections between many of the smaller objects or extending from larger objects. This shows that we have dug in too deep, and that we are following correlated noise.

Correlated noise is created when we warp datasets from individual exposures (that are each slightly offset compared to each other) into the same pixel grid, then add them to form the final result. Because it mixes nearby pixel values, correlated noise is a form of convolution and it smooths the image. In terms of the number of exposures (and thus correlated noise), the XDF dataset is by no means an ordinary dataset. It is the result of warping and adding roughly 80 separate exposures which can create strong correlated noise/smoothing. In common surveys the number of exposures is usually 10 or less.

Let’s tweak NoiseChisel’s configuration a little to get a better result on this dataset. Don’t forget that “Good statistical analysis is not a purely routine matter, and generally calls for more than one pass through the computer” (Anscombe 1973, see Section 1.2 [Science and its tools], page 2). A good scientist must have a good understanding of her tools to make a meaningful analysis. So don’t hesitate in playing with the default configuration and reviewing the manual when you have a new dataset in front of you. Robust data analysis is an art, therefore a good scientist must first be a good artist.

NoiseChisel can produce “Check images” to help you visualize and inspect how each step is done. You can see all the check images it can produce with this command.

```bash
$ astnoisechisel --help | grep check
```

Let’s check the overall detection process to get a better feeling of what NoiseChisel is doing with the following command. To learn the details of NoiseChisel in more detail, please see Section 7.2 [NoiseChisel], page 269, Akhlaghi and Ichikawa [2015] (https://arxiv.org/abs/1505.01664) and Akhlaghi [2019] (https://arxiv.org/abs/1909.11230).

```bash
$ astnoisechisel flat-ir/xdf-f160w.fits --checkdetection
```

The check images/tables are also multi-extension FITS files. As you saw from the command above, when check datasets are requested, NoiseChisel won’t go to the end. It will abort as soon as all the extensions of the check image are ready. Please list the extensions of the output with `astfits` and then opening it with `ds9` as we done above. If you have read the paper, you will see why there are so many extensions in the check image.

```bash
$ astfits xdf-f160w_detcheck.fits
$ ds9 -mecube xdf-f160w_detcheck.fits -zscale -zoom to fit
```

In order to understand the parameters and their biases (especially as you are starting to use Gnuastro, or running it a new dataset), it is strongly encouraged to play with the different parameters and use the respective check images to see which step is affected by your changes and how, for example see Section 2.3 [Detecting large extended targets], page 61.
The OPENED_AND_LABELED extension shows the initial detection step of NoiseChisel. We see these thin connections between smaller points are already present here (a relatively early stage in the processing). Such connections at the lowest surface brightness limits usually occur when the dataset is too smoothed. Because of correlated noise, the dataset is already artificially smoothed, therefore further smoothing it with the default kernel may be the problem. One solution is thus to use a sharper kernel (NoiseChisel’s first step in its processing).

By default NoiseChisel uses a Gaussian with full-width-half-maximum (FWHM) of 2 pixels. We can use Gnuastro’s MakeProfiles to build a kernel with FWHM of 1.5 pixel (truncated at 5 times the FWHM, like the default) using the following command. MakeProfiles is a powerful tool to build any number of mock profiles on one image or independently, to learn more of its features and capabilities, see Section 8.1 [MakeProfiles], page 332.

```
$ astmkprof --kernel=gaussian,1.5,5 --oversample=1
```

Please open the output kernel.fits and have a look (it is very small and sharp). We can now tell NoiseChisel to use this instead of the default kernel with the following command (we’ll keep checking the detection steps)

```
$ astnoisechisel flat-ir/xdf-f160w.fits --kernel=kernel.fits --checkdetection
```

Looking at the OPENED_AND_LABELED extension, we see that the thin connections between smaller peaks has now significantly decreased. Going two extensions/steps ahead (in the first HOLES-FILLED), you can see that during the process of finding false pseudo-detections, too many holes have been filled: do you see how the many of the brighter galaxies are connected? At this stage all holes are filled, irrespective of their size.

Try looking two extensions ahead (in the first PSEUDOS-FOR-SN), you can see that there aren’t too many pseudo-detections because of all those extended filled holes. If you look closely, you can see the number of pseudo-detections in the result NoiseChisel prints (around 5000). This is another side-effect of correlated noise. To address it, we should slightly increase the pseudo-detection threshold (before changing --dthresh, run with -P to see the default value):

```
$ astnoisechisel flat-ir/xdf-f160w.fits --kernel=kernel.fits --dthresh=0.1 --checkdetection
```

Before visually inspecting the check image, you can already see the effect of this change in NoiseChisel’s command-line output: notice how the number of pseudos has increased to more than 6000. Open the check image now and have a look, you can see how the pseudo-detections are distributed much more evenly in the image.

**Maximize the number of pseudo-detections:** For a new noise-pattern (different instrument), play with --dthresh until you get a maximal number of pseudo-detections (the total number of pseudo-detections is printed on the command-line when you run NoiseChisel).

The signal-to-noise ratio of pseudo-detections define NoiseChisel’s reference for removing false detections, so they are very important to get right. Let’s have a look at their signal-to-noise distribution with --checksn.

```
$ astnoisechisel flat-ir/xdf-f160w.fits --kernel=kernel.fits --dthresh=0.1 --checkdetection --checksn
```
Chapter 2: Tutorials

The output \texttt{(xdf-f160w\_detsn.fits)} contains two extensions for the pseudo-detections over the undetected (sky) regions and those over detections. The first column is the pseudo-detection label which you can see in the respective\textsuperscript{15} PSEUDOS-FOR-SN extension of \texttt{xdf-f160w\_detcheck.fits}. You can see the table columns with the first command below and get a feeling for its distribution with the second command (the two Table and Statistics programs will be discussed later in the tutorial)

\begin{verbatim}
$ asttable xdf-f160w\_detsn.fits -hSKY\_PSEUDODET\_SN
$ aststatistics xdf-f160w\_detsn.fits -hSKY\_PSEUDODET\_SN -c2
\end{verbatim}

The correlated noise is again visible in this pseudo-detection signal-to-noise distribution: it is highly skewed. A small change in the quantile will translate into a big change in the S/N value. For example see the difference between the three 0.99, 0.95 and 0.90 quantiles with this command:

\begin{verbatim}
$ aststatistics xdf-f160w\_detsn.fits -hSKY\_PSEUDODET\_SN -c2 \ 
   --quantile=0.99 --quantile=0.95 --quantile=0.90
\end{verbatim}

If you run NoiseChisel with \texttt{-P}, you'll see the default signal-to-noise quantile \texttt{--snquant} is 0.99. In effect with this option you specify the purity level you want (contamination by false detections). With the \texttt{aststatistics} command above, you see that a small number of extra false detections (impurity) in the final result causes a big change in completeness (you can detect more lower signal-to-noise true detections). So let’s loosen-up our desired purity level, remove the check-image options, and then mask the detected pixels like before to see if we have missed anything.

\begin{verbatim}
$ astnoisechisel flat-ir/xdf-f160w.fits --kernel=kernel.fits \ 
   --dthresh=0.1 --snquant=0.95
$ in="xdf-f160w\_detected.fits -hINPUT-NO-SKY"
$ det="xdf-f160w\_detected.fits -hDETECTIONS"
$ astarithmetic $in $det nan where --output=mask-det.fits
\end{verbatim}

Overall it seems good, but if you play a little with the color-bar and look closer in the noise, you'll see a few very sharp, but faint, objects that have not been detected. This only happens for under-sampled datasets like HST (where the pixel size is larger than the point spread function FWHM). So this won’t happen on ground-based images. Because of this, sharp and faint objects will be very small and eroded too easily during NoiseChisel’s erosion step.

To address this problem of sharp objects, we can use NoiseChisel’s \texttt{--noerodequant} option. All pixels above this quantile will not be eroded, thus allowing us to preserve faint and sharp objects. Check its default value, then run NoiseChisel like below and make the mask again. You will see many of those sharp objects are now detected.

\begin{verbatim}
$ astnoisechisel flat-ir/xdf-f160w.fits --kernel=kernel.fits \ 
   --noerodequant=0.95 --dthresh=0.1 --snquant=0.95
\end{verbatim}

This seems to be fine and we can continue with our analysis. To avoid having to write these options on every call to NoiseChisel, we’ll just make a configuration file in a visible \texttt{config} directory. Then we’ll define the hidden \texttt{.gnuastro} directory (that all Gnuastro’s programs will look into for configuration files) as a symbolic link to the \texttt{config} directory.

\textsuperscript{15} The first PSEUDOS-FOR-SN in \texttt{xdf-f160w\_detsn.fits} is for the pseudo-detections over the undetected regions and the second is for those over detected regions.
Finally, we’ll write the finalized values of the options into NoiseChisel’s standard configuration file within that directory. We’ll also put the kernel in a separate directory to keep the top directory clean of any files we later need.

```sh
$ mkdir kernel config
$ ln -s config/.gnuastro
$ mv kernel.fits kernel/noisechisel.fits
$ echo "kernel kernel/noisechisel.fits" > config/astnoisechisel.conf
$ echo "noerodequant 0.95" >> config/astnoisechisel.conf
$ echo "dthresh 0.1" >> config/astnoisechisel.conf
$ echo "snquant 0.95" >> config/astnoisechisel.conf
```

We are now ready to finally run NoiseChisel on the two filters and keep the output in a dedicated directory (nc).

```sh
$ rm *.fits
$ mkdir nc
$ astnoisechisel flat-ir/xdf-f160w.fits --output=nc/xdf-f160w.fits
$ astnoisechisel flat-ir/xdf-f125w.fits --output=nc/xdf-f125w.fits
$ astnoisechisel flat-ir/xdf-f105w.fits --output=nc/xdf-f105w.fits
```

### 2.2.12 NoiseChisel optimization for storage

As we showed before (in Section 2.2.10 [NoiseChisel and Multiextension FITS files], page 37), NoiseChisel’s output is a multi-extension FITS file with several images the same size as the input. As the input datasets get larger this output can become hard to manage and waste a lot of storage space. Fortunately there is a solution to this problem (which is also useful for Segment’s outputs).

In this small section we’ll take a short detour to show this feature. Please note that the outputs generated here are not needed for the rest of the tutorial. But first, let’s have a look at the contents/HDUs and volume of NoiseChisel’s output from Section 2.2.11 [NoiseChisel optimization for detection], page 39, (fast answer, its larger than 100 mega-bytes):

```sh
$ astfits nc/xdf-f160w.fits
$ ls -lh nc/xdf-f160w.fits
```

Two options can drastically decrease NoiseChisel’s output file size: 1) With the `--rawoutput` option, NoiseChisel won’t create a Sky-subtracted input. After all, it is redundant: you can always generate it by subtracting the SKY extension from the input image (which you have in your database) using the Arithmetic program. 2) With the `--oneelempertile`, you can tell NoiseChisel to store its Sky and Sky standard deviation results with one pixel per tile (instead of many pixels per tile). So let’s run NoiseChisel with these options, then have another look at the HDUs and the over-all file size:

```sh
$ astnoisechisel flat-ir/xdf-f160w.fits --oneelempertile --rawoutput \  
   --output=nc-for-storage.fits
$ astfits nc-for-storage.fits
$ ls -lh nc-for-storage.fits
```

See how `nc-for-storage.fits` has four HDUs, while `nc/xdf-f160w.fits` had five HDUs? As explained above, the missing extension is `INPUT-NO-SKY`. Also, look at the sizes of the SKY and SKY_STD HDUs, unlike before, they aren’t the same size as DETECTIONS, they only
have one pixel for each tile (group of pixels in raw input). Finally, you see that `nc-for-storage.fits` is just under 8 mega bytes (while `nc/xdf-f160w.fits` was 100 mega bytes)!

But were are not finished! You can even be more efficient in storage, archival or transferring NoiseChisel’s output by compressing this file. Try the command below to see how NoiseChisel’s output has now shrunk to about 250 kilo-bytes while keeping all the necessary information as the original 100 mega-byte output.

```
$ gzip --best nc-for-storage.fits
$ ls -lh nc-for-storage.fits.gz
```

We can get this wonderful level of compression because NoiseChisel’s output is binary with only two values: 0 and 1. Compression algorithms are highly optimized in such scenarios.

You can open `nc-for-storage.fits.gz` directly in SAO DS9 or feed it to any of Gnuastro’s programs without having to decompress it. Higher-level programs that take NoiseChisel’s output (for example Segment or MakeCatalog) can also deal with this compressed image where the Sky and its Standard deviation are one pixel-per-tile. You just have to give the “values” image as a separate option, for more, see Section 7.3 [Segment], page 284, and Section 7.4 [MakeCatalog], page 295.

Segment (the program we will introduce in the next section for identifying sub-structure), also has similar features to optimize its output for storage. Since this file was only created for a fast detour demonstration, let’s keep our top directory clean and move to the next step:

```
rm nc-for-storage.fits.gz
```

### 2.2.13 Segmentation and making a catalog

The main output of NoiseChisel is the binary detection map (DETECTIONS extension, see Section 2.2.11 [NoiseChisel optimization for detection], page 39), which only has two values of 1 or 0. This is useful when studying the noise, but hardly of any use when you actually want to study the targets/galaxies in the image, especially in such a deep field where the detection map of almost everything is connected. To find the galaxies over the detections, we’ll use Gnuastro’s Section 7.3 [Segment], page 284, program:

```
$ mkdir seg
$ astsegment nc/xdf-f160w.fits -oseg/xdf-f160w.fits
$ astsegment nc/xdf-f125w.fits -oseg/xdf-f125w.fits
$ astsegment nc/xdf-f105w.fits -oseg/xdf-f105w.fits
```

Segment’s operation is very much like NoiseChisel (in fact, prior to version 0.6, it was part of NoiseChisel). For example the output is a multi-extension FITS file, it has check images and uses the undetected regions as a reference. Please have a look at Segment’s multi-extension output with ds9 to get a good feeling of what it has done.

```
$ ds9 -mecube seg/xdf-f160w.fits -zscale -zoom to fit
```

Like NoiseChisel, the first extension is the input. The CLUMPS extension shows the true “clumps” with values that are ≥ 1, and the diffuse regions labeled as −1. In the OBJECTS extension, we see that the large detections of NoiseChisel (that may have contained many galaxies) are now broken up into separate labels. See Section 7.3 [Segment], page 284, for more. The clumps are not affected by the hard-to-deblend and low signal-to-noise diffuse
regions, they are more robust for calculating the colors (compared to objects). Therefore from this step onward, we’ll continue with clumps.

Having localized the regions of interest in the dataset, we are ready to do measurements on them with Section 7.4 [MakeCatalog], page 295. Besides the IDs, we want to measure (in this order) the Right Ascension (with \texttt{--ra}), Declination (\texttt{--dec}), magnitude (\texttt{--magnitude}), and signal-to-noise ratio (\texttt{--sn}) of the objects and clumps. Furthermore, as mentioned above, we also want measurements on clumps, so we also need to call \texttt{--clumpscat}. The following command will make these measurements on Segment’s F160W output and write them in a catalog for each object and clump in a FITS table.

\begin{verbatim}
$ mkdir cat
$ astmkcatalog seg/xdf-f160w.fits --ids --ra --dec --magnitude --sn \
   --zeropoint=25.94 --clumpscat --output=cat/xdf-f160w.fits
\end{verbatim}

From the printed statements on the command-line, you see that MakeCatalog read all the extensions in Segment’s output for the various measurements it needed. To calculate colors, we also need magnitude measurements on the other filters. So let’s repeat the command above on them, just changing the file names and zeropoint (which we got from the XDF survey webpage):

\begin{verbatim}
$ astmkcatalog seg/xdf-f125w.fits --ids --ra --dec --magnitude --sn \
   --zeropoint=26.23 --clumpscat --output=cat/xdf-f125w.fits
$ astmkcatalog seg/xdf-f105w.fits --ids --ra --dec --magnitude --sn \
   --zeropoint=26.27 --clumpscat --output=cat/xdf-f105w.fits
\end{verbatim}

However, the galaxy properties might differ between the filters (which is the whole purpose behind observing in different filters!). Also, the noise properties and depth of the datasets differ. You can see the effect of these factors in the resulting clump catalogs, with Gnuastro’s Table program. We’ll go deep into working with tables in the next section, but in summary: the \texttt{-i} option will print information about the columns and number of rows. To see the column values, just remove the \texttt{-i} option. In the output of each command below, look at the \texttt{Number of rows}; and note that they are different.

\begin{verbatim}
asttable cat/xdf-f105w.fits -hCLUMPS -i
asttable cat/xdf-f125w.fits -hCLUMPS -i
asttable cat/xdf-f160w.fits -hCLUMPS -i
\end{verbatim}

Matching the catalogs is possible (for example with Section 7.5 [Match], page 326). However, the measurements of each column are also done on different pixels: the clump labels can/will differ from one filter to another for one object. Please open them and focus on one object to see for your self. This can bias the result, if you match catalogs.

An accurate color calculation can only be done when magnitudes are measured from the same pixels on both images. Fortunately in these images, the Point spread function (PSF) are very similar, allowing us to do this directly\textsuperscript{16}. You can do this with MakeCatalog and is one of the reasons that NoiseChisel or Segment don’t generate a catalog at all (to give you the freedom of selecting the pixels to do catalog measurements on).

The F160W image is deeper, thus providing better detection/segmentation, and redder, thus observing smaller/older stars and representing more of the mass in the galaxies. We will

\textsuperscript{16} When the PSFs between two images differ largely, you would have to PSF-match the images before using the same pixels for measurements.
thus use the F160W filter as a reference and use its segment labels to identify which pixels to use for which objects/clumps. But we will do the measurements on the sky-subtracted F105W and F125W images (using MakeCatalog’s --valuesfile option) as shown below. Notice how the major difference between this call to MakeCatalog and the call to generate the F160W catalog (excluding the zero point and the output name) is the --valuesfile.

```bash
$ astmkcatalog seg/xdf-f160w.fits --ids --ra --dec --magnitude --sn --valuesfile=nc/xdf-f125w.fits --zeropoint=26.23 --clumpscat --output=cat/xdf-f125w-on-f160w-lab.fits

$ astmkcatalog seg/xdf-f160w.fits --ids --ra --dec --magnitude --sn --valuesfile=nc/xdf-f105w.fits --zeropoint=26.27 --clumpscat --output=cat/xdf-f105w-on-f160w-lab.fits
```

Look into what MakeCatalog printed on the command-line after running the commands above. You can see that (as requested) the object and clump labels were taken from the respective extensions in `seg/xdf-f160w.fits`, while the values and Sky standard deviation were taken from `nc/xdf-f105w.fits`. Since we used the same labeled image on both filters, the number of rows in both catalogs are now identical:

```bash
asttable cat/xdf-f105w-on-f160w-lab.fits -hCLUMPS -i
asttable cat/xdf-f125w-on-f160w-lab.fits -hCLUMPS -i
```

Finally, the comments in MakeCatalog’s output (COMMENT keywords in the FITS headers, or lines starting with # in plain text) contain some important information about the input datasets and other useful info (for example pixel area or per-pixel surface brightness limit). You can see them with this command:

```bash
$ astfits cat/xdf-f160w.fits -h1 | grep COMMENT
```

### 2.2.14 Working with catalogs (estimating colors)

The output of the MakeCatalog command above is a FITS table (see Section 2.2.13 [Segmentation and making a catalog], page 44). The two clump and object catalogs are available in the two extensions of the single FITS file\(^{17}\). Let’s see the extensions and their basic properties with the Fits program:

```bash
$ astfits cat/xdf-f160w.fits # Extension information
```

Now, let’s inspect the table in each extension with Gnuastro’s Table program (see Section 5.4 [Table], page 171). Note that we could have used -hOBJECTS and -hCLUMPS instead of -h1 and -h2 respectively.

```bash
$ asttable cat/xdf-f160w.fits -h1 --info # Objects catalog info.
$ asttable cat/xdf-f160w.fits -h1 # Objects catalog columns.
$ asttable cat/xdf-f160w.fits -h2 -i # Clumps catalog info.
$ asttable cat/xdf-f160w.fits -h2 # Clumps catalog columns.
```

As you see above, when given a specific table (file name and extension), Table will print the full contents of all the columns. To see the basic metadata about each column (for example name, units and comments), simply append a --info (or -i) to the command.

\(^{17}\) MakeCatalog can also output plain text tables. However, in the plain text format you can only have one table per file. Therefore, if you also request measurements on clumps, two plain text tables will be created (suffixed with _o.txt and _c.txt).
To print the contents of special column(s), just specify the column number(s) (counting from 1) or the column name(s) (if they have one). For example, if you just want the magnitude and signal-to-noise ratio of the clumps (in -h2), you can get it with any of the following commands:

```bash
$ asttable cat/xdf-f160w.fits -h2 -c5,6
$ asttable cat/xdf-f160w.fits -h2 -c5,SN
$ asttable cat/xdf-f160w.fits -h2 -c5 -c6
$ asttable cat/xdf-f160w.fits -h2 -cMAGNITUDE -cSN
```

Using column names instead of numbers has many advantages: 1) you don’t have to worry about the order of columns in the table. 2) It acts as a documentation in the script. Column meta-data (including a name) aren’t just limited to FITS tables and can also be used in plain text tables, see Section 4.8.2 [Gnuastro text table format], page 137.

Since `cat/xdf-f160w.fits` and `cat/xdf-f105w-on-f160w-lab.fits` have exactly the same number of rows, we can use Table to merge the columns of these two tables, to have one table with magnitudes in both filters. We do this with the `--catcolumnfile` option like below. You give this option a file name (which is assumed to be a table that has the same number of rows), and all the table’s columns will be concatenated/appended to the main table. So please try it out with the commands below. We’ll first look at the metadata of the first table (only the CLUMPS extension). With the second command, we’ll concatenate the two tables and write them in, `two-in-one.fits` and finally, we’ll check the new catalog’s metadata.

```bash
$ asttable cat/xdf-f160w.fits -i -hCLUMPS
$ asttable cat/xdf-f160w.fits -hCLUMPS --output=two-in-one.fits \
   --catcolumnfile=cat/xdf-f125w-on-f160w-lab.fits \
   --catcolumnhdu=CLUMPS
$ asttable two-in-one.fits -i
```

Looking at the two metadata outputs (called with `-i`), you may have noticed that both tables have the same number of rows. But what might have attracted your attention more, is that both-mags.fits has double the number of columns (as expected, after all, you merged both tables into one file). In fact you can concatenate any number of other tables in one command, for example:

```bash
$ asttable cat/xdf-f160w.fits -hCLUMPS --output=three-in-one.fits \
   --catcolumnfile=cat/xdf-f125w-on-f160w-lab.fits \
   --catcolumnfile=cat/xdf-f105w-on-f160w-lab.fits \
   --catcolumnhdu=CLUMPS --catcolumnhdu=CLUMPS
$ asttable three-in-one.fits -i
```

As you see, to avoid confusion in column names, Table has intentionally appended a `-1` to the column names of the first concatenated table (so for example we have the original RA column, and another one called RA-1). Similarly a `-2` has been added for the columns of the second concatenated table.

However, this example clearly shows a problem with this full concatenation: some columns are identical (for example HOST_OBJ_ID and HOST_OBJ_ID-1), or not needed (for example RA-1 and DEC-1 which are not necessary here). In such cases, you can use `--catcolumns` to only concatenate certain columns, not the whole table, for example this command:

```bash
$ asttable cat/xdf-f160w.fits -hCLUMPS --output=three-in-one.fits \
   --catcolumnfile=cat/xdf-f125w-on-f160w-lab.fits \
   --catcolumnfile=cat/xdf-f105w-on-f160w-lab.fits \
   --catcolumnhdu=CLUMPS --catcolumnhdu=CLUMPS
```
$ asttable cat/xdf-f160w.fits -hCLUMPS --output=two-in-one-2.fits \
   --catcolumnfile=cat/xdf-f125w-on-f160w-lab.fits \
   --catcolumnhdu=CLUMPS --catcolumns=MAGNITUDE

$ asttable three-in-one-2.fits -i

You see that we have now only appended the MAGNITUDE column of cat/xdf-f125w-on-f160w-lab.fits. This is what we needed to be able to later subtract the magnitudes. Let’s go ahead and add the F105W magnitudes also with the command below. Note how we need to call --catcolumnhdu once for every table that should be appended, but we only call --catcolumn once (assuming all the tables that should be appended have this column).

$ asttable cat/xdf-f160w.fits -hCLUMPS --output=three-in-one-2.fits \
   --catcolumnfile=cat/xdf-f125w-on-f160w-lab.fits \
   --catcolumnfile=cat/xdf-f105w-on-f160w-lab.fits \
   --catcolumnhdu=CLUMPS --catcolumnhdu=CLUMPS \
   --catcolumns=MAGNITUDE

$ asttable three-in-one-2.fits -i

But we aren’t finished yet! There is a very big problem: its not clear which one of MAGNITUDE, MAGNITUDE-1 or MAGNITUDE-2 columns belong to which filter! Right now, you know this because you just ran this command. But in one hour, you’ll start doubting your self and will be forced to go through your command history, trying to answer this question. You should never torture your future-self (or your colleagues) like this! So, let’s rename these confusing columns in the matched catalog.

Fortunately, with the --colmetadata option, you can correct the column metadata of the final table (just before it is written). It takes four values: 1) the column name or number, 2) the column name, 3) the column unit and 4) the column comments. Since the comments are usually human-friendly sentences and contain space characters, you should put them in double quotations like below. For example by adding three calls of this option to the previous command, we write the filter name in the magnitude column name and description.

$ asttable cat/xdf-f160w.fits -hCLUMPS --output=three-in-one-3.fits \
   --catcolumnfile=cat/xdf-f125w-on-f160w-lab.fits \
   --catcolumnfile=cat/xdf-f105w-on-f160w-lab.fits \
   --catcolumnhdu=CLUMPS --catcolumnhdu=CLUMPS \
   --catcolumns=MAGNITUDE \ 
   --colmetadata=MAGNITUDE,MAG-F160w,log,"Magnitude in F160W." \ 
   --colmetadata=MAGNITUDE-1,MAG-F125w,log,"Magnitude in F125W." \ 
   --colmetadata=MAGNITUDE-2,MAG-F105w,log,"Magnitude in F105W."

$ asttable three-in-one-3.fits -i

We now have both magnitudes in one table and can start doing arithmetic on them (to estimate colors, which are just a subtraction of magnitudes). To use column arithmetic, simply call the column selection option (--column or -c), put the value in single quotations and start the value with arith (followed by a space) like the example below. Column arithmetic uses the same notation as the Arithmetic program (see Section 6.2.1 [Reverse polish notation], page 199), with almost all the same operators (see Section 6.2.2 [Arithmetic operators], page 200), and some column-specific operators (that aren’t available for images). In column-arithmetic, you can identify columns by number (prefixed with a $) or name, for more see Section 5.4.1 [Column arithmetic], page 172.
So let’s estimate one color from three-in-one-3.fits using column arithmetic. All the commands below will produce the same output, try them each and focus on the differences. Note that column arithmetic can be mixed with other ways to choose output columns (the -c option).

$ asttable three-in-one-3.fits -o color-cat.fits \
   -c1,2,RA,DEC,'arith $5 $7 -'

$ asttable three-in-one-3.fits -o color-cat.fits \
   -c1,2,RA,DEC,'arith MAG-F125W MAG-F160W -'

$ asttable three-in-one-3.fits -o color-cat.fits -c1,2 \
   --column='arith MAG-F105W MAG-F160W -'

This example again highlights the important point on column metadata: do you see how clearly understandable the last two commands are? On the contrary, do you feel how cryptic the first one is? When you have column names, please use them. If your table doesn’t have column names, give them names with the --colmetadata (described above) as you are creating them. But how about the metadata for the column you just created with column arithmetic? Have a look at the column metadata of the table produced above:

$ asttable color-cat.fits -i

The name of the column produced by arithmetic column is ARITH_1! This is natural: Arithmetic has no idea what the modified column is! You could have multiplied two columns, or done much more complex transformations with many columns. Metadata can’t be set automatically. To add metadata, you can use --colmetadata like before:

$ asttable three-in-one-3.fits -o color-cat.fits -c1,2,RA,DEC \
   --column='arith MAG-F105W MAG-F160W -' \
   --colmetadata=ARITH_1,F125W-F160W,log,"Magnitude difference"

We are now ready to make our final table. We want it to have the magnitudes in all three filters, as well colors. Recall that by convention in astronomy colors are defined by subtracting the bluer magnitude from the redder magnitude. In this way a larger color value corresponds to a redder object. So from the three magnitudes, we can produce three colors (as shown below). Also, because this is the final table we are creating here and want to use it later, we’ll store it in cat/ and we’ll also give it a clear name and use the --range option to only print columns with a signal-to-noise ratio (SN column, from the F160W filter) above 5.

$ asttable three-in-one-3.fits --range=SN,5,inf -c1,2,RA,DEC,SN \
   -cMAG-F160W,MAG-F125W,MAG-F105W \
   -c'arith MAG-F125W MAG-F160W -' \
   -c'arith MAG-F105W MAG-F125W -' \
   -c'arith MAG-F105W MAG-F160W -' \
   --colmetadata=SN,SN-F160W,ratio,"F160W signal to noise ratio" \
   --colmetadata=ARITH_1,F125W-F160W,log,"Color F125W and F160W" \
   --colmetadata=ARITH_2,F105W-F125W,log,"Color F105W and F125W" \
   --colmetadata=ARITH_3,F105W-F160W,log,"Color F105W and F160W" \
   --output=cat/mags-with-color.fits

$ asttable cat/mags-with-color.fits -i
The table now has all the columns we need and it has the proper metadata to let us safely use it later (without frustrating over column orders!) or passing it to colleagues. You can now inspect the distribution of colors with the Statistics program.

```bash
$ aststatistics cat/mags-with-color.fits -cF105W-F125W
$ aststatistics cat/mags-with-color.fits -cF105W-F160W
$ aststatistics cat/mags-with-color.fits -cF125W-F160W
```

This tiny and cute ASCII histogram (and the general information printed above it) gives you a crude (but very useful and fast) feeling on the distribution. You can later use Gnuastro’s Statistics program with the `--histogram` option to build a much more fine-grained histogram as a table to feed into your favorite plotting program for a much more accurate/appealing plot (for example with PGFPLOTS in \LaTeX). If you just want a specific measure, for example the mean, median and standard deviation, you can ask for them specifically, like below:

```bash
$ aststatistics cat/mags-with-color.fits -cF105W-F160W --mean --median --std
```

We won’t go much deeper into the Statistics program here, but there is so much more you can do with it, please see Section 7.1 [Statistics], page 248, later.

Let’s finish this section of the tutorial with a useful tip on modifying column metadata. Above, updating/changing column metadata was done with the `--colmetadata` in the same command that produced the newly created Table file. But in many situations, the table is already made and you just want to update the metadata of one column. In such cases using `--colmetadata` is over-kill (wasting CPU/RAM energy or time if the table is large) because it will load the full table data and metadata into memory, just change the metadata and write it back into a file.

In scenarios when the table’s data doesn’t need to be changed and you just want to set or update the metadata, it is much more efficient to use basic FITS keyword editing. For example, in the FITS standard, column names are stored in the `TTYPE` header keywords, so let’s have a look:

```bash
$ asttable two-in-one.fits -i
$ astfits two-in-one.fits -h1 | grep TTYPE
```

Changing/updating the column names is as easy as updating the values to these keywords. You don’t need to touch the actual data! With the command below, we’ll just update the `MAGNITUDE` and `MAGNITUDE-1` columns (which are respectively stored in the `TTYPE5` and `TTYPE11` keywords) by modifying the keyword values and checking the effect by listing the column metadata again:

```bash
$ astfits two-in-one.fits -h1
   --update=TTYPE5,MAG-F160W
   --update=TTYPE11,MAG-F125W
$ asttable two-in-one.fits -i
```

You can see that the column names have indeed been changed without touching any of the data. You can do the same for the column units or comments by modifying the keywords starting with `TUNIT` or `TCOMM`.

Generally, Gnuastro’s table is a very useful program in data analysis and what you have seen so far is just the tip of the iceberg. But to keep the tutorial short, we’ll stop reviewing
Chapter 2: Tutorials

the features here, for more, please see Section 5.4 [Table], page 171. Finally, let’s delete all
the temporary FITS tables we placed in the top project directory:

```
rm *.fits
```

### 2.2.15 Aperture photometry

The colors we calculated in Section 2.2.14 [Working with catalogs (estimating colors)],
page 46, used a different segmentation map for each object. This might not satisfy some
science cases that need the flux within a fixed area/aperture. Fortunately Gnuastro’s mod-
ular programs make it very easy do this type of measurement (photometry). To do this, we
can ignore the labeled images of NoiseChisel of Segment, we can just built our own labeled
image! That labeled image can then be given to MakeCatalog

To generate the apertures catalog we’ll use Gnuastro’s MakeProfiles (see Section 8.1
[MakeProfiles], page 332). But first we need a list of positions (aperture photometry needs
a-priori knowledge of your target positions). So we’ll first read the clump positions from
the F160W catalog, then use AWK to set the other parameters of each profile to be a fixed
circle of radius 5 pixels (recall that we want all apertures to have an identical size/area in
this scenario).

```
$ rm *.fits *.txt
$ asttable cat/xdf-f160w.fits -hCLUMPS -cRA,DEC
   | awk '!/#/\{print NR, $1, $2, 5, 5, 0, 0, 1, NR, 1\}' |
   > apertures.txt
$ cat apertures.txt
```

We can now feed this catalog into MakeProfiles using the command below to build
the apertures over the image. The most important option for this particular job is
```
--mforflatpix
```
It tells MakeProfiles that the values in the magnitude column should be
used for each pixel of a flat profile. Without it, MakeProfiles would build the profiles such
that the sum of the pixels of each profile would have a magnitude (in log-scale) of the value
given in that column (what you would expect when simulating a galaxy for example). See
Section 8.1.5 [Invoking MakeProfiles], page 340, for details on the options.

```
$ astmkprof apertures.txt --background=flat-ir/xdf-f160w.fits
   --clearcanvas --replace --type=int16 --mforflatpix
   --mode=wcs
```

The first thing you might notice in the printed information is that the profiles are
not built in order. This is because MakeProfiles works in parallel, and parallel CPU
operations are asynchronous. You can try running MakeProfiles with one thread (using
```
--numthreads=1
```
to see how order is respected in that case, but slower (note that the multi-threaded run will be much more faster when more mathematically-complicated pro-
files are built, like Séric profiles).

Open `apertures.fits` with a FITS viewer and look around at the circles placed over
the targets. Also open the input image and Segment’s clumps image and compare them
with the positions of these circles. Where the apertures overlap, you will notice that one
label has replaced the other (because of the `--replace` option). In the future, MakeCatalog
will be able to work with overlapping labels, but currently it doesn’t. If you are interested,
please join us in completing Gnuastro with added improvements like this (see task 14750\[18\]).

\[18\] https://savannah.gnu.org/task/index.php?14750
We can now feed the `apertures.fits` labeled image into MakeCatalog instead of Segment’s output as shown below. In comparison with the previous MakeCatalog call, you will notice that there is no more `--clumpscat` option, since there is no more separate “clump” image now, each aperture is treated as a separate “object”.

```
$ astmkcatalog apertures.fits -h1 --zeropoint=26.27 \
   --valuesfile=nc/xdf-f105w.fits \
   --ids --ra --dec --magnitude --sn \
   --output=cat/xdf-f105w-aper.fits
```

This catalog has the same number of rows as the catalog produced from clumps in Section 2.2.14 [Working with catalogs (estimating colors)], page 46. Therefore similar to how we found colors, you can compare the aperture and clump magnitudes for example.

You can also change the filter name and zero point magnitudes and run this command again to have the fixed aperture magnitude in the F160W filter and measure colors on apertures.

### 2.2.16 Matching catalogs

In the example above, we had the luxury to generate the catalogs ourselves, and where thus able to generate them in a way that the rows match. But this isn’t generally the case. In many situations, you need to use catalogs from many different telescopes, or catalogs with high-level calculations that you can’t simply regenerate with the same pixels without spending a lot of time or using heavy computation. In such cases, when each catalog has the coordinates of its own objects, you can use the coordinates to match the rows with Gnuastro’s Match program (see Section 7.5 [Match], page 326).

As the name suggests, Gnuastro’s Match program will match rows based on distance (or aperture in 2D) in one, two, or three columns. For this tutorial, let’s try matching the two catalogs that weren’t created from the same labeled images, recall how each has a different number of rows:

```
$ asttable cat/xdf-f105w.fits -hCLUMPS -i
$ asttable cat/xdf-f160w.fits -hCLUMPS -i
```

You give Match two catalogs (from the two different filters we derived above) as argument, and the HDUs containing them (if they are FITS files) with the `--hdu` and `--hdu2` options. The `--ccol1` and `--ccol2` options specify the coordinate-columns which should be matched with which in the two catalogs. With `--aperture` you specify the acceptable error (radius in 2D), in the same units as the columns.

```
$ astmatch cat/xdf-f160w.fits cat/xdf-f105w.fits \
   --hdu=CLUMPS --hdu2=CLUMPS \
   --ccol1=RA,DEC --ccol2=RA,DEC \
   --aperture=0.5/3600 --log \
   --output=matched.fits
```

From the second command, you see that the output has two extensions and that both have the same number of rows. The rows in each extension correspond with the rows in the other. You can also see which objects didn’t match with the `--notmatched`, like below. Note how each extension now has a different number of rows.

```
$ astmatch cat/xdf-f160w.fits cat/xdf-f105w.fits \
```
Chapter 2: Tutorials

--hdu=CLUMPS --hdu2=CLUMPS
--ccol1=RA,DEC --ccol2=RA,DEC
--aperture=0.5/3600 --log
--output=matched.fits --notmatched

$ astfits matched.fits

The --outcols of Match is a very convenient feature: you can use it to specify which columns from the two catalogs you want in the output (merge two input catalogs into one). If the first character is an 'a', the respective matched column (number or name, similar to Table above) in the first catalog will be written in the output table. When the first character is a 'b', the respective column from the second catalog will be written in the output. Also, if the first character is followed by _all, then all the columns from the respective catalog will be put in the output.

$ astmatch cat/xdf-f160w.fits cat/xdf-f105w.fits
--hdu=CLUMPS --hdu2=CLUMPS
--ccol1=RA,DEC --ccol2=RA,DEC
--aperture=0.35/3600 --log
--outcols=a_all,bMAGNITUDE,bSN
--output=matched.fits

$ astfits matched.fits

2.2.17 Finding reddest clumps and visual inspection

As a final step, let’s go back to the original clumps-based color measurement we generated in Section 2.2.14 [Working with catalogs (estimating colors)], page 46. We’ll find the objects with the strongest color and make a cutout to inspect them visually and finally, we’ll see how they are located on the image. With the command below, we’ll select the reddest objects (those with a color larger than 1.5):

$ asttable cat/mags-with-color.fits --range=F105W-F160W,1.5,inf

You can see how many they are by piping it to wc -l:

$ asttable cat/mags-with-color.fits --range=F105W-F160W,1.5,inf | wc -l

Let’s crop the F160W image around each of these objects, but we first need a unique identifier for them. We’ll define this identifier using the object and clump labels (with an underscore between them) and feed the output of the command above to AWK to generate a catalog. Note that since we are making a plain text table, we’ll define the necessary (for the string-type first column) metadata manually (see Section 4.8.2 [Gnuastro text table format], page 137).

$ echo "# Column 1: ID [name, str10] Object ID" > reddest.txt
$ asttable cat/mags-with-color.fits --range=F105W-F160W,1.5,inf | awk '{printf("%d_%-10d %f %f\n", $1, $2, $3, $4)}' > reddest.txt

$ mkdir crop-red

We can now feed reddest.txt into Gnuastro’s Crop program to see what these objects look like. To keep things clean, we’ll make a directory called crop-red and ask Crop to save the crops in this directory. We’ll also add a -f160w.fits suffix to the crops (to remind us which filter they came from). The width of the crops will be 15 arc-seconds (or 15/3600 degrees, which is the units of the WCS).

$ mkdir crop-red
You can see all the cropped FITS files in the crop-red directory. Like the MakeProfiles command in Section 2.2.15 [Aperture photometry], page 51, you might notice that the crops aren’t made in order. This is because each crop is independent of the rest, therefore crops are done in parallel, and parallel operations are asynchronous. In the command above, you can change f160w to f105w to make the crops in both filters.

To view the crops more easily (not having to open ds9 for each image), you can convert the FITS crops into the JPEG format with a shell loop like below.

```bash
$ cd crop-red
$ for f in *.fits; do
    astconvertt $f --fluxlow=-0.001 --fluxhigh=0.005 --invert -ojpg;
done
$ cd ..
$ ls crop-red/
```

You can now use your general graphic user interface image viewer to flip through the images more easily, or import them into your papers/reports.

The for loop above to convert the images will do the job in series: each file is converted only after the previous one is complete. If you have GNU Parallel (https://www.gnu.org/s/parallel), you can greatly speed up this conversion. GNU Parallel will run the separate commands simultaneously on different CPU threads in parallel. For more information on efficiently using your threads, see Section 4.5 [Multi-threaded operations], page 127. Here is a replacement for the shell for loop above using GNU Parallel.

```bash
$ cd crop-red
$ parallel astconvertt --fluxlow=-0.001 --fluxhigh=0.005 --invert -ojpg ::: *.fits
$ cd ..
```

Did you notice how much faster this one was? When possible, its always very helpful to do your analysis in parallel. But the problem is that many operations are not as simple as this. For such cases, you can use Make (https://en.wikipedia.org/wiki/Make_(software)) which will greatly help designing workflows. But that is beyond the topic here.

As the final action, let’s see how these objects are positioned over the dataset. DS9 has the “Region” concept for this purpose. You just have to convert your catalog into a “region file” to feed into DS9. To do that, you can use AWK again as shown below.

```bash
$ awk 'BEGIN{print "# Region file format: DS9 version 4.1"; print "global color=green width=2"; print "fk5";}
!/"#/{printf "circle(%s,%s,1") # text={%s}\"n","$2","$3","$1;}}"
reddest.txt > reddest.reg
```

This region file can be loaded into DS9 with its -regions option to display over any image (that has world coordinate system). In the example below, we’ll open Segment’s output and load the regions over all the extensions (to see the image and the respective clump):

```bash
$ ds9 -mecube seg/xdf-f160w.fits -zscale -zoom to fit
```
2.2.18 Writing scripts to automate the steps

In the previous sub-sections, we went through a series of steps like downloading the necessary datasets (in Section 2.2.3 [Setup and data download], page 27), detecting the objects in the image, and finally selecting a particular subset of them to inspect visually (in Section 2.2.17 [Finding reddest clumps and visual inspection], page 53). To benefit most effectively from this subsection, please go through the previous sub-sections, and if you haven’t actually done them, we recommended to do/run them before continuing here.

Each sub-section/step of the sub-sections above involved several commands on the command-line. Therefore, if you want to reproduce the previous results (for example to only change one part, and see its effect), you’ll have to go through all the sections above and read through them again. If you done the commands recently, you may also have them in the history of your shell (command-line environment). You can see many of your previous commands on the shell (even if you have closed the terminal) with the `history` command, like this:

```bash
$ history
```

Try it in your terminal to see for yourself. By default in GNU Bash, it shows the last 500 commands. You can also save this “history” of previous commands to a file using shell redirection (to have it after your next 500 commands), with this command:

```bash
$ history > my-previous-commands.txt
```

This is a good way to temporarily keep track of every single command you ran. But in the middle of all the useful commands, you will have many extra commands, like tests that you did before/after the good output of a step (that you decided to continue working on), or an unrelated job you had to do in the middle of this project. Because of these impurities, after a few days (that you have forgot the context: tests you didn’t end-up using, or unrelated jobs) reading this full history will be very frustrating.

Keeping the final commands that were used in each step of an analysis is a common problem for anyone who is doing something serious with the computer. But simply keeping the most important commands in a text file is not enough, the small steps in the middle (like making a directory to keep the outputs of one step) are also important. In other words, the only way you can be sure that you are under control of your processing (and actually understand how you produced your final result) is to run the commands automatically.

Fortunately, typing commands interactively with your fingers isn’t the only way to operate the shell. The shell can also take its orders/commands from a plain-text file, which is called a script. When given a script, the shell will read it line-by-line as if you have actually typed it manually.

Let’s continue with an example: try typing the commands below in your shell. With these commands we are making a text file (`a.txt`) containing a simple $3 \times 3$ matrix, converting it to a FITS image and computing its basic statistics. After the first three commands open `a.txt` with a text editor to actually see the values we wrote in it, and after the fourth, open the FITS file to see the matrix as an image. `a.txt` is created through the shell’s redirection feature: `>’ overwrites the existing contents of a file, and ‘>>&’ appends the new contents after the old contents.

```bash
$ echo "1 1 1" > a.txt
```
$ echo "1 2 1" >> a.txt
$ echo "1 1 1" >> a.txt
$ astconvertt a.txt --output=a.fits
$ aststatistic a.fits

To automate these series of commands, you should put them in a text file. But that text file must have two special features: 1) It should tell the shell what program should interpret the script. 2) The operating system should know that the file can be directly executed.

For the first, Unix-like operating systems define the shebang concept (also known as sha-bang or hashbang). In the shebang convention, the first two characters of a file should be ‘#!/’. When confronted with these characters, the script will be interpreted with the program that follows them. In this case, we want to write a shell script and the most common shell program is GNU Bash which is installed in /bin/bash. So the first line of your script should be ‘#!/bin/bash’.

Using your favorite text editor, make a new empty file, let’s call it my-first-script.sh. Write the GNU Bash shebang (above) as its first line. After the shebang, copy the series of commands we ran above. Just note that the ‘$’ sign at the start of every line above is the prompt of the interactive shell (you never actually typed it, remember?). Therefore, commands in a shell script should not start with a ‘$'. Once you add the commands, close the text editor and run the cat command to confirm its contents. It should look like the example below. Recall that you should only type the line that starts with a ‘$’, the lines without a ‘$’, are printed automatically on the command-line (they are the contents of your script).

```
$ cat my-first-script.sh
#!/bin/bash
echo "1 1 1" > a.txt
echo "1 2 1" >> a.txt
echo "1 1 1" >> a.txt
astconvertt a.txt --output=a.fits
aststatistic a.fits
```

The script contents are now ready, but to run it, you should activate the script file’s executable flag. In Unix-like operating systems, every file has three types of flags: read (or r), write (or w) and execute (or x). To toggle a file’s flags, you should use the chmod (for “change mode”) command. To activate a flag, you put a ‘+’ before the flag character (for example +x). To deactivate it, you put a ‘-’ (for example -x). In this case, you want to activate the script’s executable flag, so you should run

```
$ chmod +x my-first-script.sh
```

Your script is now ready to run/execute the series of commands. To run it, you should call it while specifying its location in the file system. Since you are currently in the same directory as the script, its easiest to use relative addressing like below (where ‘./’ means the current directory). But before running your script, first delete the two a.txt and a.fits files that were created when you interactively ran the commands.

When the script is to be run by the same shell that is calling it (like this script), the shebang is optional. But it is still recommended, because it ensures that even if the user isn’t using GNU Bash, the script will be run in GNU Bash: given the differences between various shells, writing truely portable shell scripts, that can be run by many shell programs/implementations, isn’t easy (sometimes not possible!).
$ rm a.txt a.fits
$ ls
$ ./my-first-script.sh
$ ls

The script immediately prints the statistics while doing all the previous steps in the background. With the last `ls`, you see that it automatically re-built the `a.txt` and `a.fits` files, open them and have a look at their contents.

An extremely useful feature of shell scripts is that the shell will ignore anything after a `#` character. You can thus add descriptions/comments to the commands and make them much more useful for the future. For example, after adding comments, your script might look like this:

```bash
$ cat my-first-script.sh
#!/bin/bash
# This script is my first attempt at learning to write shell scripts.
# As a simple series of commands, I am just building a small FITS image, and calculating its basic statistics.

# Write the matrix into a file.
echo "1 1 1" > a.txt
echo "1 2 1" >> a.txt
echo "1 1 1" >> a.txt

# Convert the matrix to a FITS image.
astconvertt a.txt --output=a.fits

# Calculate the statistics of the FITS image.
aststatistics a.fits
```

Isn’t this much more easier to read now? Comments help to provide human-friendly context to the raw commands. At the time you make a script, comments may seem like an extra effort and slow you down. But in one year, you will forget almost everything about your script and you will appreciate the effort so much! Think of the comments as an email to your future-self and always put a well-written description of the context/purpose (most importantly, things that aren’t directly clear by reading the commands) in your scripts.

The example above was very basic and mostly redundant series of commands, to show the basic concepts behind scripts. You can put any (arbitrarily long and complex) series of commands in a script by following the two rules: 1) add a shebang, and 2) enable the executable flag. Infact, as you continue your own research projects, you will find that any time you are dealing with more than two or three commands, keeping them in a script (and modifying that script, and running it) is much more easier, and future-proof, then typing the commands directly on the command-line and relying on things like `history`. Here are some tips that will come in handy when you are writing your scripts:

As a more realistic example, let’s have a look at a script that will do the steps of Section 2.2.3 [Setup and data download], page 27, and Section 2.2.4 [Dataset inspection and cropping], page 27. In particular note how often we are using variables to avoid repeating
fixed strings of characters (usually file/directory names). This greatly helps in scaling up your project, and avoiding hard-to-find bugs that are caused by typos in those fixed strings.

```bash
$ cat gnuastro-tutorial-1.sh
#!/bin/bash

# Download the input datasets
# ---------------------------
#
# The default file names have this format (where 'FILTER' differs for each filter):
#     hlsp_xdf_hst_wfc3ir-60mas_hudf_FILTER_v1_sci.fits
# To make the script easier to read, a prefix and suffix variable are used to sandwich the filter name into one short line.
# downloaddir=download
xdfsuffix=_v1_sci.fits
xdfprefix=hlsp_xdf_hst_wfc3ir-60mas_hudf_
xdffurl=http://archive.stsci.edu/pub/hlsp/xdf

# The file name and full URLs of the input data.
f105w_in=$xdfprefix"f105w"$xdfsuffix
f160w_in=$xdfprefix"f160w"$xdfsuffix
f105w_full=$xdffurl/$f105w_in
f160w_full=$xdffurl/$f160w_in

# Go into the download directory and download the images there, then come back up to the top running directory.
mkdir $downloaddir
cd $downloaddir
wget $f105w_full
wget $f160w_full
cd ..

# Only work on the deep region
# ----------------------------
#
# To help in readability, each vertice of the deep/flat field is stored as a separate variable. They are then merged into one variable to define the polygon.
flatdir=flat-ir
vertice1="53.187414,-27.779152"
vertice2="53.159507,-27.759633"
vertice3="53.134517,-27.787144"
vertice4="53.161906,-27.807208"
f105w_flat=$flatdir/xdf-f105w.fits
```
f160w_flat=$flatdir/xdf-f160w.fits
deep_polygon="$vertex1:$vertex2:$vertex3:$vertex4"

mkdir $flatdir
astcrop --mode=wcs -h0 --output=$f105w_flat  
   --polygon=$deep_polygon $downloaddir/$f105w_in
astcrop --mode=wcs -h0 --output=$f160w_flat  
   --polygon=$deep_polygon $downloaddir/$f160w_in

The first thing you may notice is that even if you already have the downloaded input images, this script will always try to re-download them. Also, if you re-run the script, you will notice that mkdir prints an error message that the download directory already exists. Therefore, the script above isn’t too useful and some modifications are necessary to make it more generally useful. Here are some general tips that are often very useful when writing scripts:

**Stop script if a command crashes**
By default, if a command in a script crashes (aborts and fails to do what it was meant to do), the script will continue onto the next command. In GNU Bash, you can tell the shell to stop a script in the case of a crash by adding this line at the start of your script:

```
set -e
```

**Check if a file/directory exists to avoid re-creating it**
Conditionals are a very useful feature in scripts. One common conditional is to check if a file exists or not. Assuming the file’s name is FILENAME, you can check its existence (to avoid re-doing the commands that build it) like this:

```
if [ -f FILENAME ]; then
  echo "FILENAME exists"
else
  # Some commands to generate the file
  echo "done" > FILENAME
fi
```

To check the existence of a directory instead of a file, use -d instead of -f. To negate a conditional, use ‘!’ and note that conditionals can be written in one line also (useful for when its short).

One common scenario that you’ll need to check the existence of directories is when you are making them: the default mkdir command will crash if the desired directory already exists. On some systems (including GNU/Linux distributions), mkdir has options to deal with such cases. But if you want your script to be portable, its best to check yourself like below:

```
if ! [ -d DIRNAME ]; then mkdir DIRNAME; fi
```

Taking these tips into consideration, we can write a better version of the script above that includes checks on every step to avoid repeating steps/commands. Please compare this script with the previous one carefully to spot the differences. These are very important points that you will definitely encounter during your own research, and knowing them can greatly help your productivity, so pay close attention (even in the comments).

```
$ cat gnuastro-tutorial-2.sh
```
#!/bin/bash
set -e

# Download the input datasets
# ---------------------------
# The default file names have this format (where ‘FILTER’ differs for
# each filter):
# hlsp_xdf_hst_wfc3ir-60mas_hudf_FILTER_v1_sci.fits
# To make the script easier to read, a prefix and suffix variable are
# used to sandwich the filter name into one short line.
downloaddir=download
dfsuffix=v1_sci.fits
dfprefix=hlsp_xdf_hst_wfc3ir-60mas_hudf_
dfurl=http://archive.stsci.edu/pub/hlsp/xdf

# The file name and full URLs of the input data.
f105w_in=$dfprefix"f105w"$dfsuffix
f160w_in=$dfprefix"f160w"$dfsuffix
f105w_full=$dfurl/$f105w_in
f160w_full=$dfurl/$f160w_in

# Go into the download directory and download the images there,
# then come back up to the top running directory.
if ! [ -d $downloaddir ]; then mkdir $downloaddir; fi
if ! [ -f $f105w_in ]; then wget $f105w_full; fi
if ! [ -f $f160w_in ]; then wget $f160w_full; fi
if ..

# Only work on the deep region
# ----------------------------
# To help in readability, each vertex of the deep/flat field is stored
# as a separate variable. They are then merged into one variable to
# define the polygon.
flatdir=flat-ir
vertex1="53.187414,-27.779152"
vertex2="53.159507,-27.759633"
vertex3="53.134517,-27.787144"
vertex4="53.161906,-27.807208"
f105w_flat=$flatdir/xdf-f105w.fits
f160w_flat=$flatdir/xdf-f160w.fits
deep_polygon="$vertex1:$vertex2:$vertex3:$vertex4"
Chapter 2: Tutorials

if ![ -d $flatdir ]; then mkdir $flatdir; fi
if ![ -f $f105w_flat ]; then
  astcrop --mode=wcs -h0 --output=$f105w_flat \
  --polygon=$deep_polygon $downloaddir/$f105w_in
fi
if ![ -f $f160w_flat ]; then
  astcrop --mode=wcs -h0 --output=$f160w_flat \
  --polygon=$deep_polygon $downloaddir/$f160w_in
fi

2.2.19 Citing and acknowledging Gnuastro

In conclusion, we hope this extended tutorial has been a good starting point to help in your exciting research. If this book or any of the programs in Gnuastro have been useful for your research, please cite the respective papers, and acknowledge the funding agencies that made all of this possible. Without citations, we won’t be able to secure future funding to continue working on Gnuastro or improving it, so please take software citation seriously (for all the scientific software you use, not just Gnuastro).

To help you in this aspect is well, all Gnuastro programs have a --cite option to facilitate the citation and acknowledgment. Just note that it may be necessary to cite additional papers for different programs, so please try it out on all the programs that you used, for example:

$ astmkcatalog --cite
$ astnoisechisel --cite

2.3 Detecting large extended targets

The outer wings of large and extended objects can sink into the noise very gradually and can have a large variety of shapes (for example due to tidal interactions). Therefore separating the outer boundaries of the galaxies from the noise can be particularly tricky. Besides causing an under-estimation in the total estimated brightness of the target, failure to detect such faint wings will also cause a bias in the noise measurements, thereby hampering the accuracy of any measurement on the dataset. Therefore even if they don’t constitute a significant fraction of the target’s light, or aren’t your primary target, these regions must not be ignored. In this tutorial, we’ll walk you through the strategy of detecting such targets using Section 7.2 [NoiseChisel], page 269.

Don’t start with this tutorial: If you haven’t already completed Section 2.2 [General program usage tutorial], page 24, we strongly recommend going through that tutorial before starting this one. Basic features like access to this book on the command-line, the configuration files of Gnuastro’s programs, benefiting from the modular nature of the programs, viewing multi-extension FITS files, or using NoiseChisel’s outputs are discussed in more detail there.

We’ll try to detect the faint tidal wings of the beautiful M51 group\(^20\) in this tutorial. We’ll use a dataset/image from the public Sloan Digital Sky Survey (http://www.sdss.

\(^20\) https://en.wikipedia.org/wiki/M51_Group
or SDSS. Due to its more peculiar low surface brightness structure/features, we’ll focus on the dwarf companion galaxy of the group (or NGC 5195). To get the image, you can use SDSS’s Simple field search (https://dr12.sdss.org/fields) tool. As long as it is covered by the SDSS, you can find an image containing your desired target either by providing a standard name (if it has one), or its coordinates. To access the dataset we will use here, write NGC5195 in the “Object Name” field and press “Submit” button.

**Type the example commands:** Try to type the example commands on your terminal and use the history feature of your command-line (by pressing the “up” button to retrieve previous commands). Don’t simply copy and paste the commands shown here. This will help simulate future situations when you are processing your own datasets.

You can see the list of available filters under the color image. For this demonstration, we’ll use the r-band filter image. By clicking on the “r-band FITS” link, you can download the image. Alternatively, you can just run the following command to download it with GNU Wget21. To keep things clean, let’s also put it in a directory called ngc5195. With the -O option, we are asking Wget to save the downloaded file with a more manageable name: r.fits.bz2 (this is an r-band image of NGC 5195, which was the directory name).

```bash
$ mkdir ngc5195
$ cd ngc5195
$ topurl=https://dr12.sdss.org/sas/dr12/boss/photoObj/frames
$ wget $topurl/301/3716/6/frame-r-003716-6-0117.fits.bz2 -Or.fits.bz2
```

This server keeps the files in a Bzip2 compressed file format. So we’ll first decompress it with the following command. By convention, compression programs delete the original file (compressed when uncompressing, or uncompressed when compressing). To keep the original file, you can use the --keep or -k option which is available in most compression programs for this job. Here, we don’t need the compressed file any more, so we’ll just let bunzip delete it for us and keep the directory clean.

```bash
$ bunzip2 r.fits.bz2
```

**2.3.1 NoiseChisel optimization**

In Section 2.3 [Detecting large extended targets], page 61, we downloaded the single exposure SDSS image. Let’s see how NoiseChisel operates on it with its default parameters:

```bash
$ astnoisechisel r.fits -h0
```

As described in Section 2.2.10 [NoiseChisel and Multiextension FITS files], page 37, NoiseChisel’s default output is a multi-extension FITS file. Open the output r_detected.fits file and have a look at the extensions, the first extension is only meta-data and contains NoiseChisel’s configuration parameters. The rest are the Sky-subtracted input, the detection map, Sky values and Sky standard deviation.

```bash
$ ds9 -mecube r_detected.fits -zsclae -zoom to fit
```

Flipping through the extensions in a FITS viewer, you will see that the first image (Sky-subtracted image) looks reasonable: there are no major artifacts due to bad Sky subtraction.

---

21 To make the command easier to view on screen or in a page, we have defined the top URL of the image as the topurl shell variable. You can just replace the value of this variable with `$topurl` in the `wget` command.
compared to the input. The second extension also seems reasonable with a large detection map that covers the whole of NGC5195, but also extends beyond towards the bottom of the image.

Now try flipping between the DETECTIONS and SKY extensions. In the SKY extension, you’ll notice that there is still significant signal beyond the detected pixels. You can tell that this signal belongs to the galaxy because the far-right side of the image is dark and the brighter parts are just surrounding the detected pixels.

The fact that signal from the galaxy remains in the SKY HDU shows that you haven’t done a good detection. The SKY extension must not contain any light around the galaxy. Generally, any time your target is much larger than the tile size and the signal is almost flat (like this case), this will happen. Therefore, when there are large objects in the dataset, the best place to check the accuracy of your detection is the estimated Sky image.

When dominated by the background, noise has a symmetric distribution. However, signal is not symmetric (we don’t have negative signal). Therefore when non-constant signal is present in a noisy dataset, the distribution will be positively skewed. This skewness is a good measure of how much signal we have in the distribution. The skewness can be accurately measured by the difference in the mean and median: assuming no strong outliers, the more distant they are, the more skewed the dataset is. For more see Section 7.1.4.3 [Quantifying signal in a tile], page 255.

However, skewness is only a proxy for signal when the signal has structure (varies per pixel). Therefore, when it is approximately constant over a whole tile, or sub-set of the image, the signal’s effect is just to shift the symmetric center of the noise distribution to the positive and there won’t be any skewness (major difference between the mean and median). This positive shift that preserves the symmetric distribution is the Sky value. When there is a gradient over the dataset, different tiles will have different constant shifts/Sky-values, for example see Figure 11 of Akhlaghi and Ichikawa [2015] (https://arxiv.org/abs/1505.01664).

To get less scatter in measuring the mean and median (and thus better estimate the skewness), you will need a larger tile. So let’s play with the tessellation a little to see how it affects the result. In Gnuastro, you can see the option values (--tilesize in this case) by adding the -P option to your last command. Try running NoiseChisel with -P to see its default tile size.

You can clearly see that the default tile size is indeed much smaller than this (huge) galaxy and its tidal features. As a result, NoiseChisel was unable to identify the skewness within the tiles under the outer parts of M51 and NGC 5159 and the threshold has been over-estimated on those tiles. To see which tiles were used for estimating the quantile threshold (no skewness was measured), you can use NoiseChisel’s --checkqthresh option:

$ astnoisechisel r.fits -h0 --checkqthresh

Did you see how NoiseChisel aborted after finding and applying the quantile thresholds? When you call any of NoiseChisel’s --check* options, by default, it will abort as soon as all the check steps have been written in the check file (a multi-extension FITS file). This allows you to focus on the problem you wanted to check as soon as possible (you can disable this feature with the --continueaftercheck option).

22 In processed images, where the Sky value can be over-estimated, this constant shift can be negative.
To optimize the threshold-related settings for this image, let’s playing with this quantile threshold check image a little. Don’t forget that “Good statistical analysis is not a purely routine matter, and generally calls for more than one pass through the computer” (Anscombe 1973, see Section 1.2 [Science and its tools], page 2). A good scientist must have a good understanding of her tools to make a meaningful analysis. So don’t hesitate in playing with the default configuration and reviewing the manual when you have a new dataset in front of you. Robust data analysis is an art, therefore a good scientist must first be a good artist.

The first extension of r_qthresh.fits (CONVOLVED) is the convolved input image where the threshold(s) is(are) defined and applied. For more on the effect of convolution and thresholding, see Sections 3.1.1 and 3.1.2 of Akhlaghi and Ichikawa [2015] (https://arxiv.org/abs/1505.01664). The second extension (QTHRESH_ERODE) has a blank value for all the pixels of any tile that was identified as having significant signal. The next two extensions (QTHRESH_NOERODE and QTHRESH_EXPAND) are the other two quantile thresholds that are necessary in NoiseChisel’s later steps. Every step in this file is repeated on the three thresholds.

Play a little with the color bar of the QTHRESH_ERODE extension, you clearly see how the non-blank tiles around NGC 5195 have a gradient. As one line of attack against discarding too much signal below the threshold, NoiseChisel rejects outlier tiles. Go forward by three extensions to VALUE1_NO_OUTLIER and you will see that many of the tiles over the galaxy have been removed in this step. For more on the outlier rejection algorithm, see the latter half of Section 7.1.4.3 [Quantifying signal in a tile], page 255.

However, the default outlier rejection parameters weren’t enough, and when you play with the color-bar, you still see a strong gradient around the outer tidal feature of the galaxy. You have two strategies for fixing this problem: 1) Increase the tile size to get more accurate measurements of skewness. 2) Strengthen the outlier rejection parameters to discard more of the tiles with signal. Fortunately in this image we have a sufficiently large region on the right of the image that the galaxy doesn’t extend to. So we can use the more robust first solution. In situations where this doesn’t happen (for example if the field of view in this image was shifted to have more of M51 and less sky) you are limited to a combination of the two solutions or just to the second solution.

Skipping convolution for faster tests: The slowest step of NoiseChisel is the convolution of the input dataset. Therefore when your dataset is large (unlike the one in this test), and you are not changing the input dataset or kernel in multiple runs (as in the tests of this tutorial), it is faster to do the convolution separately once (using Section 6.3 [Convolve], page 216) and use NoiseChisel’s --convolved option to directly feed the convolved image and avoid convolution. For more on --convolved, see Section 7.2.1.1 [NoiseChisel input], page 273.

To identify the skewness caused by the flat NGC 5195 and M51 tidal features on the tiles under it, we thus have to choose a tile size that is larger than the gradient of the signal. Let’s try a tile size of 100 by 100 pixels:

$ astnoisechisel r.fits -h0 --tilesize=100,100 --checkqthresh

You can clearly see the effect of this increased tile size: the tiles are much larger and when you look into VALUE1_NO_OUTLIER, you see that all the tiles are nicely grouped on the right side of the image (the farthest from M51, where we didn’t see any gradient before).
Things look good now, so let’s remove \texttt{--checkqthresh} and let NoiseChisel proceed with its detection.

$$\texttt{astnoisechisel \ r.fits \ -h0 \ --tilesize=100,100}$$

The resulting detected pixels have expanded a little, but not as much as we may have expected from the tiles that were used for the thresholding: there is still a gradient in the SKY image that is far from the tiles used. Let’s check the next series of detection steps by adding the \texttt{--checkdetection} option this time:

$$\texttt{astnoisechisel \ r.fits \ -h0 \ --tilesize=100,100 \ --checkdetection}$$

The output now has 16 extensions, showing every step that is taken by NoiseChisel. The first and second (INPUT and CONVOLVED) are clear from their names. The third (THRESHOLDED) is the thresholded image after finding the quantile threshold (last extension of the output of \texttt{--checkqthresh}). The fourth HDU (ERODED) is new: it’s the name-stake of NoiseChisel, or eroding pixels that are above the threshold. By erosion, we mean that all pixels with a value of 1 (above the threshold) that are touching a pixel with a value of 0 (below the threshold) will be flipped to zero (or “carved” out). You can see its effect directly by flipping between the THRESHOLDED and ERODED extensions.

In the fifth extension (OPENED-AND-LABELED) the image is “opened”, which is a name for eroding once, then dilating. This is good to remove thin connections that are only due to noise. Each separate connected group of pixels is also given its unique label here. Do you see how just beyond the large M51 detection, there are many smaller detections that get smaller as you go more distant? This hints at the solution: the default number of erosions is too much. Let’s see how many erosions take place by default:

$$\texttt{astnoisechisel \ r.fits \ -h0 \ --tilesize=100,100 \ --erode=1 \ --checkdetection}$$

Looking at the OPENED-AND-LABELED extension again, we see that the main/large detection is now much larger than before. While the immediately-outer connected regions are still present, they have decreased dramatically, so we can pass this step.

After the OPENED-AND-LABELED extension, NoiseChisel goes onto finding false detections using the undetected pixels. The process is fully described in Section 3.1.5. (Defining and Removing False Detections) of arXiv:1505.01664 (https://arxiv.org/pdf/1505.01664.pdf). Please compare the extensions to what you read there and things will be very clear. In the last HDU (DETECTION-FINAL), we have the final detected pixels that will be used to estimate the Sky and its Standard deviation. We see that the main detection has indeed been detected very far out, so let’s see how the full NoiseChisel will estimate the Sky and its standard deviation (by removing \texttt{--checkdetection}):

$$\texttt{astnoisechisel \ r.fits \ -h0 \ --tilesize=100,100 \ --erode=1}$$

\footnote{Pixels with a value of 2 are very high signal-to-noise pixels, they are not eroded, to preserve sharp and bright sources.}
The **DETECTIONS** extension of `r_detected.fits` closely follows what the **DETECTION-FINAL** of the check image (looks good!). But if you go ahead to the **SKY** extension, you’ll see the footprint of the galaxy again! It is MUCH better than before, but still problematic.

The Sky is estimated over the same tiles that were used for quantile thresholding, but this time, we first look at what fraction of a tile has un-detected pixels: the tiles that are fully covered by a detection will have a sky (un-detected) fraction of 0, and if it has no detections within it, it will have a sky fraction of 1. You can define your acceptable sky fraction through the `--minskyfrac` option. Please run the previous command with `-P` to see its default value. Let’s increase `--minskyfrac` to 0.8 to see how it looks:

```
$ astnoisechisel r.fits -h0 --tilesize=100,100 --erode=1 \
   --minskyfrac=0.8
```

The M51 footprint on the **SKY** extension is now much less, which is good! But it is still present! This is happening because the wings are so diffuse and large. Look at the **DETECTIONS** again, you will see the right-ward edges of M51’s detected pixels have many “holes” that are fully surrounded by signal (value of 1) and the signal stretches out in the noise very thinly (the size of the holes increases as we go out). This suggests that there is still undetected signal that is causing that bias in the SKY extension. Therefore, we should dig deeper into the noise.

With the `--detgrowquant` option, NoiseChisel will use the detections as seeds and grow them in to the noise. Its value is the ultimate limit of the growth in units of quantile (between 0 and 1). Therefore `--detgrowquant=1` means no growth and `--detgrowquant=0.5` means an ultimate limit of the Sky level (which is usually too much and will cover the whole image!). See Figure 2 of arXiv:1909.11230 ([https://arxiv.org/pdf/1909.11230.pdf](https://arxiv.org/pdf/1909.11230.pdf)) for more on this option. Try running the previous command with various values (from 0.6 to higher values) to see this option’s effect on this dataset. For this particularly huge galaxy (with signal that extends very gradually into the noise), we’ll set it to 0.7:

```
$ astnoisechisel r.fits -h0 --tilesize=100,100 --erode=1 \
   --minskyfrac=0.8 --detgrowquant=0.8
```

Beyond this level (smaller `--detgrowquant` values), you see the smaller background galaxies starting to create thin spider-leg-like features, showing that we are following correlated noise for too much. Please try it for yourself by changing it to 0.6 for example.

When you look at the **DETECTIONS** extension of the command shown above, you see the wings of the galaxy being detected much farther out, But you also see many holes which are clearly just caused by noise. After growing the objects, NoiseChisel also allows you to fill such holes when they are smaller than a certain size through the `--detgrowmaxholesize` option. In this case, a maximum area/size of 10,000 pixels seems to be good:

```
$ astnoisechisel r.fits -h0 --tilesize=100,100 --erode=1 \
   --minskyfrac=0.8 --detgrowquant=0.8 \
   --detgrowmaxholesize=10000
```

The footprint of the galaxy has almost disappeared (the maximum value is now outside the galaxy) but still exists in the **SKY** extension. Let’s calculate the significance of the undetected gradient, in units of noise. Since the gradient is roughly along the horizontal axis, we’ll collapse the image along the second (vertical) FITS dimension to have a 1D array (a table column, see its values with the second command).
We can now calculate the minimum and maximum values of this array and define their difference (in units of noise) as the gradient:

$$ \text{grad} = (\text{astarithmetic } r_{\text{detected}.fits} \ 2 \ \text{collapse-mean set-i} \ \ \ \ \ \ i \ \text{maxvalue} \ \text{iminvalue} \ -h\text{SKY} \ -q) $$

$$ \text{echo } \text{grad} $$

$$ \text{std} = (\text{astastatistics } r_{\text{detected}.fits} \ -h\text{SKY_STD} --\text{mean}) $$

$$ \text{echo } \text{std} $$

$$ \text{astarithmetic } -q \ \text{grad} \ \text{std} / $$

The undetected gradient (\text{grad} above) is thus almost 1/10th of the noise-level (which is good). But don’t forget that this is per-pixel: individually its small, but it extends over millions of pixels, so the total flux may still be relevant.

When looking at the raw input shallow image, you don’t see anything so far out of the galaxy. You might just think that “this is all noise, I have just dug too deep and I’m following systematics”? If you feel like this, have a look at the deep images of this system in Watkins et al. [2015] (https://arxiv.org/abs/1501.04599), or a 12 hour deep image of this system (with a 12-inch telescope): https://i.redd.it/jfqgpqg0hfk11.jpg

In these deeper images you clearly see how the outer edges of the M51 group follow this exact structure, below in Section 2.3.2 [Achieved surface brightness level], page 68, we’ll measure the exact level.

As the gradient in the \text{SKY} extension shows, and the deep images cited above confirm, the galaxy’s signal extends even beyond this. But this is already far deeper than what most (if not all) other tools can detect. Therefore, we’ll stop configuring NoiseChisel at this point in the tutorial and let you play with it a little more while reading more about it in Section 7.2 [NoiseChisel], page 269.

After finishing this tutorial please go through the NoiseChisel paper and its options and play with them to see if you can further decrease the gradient. This will greatly help you get a good feeling of the options. When you do find a better configuration feel free to contact us for feedback. Don’t forget that good data analysis is an art, so like a sculptor, master your chisel for a good result.

**This NoiseChisel configuration is NOT GENERIC:** Don’t use the configuration derived above, on another image blindly. If you are unsure, just use the default values. As you saw above, the reason we chose this particular configuration for NoiseChisel to detect the wings of the M51 group was strongly influenced by the noise properties of this particular image. So as long as your image noise has similar properties (from the same data-reduction step of the same database), you can use this configuration on any image. But for images from other instruments, or higher-level/reduced SDSS products, please follow a similar logic to what was presented here and find the best configuration yourself.

---

24 The image is taken from this Reddit discussion: https://www.reddit.com/r/Astronomy/comments/9d6x0q/12_hours_of_exposure_on_the_whirlpool_galaxy/
2.3.2 Achieved surface brightness level

In Section 2.3.1 [NoiseChisel optimization], page 62, we showed how to customize NoiseChisel for a single-exposure SDSS image of the M51 group. Let’s measure how deep we carved the signal out of noise. For this measurement, we’ll need to estimate the average flux on the outer edges of the detection. Fortunately all this can be done with a few simple commands (and no higher-level language mini-environments like Python or IRAF) using Section 6.2 [Arithmetic], page 199, and Section 7.4 [MakeCatalog], page 295.

First, let’s separate each detected region, or give a unique label/counter to all the connected pixels of NoiseChisel’s detection map:

```bash
$ det="r_detected.fits -hDETECTIONS"
$ astarithmetic $det 2 connected-components -olabeled.fits
```

You can find the label of the main galaxy visually (by opening the image and hovering your mouse over the M51 group’s label). But to have a little more fun, let’s do this automatically (which is necessary in a general scenario). The M51 group detection is by far the largest detection in this image, this allows us to find its ID/label easily. We’ll first run MakeCatalog to find the area of all the labels, then we’ll use Table to find the ID of the largest object and keep it as a shell variable (id):

```bash
# Run MakeCatalog to find the area of each label.
$ astmkcatalog labeled.fits --ids --geoarea -h1 -ocat.fits

## Sort the table by the area column.
$ asttable cat.fits --sort=AREA_FULL

## The largest object, is the last one, so we’ll use ‘--tail’.
$ asttable cat.fits --sort=AREA_FULL --tail=1

## We only want the ID, so let’s only ask for that column:
$ asttable cat.fits --sort=AREA_FULL --tail=1 --column=OBJ_ID

## Now, let’s put this result in a variable (instead of printing)
$ id=$(asttable cat.fits --sort=AREA_FULL --tail=1 --column=OBJ_ID)

## Just to confirm everything is fine.
$ echo $id
```

To separate the outer edges of the detections, we’ll need to “erode” the M51 group detection. We’ll erode three times (to have more pixels and thus less scatter), using a maximum connectivity of 2 (8-connected neighbors). We’ll then save the output in `eroded.fits`.

```bash
$ astarithmetic labeled.fits $id eq 2 erode 2 erode 2 erode \
```

**Smart NoiseChisel**: As you saw during this section, there is a clear logic behind the optimal parameter value for each dataset. Therefore, we plan to capabilities to (optionally) automate some of the choices made here based on the actual dataset, please join us in doing this if you are interested. However, given the many problems in existing “smart” solutions, such automatic changing of the configuration may cause more problems than they solve. So even when they are implemented, we would strongly recommend quality checks for a robust analysis.
In `labeled.fits`, we can now set all the 1-valued pixels of `eroded.fits` to 0 using Arithmetic's `where` operator added to the previous command. We'll need the pixels of the M51 group in `labeled.fits` two times: once to do the erosion, another time to find the outer pixel layer. To do this (and be efficient and more readable) we'll use the `set-i` operator. In the command below, it will save/set/name the pixels of the M51 group as the ‘i’. In this way we can use it any number of times afterwards, while only reading it from disk and finding M51’s pixels once.

```
$ astarithmetic labeled.fits $id eq set-i i \
  i 2 erode 2 erode 2 erode 0 where -oedge.fits
```

Open the image and have a look. You’ll see that the detected edge of the M51 group is now clearly visible. You can use `edge.fits` to mark (set to blank) this boundary on the input image and get a visual feeling of how far it extends:

```
$ astarithmetic r.fits edge.fits nan where -ob-masked.fits -h0
```

To quantify how deep we have detected the low-surface brightness regions, we’ll use the command below. In short it just divides all the non-zero pixels of `edge.fits` in the Sky subtracted input (first extension of NoiseChisel’s output) by the pixel standard deviation of the same pixel. This will give us a signal-to-noise ratio image. The mean value of this image shows the level of surface brightness that we have achieved.

You can also break the command below into multiple calls to Arithmetic and create temporary files to understand it better. However, if you have a look at Section 6.2.1 [Reverse polish notation], page 199, and Section 6.2.2 [Arithmetic operators], page 200, you should be able to easily understand what your computer does when you run this command25.

```
$ edge="edge.fits -h1"
$ skystd="r_detected.fits -hSKY_STD"
$ skysub="r_detected.fits -hINPUT-NO-SKY"
$ astarithmetic $skysub $skystd / $edge not nan where \
  meanvalue --quiet
```

We have thus detected the wings of the M51 group down to roughly 1/3rd of the noise level in this image! But the signal-to-noise ratio is a relative measurement. Let’s also measure the depth of our detection in absolute surface brightness units; or magnitudes per square arcseconds. To find out, we’ll first need to calculate how many pixels of this image are in one arcsecond-squared. Gnuastro Fits program has the `--pixelscale` option for this job:

```
## Get the image pixel scale:
$ astfits r.fits -h0 --pixelscale

## Avoid all the human-friendly text (just print numbers):
$ astfits r.fits -h0 --pixelscale --quiet
```

25 `edge.fits` (extension 1) is a binary (0 or 1 valued) image. Applying the `not` operator on it, just flips all its pixels. Through the `where` operator, we are setting all the newly 1-valued pixels in `r_detected.fits` (extension INPUT-NO-SKY) to NaN/blank. In the second line, we are dividing all the non-blank values by `r_detected.fits` (extension SKY_STD). This gives the signal-to-noise ratio for each of the pixels on the boundary. Finally, with the `meanvalue` operator, we are taking the mean value of all the non-blank pixels and reporting that as a single number.
## Take the first value, and convert it to arcseconds.

```
$ pixscale=$(astfits r.fits -h0 --pixelscale --quiet \
    | awk '{print $1*3600}')
```

## For a check:

```
$ echo $pixscale
```

Note that we multiplied the value by 3600 so we work in units of arc-seconds not degrees.

Now, let’s calculate the average sky-subtracted flux in the border region per pixel.

```
$ f=$(astarithmetic r_detected.fits edge.fits not nan where set-i \
    i sumvalue i numbervalue / -q -hINPUT-NO-SKY)
```

```
$ echo $f
```

We can just multiply the two to get the average flux on this border in one arcsecond squared. The pixel values are calibrated to be in units of “nanomaggy”, so the zero point magnitude is 22.5\(^{26}\). Therefore we can get the surface brightness of the outer edge (in magnitudes per arcsecond squared) using the following command. Just note that \(\log\) in AWK is in base-2 (not 10), and that AWK doesn’t have a \(\log_{10}\) operator. So we’ll do an extra division by \(\log(10)\) to correct for this.

```
$ z=22.5
$ echo "$pixscale $f $z" | awk '{print -2.5*log($1*$2)/log(10)+$3}'
```

--> 28.6269

On a single-exposure SDSS image, we have reached a surface brightness limit fainter than 28 magnitudes per arcseconds squared!

In interpreting this value, you should just have in mind that NoiseChisel works based on the contiguity of signal in the pixels. Therefore the larger the object, the deeper NoiseChisel can carve it out of the noise. In other words, this reported depth, is only for this particular object and dataset, processed with this particular NoiseChisel configuration: if the M51 group in this image was larger/smaller than this, or if the image was larger/smaller, or if we had used a different configuration, we would go deeper/shallower.

To avoid typing all these options every time you run NoiseChisel on this image, you can use Gnuastro’s configuration files, see Section 4.2 [Configuration files], page 120. For an applied example of setting/using them, see Section 2.2.8 [Option management and configuration files], page 34.

To continue your analysis of such datasets with extended emission, you can use Section 7.3 [Segment], page 284, to identify all the “clumps” over the diffuse regions: background galaxies and foreground stars.

```
$ astsegment r_detected.fits
```

Open the output `r_detected_segmented.fits` as a multi-extension data cube like before and flip through the first and second extensions to see the detected clumps (all pixels with a value larger than 1). To optimize the parameters and make sure you have detected what you wanted, we recommend to visually inspect the detected clumps on the input image.

\(^{26}\) From https://www.sdss.org/dr12/algorithms/magnitudes
For visual inspection, you can make a simple shell script like below. It will first call MakeCatalog to estimate the positions of the clumps, then make an SAO ds9 region file and open ds9 with the image and region file. Recall that in a shell script, the numeric variables (like \$1, \$2, and \$3 in the example below) represent the arguments given to the script. But when used in the AWK arguments, they refer to column numbers.

To create the shell script, using your favorite text editor, put the contents below into a file called `check-clumps.sh`. Recall that everything after a `#` is just comments to help you understand the command (so read them!). Also note that if you are copying from the PDF version of this book, fix the single quotes in the AWK command.

```bash
#!/bin/bash
set -e  # Stop execution when there is an error.
set -u  # Stop execution when a variable is not initialized.

# Run MakeCatalog to write the coordinates into a FITS table.
# Default output is `$1_cat.fits`.
astmkcatalog $1.fits --clumpscat --ids --ra --dec

# Use Gnuastro's Table program to read the RA and Dec columns of the
# clumps catalog (in the 'CLUMPS' extension). Then pipe the columns
# to AWK for saving as a DS9 region file.
asttable $1"_cat.fits" -hCLUMPS -cRA,DEC
   | awk 'BEGIN { print "# Region file format: DS9 version 4.1"; 
          print "global color=green width=1"; 
          print "fk5" } 
          { printf "circle(%s,%s,1")\n", $1, $2 }' > $1.reg

# Show the image (with the requested color scale) and the region file.
ds9 -geometry 1800x3000 -mecube $1.fits -zoom to fit
   -scale limits $2 $3 -regions load all $1.reg

# Clean up (delete intermediate files).
rm $1"_cat.fits" $1.reg
```

Finally, you just have to activate the script’s executable flag with the command below. This will enable you to directly/easily call the script as a command.

```
$ chmod +x check-clumps.sh
```

This script doesn’t expect the `.fits` suffix of the input’s filename as the first argument. Because the script produces intermediate files (a catalog and DS9 region file, which are later deleted). However, we don’t want multiple instances of the script (on different files in the same directory) to collide (read/write to the same intermediate files). Therefore, we have used suffixes added to the input’s name to identify the intermediate files. Note how all the \$1 instances in the commands (not within the AWK command\footnote{In AWK, \$1 refers to the first column, while in the shell script, it refers to the first argument.}) are followed by a suffix. If you want to keep the intermediate files, put a `#` at the start of the last line.

The few, but high-valued, bright pixels in the central parts of the galaxies can hinder easy visual inspection of the fainter parts of the image. With the second and third arguments
Chapter 2: Tutorials

72

to this script, you can set the numerical values of the color map (first is minimum/black,
second is maximum/white). You can call this script with any28 output of Segment (when
--rawoutput is not used) with a command like this:

$ ./check-clumps.sh r_detected_segmented -0.1 2

Go ahead and run this command. You will see the intermediate processing being done
and finally it opens SAO DS9 for you with the regions superimposed on all the extensions
of Segment’s output. The script will only finish (and give you control of the command-line)
when you close DS9. If you need your access to the command-line before closing DS9, add
a & after the end of the command above.

While DS9 is open, slide the dynamic range (values for black and white, or mini-
mum/maximum values in different color schemes) and zoom into various regions of the
M51 group to see if you are satisfied with the detected clumps. Don’t forget that through
the “Cube” window that is opened along with DS9, you can flip through the extensions and
see the actual clumps also. The questions you should be asking your self are these: 1) Which
real clumps (as you visually feel) have been missed? In other words, is the completeness
good? 2) Are there any clumps which you feel are false? In other words, is the purity
good?

Note that completeness and purity are not independent of each other, they are anti-
correlated: the higher your purity, the lower your completeness and vice-versa. You can see
this by playing with the purity level using the --snquant option. Run Segment as shown
above again with -P and see its default value. Then increase/decrease it for higher/lower
purity and check the result as before. You will see that if you want the best purity, you
have to sacrifice completeness and vice versa.

One interesting region to inspect in this image is the many bright peaks around the
central parts of M51. Zoom into that region and inspect how many of them have actually
been detected as true clumps. Do you have a good balance between completeness and
purity? Also look out far into the wings of the group and inspect the completeness and
purity there.

An easier way to inspect completeness (and only completeness) is to mask all the pixels
detected as clumps and visually inspecting the rest of the pixels. You can do this using
Arithmetic in a command like below. For easy reading of the command, we’ll define the
shell variable $i for the image name and save the output in masked.fits.

$ in="r_detected_segmented.fits -hINPUT"
$ clumps="r_detected_segmented.fits -hCLUMPS"
$ astarithmetic $in $clumps 0 gt nan where -oclumps-masked.fits

Inspecting clumps-masked.fits, you can see some very diffuse peaks that have been
missed, especially as you go farther away from the group center and into the diffuse wings.
This is due to the fact that with this configuration, we have focused more on the sharper
clumps. To put the focus more on diffuse clumps, you can use a wider convolution kernel.
Using a larger kernel can also help in detecting the existing clumps to fainter levels (thus
better separating them from the surrounding diffuse signal).

28 Some modifications are necessary based on the input dataset: depending on the dynamic range, you
have to adjust the second and third arguments. But more importantly, depending on the dataset’s world
coordinate system, you have to change the region width, in the AWK command. Otherwise the circle
regions can be too small/large.
You can make any kernel easily using the --kernel option in Section 8.1 [MakeProfiles], page 332. But note that a larger kernel is also going to wash-out many of the sharp/small clumps close to the center of M51 and also some smaller peaks on the wings. Please continue playing with Segment’s configuration to obtain a more complete result (while keeping reasonable purity). We’ll finish the discussion on finding true clumps at this point.

The properties of the clumps within M51, or the background objects can then easily be measured using Section 7.4 [MakeCatalog], page 295. To measure the properties of the background objects (detected as clumps over the diffuse region), you shouldn’t mask the diffuse region. When measuring clump properties with Section 7.4 [MakeCatalog], page 295, and using the --clumpscat, the ambient flux (from the diffuse region) is calculated and subtracted. If the diffuse region is masked, its effect on the clump brightness cannot be calculated and subtracted.

To keep this tutorial short, we’ll stop here. See Section 2.2.13 [Segmentation and making a catalog], page 44, and Section 7.3 [Segment], page 284, for more on using Segment, producing catalogs with MakeCatalog and using those catalogs.
3 Installation

The latest released version of Gnuastro source code is always available at the following URL:

http://ftpmirror.gnu.org/gnuastro/gnuastro-latest.tar.gz

Section 1.1 [Quick start], page 1, describes the commands necessary to configure, build, and install Gnuastro on your system. This chapter will be useful in cases where the simple procedure above is not sufficient, for example your system lacks a mandatory/optional dependency (in other words, you can’t pass the $./configure step), or you want greater customization, or you want to build and install Gnuastro from other random points in its history, or you want a higher level of control on the installation. Thus if you were happy with downloading the tarball and following Section 1.1 [Quick start], page 1, then you can safely ignore this chapter and come back to it in the future if you need more customization.

Section 3.1 [Dependencies], page 74, describes the mandatory, optional and bootstrapping dependencies of Gnuastro. Only the first group are required/mandatory when you are building Gnuastro using a tarball (see Section 3.2.1 [Release tarball], page 84), they are very basic and low-level tools used in most astronomical software, so you might already have them installed, if not they are very easy to install as described for each. Section 3.2 [Downloading the source], page 84, discusses the two methods you can obtain the source code: as a tarball (a significant snapshot in Gnuastro’s history), or the full history1. The latter allows you to build Gnuastro at any random point in its history (for example to get bug fixes or new features that are not released as a tarball yet).

The building and installation of Gnuastro is heavily customizable, to learn more about them, see Section 3.3 [Build and install], page 89. This section is essentially a thorough explanation of the steps in Section 1.1 [Quick start], page 1. It discusses ways you can influence the building and installation. If you encounter any problems in the installation process, it is probably already explained in Section 3.3.5 [Known issues], page 102. In Appendix B [Other useful software], page 540, the installation and usage of some other free software that are not directly required by Gnuastro but might be useful in conjunction with it is discussed.

3.1 Dependencies

A minimal set of dependencies are mandatory for building Gnuastro from the standard tarball release. If they are not present you cannot pass Gnuastro’s configuration step. The mandatory dependencies are therefore very basic (low-level) tools which are easy to obtain, build and install, see Section 3.1.1 [Mandatory dependencies], page 75, for a full discussion.

If you have the packages of Section 3.1.2 [Optional dependencies], page 77, Gnuastro will have additional functionality (for example converting FITS images to JPEG or PDF). If you are installing from a tarball as explained in Section 1.1 [Quick start], page 1, you can stop reading after this section. If you are cloning the version controlled source (see Section 3.2.2 [Version controlled source], page 85), an additional bootstrapping step is required before configuration and its dependencies are explained in Section 3.1.3 [Bootstrapping dependencies], page 79.

1 Section 3.1.3 [Bootstrapping dependencies], page 79, are required if you clone the full history.
Your operating system’s package manager is an easy and convenient way to download and install the dependencies that are already pre-built for your operating system. In Section 3.1.4 [Dependencies from package managers], page 81, we’ll list some common operating system package manager commands to install the optional and mandatory dependencies.

3.1.1 Mandatory dependencies
The mandatory Gnuastro dependencies are very basic and low-level tools. They all follow the same basic GNU based build system (like that shown in Section 1.1 [Quick start], page 1), so even if you don’t have them, installing them should be pretty straightforward. In this section we explain each program and any specific note that might be necessary in the installation.

3.1.1.1 GNU Scientific library
The GNU Scientific Library (http://www.gnu.org/software/gsl/), or GSL, is a large collection of functions that are very useful in scientific applications, for example integration, random number generation, and Fast Fourier Transform among many others. To install GSL from source, you can run the following commands after you have downloaded gsl-latest.tar.gz (http://ftpmirror.gnu.org/gsl/gsl-latest.tar.gz):

```
$ tar xf gsl-latest.tar.gz
$ cd gsl-X.X # Replace X.X with version number.
$ ./configure
$ make -j8 # Replace 8 with no. CPU threads.
$ make check
$ sudo make install
```

3.1.1.2 CFITSIO
CFITSIO (http://heasarc.gsfc.nasa.gov/fitsio/) is the closest you can get to the pixels in a FITS image while remaining faithful to the FITS standard (http://fits.gsfc.nasa.gov/fits_standard.html). It is written by William Pence, the principal author of the FITS standard2, and is regularly updated. Setting the definitions for all other software packages using FITS images.

Some GNU/Linux distributions have CFITSIO in their package managers, if it is available and updated, you can use it. One problem that might occur is that CFITSIO might not be configured with the --enable-reentrant option by the distribution. This option allows CFITSIO to open a file in multiple threads, it can thus provide great speed improvements. If CFITSIO was not configured with this option, any program which needs this capability will warn you and abort when you ask for multiple threads (see Section 4.5 [Multi-threaded operations], page 127).

To install CFITSIO from source, we strongly recommend that you have a look through Chapter 2 (Creating the CFITSIO library) of the CFITSIO manual and understand the options you can pass to $ ./configure (they aren’t too much). This is a very basic package for most astronomical software and it is best that you configure it nicely with your system.

---

Once you download the source and unpack it, the following configure script should be enough for most purposes. Don’t forget to read chapter two of the manual though, for example the second option is only for 64bit systems. The manual also explains how to check if it has been installed correctly.

CFITSIO comes with two executable files called \texttt{fpack} and \texttt{funpack}. From their manual: they “are standalone programs for compressing and uncompressing images and tables that are stored in the FITS (Flexible Image Transport System) data format. They are analogous to the \texttt{gzip} and \texttt{gunzip} compression programs except that they are optimized for the types of astronomical images that are often stored in FITS format”. The commands below will compile and install them on your system along with CFITSIO. They are not essential for Gnuastro, since they are just wrappers for functions within CFITSIO, but they can come in handy. The \texttt{make utils} command is only available for versions above 3.39, it will build these executable files along with several other executable test files which are deleted in the following commands before the installation (otherwise the test files will also be installed).

The commands necessary to decompress, build and install CFITSIO from source are described below. Let’s assume you have downloaded \texttt{cfitsio\_latest.tar.gz} (\url{http://heasarc.gsfc.nasa.gov/FTP/software/fitsio/c/cfitsio\_latest.tar.gz}) and are in the same directory:

```
$ tar xf cfitsio\_latest.tar.gz
$ cd cfitsio\-X.XX # Replace X.XX with version
$ ./configure --prefix=/usr/local --enable-sse2 --enable-reentrant
$ make
$ make utils
$ ./testprog > testprog\_lis
$ diff testprog\_lis testprog\_out # Should have no output
$ cmp testprog\_fit testprog\_std # Should have no output
$ rm cookbook fitscopy imcopy smem speed testprog
$ sudo make install
```

### 3.1.1.3 WCSLIB

WCSLIB (\url{http://www.atnf.csiro.au/people/mcalabre/WCS/}) is written and maintained by one of the authors of the World Coordinate System (WCS) definition in the FITS standard (\url{http://fits.gsfc.nasa.gov/fits\_standard.html}), Mark Calabretta. It might be already built and ready in your distribution’s package management system. However, here the installation from source is explained, for the advantages of installation from source please see Section 3.1.1 [Mandatory dependencies], page 75. To install WCSLIB you will need to have CFITSIO already installed, see Section 3.1.1.2 [CFITSIO], page 75.

WCSLIB also has plotting capabilities which use PGLOT (a plotting library for C). If you want to use those capabilities in WCSLIB, Section B.2 [PGPLOT], page 543, provides the PGPLOT installation instructions. However PGPLOT is old\footnote{As of early June 2016, its most recent version was uploaded in February 2001.}, so its installation is not easy, there are also many great modern WCS plotting tools (mostly in written in Python).

---

Hence, if you will not be using those plotting functions in WCSLIB, you can configure it with the \texttt{--without-pgplot} option as shown below.

If you have the cURL library\(^5\) on your system and you installed CFITSIO version 3.42 or later, you will need to also link with the cURL library at configure time (through the \texttt{-lcurl} option as shown below). CFITSIO uses the cURL library for its HTTPS (or HTTP Secure\(^6\)) support and if it is present on your system, CFITSIO will depend on it. Therefore, if \texttt{./configure} command below fails (you don’t have the cURL library), then remove this option and rerun it.

Let’s assume you have downloaded 	exttt{wcslib.tar.bz2} (ftp://ftp.atnf.csiro.au/pub/software/wcslib/wcslib.tar.bz2) and are in the same directory, to configure, build, check and install WCSLIB follow the steps below.

\begin{verbatim}
$ tar xf wcslib.tar.bz2

## In the 'cd' command, replace 'X.X' with version number.
$ cd wcslib-X.X

## If './configure' fails, remove '-lcurl' and run again.
$ ./configure LIBS="-pthread -lcurl -lm" --without-pgplot --disable-fortran

## Will fail if you don't have user rights.
$ make

$ make check

$ sudo make install
\end{verbatim}

3.1.2 Optional dependencies

The libraries listed here are only used for very specific applications, therefore they are optional and Gnuastro can be built without them (with only those specific features disabled). Since these are pretty low-level tools, they are not too hard to install from source, but you can also use your operating system’s package manager to easily install all of them. For more, see Section 3.1.4 [Dependencies from package managers], page 81.

If the \texttt{./configure} script can't find any of these optional dependencies, it will notify you of the operation(s) you can’t do due to not having them. If you continue the build and request an operation that uses a missing library, Gnuastro’s programs will warn that the optional library was missing at build-time and abort. Since Gnuastro was built without that library, installing the library afterwards won’t help. The only way is to re-build Gnuastro from scratch (after the library has been installed). However, for program dependencies (like cURL or GhostScript) things are easier: you can install them after building Gnuastro also. This is because libraries are used to build the internal structure of Gnuastro’s executables. However, a program dependency is called by Gnuastro’s programs at run-time and has no effect on their internal structure. So if a dependency program becomes available later, it will be used next time it is requested.

GNU Libtool

Libtool is a program to simplify managing of the libraries to build an executable (a program). GNU Libtool has some added functionality compared to other im-

\(^5\) https://curl.haxx.se
\(^6\) https://en.wikipedia.org/wiki/HTTPS
implementations. If GNU Libtool isn’t present on your system at configuration time, a warning will be printed and Section 10.2 [BuildProgram], page 380, won’t be built or installed. The configure script will look into your search path (PATH) for GNU Libtool through the following executable names: `libtool` (acceptable only if it is the GNU implementation) or `glibtool`. See Section 3.3.1.2 [Installation directory], page 92, for more on PATH.

GNU Libtool (the binary/executable file) is a low-level program that is probably already present on your system, and if not, is available in your operating system package manager\(^7\). If you want to install GNU Libtool’s latest version from source, please visit its webpage (https://www.gnu.org/software/libtool/).

GNU’s tarball is shipped with an internal implementation of GNU Libtool. Even if you have GNU Libtool, GNU’s internal implementation is used for the building and installation of GNU. As a result, you can still build, install and use GNU even if you don’t have GNU Libtool installed on your system. However, this internal Libtool does not get installed. Therefore, after GNU’s installation, if you want to use Section 10.2 [BuildProgram], page 380, to compile and link your own C source code which uses the Section 10.3 [GNU library], page 384, you need to have GNU Libtool available on your system (independent of GNU). See Section 10.1 [Review of library fundamentals], page 372, to learn more about libraries.

\(^7\) Note that we want the binary/executable Libtool program which can be run on the command-line. In Debian-based operating systems which separate various parts of a package, you want want `libtool-bin`, the `libtool` package won’t contain the executable program.
cURL

CURL’s executable (curl) is called by Section 5.5 [Query], page 183, for submitting queries to remote datasets and retrieving the results. It isn’t necessary for the build of Gnuastro from source (only a warning will be printed if it can’t be found at configure time), so if you don’t have it at build-time there is no problem. Just be sure to have it when you run astquery, otherwise you’ll get an error about not finding curl.

GPL Ghostscript

GPL Ghostscript’s executable (gs) is called by ConvertType to compile a PDF file from a source PostScript file, see Section 5.3 [ConvertType], page 162. Therefore its headers (and libraries) are not needed.

3.1.3 Bootstrapping dependencies

Bootstrapping is only necessary if you have decided to obtain the full version controlled history of Gnuastro, see Section 3.2.2 [Version controlled source], page 85, and Section 3.2.2.1 [Bootstrapping], page 86. Using the version controlled source enables you to always be up to date with the most recent development work of Gnuastro (bug fixes, new functionalities, improved algorithms, etc). If you have downloaded a tarball (see Section 3.2 [Downloading the source], page 84), then you can ignore this subsection.

To successfully run the bootstrapping process, there are some additional dependencies to those discussed in the previous subsections. These are low level tools that are used by a large collection of Unix-like operating systems programs, therefore they are most probably already available in your system. If they are not already installed, you should be able to easily find them in any GNU/Linux distribution package management system (apt-get, yum, pacman, etc). The short names in parenthesis in typewriter font after the package name can be used to search for them in your package manager. For the GNU Portability Library, GNU Autoconf Archive and TEX Live, it is recommended to use the instructions here, not your operating system’s package manager.

GNU Portability Library (Gnulib)

To ensure portability for a wider range of operating systems (those that don’t include GNU C library, namely glibc), Gnuastro depends on the GNU portability library, or Gnulib. Gnulib keeps a copy of all the functions in glibc, implemented (as much as possible) to be portable to other operating systems. The bootstrap script can automatically clone Gnulib (as a gnulib/ directory inside Gnuastro), however, as described in Section 3.2.2.1 [Bootstrapping], page 86, this is not recommended.

The recommended way to bootstrap Gnuastro is to first clone Gnulib and the Autoconf archives (see below) into a local directory outside of Gnuastro. Let’s call it DEVDIR⁸ (which you can set to any directory). Currently in Gnuastro,

⁸ If you are not a developer in Gnulib or Autoconf archives, DEVDIR can be a directory that you don’t backup. In this way the large number of files in these projects won’t slow down your backup process or take bandwidth (if you backup to a remote server).
both Gnulib and Autoconf archives have to be cloned in the same top directory like the case here:

```bash
$ DEVDIR=/home/yourname/Development
$ cd $DEVDIR
$ git clone git://git.sv.gnu.org/gnulib.git
$ git clone git://git.sv.gnu.org/autoconf-archive.git
```

You now have the full version controlled source of these two repositories in separate directories. Both these packages are regularly updated, so every once in a while, you can run `$ git pull` within them to get any possible updates.

**GNU Automake (automake)**

GNU Automake will build the `Makefile.in` files in each sub-directory using the (hand-written) `Makefile.am` files. The `Makefile.in` files are subsequently used to generate the `Makefiles` when the user runs `./configure` before building.

**GNU Autoconf (autoconf)**

GNU Autoconf will build the `configure` script using the configurations we have defined (hand-written) in `configure.ac`.

**GNU Autoconf Archive**

These are a large collection of tests that can be called to run at `./configure` time. See the explanation under GNU Portability Library above for instructions on obtaining it and keeping it up to date.

**GNU Libtool (libtool)**

GNU Libtool is in charge of building all the libraries in Gnuastro. The libraries contain functions that are used by more than one program and are installed for use in other programs. They are thus put in a separate directory (`lib/`).

**GNU help2man (help2man)**

GNU help2man is used to convert the output of the `--help` option (Section 4.3.2 [--help], page 124) to the traditional Man page (Section 4.3.3 [Man pages], page 125).

**\LaTeX{} and some \TeX{} packages**

Some of the figures in this book are built by \LaTeX{} (using the PGF/TikZ package). The \LaTeX{} source for those figures is version controlled for easy maintenance not the actual figures. So the `./bootstrap` script will run \LaTeX{} to build the figures. The best way to install \LaTeX{} and all the necessary packages is through \TeX{} Live (https://www.tug.org/texlive/) which is a package manager for \TeX{} related tools that is independent of any operating system. It is thus preferred to the \TeX{} Live versions distributed by your operating system.

---

9 If you already have the Autoconf archives in a separate directory, or can’t clone it in the same directory as Gnulib, or you have it with another directory name (not `autoconf-archive/`), you can follow this short step. Set `AUTOCONFARCHIVES` to your desired address. Then define a symbolic link in `DEVDIR` with the following command so Gnuastro’s bootstrap script can find it:

```bash
$ ln -s $AUTOCONFARCHIVES $DEVDIR/autoconf-archive
```

10 If your internet connection is active, but Git complains about the network, it might be due to your network setup not recognizing the git protocol. In that case use the following URL for the HTTP protocol instead (for Autoconf archives, replace the name): `http://git.sv.gnu.org/r/gnulib.git`
To install \TeX{} Live, go to the webpage and download the appropriate installer by following the “download” link. Note that by default the full package repository will be downloaded and installed (around 4 Giga Bytes) which can take very long to download and to update later. However, most packages are not needed by everyone, it is easier, faster and better to install only the “Basic scheme” (consisting of only the most basic \TeX{} and \LaTeX{} packages, which is less than 200 Mega bytes)\textsuperscript{11}.

After the installation, be sure to set the environment variables as suggested in the end of the outputs. Any time you confront (need) a package you don’t have, simply install it with a command like below (similar to how you install software from your operating system’s package manager)\textsuperscript{12}. To install all the necessary \TeX{} packages for a successful Gnuastro bootstrap, run this command:

```
$ su
# tlmgr install epsf jknapltx caption biblatex biber iftex \ etoolbox logreq xstring xkeyval pgf ms \   xcolor pgfplots times rsfs ps2eps epspdf
```

ImageMagick (imagemagick)

ImageMagick is a wonderful and robust program for image manipulation on the command-line. bootstrap uses it to convert the book images into the formats necessary for the various book formats.

### 3.1.4 Dependencies from package managers

The most basic way to install a package on your system is to build the packages from source yourself. Alternatively, you can use your operating system’s package manager to download pre-compiled files and install them. The latter choice is easier and faster. However, we recommend that you build the Section 3.1.1 [Mandatory dependencies], page 75, yourself from source (all necessary commands and links are given in the respective section). Here are some basic reasons behind this recommendation.

1. Your distribution’s pre-built package might not be the most recent release.
2. For each package, Gnuastro might perform better (or require) certain configuration options that your distribution’s package managers didn’t add for you. If present, these configuration options are explained during the installation of each in the sections below (for example in Section 3.1.1.2 [CFITSIO], page 75). When the proper configuration has not been set, the programs should complain and inform you.
3. For the libraries, they might separate the binary file from the header files which can cause confusion, see Section 3.3.5 [Known issues], page 102.
4. Like any other tool, the science you derive from Gnuastro’s tools highly depend on these lower level dependencies, so generally it is much better to have a close connection with them. By reading their manuals, installing them and staying up to date with changes/bugs in them, your scientific results and understanding (of what is going on, and thus how you interpret your scientific results) will also correspondingly improve.

\textsuperscript{11}You can also download the DVD iso file at a later time to keep as a backup for when you don’t have internet connection if you need a package.

\textsuperscript{12}After running \TeX{}, or \LaTeX{}, you might get a warning complaining about a missing file. Run ‘\texttt{tlmgr info missingfile}’ to see the package(s) containing that file which you can install.
Based on your package manager, you can use any of the following commands to install the mandatory and optional dependencies. If your package manager isn’t included in the list below, please send us the respective command, so we add it. Gnuastro itself is also already packaged in some package managers (for example Debian or Homebrew).

As discussed above, we recommend installing the mandatory dependencies manually from source (see Section 3.1.1 [Mandatory dependencies], page 75). Therefore, in each command below, first the optional dependencies are given. The mandatory dependencies are included after an empty line. If you would also like to install the mandatory dependencies with your package manager, just ignore the empty line.

For better archivability and compression ratios, Gnuastro’s recommended tarball compression format is with the Lzip (http://lzip.nongnu.org/lzip.html) program, see Section 3.2.1 [Release tarball], page 84. Therefore, the package manager commands below also contain Lzip.

**apt-get** (Debian-based OSs: Debian, Ubuntu, Linux Mint, etc)

Debian (https://en.wikipedia.org/wiki/Debian) is one of the oldest GNU/Linux distributions. It thus has a very extended user community and a robust internal structure and standards. All of it is free software and based on the work of volunteers around the world. Many distributions are thus derived from it, for example Ubuntu and Linux Mint. This arguably makes Debian-based OSs the largest, and most used, class of GNU/Linux distributions. All of them use Debian’s Advanced Packaging Tool (APT, for example `apt-get`) for managing packages.

```
$ sudo apt-get install ghostscript libtool-bin libjpeg-dev \
   libtiff-dev libgit2-dev curl lzip \
   libgsl0-dev libcfitsio-dev wcslib-dev
```

Gnuastro is packaged (https://tracker.debian.org/pkg/gnuastro) in Debian (and thus some of its derivate operating systems). Just make sure it is the most recent version.

**dnf**

**yum** (Red Hat-based OSs: Red Hat, Fedora, CentOS, Scientific Linux, etc)

Red Hat Enterprise Linux (https://en.wikipedia.org/wiki/Red_Hat) (RHEL) is released by Red Hat Inc. RHEL requires paid subscriptions for use of its binaries and support. But since it is free software, many other teams use its code to spin-off their own distributions based on RHEL. Red Hat-based GNU/Linux distributions initially used the “Yellowdog Updated, Modifier” (YUM) package manager, which has been replaced by “Dandified yum” (DNF). If the latter isn’t available on your system, you can use `yum` instead of `dnf` in the command below.

```
$ sudo dnf install ghostscript libtool libjpeg-devel \
   libtiff-devel libgit2-devel lzip curl \
   gsl-devel cfitsio-devel wcslib-devel
```

---

13 https://en.wikipedia.org/wiki/List_of_Linux_distributions#Debian-based
**brew** *(macOS)*

macOS ([https://en.wikipedia.org/wiki/MacOS](https://en.wikipedia.org/wiki/MacOS)) is the operating system used on Apple devices. macOS does not come with a package manager pre-installed, but several widely used, third-party package managers exist, such as Homebrew or MacPorts. Both are free software. Currently we have only tested Gnuastro’s installation with Homebrew as described below.

If not already installed, first obtain Homebrew by following the instructions at [https://brew.sh](https://brew.sh). Homebrew manages packages in different ‘taps’. To install WCSLIB (discussed in [Section 3.1.1](#) [Mandatory dependencies], page 75) via Homebrew you will need to tap into brewsci/science first (the tap may change in the future, but can be found by calling `brew search wcslib`).

```
$ brew install ghostscript libtool libjpeg libtiff \
   libgit2 curl lzip \
   gsl cfitsio
$ brew tap brewsci/science
$ brew install wcslib
```

**pacman** *(Arch Linux)*

Arch Linux ([https://en.wikipedia.org/wiki/Arch_Linux](https://en.wikipedia.org/wiki/Arch_Linux)) is a smaller GNU/Linux distribution, which follows the KISS principle (“keep it simple, stupid”) as a general guideline. It “focuses on elegance, code correctness, minimalism and simplicity, and expects the user to be willing to make some effort to understand the system’s operation”. Arch Linux uses “Package manager” (Pacman) to manage its packages/components.

```
$ sudo pacman -S ghostscript libtool libjpeg libtiff \
   libgit2 curl lzip \
   gsl cfitsio wcslib
```

**zypper** *(openSUSE and SUSE Linux Enterprise Server)*

SUSE Linux Enterprise Server¹⁴ (SLES) is the commercial offering which shares code and tools. Many additional packages are offered in the Build Service¹⁵. openSUSE and SLES use zypper (cli) and YaST (GUI) for managing repositories and packages.

```
$ sudo zypper install ghostscript_any libtool pkgconfig \
   libcurl-devel libgit2-devel libjpeg62-devel \
   libtiff-devel curl \
   gsl-devel cfitsio-devel wcslib-devel
```

When building Gnuastro, run the configure script with the following `CPPFLAGS` environment variable:

```
$ ./configure CPPFLAGS="-I/usr/include/cfitsio"
```

---

¹⁴ [https://www.suse.com/products/server](https://www.suse.com/products/server)

¹⁵ [https://build.opensuse.org](https://build.opensuse.org)
Usually, when libraries are installed by operating system package managers, there should be no problems when configuring and building other programs from source (that depend on the libraries: Gnuastro in this case). However, in some special conditions, problems may pop-up during the configuration, building, or checking/running any of Gnuastro’s programs. The most common of such problems and their solution are discussed below.

**Not finding library during configuration:** If a library is installed, but during Gnuastro’s `configure` step the library isn’t found, then configure Gnuastro like the command below (correcting `/path/to/lib`). For more, see Section 3.3.5 [Known issues], page 102, and Section 3.3.1.2 [Installation directory], page 92.

```
$ ./configure LDFLAGS="-L/path/to/lib"
```

**Not finding header (.h) files while building:** If a library is installed, but during Gnuastro’s `make` step, the library’s header (file with a `.h` suffix) isn’t found, then configure Gnuastro like the command below (correcting `/path/to/include`). For more, see Section 3.3.5 [Known issues], page 102, and Section 3.3.1.2 [Installation directory], page 92.

```
$ ./configure CPPFLAGS="-I/path/to/include"
```

**Gnuastro’s programs don’t run during check or after install:** If a library is installed, but the programs don’t run due to linking problems, set the `LD_LIBRARY_PATH` variable like below (assuming Gnuastro is installed in `/path/to/installed`). For more, see Section 3.3.5 [Known issues], page 102, and Section 3.3.1.2 [Installation directory], page 92.

```
$ export LD_LIBRARY_PATH="$LD_LIBRARY_PATH:/path/to/installed/lib"
```

### 3.2 Downloading the source

Gnuastro’s source code can be downloaded in two ways. As a tarball, ready to be configured and installed on your system (as described in Section 1.1 [Quick start], page 1), see Section 3.2.1 [Release tarball], page 84. If you want official releases of stable versions this is the best, easiest and most common option. Alternatively, you can clone the version controlled history of Gnuastro, run one extra bootstrapping step and then follow the same steps as the tarball. This will give you access to all the most recent work that will be included in the next release along with the full project history. The process is thoroughly introduced in Section 3.2.2 [Version controlled source], page 85.

#### 3.2.1 Release tarball

A release tarball (commonly compressed) is the most common way of obtaining free and open source software. A tarball is a snapshot of one particular moment in the Gnuastro development history along with all the necessary files to configure, build, and install Gnuastro easily (see Section 1.1 [Quick start], page 1). It is very straightforward and needs the least set of dependencies (see Section 3.1.1 [Mandatory dependencies], page 75). Gnuastro has tarballs for official stable releases and pre-releases for testing. See Section 1.5 [Version
Chapter 3: Installation

numbering], page 7, for more on the two types of releases and the formats of the version numbers. The URLs for each type of release are given below.


This URL hosts the official stable releases of Gnuastro. Always use the most recent version (see Section 1.5 [Version numbering], page 7). By clicking on the “Last modified” title of the second column, the files will be sorted by their date which you can also use to find the latest version. It is recommended to use a mirror to download these tarballs, please visit [http://ftpmirror.gnu.org/gnuastro/](http://ftpmirror.gnu.org/gnuastro/) and see below.

Pre-release tar-balls ([http://alpha.gnu.org/gnu/gnuastro](http://alpha.gnu.org/gnu/gnuastro)):

This URL contains unofficial pre-release versions of Gnuastro. The pre-release versions of Gnuastro here are for enthusiasts to try out before an official release. If there are problems, or bugs then the testers will inform the developers to fix before the next official release. See Section 1.5 [Version numbering], page 7, to understand how the version numbers here are formatted. If you want to remain even more up-to-date with the developing activities, please clone the version controlled source as described in Section 3.2.2 [Version controlled source], page 85.

Gnuastro’s official/stable tarball is released with two formats: Gzip (with suffix .tar.gz) and Lzip (with suffix .tar.lz). The pre-release tarballs (after version 0.3) are released only as an Lzip tarball. Gzip is a very well-known and widely used compression program created by GNU and available in most systems. However, Lzip provides a better compression ratio and more robust archival capacity. For example Gnuastro 0.3’s tarball was 2.9MB and 4.3MB with Lzip and Gzip respectively, see the Lzip webpage ([http://www.nongnu.org/lzip/lzip.html](http://www.nongnu.org/lzip/lzip.html)) for more. Lzip might not be pre-installed in your operating system, if so, installing it from your operating system’s package manager or from source is very easy and fast (it is a very small program).

The GNU FTP server is mirrored (has backups) in various locations on the globe ([http://www.gnu.org/order/ftp.html](http://www.gnu.org/order/ftp.html)). You can use the closest mirror to your location for a more faster download. Note that only some mirrors keep track of the pre-release (alpha) tarballs. Also note that if you want to download immediately after and announcement (see Section 1.9 [Announcements], page 13), the mirrors might need some time to synchronize with the main GNU FTP server.

3.2.2 Version controlled source

The publicly distributed Gnuastro tar-ball (for example gnuastro-X.X.tar.gz) does not contain the revision history, it is only a snapshot of the source code at one significant instant of Gnuastro’s history (specified by the version number, see Section 1.5 [Version numbering], page 7), ready to be configured and built. To be able to develop successfully, the revision history of the code can be very useful to track when something was added or changed, also some updates that are not yet officially released might be in it.

We use Git for the version control of Gnuastro. For those who are not familiar with it, we recommend the ProGit book ([https://git-scm.com/book/en](https://git-scm.com/book/en)). The whole book is publicly available for online reading and downloading and does a wonderful job at explaining the concepts and best practices.
Let’s assume you want to keep Gnuastro in the **TOPGNUASTRO** directory (can be any directory, change the value below). The full version controlled history of Gnuastro can be cloned in **TOPGNUASTRO/gnuastro** by running the following commands\(^\text{16}\):

\[
\begin{align*}
$\text{TOPGNUASTRO} & = \text{/home/yourname/Research/projects/} \\
$ & \text{cd $TOPGNUASTRO} \\
$ & \text{git clone git://git.sv.gnu.org/gnuastro.git}
\end{align*}
\]

The **$TOPGNUASTRO/gnuastro** directory will contain hand-written (version controlled) source code for Gnuastro’s programs, libraries, this book and the tests. All are divided into sub-directories with standard and very descriptive names. The version controlled files in the top cloned directory are either mainly in capital letters (for example **THANKS** and **README**) or mainly written in small-caps (for example **configure.ac** and **Makefile.am**). The former are non-programming, standard writing for human readers containing high-level information about the whole package. The latter are instructions to customize the GNU build system for Gnuastro. For more on Gnuastro’s source code structure, please see Chapter 11 [Developing], page 516. We won’t go any deeper here.

The cloned Gnuastro source cannot immediately be configured, compiled, or installed since it only contains hand-written files, not automatically generated or imported files which do all the hard work of the build process. See Section 3.2.2.1 [Bootstrapping], page 86, for the process of generating and importing those files (its not too hard!). Once you have bootstrapped Gnuastro, you can run the standard procedures (in Section 1.1 [Quick start], page 1). Very soon after you have cloned it, Gnuastro’s main **master** branch will be updated on the main repository (since the developers are actively working on Gnuastro), for the best practices in keeping your local history in sync with the main repository see Section 3.2.2.2 [Synchronizing], page 88.

### 3.2.2.1 Bootstrapping

The version controlled source code lacks the source files that we have not written or are automatically built. These automatically generated files are included in the distributed tar ball for each distribution (for example **gnuastro-X.X.tar.gz**, see Section 1.5 [Version numbering], page 7) and make it easy to immediately configure, build, and install Gnuastro. However from the perspective of version control, they are just bloatware and sources of confusion (since they are not changed by Gnuastro developers).

The process of automatically building and importing necessary files into the cloned directory is known as **bootstrapping**. All the instructions for an automatic bootstrapping are available in **bootstrap** and configured using **bootstrap.conf**. **bootstrap** and **COPYING** (which contains the software copyright notice) are the only files not written by Gnuastro developers but under version control to enable simple bootstrapping and legal information on usage immediately after cloning. **bootstrap.conf** is maintained by the GNU Portability Library (Gnulib) and this file is an identical copy, so do not make any changes in this file since it will be replaced when Gnulib releases an update. Make all your changes in **bootstrap.conf**.

The bootstrapping process has its own separate set of dependencies, the full list is given in Section 3.1.3 [Bootstrapping dependencies], page 79. They are generally very low-level and

\(^\text{16}\) If your internet connection is active, but Git complains about the network, it might be due to your network setup not recognizing the Git protocol. In that case use the following URL which uses the HTTP protocol instead: [http://git.sv.gnu.org/r/gnuastro.git](http://git.sv.gnu.org/r/gnuastro.git)
used by a very large set of commonly used programs, so they are probably already installed on your system. The simplest way to bootstrap Gnuastro is to simply run the bootstrap script within your cloned Gnuastro directory as shown below. However, please read the next paragraph before doing so (see Section 3.2.2 [Version controlled source], page 85, for TOPGNUASTRO).

```
$ cd TOPGNUASTRO/gnuastro
$ ./bootstrap # Requires internet connection
```

Without any options, `bootstrap` will clone Gnulib within your cloned Gnuastro directory (TOPGNUASTRO/gnuastro/gnulib) and download the necessary Autoconf archives macros. So if you run bootstrap like this, you will need an internet connection every time you decide to bootstrap. Also, Gnulib is a large package and cloning it can be slow. It will also keep the full Gnulib repository within your Gnuastro repository, so if another one of your projects also needs Gnulib, and you insist on running bootstrap like this, you will have two copies. In case you regularly backup your important files, Gnulib will also slow down the backup process. Therefore while the simple invocation above can be used with no problem, it is not recommended. To do better, see the next paragraph.

The recommended way to get these two packages is thoroughly discussed in Section 3.1.3 [Bootstrapping dependencies], page 79, (in short: clone them in the separate DEVDIR/directory). The following commands will take you into the cloned Gnuastro directory and run the `bootstrap` script, while telling it to copy some files (instead of making symbolic links, with the --copy option, this is not mandatory) and where to look for Gnulib (with the --gnulib-srcdir option). Please note that the address given to --gnulib-srcdir has to be an absolute address (so don’t use ~ or ../ for example).

```
$ cd $TOPGNUASTRO/gnuastro
$ ./bootstrap --copy --gnulib-srcdir=$DEVDIR/gnulib
```

Since Gnulib and Autoconf archives are now available in your local directories, you don’t need an internet connection every time you decide to remove all untracked files and redo the bootstrap (see box below). You can also use the same command on any other project that uses Gnulib. All the necessary GNU C library functions, Autoconf macros and Automake inputs are now available along with the book figures. The standard GNU build system (Section 1.1 [Quick start], page 1) will do the rest of the job.

---

**Undoing the bootstrap:** During the development, it might happen that you want to remove all the automatically generated and imported files. In other words, you might want to reverse the bootstrap process. Fortunately Git has a good program for this job: `git clean`. Run the following command and every file that is not version controlled will be removed.

```
git clean -fxd
```

It is best to commit any recent change before running this command. You might have created new files since the last commit and if they haven’t been committed, they will all be gone forever (using `rm`). To get a list of the non-version controlled files instead of deleting them, add the `n` option to `git clean`, so it becomes `-fxdn`.

---

17 The --copy option is recommended because some backup systems might do strange things with symbolic links.
Besides the `bootstrap` and `bootstrap.conf`, the `bootstrapped/` directory and `README-hacking` file are also related to the bootstrapping process. The former hosts all the imported (bootstrapped) directories. Thus, in the version controlled source, it only contains a `REAME` file, but in the distributed tar-ball it also contains sub-directories filled with all bootstrapped files. `README-hacking` contains a summary of the bootstrapping process discussed in this section. It is a necessary reference when you haven’t built this book yet. It is thus not distributed in the Gnuastro tarball.

### 3.2.2.2 Synchronizing

The bootstrapping script (see Section 3.2.2.1 [Bootstrapping], page 86) is not regularly needed: you mainly need it after you have cloned Gnuastro (once) and whenever you want to re-import the files from GnuLib, or Autoconf archives (not too common). However, Gnuastro developers are constantly working on Gnuastro and are pushing their changes to the official repository. Therefore, your local Gnuastro clone will soon be out-dated. Gnuastro has two mailing lists dedicated to its developing activities (see Section 11.10 [Developing mailing lists], page 531). Subscribing to them can help you decide when to synchronize with the official repository.

To pull all the most recent work in Gnuastro, run the following command from the top Gnuastro directory. If you don’t already have a built system, ignore `make distclean`. The separate steps are described in detail afterwards.

```
$ make distclean && git pull && autoreconf -f
```

You can also run the commands separately:

```
$ make distclean
$ git pull
$ autoreconf -f
```

If Gnuastro was already built in this directory, you don’t want some outputs from the previous version being mixed with outputs from the newly pulled work. Therefore, the first step is to clean/delete all the built files with `make distclean`. Fortunately the GNU build system allows the separation of source and built files (in separate directories). This is a great feature to keep your source directory clean and you can use it to avoid the cleaning step. Gnuastro comes with a script with some useful options for this job. It is useful if you regularly pull recent changes, see Section 3.3.2 [Separate build and source directories], page 98.

After the pull, we must re-configure Gnuastro with `autoreconf -f` (part of GNU Autoconf). It will update the `./configure` script and all the `Makefile.in` files based on the hand-written configurations (in `configure.ac` and the `Makefile.am` files). After running `autoreconf -f`, a warning about `TEXI2DVI` might show up, you can ignore that.

The most important reason for re-building Gnuastro’s build system is to generate/update the version number for your updated Gnuastro snapshot. This generated version number will include the commit information (see Section 1.5 [Version numbering], page 7). The

---

18 https://savannah.gnu.org/task/index.php?13993 is defined for you to check if significant (for Gnuastro) updates are made in these repositories, since the last time you pulled from them.

19 In the GNU build system, `./configure` will use the `Makefile.in` files to create the necessary `Makefile` files that are later read by `make` to build the package.
version number is included in nearly all outputs of Gnuastro’s programs, therefore it is vital for reproducing an old result.

As a summary, be sure to run ‘autoreconf -f’ after every change in the Git history. This includes synchronization with the main server or even a commit you have made yourself.

If you would like to see what has changed since you last synchronized your local clone, you can take the following steps instead of the simple command above (don’t type anything after #):

```
$ git checkout master # Confirm if you are on master.
$ git fetch origin # Fetch all new commits from server.
$ git log master..origin/master # See all the new commit messages.
$ git merge origin/master # Update your master branch.
$ autoreconf -f # Update the build system.
```

By default git log prints the most recent commit first, add the --reverse option to see the changes chronologically. To see exactly what has been changed in the source code along with the commit message, add a -p option to the git log.

If you want to make changes in the code, have a look at Chapter 11 [Developing], page 516, to get started easily. Be sure to commit your changes in a separate branch (keep your master branch to follow the official repository) and re-run autoreconf -f after the commit. If you intend to send your work to us, you can safely use your commit since it will be ultimately recorded in Gnuastro’s official history. If not, please upload your separate branch to a public hosting service, for example GitLab (https://gitlab.com), and link to it in your report/paper. Alternatively, run make distcheck and upload the output gnuastro-X.X.X.XXXX.tar.gz to a publicly accessible webpage so your results can be considered scientific (reproducible) later.

### 3.3 Build and install

This section is basically a longer explanation to the sequence of commands given in Section 1.1 [Quick start], page 1. If you didn’t have any problems during the Section 1.1 [Quick start], page 1, steps, you want to have all the programs of Gnuastro installed in your system, you don’t want to change the executable names during or after installation, you have root access to install the programs in the default system wide directory, the Letter paper size of the print book is fine for you or as a summary you don’t feel like going into the details when everything is working, you can safely skip this section.

If you have any of the above problems or you want to understand the details for a better control over your build and install, read along. The dependencies which you will need prior to configuring, building and installing Gnuastro are explained in Section 3.1 [Dependencies], page 74. The first three steps in Section 1.1 [Quick start], page 1, need no extra explanation, so we will skip them and start with an explanation of Gnuastro specific configuration options and a discussion on the installation directory in Section 3.3.1 [Configuring], page 90, followed by some smaller subsections: Section 3.3.3 [Tests], page 101, Section 3.3.4 [A4 print book], page 102, and Section 3.3.5 [Known issues], page 102, which explains the solutions to known problems you might encounter in the installation steps and ways you can solve them.
3.3.1 Configuring

The $ ./configure step is the most important step in the build and install process. All the required packages, libraries, headers and environment variables are checked in this step. The behaviors of make and make install can also be set through command line options to this command.

The configure script accepts various arguments and options which enable the final user to highly customize whatever she is building. The options to configure are generally very similar to normal program options explained in Section 4.1.1 [Arguments and options], page 106. Similar to all GNU programs, you can get a full list of the options along with a short explanation by running

$ ./configure --help

A complete explanation is also included in the INSTALL file. Note that this file was written by the authors of GNU Autoconf (which builds the configure script), therefore it is common for all programs which use the $ ./configure script for building and installing, not just Gnuastro. Here we only discuss cases where you don’t have super-user access to the system and if you want to change the executable names. But before that, a review of the options to configure that are particular to Gnuastro are discussed.

3.3.1.1 Gnuastro configure options

Most of the options to configure (which are to do with building) are similar for every program which uses this script. Here the options that are particular to Gnuastro are discussed. The next topics explain the usage of other configure options which can be applied to any program using the GNU build system (through the configure script).

--enable-debug

Compile/build Gnuastro with debugging information, no optimization and without shared libraries.

In order to allow more efficient programs when using Gnuastro (after the installation), by default Gnuastro is built with a 3rd level (a very high level) optimization and no debugging information. By default, libraries are also built for static and shared linking (see Section 10.1.2 [Linking], page 376). However, when there are crashes or unexpected behavior, these three features can hinder the process of localizing the problem. This configuration option is identical to manually calling the configuration script with CFLAGS="-g -O0" --disable-shared.

In the (rare) situations where you need to do your debugging on the shared libraries, don’t use this option. Instead run the configure script by explicitly setting CFLAGS like this:

$ ./configure CFLAGS="-g -O0"

--enable-check-with-valgrind

Do the make check tests through Valgrind. Therefore, if any crashes or memory-related issues (segmentation faults in particular) occur in the tests, the output of Valgrind will also be put in the tests/test-suite.log file without having to manually modify the check scripts. This option will also activate Gnuastro’s debug mode (see the --enable-debug configure-time option described above).
Valgrind is free software. It is a program for easy checking of memory-related issues in programs. It runs a program within its own controlled environment and can thus identify the exact line-number in the program’s source where a memory-related issue occurs. However, it can significantly slow-down the tests. So this option is only useful when a segmentation fault is found during make check.

--enable-progname
Only build and install progname along with any other program that is enabled in this fashion. progname is the name of the executable without the ast, for example crop for Crop (with the executable name of astcrop).

Note that by default all the programs will be installed. This option (and the --disable-progname options) are only relevant when you don’t want to install all the programs. Therefore, if this option is called for any of the programs in Gnuastro, any program which is not explicitly enabled will not be built or installed.

--disable-progname
--enable-progname=no
Do not build or install the program named progname. This is very similar to the --enable-progname, but will build and install all the other programs except this one.

Note: If some programs are enabled and some are disabled, it is equivalent to simply enabling those that were enabled. Listing the disabled programs is redundant.

--enable-gnulibcheck
Enable checks on the GNU Portability Library (Gnulib). Gnulib is used by Gnuastro to enable users of non-GNU based operating systems (that don’t use GNU C library or glibc) to compile and use the advanced features that this library provides. We make extensive use of such functions. If you give this option to $ ./configure, when you run $ make check, first the functions in Gnulib will be tested, then the Gnuastro executables. If your operating system does not support glibc or has an older version of it and you have problems in the build process ($ make), you can give this flag to configure to see if the problem is caused by Gnulib not supporting your operating system or Gnuastro, see Section 3.3.5 [Known issues], page 102.

--disable-guide-message
--enable-guide-message=no
Do not print a guiding message during the GNU Build process of Section 1.1 [Quick start], page 1. By default, after each step, a message is printed guiding the user what the next command should be. Therefore, after ./configure, it will suggest running make. After make, it will suggest running make check and so on. If Gnuastro is configured with this option, for example

$ ./configure --disable-guide-message
Then these messages will not be printed after any step (like most programs). For people who are not yet fully accustomed to this build system, these guidelines can be very useful and encouraging. However, if you find those messages annoying, use this option.

`--without-libgit2`
Build Gnuastro without libgit2 (for including Git commit hashes in output files), see Section 3.1.2 [Optional dependencies], page 77. libgit2 is an optional dependency, with this option, Gnuastro will ignore any possibly existing libgit2 that may already be on the system.

`--without-libjpeg`
Build Gnuastro without libjpeg (for reading/writing to JPEG files), see Section 3.1.2 [Optional dependencies], page 77. libjpeg is an optional dependency, with this option, Gnuastro will ignore any possibly existing libjpeg that may already be on the system.

`--without-libtiff`
Build Gnuastro without libtiff (for reading/writing to TIFF files), see Section 3.1.2 [Optional dependencies], page 77. libtiff is an optional dependency, with this option, Gnuastro will ignore any possibly existing libtiff that may already be on the system.

The tests of some programs might depend on the outputs of the tests of other programs. For example MakeProfiles is one of the first programs to be tested when you run `$ make check`. MakeProfiles' test outputs (FITS images) are inputs to many other programs (which in turn provide inputs for other programs). Therefore, if you don’t install MakeProfiles for example, the tests for many of the other programs will be skipped. To avoid this, in one run, you can install all the programs and run the tests but not install. If everything is working correctly, you can run configure again with only the programs you want. However, don’t run the tests and directly install after building.

### 3.3.1.2 Installation directory

One of the most commonly used options to `.configure` is `--prefix`, it is used to define the directory that will host all the installed files (or the “prefix” in their final absolute file name). For example, when you are using a server and you don’t have administrator or root access. In this example scenario, if you don’t use the `--prefix` option, you won’t be able to install the built files and thus access them from anywhere without having to worry about where they are installed. However, once you prepare your startup file to look into the proper place (as discussed thoroughly below), you will be able to easily use this option and benefit from any software you want to install without having to ask the system administrators or install and use a different version of a software that is already installed on the server.

The most basic way to run an executable is to explicitly write its full file name (including all the directory information) and run it. One example is running the configuration script with the `$ ./configure` command (see Section 1.1 [Quick start], page 1). By giving a specific directory (the current directory or `./`), we are explicitly telling the shell to look in the current directory for an executable file named ‘configure’. Directly specifying the directory is thus useful for executables in the current (or nearby) directories. However, when the program (an executable file) is to be used a lot, specifying all those directories
will become a significant burden. For example, the `ls` executable lists the contents in a given
directory and it is (usually) installed in the `/usr/bin/` directory by the operating system
maintainers. Therefore, if using the full address was the only way to access an executable,
each time you wanted a listing of a directory, you would have to run the following command
(which is very inconvenient, both in writing and in remembering the various directories).

```
$ /usr/bin/ls
```

To address this problem, we have the `PATH` environment variable. To understand it
better, we will start with a short introduction to the shell variables. Shell variable values
are basically treated as strings of characters. For example, it doesn’t matter if the value
is a name (string of alphabetic characters), or a number (string of numeric characters), or
both. You can define a variable and a value for it by running

```
$ myvariable1=a_test_value
$ myvariable2="a test value"
```

As you see above, if the value contains white space characters, you have to put the whole
value (including white space characters) in double quotes (`"`). You can see the value it
represents by running

```
$ echo $myvariable1
$ echo $myvariable2
```

If a variable has no value or it wasn’t defined, the last command will only print an empty
line. A variable defined like this will be known as long as this shell or terminal is running.
Other terminals will have no idea it existed. The main advantage of shell variables is that
if they are exported\(^{20}\), subsequent programs that are run within that shell can access their
value. So by changing their value, you can change the “environment” of a program which
uses them. The shell variables which are accessed by programs are therefore known as
“environment variables”\(^{21}\). You can see the full list of exported variables that your shell
recognizes by running:

```
$ printenv
```

`HOME` is one commonly used environment variable, it is any user’s (the one that is logged
in) top directory. Try finding it in the command above. It is used so often that the shell
has a special expansion (alternative) for it: `~`. Whenever you see file names starting with
the tilde sign, it actually represents the value to the `HOME` environment variable, so `~/doc`
is the same as `$HOME/doc`.

Another one of the most commonly used environment variables is `PATH`, it is a list of
directories to search for executable names. Its value is a list of directories (separated by a
colon, or `:`). When the address of the executable is not explicitly given (like `./configure`
above), the system will look for the executable in the directories specified by `PATH`. If you
have a computer nearby, try running the following command to see which directories your
system will look into when it is searching for executable (binary) files, one example is printed
here (notice how `/usr/bin`, in the `ls` example above, is one of the directories in `PATH`):

```
$ echo $PATH
   /usr/local/sbin:/usr/local/bin:/usr/bin
```

\(^{20}\) By running `$ export myvariable=a_test_value` instead of the simpler case in the text

\(^{21}\) You can use shell variables for other actions too, for example to temporarily keep some names or run
loops on some files.
By default PATH usually contains system-wide directories, which are readable (but not writable) by all users, like the above example. Therefore if you don’t have root (or administrator) access, you need to add another directory to PATH which you actually have write access to. The standard directory where you can keep installed files (not just executables) for your own user is the ‘~/.local/’ directory. The names of hidden files start with a '.' (dot), so it will not show up in your common command-line listings, or on the graphical user interface. You can use any other directory, but this is the most recognized.

The top installation directory will be used to keep all the package’s components: programs (executables), libraries, include (header) files, shared data (like manuals), or configuration files (see Section 10.1 [Review of library fundamentals], page 372, for a thorough introduction to headers and linking). So it commonly has some of the following sub-directories for each class of installed components respectively: `bin/`, `lib/`, `include/`, `man/`, `share/`, `etc/`. Since the PATH variable is only used for executables, you can add the ‘~/.local/bin’ directory (which keeps the executables/programs or more generally, “binary” files) to PATH with the following command. As defined below, first the existing value of PATH is used, then your given directory is added to its end and the combined value is put back in PATH (run ‘$ echo $PATH’ afterwards to check if it was added).

$ PATH=$PATH:~/local/bin

Any executable that you installed in ‘~/.local/bin’ will now be usable without having to remember and write its full address. However, as soon as you leave/close your current terminal session, this modified PATH variable will be forgotten. Adding the directories which contain executables to the PATH environment variable each time you start a terminal is also very inconvenient and prone to errors. Fortunately, there are standard ‘startup files’ defined by your shell precisely for this (and other) purposes. There is a special startup file for every significant starting step:

/etc/profile and everything in /etc/profile.d/
These startup scripts are called when your whole system starts (for example after you turn on your computer). Therefore you need administrator or root privileges to access or modify them.

‘~/.bash_profile
If you are using (GNU) Bash as your shell, the commands in this file are run, when you log in to your account through Bash. Most commonly when you login through the virtual console (where there is no graphic user interface).

‘~/.bashrc
If you are using (GNU) Bash as your shell, the commands here will be run each time you start a terminal and are already logged in. For example, when you open your terminal emulator in the graphic user interface.

For security reasons, it is highly recommended to directly type in your HOME directory value by hand in startup files instead of using variables. So in the following, let’s assume your user name is ‘name’ (so ‘~’ may be replaced with /home/name). To add ‘~/.local/bin’ to your PATH automatically on any startup file, you have to “export” the new value of PATH in the startup file that is most relevant to you by adding this line:

export PATH=$PATH:/home/name/.local/bin
Now that you know your system will look into `~/.local/bin` for executables, you can tell Gnuastro’s configure script to install everything in the top `~/.local` directory using the `--prefix` option. When you subsequently run `$ make install`, all the install-able files will be put in their respective directory under `~/.local/` (the executables in `~/.local/bin`, the compiled library files in `~/.local/lib`, the library header files in `~/.local/include` and so on, to learn more about these different files, please see Section 10.1 [Review of library fundamentals], page 372). Note that tilde (‘~’) expansion will not happen if you put a ‘=’ between `--prefix` and `~/.local`, so we have avoided the = character here which is optional in GNU-style options, see Section 4.1.1.2 [Options], page 107.

$ ./configure --prefix ~/.local

You can install everything (including libraries like GSL, CFITSIO, or WCSLIB which are Gnuastro’s mandatory dependencies, see Section 3.1.1 [Mandatory dependencies], page 75) locally by configuring them as above. However, recall that PATH is only for executable files, not libraries and that libraries can also depend on other libraries. For example WCSLIB depends on CFITSIO and Gnuastro needs both. Therefore, when you installed a library in a non-recognized directory, you have to guide the program that depends on them to look into the necessary library and header file directories. To do that, you have to define the LDFLAGS and CPPFLAGS environment variables respectively. This can be done while calling `./configure` as shown below:

```
$ ./configure LDFLAGS=-L/home/name/.local/lib  \  
    CPPFLAGS=-I/home/name/.local/include  \  
    --prefix ~/.local
```

It can be annoying/buggy to do this when configuring every software that depends on such libraries. Hence, you can define these two variables in the most relevant startup file (discussed above). The convention on using these variables doesn’t include a colon to separate values (as PATH-like variables do), they use white space characters and each value is prefixed with a compiler option: note the –L and –I above (see Section 4.1.1.2 [Options], page 107), for –I see Section 10.1.1 [Headers], page 373, and for –L, see Section 10.1.2 [Linking], page 376. Therefore we have to keep the value in double quotation signs to keep the white space characters and adding the following two lines to the startup file of choice:

```
export LDFLAGS="$LDFLAGS -L/home/name/.local/lib"
export CPPFLAGS="$CPPFLAGS -I/home/name/.local/include"
```

Dynamic libraries are linked to the executable every time you run a program that depends on them (see Section 10.1.2 [Linking], page 376, to fully understand this important concept). Hence dynamic libraries also require a special path variable called LD_LIBRARY_PATH (same formatting as PATH). To use programs that depend on these libraries, you need to add `~/.local/lib` to your LD_LIBRARY_PATH environment variable by adding the following line to the relevant start-up file:

```
export LD_LIBRARY_PATH=$LD_LIBRARY_PATH:/home/name/.local/lib
```

22 If you insist on using ‘=’, you can use `--prefix=$HOME/.local`.

23 These variables are ultimately used as options while building the programs, so every value has be an option name followed be a value as discussed in Section 4.1.1.2 [Options], page 107.
If you also want to access the Info (see Section 4.3.4 [Info], page 125) and man pages (see Section 4.3.3 [Man pages], page 125) documentations add "~/local/share/info and "~/local/share/man to your INFOPATH\(^{24}\) and MANPATH environment variables respectively.

A final note is that order matters in the directories that are searched for all the variables discussed above. In the examples above, the new directory was added after the system specified directories. So if the program, library or manuals are found in the system wide directories, the user directory is no longer searched. If you want to search your local installation first, put the new directory before the already existing list, like the example below.

```bash
export LD_LIBRARY_PATH=/home/name/.local/lib:$LD_LIBRARY_PATH
```

This is good when a library, for example CFITSIO, is already present on the system, but the system-wide install wasn’t configured with the correct configuration flags (see Section 3.1.1.2 [CFITSIO], page 75), or you want to use a newer version and you don’t have administrator or root access to update it on the whole system/server. If you update LD_LIBRARY_PATH by placing "~/local/lib first (like above), the linker will first find the CFITSIO you installed for yourself and link with it. It thus will never reach the system-wide installation.

There are important security problems with using local installations first: all important system-wide executables and libraries (important executables like ls and cp, or libraries like the C library) can be replaced by non-secure versions with the same file names and put in the customized directory ("~/local in this example). So if you choose to search in your customized directory first, please be sure to keep it clean from executables or libraries with the same names as important system programs or libraries.

### Summary:

When you are using a server which doesn’t give you administrator/root access AND you would like to give priority to your own built programs and libraries, not the version that is (possibly already) present on the server, add these lines to your startup file. See above for which startup file is best for your case and for a detailed explanation on each. Don’t forget to replace ‘/YOUR-HOME-DIR’ with your home directory (for example ‘/home/your-id’):

```bash
export PATH="/YOUR-HOME-DIR/.local/bin:$PATH"
export LDFLAGS="-L/YOUR-HOME-DIR/.local/lib $LDFLAGS"
export MANPATH="/YOUR-HOME-DIR/.local/share/man/:$MANPATH"
export CPPFLAGS="-I/YOUR-HOME-DIR/.local/include $CPPFLAGS"
export INFOPATH="/YOUR-HOME-DIR/.local/share/info/:$INFOPATH"
export LD_LIBRARY_PATH="/YOUR-HOME-DIR/.local/lib:$LD_LIBRARY_PATH"
```

Afterwards, you just need to add an extra --prefix="/YOUR-HOME-DIR/.local" to the ./configure command of the software that you intend to install. Everything else will be the same as a standard build and install, see Section 1.1 [Quick start], page 1.

---

\(^{24}\) Info has the following convention: “If the value of INFOPATH ends with a colon [or it isn’t defined] ... the initial list of directories is constructed by appending the build-time default to the value of INFOPATH.” So when installing in a non-standard directory and if INFOPATH was not initially defined, add a colon to the end of INFOPATH as shown below, otherwise Info will not be able to find system-wide installed documentation:

```bash
echo 'export INFOPATH=$INFOPATH:/home/name/.local/share/info:' >> ~/.bashrc
```

Note that this is only an internal convention of Info, do not use it for other *PATH variables.
3.3.1.3 Executable names

At first sight, the names of the executables for each program might seem to be uncommonly long, for example `astnoisechisel` or `astcrop`. We could have chosen terse (and cryptic) names like most programs do. We chose this complete naming convention (something like the commands in \( \TeX \)) so you don’t have to spend too much time remembering what the name of a specific program was. Such complete names also enable you to easily search for the programs.

To facilitate typing the names in, we suggest using the shell auto-complete. With this facility you can find the executable you want very easily. It is very similar to file name completion in the shell. For example, simply by typing the letters below (where \[ \text{[TAB]} \] stands for the Tab key on your keyboard)

\[
\text{$\ast$}\text{[TAB]}\text{[TAB]}
\]

you will get the list of all the available executables that start with `ast` in your \texttt{PATH} environment variable directories. So, all the Gnuastro executables installed on your system will be listed. Typing the next letter for the specific program you want along with a Tab, will limit this list until you get to your desired program.

In case all of this does not convince you and you still want to type short names, some suggestions are given below. You should have in mind though, that if you are writing a shell script that you might want to pass on to others, it is best to use the standard name because other users might not have adopted the same customization. The long names also serve as a form of documentation in such scripts. A similar reasoning can be given for option names in scripts: it is good practice to always use the long formats of the options in shell scripts, see Section 4.1.1.2 [Options], page 107.

The simplest solution is making a symbolic link to the actual executable. For example let’s assume you want to type `ic` to run Crop instead of `astcrop`. Assuming you installed Gnuastro executables in \texttt{/usr/local/bin} (default) you can do this simply by running the following command as root:

\[
\text{# ln -s /usr/local/bin/astcrop /usr/local/bin/ic}
\]

In case you update Gnuastro and a new version of Crop is installed, the default executable name is the same, so your custom symbolic link still works.

The installed executable names can also be set using options to \$ ./\texttt{configure}, see Section 3.3.1 [Configuring], page 90. GNU Autoconf (which configures Gnuastro for your particular system), allows the builder to change the name of programs with the three options \texttt{--program-prefix}, \texttt{--program-suffix} and \texttt{--program-transform-name}. The first two are for adding a fixed prefix or suffix to all the programs that will be installed. This will actually make all the names longer! You can use it to add versions of program names to the programs in order to simultaneously have two executable versions of a program.

The third configure option allows you to set the executable name at install time using the SED program. SED is a very useful ‘stream editor’. There are various resources on the internet to use it effectively. However, we should caution that using configure options will change the actual executable name of the installed program and on every re-install (an update for example), you have to also add this option to keep the old executable name updated. Also note that the documentation or configuration files do not change from their standard names either.
For example, let’s assume that typing `ast` on every invocation of every program is really annoying you! You can remove this prefix from all the executables at configure time by adding this option:

```
$ ./configure --program-transform-name='s/ast/ /'
```

### 3.3.1.4 Configure and build in RAM

Gnuastro’s configure and build process (the GNU build system) involves the creation, reading, and modification of a large number of files (input/output, or I/O). Therefore file I/O issues can directly affect the work of developers who need to configure and build Gnuastro numerous times. Some of these issues are listed below:

- **I/O will cause wear and tear on both the HDDs (mechanical failures) and SSDs (decreasing the lifetime).**
- **Having the built files mixed with the source files can greatly affect backing up (synchronization) of source files (since it involves the management of a large number of small files that are regularly changed). Backup software can of course be configured to ignore the built files and directories. However, since the built files are mixed with the source files and can have a large variety, this will require a high level of customization.**

One solution to address both these problems is to use the tmpfs file system ([https://en.wikipedia.org/wiki/Tmpfs](https://en.wikipedia.org/wiki/Tmpfs)). Any file in tmpfs is actually stored in the RAM (and possibly SAWP), not on HDDs or SSDs. The RAM is built for extensive and fast I/O. Therefore the large number of file I/Os associated with configuring and building will not harm the HDDs or SSDs. Due to the volatile nature of RAM, files in the tmpfs file-system will be permanently lost after a power-off. Since all configured and built files are derivative files (not files that have been directly written by hand) there is no problem in this and this feature can be considered as an automatic cleanup.

The modern GNU C library (and thus the Linux kernel) defines the `/dev/shm` directory for this purpose in the RAM (POSIX shared memory). To build in it, you can use the GNU build system’s ability to build in a separate directory (not necessarily in the source directory) as shown below. Just set `SRCDIR` as the address of Gnuastro’s top source directory (for example, the unpacked tarball).

```
$ mkdir /dev/shm/tmp-gnuastro-build
$ cd /dev/shm/tmp-gnuastro-build
$ SRCDIR/configure --srcdir=SRCDIR
$ make
```

Gnuastro comes with a script to simplify this process of configuring and building in a different directory (a “clean” build), for more see Section 3.3.2 [Separate build and source directories], page 98.

### 3.3.2 Separate build and source directories

The simple steps of Section 1.1 [Quick start], page 1, will mix the source and built files. This can cause inconvenience for developers or enthusiasts following the the most recent work (see Section 3.2.2 [Version controlled source], page 85). The current section is mainly focused on this later group of Gnuastro users. If you just install Gnuastro on major releases (following Section 1.9 [Announcements], page 13), you can safely ignore this section.
When it is necessary to keep the source (which is under version control), but not the
derivative (built) files (after checking or installing), the best solution is to keep the source
and the built files in separate directories. One application of this is already discussed in
Section 3.3.1.4 [Configure and build in RAM], page 98.

To facilitate this process of configuring and building in a separate directory, Gnuastro
comes with the `developer-build` script. It is available in the top source directory and is
not installed. It will make a directory under a given top-level directory (given to `--top-
build-dir`) and build Gnuastro in there directory. It thus keeps the source completely
separated from the built files. For easy access to the built files, it also makes a symbolic
link to the built directory in the top source files called `build`.

When run without any options, default values will be used for its configuration. As with
Gnuastro’s programs, you can inspect the default values with `-P` (or `--printparams`, the
output just looks a little different here). The default top-level build directory is `/dev/shm`;
the shared memory directory in RAM on GNU/Linux systems as described in Section 3.3.1.4
[Configure and build in RAM], page 98.

Besides these, it also has some features to facilitate the job of developers or bleeding edge
users like the `--debug` option to do a fast build, with debug information, no optimization,
and no shared libraries. Here is the full list of options you can feed to this script to configure
its operations.

---

Not all Gnuastro’s common program behavior usable here: `developer-build` is just a
non-installed script with a very limited scope as described above. It thus doesn’t have all
the common option behaviors or configuration files for example.

---

White space between option and value: `developer-build` doesn’t accept an = sign be-
tween the options and their values. It also needs at least one character between the op-
tion and its value. Therefore `-n 4` or `--numthreads 4` are acceptable, while `-n4`, `-n=4`,
or `--numthreads=4` aren’t. Finally multiple short option names cannot be merged: for
example you can say `-c -n 4`, but unlike Gnuastro’s programs, `-cn4` is not acceptable.

---

Reusable for other packages: This script can be used in any software which is configured
and built using the GNU Build System. Just copy it in the top source directory of that
software and run it from there.

---

- `-b STR`
- `--top-build-dir STR`

The top build directory to make a directory for the build. If this option isn’t
called, the top build directory is `/dev/shm` (only available in GNU/Linux op-
erating systems, see Section 3.3.1.4 [Configure and build in RAM], page 98).

- `-V`
- `--version`

Print the version string of Gnuastro that will be used in the build. This string
will be appended to the directory name containing the built files.
-a
--autoreconf

Run `autoreconf -f` before building the package. In Gnuastro, this is necessary when a new commit has been made to the project history. In Gnuastro's build system, the Git description will be used as the version, see Section 1.5 [Version numbering], page 7, and Section 3.2.2.2 [Synchronizing], page 88.

-c
--clean

Delete the contents of the build directory (clean it) before starting the configuration and building of this run.

This is useful when you have recently pulled changes from the main Git repository, or committed a change yourself and ran `autoreconf -f`, see Section 3.2.2.2 [Synchronizing], page 88. After running GNU Autoconf, the version will be updated and you need to do a clean build.

-d
--debug

Build with debugging flags (for example to use in GNU Debugger, also known as GDB, or Valgrind), disable optimization and also the building of shared libraries. Similar to running the configure script of below

```
$ ./configure --enable-debug
```

Besides all the debugging advantages of building with this option, it will also be significantly speed up the build (at the cost of slower built programs). So when you are testing something small or working on the build system itself, it will be much faster to test your work with this option.

-v
--valgrind

Build all `make check` tests within Valgrind. For more, see the description of `--enable-check-with-valgrind` in Section 3.3.1.1 [Gnuastro configure options], page 90.

-j INT
--jobs INT

The maximum number of threads/jobs for Make to build at any moment. As the name suggests (Make has an identical option), the number given to this option is directly passed on to any call of Make with its `-j` option.

-C
--check

After finishing the build, also run `make check`. By default, `make check` isn't run because the developer usually has their own checks to work on (for example defined in `tests/during-dev.sh`).

-i
--install

After finishing the build, also run `make install`.

-D
--dist

Run `make dist-lzip pdf` to build a distribution tarball (in `.tar.lz` format) and a PDF manual. This can be useful for archiving, or sending to colleagues who don't use Git for an easy build and manual.
Chapter 3: Installation 101

-u STR
--upload STR
Activate the --dist (-D) option, then use secure copy (scp, part of the SSH tools) to copy the tarball and PDF to the src and pdf sub-directories of the specified server and its directory (value to this option). For example --upload my-server:dir, will copy the tarball in the dir/src, and the PDF manual in dir/pdf of my-server server. It will then make a symbolic link in the top server directory to the tarball that is called gnuastro-latest.tar.lz.

-p
--publish
Short for --autoreconf --clean --debug --check --upload STR. --debug is added because it will greatly speed up the build. It will have no effect on the produced tarball. This is good when you have made a commit and are ready to publish it on your server (if nothing crashes). Recall that if any of the previous steps fail the script aborts.

-I
--install-archive
Short for --autoreconf --clean --check --install --dist. This is useful when you actually want to install the commit you just made (if the build and checks succeed). It will also produce a distribution tarball and PDF manual for easy access to the installed tarball on your system at a later time.

Ideally, Gnuastro’s Git version history makes it easy for a prepared system to revert back to a different point in history. But Gnuastro also needs to bootstrap files and also your collaborators might (usually do!) find it too much of a burden to do the bootstrapping themselves. So it is convenient to have a tarball and PDF manual of the version you have installed (and are using in your research) handily available.

-h
--help
-P
--printparams
Print a description of this script along with all the options and their current values.

3.3.3 Tests
After successfully building (compiling) the programs with the $ make command you can check the installation before installing. To run the tests, run

$ make check

For every program some tests are designed to check some possible operations. Running the command above will run those tests and give you a final report. If everything is OK and you have built all the programs, all the tests should pass. In case any of the tests fail, please have a look at Section 3.3.5 [Known issues], page 102, and if that still doesn’t fix your problem, look that the ./tests/test-suite.log file to see if the source of the error is something particular to your system or more general. If you feel it is general, please contact...
us because it might be a bug. Note that the tests of some programs depend on the outputs of other program’s tests, so if you have not installed them they might be skipped or fail. Prior to releasing every distribution all these tests are checked. If you have a reasonably modern terminal, the outputs of the successful tests will be colored green and the failed ones will be colored red.

These scripts can also act as a good set of examples for you to see how the programs are run. All the tests are in the tests/ directory. The tests for each program are shell scripts (ending with .sh) in a sub-directory of this directory with the same name as the program. See Section 11.7 [Test scripts], page 529, for more detailed information about these scripts in case you want to inspect them.

### 3.3.4 A4 print book

The default print version of this book is provided in the letter paper size. If you would like to have the print version of this book on paper and you are living in a country which uses A4, then you can rebuild the book. The great thing about the GNU build system is that the book source code which is in Texinfo is also distributed with the program source code, enabling you to do such customization (hacking).

In order to change the paper size, you will need to have GNU Texinfo installed. Open doc/gnuastro.texi with any text editor. This is the source file that created this book. In the first few lines you will see this line:

```
@c@afourpaper
```

In Texinfo, a line is commented with @c. Therefore, un-comment this line by deleting the first two characters such that it changes to:

```
@afourpaper
```

Save the file and close it. You can now run the following command

```
$ make pdf
```

and the new PDF book will be available in SRCdir/doc/gnuastro.pdf. By changing the pdf in $ make pdf to ps or dvi you can have the book in those formats. Note that you can do this for any book that is in Texinfo format, they might not have @afourpaper line, so you can add it close to the top of the Texinfo source file.

### 3.3.5 Known issues

Depending on your operating system and the version of the compiler you are using, you might confront some known problems during the configuration ($ ./configure), compilation ($ make) and tests ($ make check). Here, their solutions are discussed.

- **$ ./configure**: Configure complains about not finding a library even though you have installed it. The possible solution is based on how you installed the package:
  - From your distribution’s package manager. Most probably this is because your distribution has separated the header files of a library from the library parts. Please also install the ‘development’ packages for those libraries too. Just add a -dev or -devel to the end of the package name and re-run the package manager. This will not happen if you install the libraries from source. When installed from source, the headers are also installed.
• From source. Then your linker is not looking where you installed the library. If you followed the instructions in this chapter, all the libraries will be installed in /usr/local/lib. So you have to tell your linker to look in this directory. To do so, configure Gnuastro like this:

```bash
$ ./configure LDFLAGS="-L/usr/local/lib"
```

If you want to use the libraries for your other programming projects, then export this environment variable in a start-up script similar to the case for LD_LIBRARY_PATH explained below, also see Section 3.3.1.2 [Installation directory], page 92.

• `$ make`: *Complains about an unknown function on a non-GNU based operating system.* In this case, please run `$ ./configure` with the `--enable-gnulibcheck` option to see if the problem is from the GNU Portability Library (Gnulib) not supporting your system or if there is a problem in Gnuastro, see Section 3.3.1.1 [Gnuastro configure options], page 90. If the problem is not in Gnulib and after all its tests you get the same complaint from `make`, then please contact us at bug-gnuastro@gnu.org. The cause is probably that a function that we have used is not supported by your operating system and we didn’t included it along with the source tar ball. If the function is available in Gnulib, it can be fixed immediately.

• `$ make`: *Can't find the headers (.h files) of installed libraries.* Your C pre-processor (CPP) isn’t looking in the right place. To fix this, configure Gnuastro with an additional CPPFLAGS like below (assuming the library is installed in /usr/local/include):

```bash
$ ./configure CPPFLAGS="-I/usr/local/include"
```

If you want to use the libraries for your other programming projects, then export this environment variable in a start-up script similar to the case for LD_LIBRARY_PATH explained below, also see Section 3.3.1.2 [Installation directory], page 92.

• `$ make check`: *Only the first couple of tests pass, all the rest fail or get skipped.* It is highly likely that when searching for shared libraries, your system doesn’t look into the /usr/local/lib directory (or wherever you installed Gnuastro or its dependencies). To make sure it is added to the list of directories, add the following line to your ~/.bashrc file and restart your terminal. Don’t forget to change /usr/local/lib if the libraries are installed in other (non-standard) directories.

```bash
export LD_LIBRARY_PATH="$LD_LIBRARY_PATH:/usr/local/lib"
```

You can also add more directories by using a colon ‘:’ to separate them. See Section 3.3.1.2 [Installation directory], page 92, and Section 10.1.2 [Linking], page 376, to learn more on the PATH variables and dynamic linking respectively.

• `$ make check`: *The tests relying on external programs (for example fitstopdf.sh fail.)* This is probably due to the fact that the version number of the external programs is too old for the tests we have preformed. Please update the program to a more recent version. For example to create a PDF image, you will need GPL Ghostscript, but older versions do not work, we have successfully tested it on version 9.15. Older versions might cause a failure in the test result.

• `$ make pdf`: *The PDF book cannot be made.* To make a PDF book, you need to have the GNU Texinfo program (like any program, the more recent the better). A working $\TeX$X program is also necessary, which you can get from TeX Live\textsuperscript{25}.

\textsuperscript{25} https://www.tug.org/texlive/
• After make check: do not copy the programs’ executables to another (for example, the installation) directory manually (using cp, or mv for example). In the default configuration\textsuperscript{26}, the program binaries need to link with Gnuastro’s shared library which is also built and installed with the programs. Therefore, to run successfully before and after installation, linking modifications need to be made by GNU Libtool at installation time. make install does this internally, but a simple copy might give linking errors when you run it. If you need to copy the executables, you can do so after installation. If your problem was not listed above, please file a bug report (Section 1.7 [Report a bug], page 11).

\footnote{If you configure Gnuastro with the \texttt{--disable-shared} option, then the libraries will be statically linked to the programs and this problem won’t exist, see Section 10.1.2 [Linking], page 376.}
4 Common program behavior

All the programs in Gnuastro share a set of common behavior mainly to do with user interaction to facilitate their usage and development. This includes how to feed input datasets into the programs, how to configure them, specifying the outputs, numerical data types, treating columns of information in tables, etc. This chapter is devoted to describing this common behavior in all programs. Because the behaviors discussed here are common to several programs, they are not repeated in each program’s description.

In Section 4.1 [Command-line], page 105, a very general description of running the programs on the command-line is discussed, like difference between arguments and options, as well as options that are common/shared between all programs. None of Gnuastro’s programs keep any internal configuration value (values for their different operational steps), they read their configuration primarily from the command-line, then from specific files in directory, user, or system-wide settings. Using these configuration files can greatly help reproducible and robust usage of Gnuastro, see Section 4.2 [Configuration files], page 120, for more.

It is not possible to always have the different options and configurations of each program on the top of your head. It is very natural to forget the options of a program, their current default values, or how it should be run and what it did. Gnuastro’s programs have multiple ways to help you refresh your memory in multiple levels (just an option name, a short description, or fast access to the relevant section of the manual. See Section 4.3 [Getting help], page 123, for more for more on benefiting from this very convenient feature.

Many of the programs use the multi-threaded character of modern CPUs, in Section 4.5 [Multi-threaded operations], page 127, we’ll discuss how you can configure this behavior, along with some tips on making best use of them. In Section 4.6 [Numeric data types], page 130, we’ll review the various types to store numbers in your datasets: setting the proper type for the usage context\(^1\) can greatly improve the file size and also speed of reading, writing or processing them.

We’ll then look into the recognized table formats in Section 4.8 [Tables], page 135, and how large datasets are broken into tiles, or mesh grid in Section 4.9 [Tessellation], page 141. Finally, we’ll take a look at the behavior regarding output files: Section 4.10 [Automatic output], page 142, describes how the programs set a default name for their output when you don’t give one explicitly (using \texttt{--output}). When the output is a FITS file, all the programs also store some very useful information in the header that is discussed in Section 4.11 [Output FITS files], page 143.

4.1 Command-line

Gnuastro’s programs are customized through the standard Unix-like command-line environment and GNU style command-line options. Both are very common in many Unix-like operating system programs. In Section 4.1.1 [Arguments and options], page 106, we’ll start with the difference between arguments and options and elaborate on the GNU style of op-

\(^1\) For example if the values in your dataset can only be integers between 0 or 65000, store them in an unsigned 16-bit type, not 64-bit floating point type (which is the default in most systems). It takes four times less space and is much faster to process.
4.1.1 Arguments and options

When you type a command on the command-line, it is passed onto the shell (a generic name for the program that manages the command-line) as a string of characters. As an example, see the “Invoking ProgramName” sections in this manual for some examples of commands with each program, like Section 5.4.2 [Invoking Table], page 176, Section 5.1.1 [Invoking Fits], page 148, or Section 7.1.5 [Invoking Statistics], page 257.

The shell then breaks up your string into separate tokens or words using any metacharacters (like white-space, tab, 1, > or ;) that are in the string. On the command-line, the first thing you usually enter is the name of the program you want to run. After that, you can specify two types of tokens: arguments and options. In the GNU-style, arguments are those tokens that are not preceded by any hyphens (–, see Section 4.1.1.1 [Arguments], page 107). Here is one example:

```
$ astcrop --center=53.162551,-27.789676 -w10/3600 --mode=wcs udf.fits
```

In the example above, we are running Section 6.1 [Crop], page 188, to crop a region of width 10 arc-seconds centered at the given RA and Dec from the input Hubble Ultra-Deep Field (UDF) FITS image. Here, the argument is `udf.fits`. Arguments are most commonly the input file names containing your data. Options start with one or two hyphens, followed by an identifier for the option (the option’s name, for example, `--center`, `-w`, `--mode` in the example above) and its value (anything after the option name, or the optional = character). Through options you can configure how the program runs (interprets the data you provided).

Arguments can be mandatory and optional and unlike options, they don’t have any identifiers. Hence, when there multiple arguments, their order might also matter (for example in `cp` which is used for copying one file to another location). The outputs of `--usage` and `--help` shows which arguments are optional and which are mandatory, see Section 4.3.1 [--usage], page 123.

As their name suggests, options can be considered to be optional and most of the time, you don’t have to worry about what order you specify them in. When the order does matter, or the option can be invoked multiple times, it is explicitly mentioned in the “Invoking ProgramName” section of each program (this is a very important aspect of an option).

If there is only one such character, you can use a backslash (\) before it. If there are multiple, it might be easier to simply put your whole argument or option value inside of double quotes ("). In such cases, everything inside the double quotes will be seen as one token or word.

For example, let’s say you want to specify the header data unit (HDU) of your FITS file using a complex expression like ‘3; images(exposure > 100)’. If you simply add these after the `--hdu` (-h) option, the programs in Gnuastro will read the value to the HDU option as ‘3’ and run. Then, the shell will attempt to run a separate command ‘images(exposure > 100)’ and complain about a syntax error. This is because the semicolon (;) is an ‘end of command’ character in the shell. To solve this problem you can simply put double quotes around the whole string you want to pass to `--hdu` as seen below:

```
$ astcrop --hdu="3; images(exposure > 100)" image.fits
```
4.1.1.1 Arguments

In Gnuastro, arguments are almost exclusively used as the input data file names. Please consult the first few paragraph of the “Invoking ProgramName” section for each program for a description of what it expects as input, how many arguments, or input data, it accepts, or in what order. Everything particular about how a program treats arguments, is explained under the “Invoking ProgramName” section for that program.

Generally, if there is a standard file name extension for a particular format, that filename extension is used to separate the kinds of arguments. The list below shows the data formats that are recognized in Gnuastro’s programs based on their file name endings. Any argument that doesn’t end with the specified extensions below is considered to be a text file (usually catalogs, see Section 4.8 [Tables], page 135). In some cases, a program can accept specific formats, for example Section 5.3 [ConvertType], page 162, also accepts .jpg images.

- .fits: The standard file name ending of a FITS image.
- .fit: Alternative (3 character) FITS suffix.
- .fits.gz: A FITS image compressed with GNU zip (gzip).
- .fits.fz: A FITS image compressed with fpack.
- .imh: IRAF format image file.

Throughout this book and in the command-line outputs, whenever we want to generalize all such astronomical data formats in a text place holder, we will use ASTRdata, we will assume that the extension is also part of this name. Any file ending with these names is directly passed on to CFITSIO to read. Therefore you don’t necessarily have to have these files on your computer, they can also be located on an FTP or HTTP server too, see the CFITSIO manual for more information.

CFITSIO has its own error reporting techniques, if your input file(s) cannot be opened, or read, those errors will be printed prior to the final error by Gnuastro.

4.1.1.2 Options

Command-line options allow configuring the behavior of a program in all GNU/Linux applications for each particular execution on a particular input data. A single option can be called in two ways: long or short. All options in Gnuastro accept the long format which has two hyphens an can have many characters (for example --hdu). Short options only have one hyphen (−) followed by one character (for example -h). You can see some examples in the list of options in Section 4.1.2 [Common options], page 109, or those for each program’s “Invoking ProgramName” section. Both formats are shown for those which support both. First the short is shown then the long.

Usually, the short options are for when you are writing on the command-line and want to save keystrokes and time. The long options are good for shell scripts, where you aren’t usually rushing. Long options provide a level of documentation, since they are more descriptive and less cryptic. Usually after a few months of not running a program, the short options will be forgotten and reading your previously written script will not be easy.

Some options need to be given a value if they are called and some don’t. You can think of the latter type of options as on/off options. These two types of options can be distinguished using the output of the --help and --usage options, which are common to all
GNU software, see Section 4.3 [Getting help], page 123. In Gnuastro we use the following strings to specify when the option needs a value and what format that value should be in. More specific tests will be done in the program and if the values are out of range (for example negative when the program only wants a positive value), an error will be reported.

**INT** The value is read as an integer.

**FLT** The value is read as a float. There are generally two types, depending on the context. If they are for fractions, they will have to be less than or equal to unity.

**STR** The value is read as a string of characters (for example a file name) or other particular settings like a HDU name, see below.

To specify a value in the short format, simply put the value after the option. Note that since the short options are only one character long, you don’t have to type anything between the option and its value. For the long option you either need white space or an = sign, for example `-h2`, `-h 2`, `--hdu 2` or `--hdu=2` are all equivalent.

The short format of on/off options (those that don’t need values) can be concatenated for example these two hypothetical sequences of options are equivalent: `-a -b -c4` and `-abc4`.

As an example, consider the following command to run Crop:

```
$ astcrop -Dr3 --wwidth 3 catalog.txt --deccol=4 ASTRdata
```

The `$` is the shell prompt, `astcrop` is the program name. There are two arguments (`catalog.txt` and `ASTRdata`) and four options, two of them given in short format (`-D`, `-r`) and two in long format (`--width` and `--deccol`). Three of them require a value and one (`-D`) is an on/off option.

If an abbreviation is unique between all the options of a program, the long option names can be abbreviated. For example, instead of typing `--printparams`, typing `--print` or maybe even `--pri` will be enough, if there are conflicts, the program will warn you and show you the alternatives. Finally, if you want the argument parser to stop parsing arguments beyond a certain point, you can use two dashes: `--`. No text on the command-line beyond these two dashes will be parsed.

Gnuastro has two types of options with values, those that only take a single value are the most common type. If these options are repeated or called more than once on the command-line, the value of the last time it was called will be assigned to it. This is very useful when you are testing/experimenting. Let’s say you want to make a small modification to one option value. You can simply type the option with a new value in the end of the command and see how the script works. If you are satisfied with the change, you can remove the original option for human readability. If the change wasn’t satisfactory, you can remove the one you just added and not worry about forgetting the original value. Without this capability, you would have to memorize or save the original value somewhere else, run the command and then change the value again which is not at all convenient and is potentially cause lots of bugs.

On the other hand, some options can be called multiple times in one run of a program and can thus take multiple values (for example see the `--column` option in Section 5.4.2 [Invoking Table], page 176. In these cases, the order of stored values is the same order that you specified on the command-line.
Gnuastro’s programs don’t keep any internal default values, so some options are mandatory and if they don’t have a value, the program will complain and abort. Most programs have many such options and typing them by hand on every call is impractical. To facilitate the user experience, after parsing the command-line, Gnuastro’s programs read special configuration files to get the necessary values for the options you haven’t identified on the command-line. These configuration files are fully described in Section 4.2 [Configuration files], page 120.

**CAUTION:** In specifying a file address, if you want to use the shell’s tilde expansion (\(^\sim\)) to specify your home directory, leave at least one space between the option name and your value. For example use `--output=\~/test` or `--output= ~/test`. Calling them with `--output=\~/test` or `--output= ~/test` will disable shell expansion.

**CAUTION:** If you forget to specify a value for an option which requires one, and that option is the last one, Gnuastro will warn you. But if it is in the middle of the command, it will take the text of the next option or argument as the value which can cause undefined behavior.

**NOTE:** In some contexts Gnuastro’s counting starts from 0 and in others 1. You can assume by default that counting starts from 1, if it starts from 0 for a special option, it will be explicitly mentioned.

### 4.1.2 Common options

To facilitate the job of the users and developers, all the programs in Gnuastro share some basic command-line options for the options that are common to many of the programs. The full list is classified as Section 4.1.2.1 [Input/Output options], page 109, Section 4.1.2.2 [Processing options], page 112, and Section 4.1.2.3 [Operating mode options], page 114. In some programs, some of the options are irrelevant, but still recognized (you won’t get an unrecognized option error, but the value isn’t used). Unless otherwise mentioned, these options are identical between all programs.

#### 4.1.2.1 Input/Output options

These options are to do with the input and outputs of the various programs.

---

**--stdin.timeout**

Number of micro-seconds to wait for writing/typing in the first line of standard input from the command-line (see Section 4.1.3 [Standard input], page 118). This is only relevant for programs that also accept input from the standard input, and you want to manually write/type the contents on the terminal. When the standard input is already connected to a pipe (output of another program), there won’t be any waiting (hence no timeout, thus making this option redundant).

If the first line-break (for example with the **ENTER** key) is not provided before the timeout, the program will abort with an error that no input was given.
Note that this time interval is only for the first line that you type. Once the first line is given, the program will assume that more data will come and accept rest of your inputs without any time limit. You need to specify the ending of the standard input, for example by pressing CTRL-D after a new line.

Note that any input you write/type into a program on the command-line with Standard input will be discarded (lost) once the program is finished. It is only recoverable manually from your command-line (where you actually typed) as long as the terminal is open. So only use this feature when you are sure that you don’t need the dataset (or have a copy of it somewhere else).

-h STR/INT
--hdu=STR/INT
The name or number of the desired Header Data Unit, or HDU, in the FITS image. A FITS file can store multiple HDUs or extensions, each with either an image or a table or nothing at all (only a header). Note that counting of the extensions starts from 0(zero), not 1(one). Counting from 0 is forced on us by CFITSIO which directly reads the value you give with this option (see Section 3.1.1.2 [CFITSIO], page 75). When specifying the name, case is not important so IMAGE, image or ImAgE are equivalent.

CFITSIO has many capabilities to help you find the extension you want, far beyond the simple extension number and name. See CFITSIO manual’s “HDU Location Specification” section for a very complete explanation with several examples. A # is appended to the string you specify for the HDU and the result is put in square brackets and appended to the FITS file name before calling CFITSIO to read the contents of the HDU for all the programs in Gnuastro.

-s STR
--searchin=STR
Where to match/search for columns when the column identifier wasn’t a number, see Section 4.8.3 [Selecting table columns], page 140. The acceptable values are name, unit, or comment. This option is only relevant for programs that take table columns as input.

-I
--ignorecase
Ignore case while matching/searching column meta-data (in the field specified by the --searchin). The FITS standard suggests to treat the column names as case insensitive, which is strongly recommended here also but is not enforced. This option is only relevant for programs that take table columns as input.

This option is not relevant to Section 10.2 [BuildProgram], page 380, hence in that program the short option -I is used for include directories, not to ignore case.

2 With the # character, CFITSIO will only read the desired HDU into your memory, not all the existing HDUs in the fits file.
The name of the output file or directory. With this option the automatic output
names explained in Section 4.10 [Automatic output], page 142, are ignored.

The data type of the output depending on the program context. This option
isn’t applicable to some programs like Section 5.1 [Fits], page 146, and will
be ignored by them. The different acceptable values to this option are fully
described in Section 4.6 [Numeric data types], page 130.

By default, if the output file already exists, Gnuastro’s programs will silently
delete it and put their own outputs in its place. When this option is activated,
if the output file already exists, the programs will not delete it, will warn you,
and will abort.

In automatic output names, don’t remove the directory information of the input
file names. As explained in Section 4.10 [Automatic output], page 142, if no
output name is specified (with --output), then the output name will be made
in the existing directory based on your input’s file name (ignoring the directory
of the input). If you call this option, the directory information of the input
will be kept and the automatically generated output name will be in the same
directory as the input (usually with a suffix added). Note that this is only
relevant if you are running the program in a different directory than the input
data.

The output table’s type. This option is only relevant when the output is a table
and its format cannot be deduced from its filename. For example, if a name
ending in .fits was given to --output, then the program knows you want a
FITS table. But there are two types of FITS tables: FITS ASCII, and FITS
binary. Thus, with this option, the program is able to identify which type you
want. The currently recognized values to this option are:

txt  A plain text table with white-space characters between the columns
     (see Section 4.8.2 [Gnuastro text table format], page 137).

fits-ascii  A FITS ASCII table (see Section 4.8.1 [Recognized table formats],
            page 136).

fits-binary  A FITS binary table (see Section 4.8.1 [Recognized table formats],
            page 136).
### 4.1.2.2 Processing options

Some processing steps are common to several programs, so they are defined as common options to all programs. Note that this class of common options is thus necessarily less common between all the programs than those described in Section 4.1.2.1 [Input/Output options], page 109, or Section 4.1.2.3 [Operating mode options], page 114, options. Also, if they are irrelevant for a program, these options will not display in the `--help` output of the program.

**--minmapsize=INT**

The minimum size (in bytes) to memory-map a processing/internal array as a file (on the non-volatile HDD/SSD), and not use the system's RAM. Before using this option, please read Section 4.7 [Memory management], page 132. By default processing arrays will only be memory-mapped to a file when the RAM is full. With this option, you can force the memory-mapping, even when there is enough RAM. To ensure this default behavior, the pre-defined value to this option is an extremely large value (larger than any existing RAM).

Please note that using a non-volatile file (in the HDD/SDD) instead of RAM can significantly increase the program’s running time, especially on HDDs (where read/write is slower). Also, note that the number of memory-mapped files that your kernel can support is limited. So when this option is necessary, it is best to give it values larger than 1 megabyte (`--minmapsize=1000000`). You can then decrease it for a specific program’s invocation on a large input after you see memory issues arise (for example an error, or the program not aborting and fully consuming your memory). If you see randomly named files remaining in this directory when the program finishes normally, please send us a bug report so we address the problem, see Section 1.7 [Report a bug], page 11.

**Limited number of memory-mapped files:** The operating system kernels usually support a limited number of memory-mapped files. Therefore never set `--minmapsize` to zero or a small number of bytes (so too many files are created). If the kernel capacity is exceeded, the program will crash.

**--quietmmap**

Don’t print any message when an array is stored in non-volatile memory (HDD/SSD) and not RAM, see the description of `--minmapsize` (above) for more.

**-Z INT[,INT[,...]]**

**--tilesize=[,INT[,...]]**

The size of regular tiles for tessellation, see Section 4.9 [Tessellation], page 141. For each dimension an integer length (in units of data-elements or pixels) is necessary. If the number of input dimensions is different from the number of values given to this option, the program will stop with an error. Values must be separated by commas (,) and can also be fractions (for example 4/2). If they are fractions, the result must be an integer, otherwise an error will be printed.
-M INT[,INT[,...]]
   --numchannels=INT[,INT[,...]]
   The number of channels for larger input tessellation, see Section 4.9 [Tessellation], page 141. The number and types of acceptable values are similar to --tilesize. The only difference is that instead of length, the integers values given to this option represent the number of channels, not their size.

-F FLT
   --remainderfrac=FLT
   The fraction of remainder size along all dimensions to add to the first tile. See Section 4.9 [Tessellation], page 141, for a complete description. This option is only relevant if --tilesize is not exactly divisible by the input dataset’s size in a dimension. If the remainder size is larger than this fraction (compared to --tilesize), then the remainder size will be added with one regular tile size and divided between two tiles at the start and end of the given dimension.

--workoverch
   Ignore the channel borders for the high-level job of the given application. As a result, while the channel borders are respected in defining the small tiles (such that no tile will cross a channel border), the higher-level program operation will ignore them, see Section 4.9 [Tessellation], page 141.

--checktiles
   Make a FITS file with the same dimensions as the input but each pixel is replaced with the ID of the tile that it is associated with. Note that the tile IDs start from 0. See Section 4.9 [Tessellation], page 141, for more on Tiling an image in Gnuastro.

--oneelempertile
   When showing the tile values (for example with --checktiles, or when the program’s output is tessellated) only use one element for each tile. This can be useful when only the relative values given to each tile compared to the rest are important or need to be checked. Since the tiles usually have a large number of pixels within them the output will be much smaller, and so easier to read, write, store, or send.

   Note that when the full input size in any dimension is not exactly divisible by the given --tilesize in that dimension, the edge tile(s) will have different sizes (in units of the input’s size), see --remainderfrac. But with this option, all displayed values are going to have the (same) size of one data-element. Hence, in such cases, the image proportions are going to be slightly different with this option.

   If your input image is not exactly divisible by the tile size and you want one value per tile for some higher-level processing, all is not lost though. You can see how many pixels were within each tile (for example to weight the values or discard some for later processing) with Gnuastro’s Statistics (see Section 7.1 [Statistics], page 248) as shown below. The output FITS file is going to have two extensions, one with the median calculated on each tile and one with the number of elements that each tile covers. You can then use the where operator
in Section 6.2 [Arithmetic], page 199, to set the values of all tiles that don’t have the regular area to a blank value.

```bash
$ aststatistics --median --number --ontile input.fits \ 
   --oneelement --output=o.fits

$ REGULAR_AREA=1600 # Check second extension of ‘o.fits’.
$ astarithmetic o.fits o.fits $REGULAR_AREA ne nan where \ 
   -h1 -h2
```

Note that if `input.fits` also has blank values, then the median on tiles with blank values will also be ignored with the command above (which is desirable).

`--inteonlyblank`
When values are to be interpolated, only change the values of the blank elements, keep the non-blank elements untouched.

`--interpmetric=STR`
The metric to use for finding nearest neighbors. Currently it only accepts the Manhattan (or taxicab) metric with `manhattan`, or the radial metric with `radial`.

The Manhattan distance between two points is defined with $|\Delta x| + |\Delta y|$. Thus the Manhattan metric has the advantage of being fast, but at the expense of being less accurate. The radial distance is the standard definition of distance in a Euclidean space: $\sqrt{\Delta x^2 + \Delta y^2}$. It is accurate, but the multiplication and square root can slow down the processing.

`--interpunnumgb=INT`
The number of nearby non-blank neighbors to use for interpolation.

### 4.1.2.3 Operating mode options

Another group of options that are common to all the programs in Gnuastro are those to do with the general operation of the programs. The explanation for those that are not only limited to Gnuastro but are common to all GNU programs start with (GNU option).

`--` (GNU option) Stop parsing the command-line. This option can be useful in scripts or when using the shell history. Suppose you have a long list of options, and want to see if removing some of them (to read from configuration files, see Section 4.2 [Configuration files], page 120) can give a better result. If the ones you want to remove are the last ones on the command-line, you don’t have to delete them, you can just add `--` before them and if you don’t get what you want, you can remove the `--` and get the same initial result.

`--usage` (GNU option) Only print the options and arguments and abort. This is very useful for when you know the what the options do, and have just forgot their long/short identifiers, see Section 4.3.1 [--usage], page 123.

`-?` (GNU option) Print all options with an explanation and abort. Adding this option will print all the options in their short and long formats, also displaying which ones need a value if they are called (with an = after the long format followed by a string specifying the format, see Section 4.1.1.2 [Options], page 107).
A short explanation is also given for what the option is for. The program will quit immediately after the message is printed and will not do any form of processing, see Section 4.3.2 [--help], page 124.

-V
--version

(GNU option) Print a short message, showing the full name, version, copyright information and program authors and abort. On the first line, it will print the official name (not executable name) and version number of the program. Following this is a blank line and a copyright information. The program will not run.

-q
--quiet

Don’t report steps. All the programs in Gnuastro that have multiple major steps will report their steps for you to follow while they are operating. If you do not want to see these reports, you can call this option and only error/warning messages will be printed. If the steps are done very fast (depending on the properties of your input) disabling these reports will also decrease running time.

--cite

Print all necessary information to cite and acknowledge Gnuastro in your published papers. With this option, the programs will print the BibTeX entry to include in your paper for Gnuastro in general, and the particular program’s paper (if that program comes with a separate paper). It will also print the necessary acknowledgment statement to add in the respective section of your paper and it will abort. For a more complete explanation, please see Section 1.11 [Acknowledgments], page 14.

Citations and acknowledgments are vital for the continued work on Gnuastro. Gnuastro started, and is continued, based on separate research projects. So if you find any of the tools offered in Gnuastro to be useful in your research, please use the output of this command to cite and acknowledge the program (and Gnuastro) in your research paper. Thank you.

Gnuastro is still new, there is no separate paper only devoted to Gnuastro yet. Therefore currently the paper to cite for Gnuastro is the paper for NoiseChisel which is the first published paper introducing Gnuastro to the astronomical community. Upon reaching a certain point, a paper completely devoted to describing Gnuastro’s many functionalities will be published, see Section 1.5.1 [GNU Astronomy Utilities 1.0], page 8.

-P
--printparams

With this option, Gnuastro’s programs will read your command-line options and all the configuration files. If there is no problem (like a missing parameter or a value in the wrong format or range) and immediately before actually running, the programs will print the full list of option names, values and descriptions, sorted and grouped by context and abort. They will also report the version number, the date they were configured on your system and the time they were reported.

As an example, you can give your full command-line options and even the input and output file names and finally just add -P to check if all the parameters are
finely set. If everything is OK, you can just run the same command (easily retrieved from the shell history, with the top arrow key) and simply remove the last two characters that showed this option.

No program will actually start its processing when this option is called. The otherwise mandatory arguments for each program (for example input image or catalog files) are no longer required when you call this option.

`--config=STR`

Parse STR as a configuration file immediately when this option is confronted (see Section 4.2 [Configuration files], page 120). The `--config` option can be called multiple times in one run of any Gnuastro program on the command-line or in the configuration files. In any case, it will be immediately read (before parsing the rest of the options on the command-line, or lines in a configuration file).

Note that by definition, options on the command-line still take precedence over those in any configuration file, including the file(s) given to this option if they are called before it. Also see `--lastconfig` and `--onlyversion` on how this option can be used for reproducible results. You can use `--checkconfig` (below) to check/confirm the parsing of configuration files.

`--checkconfig`

Print options and their values, within the command-line or configuration files, as they are parsed (see Section 4.2.2 [Configuration file precedence], page 121). If an option has already been set, or is ignored by the program, this option will also inform you with special values like `--ALREADY-SET--`. Only options that are parsed after this option are printed, so to see the parsing of all input options, it is recommended to put this option immediately after the program name before any other options.

This is a very good option to confirm where the value of each option is has been defined in scenarios where there are multiple configuration files (for debugging).

`-S`

`--setdirconf`

Update the current directory configuration file for the Gnuastro program and quit. The full set of command-line and configuration file options will be parsed and options with a value will be written in the current directory configuration file for this program (see Section 4.2 [Configuration files], page 120). If the configuration file or its directory doesn’t exist, it will be created. If a configuration file exists it will be replaced (after it, and all other configuration files have been read). In any case, the program will not run.

This is the recommended method\(^3\) to edit/set the configuration file for all future calls to Gnuastro’s programs. It will internally check if your values are in the correct range and type and save them according to the configuration file format, see Section 4.2.1 [Configuration file format], page 120. So if there are unreasonable values to some options, the program will notify you and abort before writing the final configuration file.

\(^3\) Alternatively, you can use your favorite text editor.
When this option is called, the otherwise mandatory arguments, for example input image or catalog file(s), are no longer mandatory (since the program will not run).

- U
--setusrconf

Update the user configuration file and quit (see Section 4.2 [Configuration files], page 120). See explanation under --setdirconf for more details.

--lastconfig

This is the last configuration file that must be read. When this option is confronted in any stage of reading the options (on the command-line or in a configuration file), no other configuration file will be parsed, see Section 4.2.2 [Configuration file precedence], page 121, and Section 4.2.3 [Current directory and User wide], page 122. Like all on/off options, on the command-line, this option doesn’t take any values. But in a configuration file, it takes the values of 0 or 1, see Section 4.2.1 [Configuration file format], page 120. If it is present in a configuration file with a value of 0, then all later occurrences of this option will be ignored.

--onlyversion=STR

Only run the program if Gnuastro’s version is exactly equal to STR (see Section 1.5 [Version numbering], page 7). Note that it is not compared as a number, but as a string of characters, so 0, or 0.0 and 0.00 are different. If the running Gnuastro version is different, then this option will report an error and abort as soon as it is confronted on the command-line or in a configuration file. If the running Gnuastro version is the same as STR, then the program will run as if this option was not called.

This is useful if you want your results to be exactly reproducible and not mistakenly run with an updated/newer or older version of the program. Besides internal algorithmic/behavior changes in programs, the existence of options or their names might change between versions (especially in these earlier versions of Gnuastro).

Hence, when using this option (probably in a script or in a configuration file), be sure to call it before other options. The benefit is that, when the version differs, the other options won’t be parsed and you, or your collaborators/users, won’t get errors saying an option in your configuration doesn’t exist in the running version of the program.

Here is one example of how this option can be used in conjunction with the --lastconfig option. Let’s assume that you were satisfied with the results of this command: astnoisechisel image.fits --snquant=0.95 (along with various options set in various configuration files). You can save the state of NoiseChisel and reproduce that exact result on image.fits later by following these steps (the extra spaces, and \, are only for easy readability, if you want to try it out, only one space between each token is enough).

```
$ echo "onlyversion X.XX" > reproducible.conf
$ echo "lastconfig 1" >> reproducible.conf
$ astnoisechisel image.fits --snquant=0.95 -P
```
>> reproducible.conf

--onlyversion was available from Gnuastro 0.0, so putting it immediately
at the start of a configuration file will ensure that later, you (or others using
different version) won’t get a non-recognized option error in case an option
was added/removed. --lastconfig will inform the installed NoiseChisel to
not parse any other configuration files. This is done because we don’t want the
user’s user-wide or system wide option values affecting our results. Finally, with
the third command, which has a -P (short for --printparams), NoiseChisel will
print all the option values visible to it (in all the configuration files) and the shell
will append them to reproduce.conf. Hence, you don’t have to worry about
remembering the (possibly) different options in the different configuration files.
Afterwards, if you run NoiseChisel as shown below (telling it to read this con-
figuration file with the --config option). You can be sure that there will either
be an error (for version mismatch) or it will produce exactly the same result
that you got before.

$ astnoisechisel --config=reproducible.conf

--log

Some programs can generate extra information about their outputs in a log file.
When this option is called in those programs, the log file will also be printed.
If the program doesn’t generate a log file, this option is ignored.

--log isn’t thread-safe: The log file usually has a fixed name. Therefore if two
simultaneous calls (with --log) of a program are made in the same directory,
the program will try to write to the same file. This will cause problems like
unreasonable log file, undefined behavior, or a crash.

-N INT
--numthreads=INT

Use INT CPU threads when running a Gnuastro program (see Section 4.5 [Multi-
threaded operations], page 127). If the value is zero (0), or this option is not
given on the command-line or any configuration file, the value will be deter-
mined at run-time: the maximum number of threads available to the system
when you run a Gnuastro program.

Note that multi-threaded programming is only relevant to some programs. In
others, this option will be ignored.

4.1.3 Standard input

The most common way to feed the primary/first input dataset into a program is to give its
filename as an argument (discussed in Section 4.1.1.1 [Arguments], page 107). When you
want to run a series of programs in sequence, this means that each will have to keep the
output of each program in a separate file and re-type that file’s name in the next command.
This can be very slow and frustrating (mis-typing a file’s name).

To solve the problem, the founders of Unix defined pipes to directly feed the output of
one program (its “Standard output” stream) into the “standard input” of a next program.
This removes the need to make temporary files between separate processes and became one
of the best demonstrations of the Unix-way, or Unix philosophy.
Every program has three streams identifying where it reads/writes non-file inputs/outputs: Standard input, Standard output, and Standard error. When a program is called alone, all three are directed to the terminal that you are using. If it needs an input, it will prompt you for one and you can type it in. Or, it prints its results in the terminal for you to see.

For example, say you have a FITS table/catalog containing the B and V band magnitudes (MAG_B and MAG_V columns) of a selection of galaxies along with many other columns. If you want to see only these two columns in your terminal, can use Gnuastro’s Section 5.4 [Table], page 171, program like below:

$ asttable cat.fits -cMAG_B,MAG_V

Through the Unix pipe mechanism, when the shell confronts the pipe character (|), it connects the standard output of the program before the pipe, to the standard input of the program after it. So it is literally a “pipe”: everything that you would see printed by the first program on the command (without any pipe), is now passed to the second program (and not seen by you).

To continue the previous example, let’s say you want to see the B-V color. To do this, you can pipe Table’s output to AWK (a wonderful tool for processing things like plain text tables):

$ asttable cat.fits -cMAG_B,MAG_V | awk '{print $1-$2}'

But understanding the distribution by visually seeing all the numbers under each other is not too useful! You can therefore feed this single column information into Section 7.1 [Statistics], page 248, to give you a general feeling of the distribution with the same command:

$ asttable cat.fits -cMAG_B,MAG_V | awk '{print $1-$2}' | aststatistics

Gnuastro’s programs that accept input from standard input, only look into the Standard input stream if there is no first argument. In other words, arguments take precedence over Standard input. When no argument is provided, the programs check if the standard input stream is already full or not (output from another program is waiting to be used). If data is present in the standard input stream, it is used.

When the standard input is empty, the program will wait --stdtimeout micro-seconds for you to manually enter the first line (ending with a new-line character, or the ENTER key, see Section 4.1.2.1 [Input/Output options], page 109). If it detects the first line in this time, there is no more time limit, and you can manually write/type all the lines for as long as it takes. To inform the program that Standard input has finished, press CTRL-D after a new line. If the program doesn’t catch the first line before the time-out finishes, it will abort with an error saying that no input was provided.

**Manual input in Standard input is discarded:** Be careful that when you manually fill the Standard input, the data will be discarded once the program finishes and reproducing the result will be impossible. Therefore this form of providing input is only good for temporary tests.
4.2 Configuration files

Each program needs a certain number of parameters to run. Supplying all the necessary parameters each time you run the program is very frustrating and prone to errors. Therefore all the programs read the values for the necessary options you have not given in the command line from one of several plain text files (which you can view and edit with any text editor). These files are known as configuration files and are usually kept in a directory named etc/ according to the file system hierarchy standard\(^4\).

The thing to have in mind is that none of the programs in Gnuastro keep any internal default value. All the values must either be stored in one of the configuration files or explicitly called in the command-line. In case the necessary parameters are not given through any of these methods, the program will print a missing option error and abort. The only exception to this is \(--\text{numthreads}\), whose default value is determined at runtime using the number of threads available to your system, see Section 4.5 [Multi-threaded operations], page 127. Of course, you can still provide a default value for the number of threads at any of the levels below, but if you don’t, the program will not abort. Also note that through automatic output name generation, the value to the \(--\text{output}\) option is also not mandatory on the command-line or in the configuration files for all programs which don’t rely on that value as an input\(^5\), see Section 4.10 [Automatic output], page 142.

4.2.1 Configuration file format

The configuration files for each program have the standard program executable name with a ‘\.conf’ suffix. When you download the source code, you can find them in the same directory as the source code of each program, see Section 11.4 [Program source], page 522.

Any line in the configuration file whose first non-white character is a # is considered to be a comment and is ignored. An empty line is also similarly ignored. The long name of the option should be used as an identifier. The parameter name and parameter value have to be separated by any number of ‘white-space’ characters: space, tab or vertical tab. By default several space characters are used. If the value of an option has space characters (most commonly for the hdu option), then the full value can be enclosed in double quotation signs (“, similar to the example in Section 4.1.1 [Arguments and options], page 106). If it is an option without a value in the \(--\text{help}\) output (on/off option, see Section 4.1.1.2 [Options], page 107), then the value should be 1 if it is to be ‘on’ and 0 otherwise.

In each non-commented and non-blank line, any text after the first two words (option identifier and value) is ignored. If an option identifier is not recognized in the configuration file, the name of the file, the line number of the unrecognized option, and the unrecognized identifier name will be reported and the program will abort. If a parameter is repeated more than once in the configuration files, accepts only one value, and is not set on the command-line, then only the first value will be used, the rest will be ignored.

\(^4\) http://en.wikipedia.org/wiki/Filesystem_Hierarchy_Standard

\(^5\) One example of a program which uses the value given to \(--\text{output}\) as an input is ConvertType, this value specifies the type of the output through the value to \(--\text{output}\), see Section 5.3.3 [Invoking ConvertType], page 166.
You can build or edit any of the directories and the configuration files yourself using any text editor. However, it is recommended to use the `--setdirconf` and `--setusrconf` options to set default values for the current directory or this user, see Section 4.1.2.3 [Operating mode options], page 114. With these options, the values you give will be checked before writing in the configuration file. They will also print a set of commented lines guiding the reader and will also classify the options based on their context and write them in their logical order to be more understandable.

### 4.2.2 Configuration file precedence

The option values in all the programs of Gnuastro will be filled in the following order. If an option only takes one value which is given in an earlier step, any value for that option in a later step will be ignored. Note that if the `lastconfig` option is specified in any step below, no other configuration files will be parsed (see Section 4.1.2.3 [Operating mode options], page 114).

1. Command-line options, for a particular run of ProgramName.
2. `.gnuastro/astprogname.conf` is parsed by ProgramName in the current directory.
3. `.gnuastro/gnuastro.conf` is parsed by all Gnuastro programs in the current directory.
4. `$HOME/.local/etc/astprogname.conf` is parsed by ProgramName in the user’s home directory (see Section 4.2.3 [Current directory and User wide], page 122).
5. `$HOME/.local/etc/gnuastro.conf` is parsed by all Gnuastro programs in the user’s home directory (see Section 4.2.3 [Current directory and User wide], page 122).
6. `prefix/etc/astprogname.conf` is parsed by ProgramName in the system-wide installation directory (see Section 4.2.4 [System wide], page 122, for `prefix`).
7. `prefix/etc/gnuastro.conf` is parsed by all Gnuastro programs in the system-wide installation directory (see Section 4.2.4 [System wide], page 122, for `prefix`).

The basic idea behind setting this progressive state of checking for parameter values is that separate users of a computer or separate folders in a user’s file system might need different values for some parameters.

---

**Checking the order:** You can confirm/check the order of parsing configuration files using the `--checkconfig` option with any Gnuastro program, see Section 4.1.2.3 [Operating mode options], page 114. Just be sure to place this option immediately after the program name, before any other option.

As you see above, there can also be a configuration file containing the common options in all the programs: `gnuastro.conf` (see Section 4.1.2 [Common options], page 109). If options specific to one program are specified in this file, there will be unrecognized option errors, or unexpected behavior if the option has different behavior in another program. On the other hand, there is no problem with `astprogname.conf` containing common options.

---

6 As an example, the `--setdirconf` and `--setusrconf` options will also write the common options they have read in their produced `astprogname.conf`. 
Manipulating the order: You can manipulate this order or add new files with the following two options which are fully described in Section 4.1.2.3 [Operating mode options], page 114:

--config
Allows you to define any file to be parsed as a configuration file on the command-line or within the any other configuration file. Recall that the file given to --config is parsed immediately when this option is confronted (on the command-line or in a configuration file).

--lastconfig
Allows you to stop the parsing of subsequent configuration files. Note that if this option is given in a configuration file, it will be fully read, so its position in the configuration doesn’t matter (unlike --config).

One example of benefiting from these configuration files can be this: raw telescope images usually have their main image extension in the second FITS extension, while processed FITS images usually only have one extension. If your system-wide default input extension is 0 (the first), then when you want to work with the former group of data you have to explicitly mention it to the programs every time. With this progressive state of default values to check, you can set different default values for the different directories that you would like to run Gnuastro in for your different purposes, so you won’t have to worry about this issue any more.

The same can be said about the gnuastro.conf files: by specifying a behavior in this single file, all Gnuastro programs in the respective directory, user, or system-wide steps will behave similarly. For example to keep the input’s directory when no specific output is given (see Section 4.10 [Automatic output], page 142), or to not delete an existing file if it has the same name as a given output (see Section 4.1.2.1 [Input/Output options], page 109).

4.2.3 Current directory and User wide
For the current (local) and user-wide directories, the configuration files are stored in the hidden sub-directories named .gnuastro/ and $HOME/.local/etc/ respectively. Unless you have changed it, the $HOME environment variable should point to your home directory. You can check it by running $ echo $HOME. Each time you run any of the programs in Gnuastro, this environment variable is read and placed in the above address. So if you suddenly see that your home configuration files are not being read, probably you (or some other program) has changed the value of this environment variable.

Although it might cause confusions like above, this dependence on the HOME environment variable enables you to temporarily use a different directory as your home directory. This can come in handy in complicated situations. To set the user or current directory configuration files based on your command-line input, you can use the --setdirconf or --setusrconf, see Section 4.1.2.3 [Operating mode options], page 114.

4.2.4 System wide
When Gnuastro is installed, the configuration files that are shipped with the distribution are copied into the (possibly system wide) prefix/etc/ directory. For more details on prefix, see Section 3.3.1.2 [Installation directory], page 92, (by default it is: /usr/local). This directory is the final place (with the lowest priority) that the programs in Gnuastro will check to retrieve parameter values.
If you remove an option and its value from the system wide configuration files, you either have to specify it in more immediate configuration files or set it each time in the command-line. Recall that none of the programs in Gnuastro keep any internal default values and will abort if they don’t find a value for the necessary parameters (except the number of threads and output file name). So even though you might never expect to use an optional option, it is safe to have it available in this system-wide configuration file even if you don’t intend to use it frequently.

Note that in case you install Gnuastro from your distribution’s repositories, prefix will either be set to / (the root directory) or /usr, so you can find the system wide configuration variables in /etc/ or /usr/etc/. The prefix of /usr/local/ is conventionally used for programs you install from source by yourself as in Section 1.1 [Quick start], page 1.

4.3 Getting help

Probably the first time you read this book, it is either in the PDF or HTML formats. These two formats are very convenient for when you are not actually working, but when you are only reading. Later on, when you start to use the programs and you are deep in the middle of your work, some of the details will inevitably be forgotten. Going to find the PDF file (printed or digital) or the HTML webpage is a major distraction.

GNU software have a very unique set of tools for aiding your memory on the command-line, where you are working, depending how much of it you need to remember. In the past, such command-line help was known as “online” help, because they were literally provided to you ‘on’ the command ‘line’. However, nowadays the word “online” refers to something on the internet, so that term will not be used. With this type of help, you can resume your exciting research without taking your hands off the keyboard.

Another major advantage of such command-line based help routines is that they are installed with the software in your computer, therefore they are always in sync with the executable you are actually running. Three of them are actually part of the executable. You don’t have to worry about the version of the book or program. If you rely on external help (a PDF in your personal print or digital archive or HTML from the official webpage) you have to check to see if their versions fit with your installed program.

If you only need to remember the short or long names of the options, --usage is advised. If it is what the options do, then --help is a great tool. Man pages are also provided for those who are used to this older system of documentation. This full book is also available to you on the command-line in Info format. If none of these seems to resolve the problems, there is a mailing list which enables you to get in touch with experienced Gnuastro users. In the subsections below each of these methods are reviewed.

4.3.1 --usage

If you give this option, the program will not run. It will only print a very concise message showing the options and arguments. Everything within square brackets ([ ]) is optional. For example here are the first and last two lines of Crop’s --usage is shown:

$ astcrop --usage
....
Chapter 4: Common program behavior

[--setusrconf] [--usage] [--version] [--wcsmode]
[ASCIIcatalog] FITSimage(s).fits

There are no explanations on the options, just their short and long names shown separately. After the program name, the short format of all the options that don’t require a value (on/off options) is displayed. Those that do require a value then follow in separate brackets, each displaying the format of the input they want, see Section 4.1.1.2 [Options], page 107. Since all options are optional, they are shown in square brackets, but arguments can also be optional. For example in this example, a catalog name is optional and is only required in some modes. This is a standard method of displaying optional arguments for all GNU software.

4.3.2 --help

If the command-line includes this option, the program will not be run. It will print a complete list of all available options along with a short explanation. The options are also grouped by their context. Within each context, the options are sorted alphabetically. Since the options are shown in detail afterwards, the first line of the --help output shows the arguments and if they are optional or not, similar to Section 4.3.1 [--usage], page 123.

In the --help output of all programs in Gnuastro, the options for each program are classified based on context. The first two contexts are always options to do with the input and output respectively. For example input image extensions or supplementary input files for the inputs. The last class of options is also fixed in all of Gnuastro, it shows operating mode options. Most of these options are already explained in Section 4.1.2.3 [Operating mode options], page 114.

The help message will sometimes be longer than the vertical size of your terminal. If you are using a graphical user interface terminal emulator, you can scroll the terminal with your mouse, but we promised no mice distractions! So here are some suggestions:

- **Shift + PageUP** to scroll up and **Shift + PageDown** to scroll down. For most help output this should be enough. The problem is that it is limited by the number of lines that your terminal keeps in memory and that you can’t scroll by lines, only by whole screens.

- **Pipe to **less**. A pipe is a form of shell re-direction. The **less** tool in Unix-like systems was made exactly for such outputs of any length. You can pipe (|) the output of any program that is longer than the screen to it and then you can scroll through (up and down) with its many tools. For example:

  ```bash
  $ astnoisechisel --help | less
  ```

  Once you have gone through the text, you can quit **less** by pressing the q key.

- **Redirect to a file.** This is a less convenient way, because you will then have to open the file in a text editor! You can do this with the shell redirection tool (>):

  ```bash
  $ astnoisechisel --help > filename.txt
  ```

In case you have a special keyword you are looking for in the help, you don’t have to go through the full list. GNU Grep is made for this job. For example if you only want the list of options whose --help output contains the word “axis” in Crop, you can run the following command:

  ```bash
  $ astcrop --help | grep axis
  ```
If the output of this option does not fit nicely within the confines of your terminal, GNU does enable you to customize its output through the environment variable `ARGP_HELP_FMT`, you can set various parameters which specify the formatting of the help messages. For example if your terminals are wider than 70 spaces (say 100) and you feel there is too much empty space between the long options and the short explanation, you can change these formats by giving values to this environment variable before running the program with the `--help` output. You can define this environment variable in this manner:

```
$ export ARGP_HELP_FMT=rmargin=100,opt-doc-col=20
```

This will affect all GNU programs using GNU C library’s `argp.h` facilities as long as the environment variable is in memory. You can see the full list of these formatting parameters in the “Argp User Customization” part of the GNU C library manual. If you are more comfortable to read the `--help` outputs of all GNU software in your customized format, you can add your customization (similar to the line above, without the `$` sign) to your `~/.bashrc` file. This is a standard option for all GNU software.

### 4.3.3 Man pages

Man pages were the Unix method of providing command-line documentation to a program. With GNU Info, see Section 4.3.4 [Info], page 125, the usage of this method of documentation is highly discouraged. This is because Info provides a much more easier to navigate and read environment.

However, some operating systems require a man page for packages that are installed and some people are still used to this method of command line help. So the programs in Gnuastro also have Man pages which are automatically generated from the outputs of `--version` and `--help` using the GNU help2man program. So if you run

```
$ man programname
```

You will be provided with a man page listing the options in the standard manner.

### 4.3.4 Info

Info is the standard documentation format for all GNU software. It is a very useful command-line document viewing format, fully equipped with links between the various pages and menus and search capabilities. As explained before, the best thing about it is that it is available for you the moment you need to refresh your memory on any command-line tool in the middle of your work without having to take your hands off the keyboard. This complete book is available in Info format and can be accessed from anywhere on the command-line.

To open the Info format of any installed programs or library on your system which has an Info format book, you can simply run the command below (change `executablename` to the executable name of the program or library):

```
$ info executablename
```

In case you are not already familiar with it, run `$ info info`. It does a fantastic job in explaining all its capabilities its self. It is very short and you will become sufficiently fluent in about half an hour. Since all GNU software documentation is also provided in Info, your whole GNU/Linux life will significantly improve.

Once you’ve become an efficient navigator in Info, you can go to any part of this book or any other GNU software or library manual, no matter how long it is, in a matter of seconds.
It also blends nicely with GNU Emacs (a text editor) and you can search manuals while you are writing your document or programs without taking your hands off the keyboard, this is most useful for libraries like the GNU C library. To be able to access all the Info manuals installed in your GNU/Linux within Emacs, type `Ctrl-H + i`.

To see this whole book from the beginning in Info, you can run

```
$ info gnuastro
```

If you run Info with the particular program executable name, for example `astcrop` or `astnoisechisel`:

```
$ info astprogramname
```
you will be taken to the section titled “Invoking ProgramName” which explains the inputs and outputs along with the command-line options for that program. Finally, if you run Info with the official program name, for example `Crop` or `NoiseChisel`:

```
$ info ProgramName
```
you will be taken to the top section which introduces the program. Note that in all cases, Info is not case sensitive.

### 4.3.5 help-gnuastro mailing list

Gnuastro maintains the help-gnuastro mailing list for users to ask any questions related to Gnuastro. The experienced Gnuastro users and some of its developers are subscribed to this mailing list and your email will be sent to them immediately. However, when contacting this mailing list please have in mind that they are possibly very busy and might not be able to answer immediately.

To ask a question from this mailing list, send a mail to `help-gnuastro@gnu.org`. Anyone can view the mailing list archives at [http://lists.gnu.org/archive/html/help-gnuastro/](http://lists.gnu.org/archive/html/help-gnuastro/). It is best that before sending a mail, you search the archives to see if anyone has asked a question similar to yours. If you want to make a suggestion or report a bug, please don’t send a mail to this mailing list. We have other mailing lists and tools for those purposes, see Section 1.7 [Report a bug], page 11, or Section 1.8 [Suggest new feature], page 12.

### 4.4 Installed scripts

Gnuastro’s programs (introduced in previous chapters) are designed to be highly modular and thus mainly contain lower-level operations on the data. However, in many contexts, higher-level operations (for example a sequence of calls to multiple Gnuastro programs, or a special way of running a program and using the outputs) are also very similar between various projects.

To facilitate data analysis on these higher-level steps also, Gnuastro also installs some scripts on your system with the (`astscript-`) prefix (in contrast to the other programs that only have the `ast` prefix).

Like all of Gnuastro’s source code, these scripts are also heavily commented. They are written in GNU Bash, which doesn’t need compilation. Therefore, if you open the installed scripts in a text editor, you can actually read them\(^7\). Bash is the same language

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\(^7\) Gnuastro’s installed programs (those only starting with `ast`) aren’t human-readable. They are written in C and are thus compiled (optimized in binary CPU instructions that will be given directly to your
that is mainly used when typing on the command-line. Because of these factors, Bash is much more widely known and used than C (the language of other Gnuastro programs). Gnuastro’s installed scripts also do higher-level operations, so customizing these scripts for a special project will be more common than the programs. You can always inspect them (to customize, check, or educate yourself) with this command (just replace **emacs** with your favorite text editor):

```
$ emacs $(which astscript-NAME)
```

These scripts also accept options and are in many ways similar to the programs (see Section 4.1.2 [Common options], page 109) with some minor differences:

- Currently they don’t accept configuration files themselves. However, the configuration files of the Gnuastro programs they call are indeed parsed and used by those programs. As a result, they don’t have the following options: **--checkconfig**, **--config**, **--lastconfig**, **--onlyversion**, **--printparams**, **--setdirconf** and **--setusrconf**.
- They don’t directly allocate any memory, so there is no **--minmapsize**.
- They don’t have an independent **--usage** option: when called with **--usage**, they just recommend running **--help**.
- The output of **--help** is not configurable like the programs (see Section 4.3.2 [**--help**], page 124).
- The scripts will commonly use your installed Bash and other basic command-line tools (for example AWK or SED). Different systems have different versions and implementations of these basic tools (for example GNU/Linux systems use GNU AWK and GNU SED which are far more advanced and up to date than the minimalist AWK and SED of most other systems). Therefore, unexpected errors in these tools might come up when you run these scripts. We will try our best to write these scripts in a portable way. However, if you do confront such strange errors, please submit a bug report so we fix it (see Section 1.7 [Report a bug], page 11).

### 4.5 Multi-threaded operations

Some of the programs benefit significantly when you use all the threads your computer’s CPU has to offer to your operating system. The number of threads available can be larger than the number of physical (hardware) cores in the CPU (also known as Simultaneous multithreading). For example, in Intel’s CPUs (those that implement its Hyper-threading technology) the number of threads is usually double the number of physical cores in your CPU. On a GNU/Linux system, the number of threads available can be found with the command **$ nproc** command (part of GNU Coreutils).

Gnuastro’s programs can find the number of threads available to your system internally at runtime (when you execute the program). However, if a value is given to the **--numthreads** option, the given number will be used, see Section 4.1.2.3 [Operating mode options], page 114, and Section 4.2 [Configuration files], page 120, for ways to use this option. Thus **--numthreads** is the only common option in Gnuastro’s programs with a value CPU). Because they don’t need an interpreter like Bash on every run, they are much faster and more independent than scripts. To read the source code of the programs, look into the **bin/progname** directory of Gnuastro’s source (Section 3.2 [Downloading the source], page 84). If you would like to read more about why C was chosen for the programs, please see Section 11.1 [Why C programming language?], page 516.
that doesn’t have to be specified anywhere on the command-line or in the configuration files.

4.5.1 A note on threads

Spinning off threads is not necessarily the most efficient way to run an application. Creating a new thread isn’t a cheap operation for the operating system. It is most useful when the input data are fixed and you want the same operation to be done on parts of it. For example, one input image to Crop and multiple crops from various parts of it. In this fashion, the image is loaded into memory once, all the crops are divided between the number of threads internally and each thread cuts out those parts which are assigned to it from the same image. On the other hand, if you have multiple images and you want to crop the same region(s) out of all of them, it is much more efficient to set `--numthreads=1` (so no threads spin off) and run Crop multiple times simultaneously, see Section 4.5.2 [How to run simultaneous operations], page 128.

You can check the boost in speed by first running a program on one of the data sets with the maximum number of threads and another time (with everything else the same) and only using one thread. You will notice that the wall-clock time (reported by most programs at their end) in the former is longer than the latter divided by number of physical CPU cores (not threads) available to your operating system. Asymptotically these two times can be equal (most of the time they aren’t). So limiting the programs to use only one thread and running them independently on the number of available threads will be more efficient.

Note that the operating system keeps a cache of recently processed data, so usually, the second time you process an identical data set (independent of the number of threads used), you will get faster results. In order to make an unbiased comparison, you have to first clean the system’s cache with the following command between the two runs.

```
$ sync; echo 3 | sudo tee /proc/sys/vm/drop_caches
```

**SUMMARY: Should I use multiple threads?** Depends:

- If you only have **one** data set (image in most cases!), then yes, the more threads you use (with a maximum of the number of threads available to your OS) the faster you will get your results.
- If you want to run the same operation on **multiple** data sets, it is best to set the number of threads to `1` and use Make, or GNU Parallel, as explained in Section 4.5.2 [How to run simultaneous operations], page 128.

4.5.2 How to run simultaneous operations

There are two approaches to simultaneously execute a program: using GNU Parallel or Make (GNU Make is the most common implementation). The first is very useful when you only want to do one job multiple times and want to get back to your work without actually

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8 A third way would be to open multiple terminal emulator windows in your GUI, type the commands separately on each and press `Enter` once on each terminal, but this is far too frustrating, tedious and prone to errors. It’s therefore not a realistic solution when tens, hundreds or thousands of operations (your research targets, multiplied by the operations you do on each) are to be done.
keeping the command you ran. The second is usually for more important operations, with lots of dependencies between the different products (for example a full scientific research).

**GNU Parallel**

When you only want to run multiple instances of a command on different threads and get on with the rest of your work, the best method is to use GNU parallel. Surprisingly GNU Parallel is one of the few GNU packages that has no Info documentation but only a Man page, see Section 4.3.4 [Info], page 125. So to see the documentation after installing it please run

```bash
$ man parallel
```

As an example, let’s assume we want to crop a region fixed on the pixels (500, 600) with the default width from all the FITS images in the ./data directory ending with sci.fits to the current directory. To do this, you can run:

```bash
$ parallel astcrop --numthreads=1 --xc=500 --yc=600 ::: 
   ./data/*sci.fits
```

GNU Parallel can help in many more conditions, this is one of the simplest, see the man page for lots of other examples. For absolute beginners: the backslash (\) is only a line breaker to fit nicely in the page. If you type the whole command in one line, you should remove it.

**Make**

Make is a program for building “targets” (e.g., files) using “recipes” (a set of operations) when their known “prerequisites” (other files) have been updated. It elegantly allows you to define dependency structures for building your final output and updating it efficiently when the inputs change. It is the most common infra-structure to build software today.

Scientific research methodology is very similar to software development: you start by testing a hypothesis on a small sample of objects/targets with a simple set of steps. As you are able to get promising results, you improve the method and use it on a larger, more general, sample. In the process, you will confront many issues that have to be corrected (bugs in software development jargon). Make a wonderful tool to manage this style of development. It has been used to make reproducible papers, for example see the reproduction pipeline ([https://gitlab.com/makhlaghi/NoiseChisel-paper](https://gitlab.com/makhlaghi/NoiseChisel-paper)) of the paper introducing Section 7.2 [NoiseChisel], page 269, (one of Gnuastro’s programs).

GNU Make\(^9\) is the most common implementation which (similar to nearly all GNU programs, comes with a wonderful manual\(^10\)). Make is very basic and simple, and thus the manual is short (the most important parts are in the first roughly 100 pages) and easy to read/understand.

Make comes with a `--jobs` (-j) option which allows you to specify the maximum number of jobs that can be done simultaneously. For example if you have 8 threads available to your operating system. You can run:

```bash
$ make -j8
```

With this command, Make will process your Makefile and create all the targets (can be thousands of FITS images for example) simultaneously on 8 threads,

---

\(^9\) [https://www.gnu.org/software/make/](https://www.gnu.org/software/make/)

while fully respecting their dependencies (only building a file/target when its prerequisites are successfully built). Make is thus strongly recommended for managing scientific research where robustness, archiving, reproducibility and speed\textsuperscript{11} are important.

4.6 Numeric data types

At the lowest level, the computer stores everything in terms of 1 or 0. For example, each program in Gnuastro, or each astronomical image you take with the telescope is actually a string of millions of these zeros and ones. The space required to keep a zero or one is the smallest unit of storage, and is known as a \textit{bit}. However, understanding and manipulating this string of bits is extremely hard for most people. Therefore, different standards are defined to package the bits into separate \textit{types} with a fixed interpretation of the bits in each package.

To store numbers, the most basic standard/type is for integers ($\ldots, -2, -1, 0, 1, 2, \ldots$). The common integer types are 8, 16, 32, and 64 bits wide (more bits will give larger limits). Each bit corresponds to a power of 2 and they are summed to create the final number. In the integer types, for each width there are two standards for reading the bits: signed and unsigned. In the ‘signed’ convention, one bit is reserved for the sign (stating that the integer is positive or negative). The ‘unsigned’ integers use that bit in the actual number and thus contain only positive numbers (starting from zero).

Therefore, at the same number of bits, both signed and unsigned integers can allow the same number of integers, but the positive limit of the \textit{unsigned} types is double their \textit{signed} counterparts with the same width (at the expense of not having negative numbers). When the context of your work doesn’t involve negative numbers (for example counting, where negative is not defined), it is best to use the \textit{unsigned} types. For the full numerical range of all integer types, see below.

Another standard of converting a given number of bits to numbers is the floating point standard, this standard can \textit{approximately} store any real number with a given precision. There are two common floating point types: 32-bit and 64-bit, for single and double precision floating point numbers respectively. The former is sufficient for data with less than 8 significant decimal digits (most astronomical data), while the latter is good for less than 16 significant decimal digits. The representation of real numbers as bits is much more complex than integers. If you are interested to learn more about it, you can start with the Wikipedia article (https://en.wikipedia.org/wiki/Floating_point).

Practically, you can use Gnuastro’s Arithmetic program to convert/change the type of an image/datacube (see Section 6.2 [Arithmetic], page 199), or Gnuastro Table program to convert a table column’s data type (see Section 5.4.1 [Column arithmetic], page 172). Conversion of a dataset’s type is necessary in some contexts. For example the program/library, that you intend to feed the data into, only accepts floating point values, but you have an integer image/column. Another situation that conversion can be helpful is when you know

\textsuperscript{11} Besides its multi-threaded capabilities, Make will only re-build those targets that depend on a change you have made, not the whole work. For example, if you have set the prerequisites properly, you can easily test the changing of a parameter on your paper’s results without having to re-do everything (which is much faster). This allows you to be much more productive in easily checking various ideas/assumptions of the different stages of your research and thus produce a more robust result for your exciting science.
that your data only has values that fit within \texttt{int8} or \texttt{uint16}. However it is currently formatted in the \texttt{float64} type.

The important thing to consider is that operations involving wider, floating point, or signed types can be significantly slower than smaller-width, integer, or unsigned types respectively. Note that besides speed, a wider type also requires much more storage space (by 4 or 8 times). Therefore, when you confront such situations that can be optimized and want to store/archive/transfer the data, it is best to use the most efficient type. For example if your dataset (image or table column) only has positive integers less than 65535, store it as an unsigned 16-bit integer for faster processing, faster transfer, and less storage space.

The short and long names for the recognized numeric data types in Gnuastro are listed below. Both short and long names can be used when you want to specify a type. For example, as a value to the common option \texttt{--type} (see Section 4.1.2.1 [Input/Output options], page 109), or in the information comment lines of Section 4.8.2 [Gnuastro text table format], page 137. The ranges listed below are inclusive.

\begin{verbatim}
\begin{itemize}
  \item \texttt{u8} \quad \texttt{uint8} \quad 8-bit unsigned integers, range: [0 to $2^8 - 1$] or [0 to 255].
  \item \texttt{i8} \quad \texttt{int8} \quad 8-bit signed integers, range: [$-2^7$ to $2^7 - 1$] or [$-128$ to 127].
  \item \texttt{u16} \quad \texttt{uint16} \quad 16-bit unsigned integers, range: [0 to $2^{16} - 1$] or [0 to 65535].
  \item \texttt{i16} \quad \texttt{int16} \quad 16-bit signed integers, range: [$-2^{15}$ to $2^{15} - 1$] or [$-32768$ to 32767].
  \item \texttt{u32} \quad \texttt{uint32} \quad 32-bit unsigned integers, range: [0 to $2^{32} - 1$] or [0 to 4294967295].
  \item \texttt{i32} \quad \texttt{int32} \quad 32-bit signed integers, range: [$-2^{31}$ to $2^{31} - 1$] or [$-2147483648$ to 2147483647].
  \item \texttt{u64} \quad \texttt{uint64} \quad 64-bit unsigned integers, range [0 to $2^{64} - 1$] or [0 to 18446744073709551615].
  \item \texttt{i64} \quad \texttt{int64} \quad 64-bit signed integers, range: [$-2^{63}$ to $2^{63} - 1$] or [$-9223372036854775808$ to 9223372036854775807].
  \item \texttt{f32} \quad \texttt{float32} \quad 32-bit (single-precision) floating point types. The maximum (minimum is its negative) possible value is $3.402823 \times 10^{38}$. Single-precision floating points can accurately represent a floating point number up to $\sim 7.2$ significant decimals.
\end{itemize}
\end{verbatim}
Given the heavy noise in astronomical data, this is usually more than sufficient for storing results.

\texttt{f64}  
\texttt{float64}  
64-bit (double-precision) floating point types. The maximum (minimum is its negative) possible value is \( \sim 10^{308} \). Double-precision floating points can accurately represent a floating point number \( \sim 15.9 \) significant decimals. This is usually good for processing (mixing) the data internally, for example a sum of single precision data (and later storing the result as \texttt{float32}).

\begin{table}[h]
\centering
\small
\begin{tabular}{|l|}
\hline
\textbf{Some file formats don’t recognize all types.} For example the FITS standard (see Section 5.1 [Fits], page 146) does not define \texttt{uint64} in binary tables or images. When a type is not acceptable for output into a given file format, the respective Gnuastro program or library will let you know and abort. On the command-line, you can convert the numerical type of an image, or table column into another type with Section 6.2 [Arithmetic], page 199, or Section 5.4 [Table], page 171, respectively. If you are writing your own program, you can use the \texttt{gal_data_copy_to_new_type()} function in Gnuastro’s library, see Section 10.3.6.4 [Copying datasets], page 407. \\
\hline
\end{tabular}
\end{table}

### 4.7 Memory management

In this section we’ll review how Gnuastro manages your input data in the available memory of your system. But before that, let’s have a short basic introduction to the types of memory most relevant to this discussion.

Input datasets (that are later fed into programs for analysis) are commonly first stored in \textit{non-volatile memory}. This is a type of memory that doesn’t need any constant power to keep the data, like HDDs or SSDs and is primarily aimed for long-term storage. So data in this type of storage is preserved when you turn off your computer. But non-volatile memory is much slower in reading or writing than the speeds that CPUs can process the data. Thus relying on this type of memory alone would create a bad bottleneck in the input/output (I/O) phase of any processing.

The first step to decrease this bottleneck is to have a faster storage space, but with more limited volume. For this type of storage, computers have a Random Access Memory (or RAM). RAM is classified as a \textit{volatile memory} because it needs a constant power source to keep the information. In other words, the moment power is cut-off, all the stored information in it is gone (hence the ‘volatile’ name). By assuming that sufficient power is always available, volatile memory is much faster than non-volatile memory.

Hence, the general/simplistic way that programs deal with memory is the following (this is general to all programs, not just Gnuastro’s): 1) Load/copy the input data from the non-volatile memory into RAM. 2) Use the copy in RAM as input for all the internal processing as well as the intermediate data that is necessary during the processing. 3) Finally, when the analysis is complete, write the final output data back into non-volatile memory, and delete all the used space in the RAM (the initial copy and all the intermediate data). The RAM is most important for the data of the intermediate steps (that you never see as a user of a program!).
When the datasets are small (compared to the available space in your system’s RAM when they are run) the steps above are roughly accurate in Gnuastro’s programs and libraries. The only exception is that deleting the intermediate data is not only done at the end of the program. As soon as an intermediate dataset is no longer necessary for the next internal steps, it is deleted. This allows Gnuastro programs to minimize their usage of your system’s RAM.

The situation gets complicated when the datasets are large (compared to your available RAM when they are run). For example if a dataset if half the size of your system’s available RAM, and the program’s analysis needs three or more intermediately processed versions of it in a certain phase of its analysis, there won’t be enough RAM to keep those higher-level versions. In such cases, programs that don’t do any memory management will crash. But fortunately Gnuastro’s programs do have a memory management plans for such situations.

When the necessary amount of space for an intermediate dataset cannot be allocated in the RAM, instead of crashing, Gnuastro’s programs will not use the RAM at all. They will use the “memory-mapped file” concept in modern operating systems to create a randomly-named file in your non-volatile memory and use that instead. That file will have the exact size (in bytes) of that intermediate dataset. Any time the program needs that intermediate dataset, the operating system will directly go to that file, and bypass your RAM. As soon as that file is no longer necessary for the analysis, it will be deleted. But as mentioned above, non-volatile memory has much slower I/O speed than the RAM. Hence in such situations, the programs will become noticeably slower.

By default, Gnuastro’s programs and libraries will notify you with a statement like below, the moment that an intermediate dataset is memory-mapped (can happen in any phase of their analysis). It shows the location of the memory-mapped file and its size, complemented with a small description of the cause and a pointer to this section of the book for more information on how to deal with it (if necessary).

```
astarithmetic: ./gnuastro_mmap/B1QgVf: temporary memory-mapped file
(XXXXX bytes) for intermediate data that is not stored in RAM (see
the "Memory management" section of Gnuastro’s manual)
```

Finally, when the intermediate dataset is no longer necessary, the program will automatically delete it and let you know with a statement like this:

```
astarithmetic: ./gnuastro_mmap/B1QgVf: deleted
```

To disable these messages, you can run the program with `--quietmmap`, or set the `quietmmap` variable in the allocating library function to be non-zero.

An important component of these messages is the name of the memory-mapped file. Knowing that the file has been deleted is important for the user if the program crashes for any reason: internal (for example a parameter is given wrongly) or (for example you mistakenly kill the running job) reason. In the event of a crash, the memory-mapped files will not be deleted and you have to manually delete them because they are usually large and they may soon fill your full storage if not deleted in a long time due to successive crashes.

This brings us to managing the memory-mapped files in your non-volatile memory: knowing where they are saved, placing them in different places of your file system, or deleting them when necessary. As the examples above show, memory-mapped files are stored in a hidden sub-directory of the the running directory: `.gnuastro_mmap`. If this directory doesn’t exist, Gnuastro will automatically create it if it needs to memory-map an
internal dataset. However, if the `.gnuastro_mmap` sub-directory exists and isn’t writable, or it can’t be created, then the file will be created in the running directory with a `.gnuastro_mmap_` prefix.

Therefore one easy way to delete all memory-mapped files is to delete everything within this directory:

```bash
rm -f .gnuastro_mmap/*
```

A much more common issue when dealing with memory-mapped files is their location. For example you may be running a program in a partition that is hosted by a HDD. But you also have another partition on an SSD (which has much faster I/O). So you want your memory-mapped files to be created in the SSD to speed up your processing. Another common scenario is this: you want your project source directory to only contain your plain-text scripts and you want your project’s built products (even the temporary memory-mapped files) to be built in a different location because they are large and hard to maintain with the valuable scripts.

To do host the memory-mapped files in another location, you can set `.gnuastro_mmap` to be a symbolic link to that location. For example, let’s assume you want your memory-mapped files to be stored in `/path/to/dir/for/mmap`. All you have to do is to run following command before your Gnuastro analysis command:

```bash
ln -s /path/to/dir/for/mmap .gnuastro_mmap
```

The programs will delete the memory-mapped file when it is no longer needed, but they won’t delete the `.gnuastro_mmap` directory that hosts them. So if your project involves many Gnuastro programs and you want your memory-mapped files to be in a different location, you just have to make the symbolic link above once.

Another memory-management scenario that may happen is this: you don’t want a Gnuastro program to allocate internal datasets in the RAM at all. For example the speed of your Gnuastro-related project doesn’t matter at that moment, and you have higher-priority jobs that are being run at the same time. In such cases, you can use the `--minmapsize` option that is available in all Gnuastro programs (see Section 4.1.2.2 [Processing options], page 112). Any intermediate dataset that has a size larger than the value of this option will be memory-mapped, even if there is space available in your RAM. For example if you want any intermediate dataset larger than 1 megabyte to be memory-mapped, use `--minmapsize=1000000`.

You shouldn’t set the value of `--minmapsize` to be too small, otherwise even small intermediate values (that are very numerous) in the program will be memory-mapped. However the kernel can only host a limited number of memory-mapped files at every moment (by all running programs combined). For example in the default\(^\text{12}\) Linux kernel on GNU/Linux operating systems this limit is roughly 64000. If the total number of memory-mapped files exceeds this number, all the programs using them will crash. Small/numerous intermediate values will rarely exceed a mega byte, so based on our experience, this is a good value in such scenarios.

Actually, the default behavior for Gnauro’s programs (to only use memory-mapped files when there isn’t enough RAM) is a side-effect of `--minmapsize`. The pre-defined

---

\(^{12}\) If you need to host more memory-mapped files at one moment, you need to build your own customized Linux kernel.
value to this option is an extremely large value in the lowest-level Gnuastro configuration file (the installed gnuastro.conf described in Section 4.2.2 [Configuration file precedence], page 121). This value is larger than the largest available RAM. You can check by running any Gnuastro program with a -P option. Because no dataset will be larger than this, by default the programs will first attempt to use the RAM for temporary storage. But if writing in the RAM fails (for any reason, mainly due to lack of available space), then a memory-mapped file will be created.

4.8 Tables

“A table is a collection of related data held in a structured format within a database. It consists of columns, and rows.” (from Wikipedia). Each column in the table contains the values of one property and each row is a collection of properties (columns) for one target object. For example, let’s assume you have just ran MakeCatalog (see Section 7.4 [MakeCatalog], page 295) on an image to measure some properties for the labeled regions (which might be detected galaxies for example) in the image. For each labeled region (detected galaxy), there will be a row which groups its measured properties as columns, one column for each property. One such property can be the object’s magnitude, which is the sum of pixels with that label, or its center can be defined as the light-weighted average value of those pixels. Many such properties can be derived from the raw pixel values and their position, see Section 7.4.5 [Invoking MakeCatalog], page 307, for a long list.

As a summary, for each labeled region (or, galaxy) we have one row and for each measured property we have one column. This high-level structure is usually the first step for higher-level analysis, for example finding the stellar mass or photometric redshift from magnitudes in multiple colors. Thus, tables are not just outputs of programs, in fact it is much more common for tables to be inputs of programs. For example, to make a mock galaxy image, you need to feed in the properties of each galaxy into Section 8.1 [MakeProfiles], page 332, for it do the inverse of the process above and make a simulated image from a catalog, see Section 2.1 [Sufi simulates a detection], page 17. In other cases, you can feed a table into Section 6.1 [Crop], page 188, and it will crop out regions centered on the positions within the table, see Section 2.2.17 [Finding reddest clumps and visual inspection], page 53. So to end this relatively long introduction, tables play a very important role in astronomy, or generally all branches of data analysis.

In Section 4.8.1 [Recognized table formats], page 136, the currently recognized table formats in Gnuastro are discussed. You can use any of these tables as input or ask for them to be built as output. The most common type of table format is a simple plain text file with each row on one line and columns separated by white space characters, this format is easy to read/write by eye/hand. To give it the full functionality of more specific table types like the FITS tables, Gnuastro has a special convention which you can use to give each column a name, type, unit, and comments, while still being readable by other plain text table readers. This convention is described in Section 4.8.2 [Gnuastro text table format], page 137.

When tables are input to a program, the program reading it needs to know which column(s) it should use for its desired purposes. Gnuastro’s programs all follow a similar convention, on the way you can select columns in a table. They are thoroughly discussed in Section 4.8.3 [Selecting table columns], page 140.
4.8.1 Recognized table formats

The list of table formats that Gnuastro can currently read from and write to are described below. Each has their own advantage and disadvantages, so a short review of the format is also provided to help you make the best choice based on how you want to define your input tables or later use your output tables.

Plain text table
This is the most basic and simplest way to create, view, or edit the table by hand on a text editor. The other formats described below are less eye-friendly and have a more formal structure (for easier computer readability). It is fully described in Section 4.8.2 [Gnuastro text table format], page 137.

FITS ASCII tables
The FITS ASCII table extension is fully in ASCII encoding and thus easily readable on any text editor (assuming it is the only extension in the FITS file). If the FITS file also contains binary extensions (for example an image or binary table extensions), then there will be many hard to print characters. The FITS ASCII format doesn’t have new line characters to separate rows. In the FITS ASCII table standard, each row is defined as a fixed number of characters (value to the NAXIS1 keyword), so to visually inspect it properly, you would have to adjust your text editor’s width to this value. All columns start at given character positions and have a fixed width (number of characters).

Numbers in a FITS ASCII table are printed into ASCII format, they are not in binary (that the CPU uses). Hence, they can take a larger space in memory, loose their precision, and take longer to read into memory. If you are dealing with integer type columns (see Section 4.6 [Numeric data types], page 130), another issue with FITS ASCII tables is that the type information for the column will be lost (there is only one integer type in FITS ASCII tables). One problem with the binary format on the other hand is that it isn’t portable (different CPUs/compilers) have different standards for translating the zeros and ones. But since ASCII characters are defined on a byte and are well recognized, they are better for portability on those various systems. Gnuastro’s plain text table format described below is much more portable and easier to read/write/interpret by humans manually.

Generally, as the name implies, this format is useful for when your table mainly contains ASCII columns (for example file names, or descriptions). They can be useful when you need to include columns with structured ASCII information along with other extensions in one FITS file. In such cases, you can also consider header keywords (see Section 5.1 [Fits], page 146).

FITS binary tables
The FITS binary table is the FITS standard’s solution to the issues discussed with keeping numbers in ASCII format as described under the FITS ASCII table title above. Only columns defined as a string type (a string of ASCII characters) are readable in a text editor. The portability problem with binary formats discussed above is mostly solved thanks to the portability of CFITSIO (see Section 3.1.1.2 [CFITSIO], page 75) and the very long history of the FITS format which has been widely used since the 1970s.
In the case of most numbers, storing them in binary format is more memory efficient than ASCII format. For example, to store \(-25.72034\) in ASCII format, you need 9 bytes/characters. But if you keep this same number (to the approximate precision possible) as a 4-byte (32-bit) floating point number, you can keep/transmit it with less than half the amount of memory. When catalogs contain thousands/millions of rows in tens/hundreds of columns, this can lead to significant improvements in memory/band-width usage. Moreover, since the CPU does its operations in the binary formats, reading the table in and writing it out is also much faster than an ASCII table.

When you are dealing with integer numbers, the compression ratio can be even better, for example if you know all of the values in a column are positive and less than 255, you can use the \texttt{unsigned char} type which only takes one byte! If they are between \(-128\) and 127, then you can use the (signed) \texttt{char} type. So if you are thoughtful about the limits of your integer columns, you can greatly reduce the size of your file and also the speed at which it is read/written. This can be very useful when sharing your results with collaborators or publishing them. To decrease the file size even more you can name your output as ending in \texttt{.fits.gz} so it is also compressed after creation. Just note that compression/decompressing is CPU intensive and can slow down the writing/reading of the file.

Fortunately the FITS Binary table format also accepts ASCII strings as column types (along with the various numerical types). So your dataset can also contain non-numerical columns.

\subsection{Gnuastro text table format}

Plain text files are the most generic, portable, and easiest way to (manually) create, (visually) inspect, or (manually) edit a table. In this format, the ending of a row is defined by the new-line character (a line on a text editor). So when you view it on a text editor, every row will occupy one line. The delimiters (or characters separating the columns) are white space characters (space, horizontal tab, vertical tab) and a comma (\texttt{,}). The only further requirement is that all rows/lines must have the same number of columns.

The columns don’t have to be exactly under each other and the rows can be arbitrarily long with different lengths. For example the following contents in a file would be interpreted as a table with 4 columns and 2 rows, with each element interpreted as a \texttt{double} type (see Section 4.6 [Numeric data types], page 130).

\begin{verbatim}
1  2.234948  128  39.8923e8
2 , 4.454  792  72.98348e7
\end{verbatim}

However, the example above has no other information about the columns (it is just raw data, with no meta-data). To use this table, you have to remember what the numbers in each column represent. Also, when you want to select columns, you have to count their position within the table. This can become frustrating and prone to bad errors (getting the columns wrong) especially as the number of columns increase. It is also bad for sending to a colleague, because they will find it hard to remember/use the columns properly.

To solve these problems in Gnuastro’s programs/libraries you aren’t limited to using the column’s number, see Section 4.8.3 [Selecting table columns], page 140. If the columns have
names, units, or comments you can also select your columns based on searches/matches in these fields, for example see Section 5.4 [Table], page 171. Also, in this manner, you can’t guide the program reading the table on how to read the numbers. As an example, the first and third columns above can be read as integer types: the first column might be an ID and the third can be the number of pixels an object occupies in an image. So there is no need to read these to columns as a \texttt{double} type (which takes more memory, and is slower).

In the bare-minimum example above, you also can’t use strings of characters, for example the names of filters, or some other identifier that includes non-numerical characters. In the absence of any information, only numbers can be read robustly. Assuming we read columns with non-numerical characters as string, there would still be the problem that the strings might contain space (or any delimiter) character for some rows. So, each ‘word’ in the string will be interpreted as a column and the program will abort with an error that the rows don’t have the same number of columns.

To correct for these limitations, Gnuastro defines the following convention for storing the table meta-data along with the raw data in one plain text file. The format is primarily designed for ease of reading/writing by eye/fingers, but is also structured enough to be read by a program.

When the first non-white character in a line is \#, or there are no non-white characters in it, then the line will not be considered as a row of data in the table (this is a pretty standard convention in many programs, and higher level languages). In the former case, the line is interpreted as a \textit{comment}. If the comment line starts with ‘\# Column N:’, then it is assumed to contain information about column N (a number, counting from 1). Comment lines that don’t start with this pattern are ignored and you can use them to include any further information you want to store with the table in the text file. A column information comment is assumed to have the following format:

\texttt{# Column N: NAME [UNIT, TYPE, BLANK] COMMENT}

Any sequence of characters between ‘:’ and ‘[’ will be interpreted as the column name (so it can contain anything except the ‘[’ character). Anything between the ‘]’ and the end of the line is defined as a comment. Within the brackets, anything before the first ‘,’ is the units (physical units, for example km/s, or erg/s), anything before the second ‘,’ is the short type identifier (see below, and Section 4.6 [Numeric data types], page 130).

Finally (still within the brackets), any non-white characters after the second ‘,’ are interpreted as the blank value for that column (see Section 6.1.3 [Blank pixels], page 191). The blank value can either be in the same type as the column (for example $-99$ for a signed integer column), or any string (for example NaN in that same column). In both cases, the values will be stored in memory as Gnuastro’s fixed blank values for each type. For floating point types, Gnuastro’s internal blank value is IEEE NaN (Not-a-Number). For signed integers, it is the smallest possible value and for unsigned integers its the largest possible value.

When a formatting problem occurs (for example you have specified the wrong type code, see below), or the column was already given meta-data in a previous comment, or the column number is larger than the actual number of columns in the table (the non-commented or empty lines), then the comment information line will be ignored.

When a comment information line can be used, the leading and trailing white space characters will be stripped from all of the elements. For example in this line:
The NAME field will be ‘column name’ and the TYPE field will be ‘f32’. Note how all
the white space characters before and after strings are not used, but those in the middle
remained. Also, white space characters aren’t mandatory. Hence, in the example above,
the BLANK field will be given the value of ‘-99’.

Except for the column number (N), the rest of the fields are optional. Also, the column
information comments don’t have to be in order. In other words, the information for
column N + m (m > 0) can be given in a line before column N. Also, you don’t have to
specify information for all columns. Those columns that don’t have this information will
be interpreted with the default settings (like the case above: values are double precision
floating point, and the column has no name, unit, or comment). So these lines are all
acceptable for any table (the first one, with nothing but the column number is redundant):

# Column 5: column name [km/s, f32,-99] Redshift as speed

The data type of the column should be specified with one of the following values:

- For a numeric column, you can use any of the numeric types (and their recognized
  identifiers) described in Section 4.6 [Numeric data types], page 130.
- ‘strN’: for strings. The N value identifies the length of the string (how many characters
  it has). The start of the string on each row is the first non-delimiter character of the
  column that has the string type. The next N characters will be interpreted as a string
  and all leading and trailing white space will be removed.

If the next column’s characters, are closer than N characters to the start of the string
column in that line/row, they will be considered part of the string column. If there is a
new-line character before the ending of the space given to the string column (in other
words, the string column is the last column), then reading of the string will stop, even
if the N characters are not complete yet. See tests/table/table.txt for one example.

Therefore, the only time you have to pay attention to the positioning and spaces given
to the string column is when it is not the last column in the table.

The only limitation in this format is that trailing and leading white space characters will
be removed from the columns that are read. In most cases, this is the desired behavior,
but if trailing and leading white-spaces are critically important to your analysis, define
your own starting and ending characters and remove them after the table has been read.

For example in the sample table below, the two ‘|’ characters (which are arbitrary) will
remain in the value of the second column and you can remove them manually later.

If only one of the leading or trailing white spaces is important for your work, you can
only use one of the ‘|’s.

# Column 1: ID [label, u8]
# Column 2: Notes [no unit, str50]
1 leading and trailing white space is ignored here 2.3442e10
2 | but they will be preserved here | 8.2964e11

Note that the FITS binary table standard does not define the unsigned int and
unsigned long types, so if you want to convert your tables to FITS binary tables, use
other types. Also, note that in the FITS ASCII table, there is only one integer type (long).
So if you convert a Gnuastro plain text table to a FITS ASCII table with the Section 5.4 [Table], page 171, program, the type information for integers will be lost. Conversely if integer types are important for you, you have to manually set them when reading a FITS ASCII table (for example with the Table program when reading/converting into a file, or with the gnuastro/table.h library functions when reading into memory).

### 4.8.3 Selecting table columns

At the lowest level, the only defining aspect of a column in a table is its number, or position. But selecting columns purely by number is not very convenient and, especially when the tables are large it can be very frustrating and prone to errors. Hence, table file formats (for example see Section 4.8.1 [Recognized table formats], page 136) have ways to store additional information about the columns (meta-data). Some of the most common pieces of information about each column are its name, the units of data in the it, and a comment for longer/informal description of the column’s data.

To facilitate research with Gnuastro, you can select columns by matching, or searching in these three fields, besides the low-level column number. To view the full list of information on the columns in the table, you can use the Table program (see Section 5.4 [Table], page 171) with the command below (replace table-file with the filename of your table, if its FITS, you might also need to specify the HDU/extension which contains the table):

```
$ asttable --information table-file
```

Gnuastro’s programs need the columns for different purposes, for example in Crop, you specify the columns containing the central coordinates of the crop centers with the --coordcol option (see Section 6.1.4.1 [Crop options], page 193). On the other hand, in MakeProfiles, to specify the column containing the profile position angles, you must use the --pcol option (see Section 8.1.5.1 [MakeProfiles catalog], page 342). Thus, there can be no unified common option name to select columns for all programs (different columns have different purposes). However, when the program expects a column for a specific context, the option names end in the col suffix like the examples above. These options accept values in integer (column number), or string (metadata match/search) format.

If the value can be parsed as a positive integer, it will be seen as the low-level column number. Note that column counting starts from 1, so if you ask for column 0, the respective program will abort with an error. When the value can’t be interpreted as an a integer number, it will be seen as a string of characters which will be used to match/search in the table’s meta-data. The meta-data field which the value will be compared with can be selected through the --searchin option, see Section 4.1.2.1 [Input/Output options], page 109. --searchin can take three values: name, unit, comment. The matching will be done following this convention:

- If the value is enclosed in two slashes (for example -x/RA_/, or --coordcol=/RA_/), see Section 6.1.4.1 [Crop options], page 193), then it is assumed to be a regular expression with the same convention as GNU AWK. GNU AWK has a very well written chapter (https://www.gnu.org/software/gawk/manual/html_node/Regexp.html) describing regular expressions, so we we will not continue discussing them here. Regular expressions are a very powerful tool in matching text and useful in many contexts. We thus strongly encourage reviewing this chapter for greatly improving the quality of your work in many cases, not just for searching column meta-data in Gnuastro.
• When the string isn’t enclosed between ‘/’s, any column that exactly matches the given value in the given field will be selected.

Note that in both cases, you can ignore the case of alphabetic characters with the **--ignorecase** option, see Section 4.1.2.1 [Input/Output options], page 109. Also, in both cases, multiple columns may be selected with one call to this function. In this case, the order of the selected columns (with one call) will be the same order as they appear in the table.

### 4.9 Tessellation

It is sometimes necessary to classify the elements in a dataset (for example pixels in an image) into a grid of individual, non-overlapping tiles. For example when background sky gradients are present in an image, you can define a tile grid over the image. When the tile sizes are set properly, the background’s variation over each tile will be negligible, allowing you to measure (and subtract) it. In other cases (for example spatial domain convolution in Gnuastro, see Section 6.3 [Convolve], page 216), it might simply be for speed of processing: each tile can be processed independently on a separate CPU thread. In the arts and mathematics, this process is formally known as *tessellation* ([https://en.wikipedia.org/wiki/Tessellation](https://en.wikipedia.org/wiki/Tessellation)).

The size of the regular tiles (in units of data-elements, or pixels in an image) can be defined with the **--tilesize** option. It takes multiple numbers (separated by a comma) which will be the length along the respective dimension (in FORTRAN/FITS dimension order). Divisions are also acceptable, but must result in an integer. For example **--tilesize=30,40** can be used for an image (a 2D dataset). The regular tile size along the first FITS axis (horizontal when viewed in SAO ds9) will be 30 pixels and along the second it will be 40 pixels. Ideally, **--tilesize** should be selected such that all tiles in the image have exactly the same size. In other words, that the dataset length in each dimension is divisible by the tile size in that dimension.

However, this is not always possible: the dataset can be any size and every pixel in it is valuable. In such cases, Gnuastro will look at the significance of the remainder length, if it is not significant (for example one or two pixels), then it will just increase the size of the first tile in the respective dimension and allow the rest of the tiles to have the required size. When the remainder is significant (for example one pixel less than the size along that dimension), the remainder will be added to one regular tile’s size and the large tile will be cut in half and put in the two ends of the grid/tessellation. In this way, all the tiles in the central regions of the dataset will have the regular tile sizes and the tiles on the edge will be slightly larger/smaller depending on the remainder significance. The fraction which defines the remainder significance along all dimensions can be set through **--remainderfrac**.

The best tile size is directly related to the spatial properties of the property you want to study (for example, gradient on the image). In practice we assume that the gradient is not present over each tile. So if there is a strong gradient (for example in long wavelength ground based images) or the image is of a crowded area where there isn’t too much blank area, you have to choose a smaller tile size. A larger mesh will give more pixels and and so the scatter in the results will be less (better statistics).

For raw image processing, a single tessellation/grid is not sufficient. Raw images are the unprocessed outputs of the camera detectors. Modern detectors usually have multiple
readout channels each with its own amplifier. For example the Hubble Space Telescope Advanced Camera for Surveys (ACS) has four amplifiers over its full detector area dividing the square field of view to four smaller squares. Ground based image detectors are not exempt, for example each CCD of Subaru Telescope’s Hyper Suprime-Cam camera (which has 104 CCDs) has four amplifiers, but they have the same height of the CCD and divide the width by four parts.

The bias current on each amplifier is different, and initial bias subtraction is not perfect. So even after subtracting the measured bias current, you can usually still identify the boundaries of different amplifiers by eye. See Figure 11(a) in Akhlaghi and Ichikawa (2015) for an example. This results in the final reduced data to have non-uniform amplifier-shaped regions with higher or lower background flux values. Such systematic biases will then propagate to all subsequent measurements we do on the data (for example photometry and subsequent stellar mass and star formation rate measurements in the case of galaxies).

Therefore an accurate analysis requires a two layer tessellation: the top layer contains larger tiles, each covering one amplifier channel. For clarity we’ll call these larger tiles “channels”. The number of channels along each dimension is defined through the --numchannels. Each channel is then covered by its own individual smaller tessellation (with tile sizes determined by the --tilesize option). This will allow independent analysis of two adjacent pixels from different channels if necessary. If the image is processed or the detector only has one amplifier, you can set the number of channels in both dimension to 1.

The final tessellation can be inspected on the image with the --checktiles option that is available to all programs which use tessellation for localized operations. When this option is called, a FITS file with a _tiled.fits suffix will be created along with the outputs, see Section 4.10 [Automatic output], page 142. Each pixel in this image has the number of the tile that covers it. If the number of channels in any dimension are larger than unity, you will notice that the tile IDs are defined such that the first channels is covered first, then the second and so on. For the full list of processing-related common options (including tessellation options), please see Section 4.1.2.2 [Processing options], page 112.

### 4.10 Automatic output

All the programs in Gnuastro are designed such that specifying an output file or directory (based on the program context) is optional. When no output name is explicitly given (with --output, see Section 4.1.2.1 [Input/Output options], page 109), the programs will automatically set an output name based on the input name(s) and what the program does. For example when you are using ConvertType to save FITS image named dataset.fits to a JPEG image and don’t specify a name for it, the JPEG output file will be name dataset.jpg. When the input is from the standard input (for example a pipe, see Section 4.1.3 [Standard input], page 118), and --output isn’t given, the output name will be the program’s name (for example converttype.jpg).

Another very important part of the automatic output generation is that all the directory information of the input file name is stripped off of it. This feature can be disabled with the --keepinputdir option, see Section 4.1.2.1 [Input/Output options], page 109. It is the
default because astronomical data are usually very large and organized specially with special
file names. In some cases, the user might not have write permissions in those directories\textsuperscript{13}.

Let’s assume that we are working on a report and want to process the FITS images from
two projects (ABC and DEF), which are stored in the sub-directories named ABCproject/
and DEFproject/ of our top data directory (/mnt/data). The following shell commands
show how one image from the former is first converted to a JPEG image through Convert-
Type and then the objects from an image in the latter project are detected using NoiseChisel.
The text after the # sign are comments (not typed!).

```
$ pwd # Current location
/home/username/research/report
$ ls # List directory contents
ABC01.jpg
$ ls /mnt/data/ABCproject # Archive 1
ABC01.fits ABC02.fits ABC03.fits
$ ls /mnt/data/DEFproject # Archive 2
DEF01.fits DEF02.fits DEF03.fits
$ astconvertt /mnt/data/ABCproject/ABC02.fits --output=jpg # Prog 1
$ ls
ABC01.jpg ABC02.jpg
$ astnoisechisel /mnt/data/DEFproject/DEF01.fits # Prog 2
$ ls
ABC01.jpg ABC02.jpg DEF01_detected.fits
```

### 4.11 Output FITS files

The output of many of Gnuastro’s programs are (or can be) FITS files. The FITS format
has many useful features for storing scientific datasets (cubes, images and tables) along with
a robust features for archivability. For more on this standard, please see Section 5.1 [Fits],
page 146.

As a community convention described in Section 5.1 [Fits], page 146, the first extension of
all FITS files produced by Gnuastro’s programs only contains the meta-data that is intended
for the file’s extension(s). For a Gnuastro program, this generic meta-data (that is stored
as FITS keyword records) is its configuration when it produced this dataset: file name(s)
of input(s) and option names, values and comments. Note that when the configuration is
too trivial (only input filename, for example the program Section 5.4 [Table], page 171) no
meta-data is written in this extension.

FITS keywords have the following limitations in regards to generic option names and
values which are described below:

- If a keyword (option name) is longer than 8 characters, the first word in the record (80
  character line) is \texttt{HIERARCH} which is followed by the keyword name.
- Values can be at most 75 characters, but for strings, this changes to 73 (because of
  the two extra '/' characters that are necessary). However, if the value is a file name,
  containing slash ('/') characters to separate directories, Gnuastro will break the value
  into multiple keywords.

\textsuperscript{13} In fact, even if the data is stored on your own computer, it is advised to only grant write permissions to
the super user or root. This way, you won’t accidentally delete or modify your valuable data!
• Keyword names ignore case, therefore they are all in capital letters. Therefore, if you want to use Grep to inspect these keywords, use the \texttt{-i} option, like the example below.

\texttt{$\ astfits$ \texttt{image_detected.fits} \texttt{-h0 \ | \ grep \ -i \ snquant}}

The keywords above are classified (separated by an empty line and title) as a group titled “ProgramName configuration”. This meta-data extension, as well as all the other extensions (which contain data), also contain have final group of keywords to keep the basic date and version information of Gnuastro, its dependencies and the pipeline that is using Gnuastro (if its under version control).

\begin{description}
\item[DATE] The creation time of the FITS file. This date is written directly by CFITSIO and is in UT format.
\item[COMMIT] Git’s commit description from the running directory of Gnuastro’s programs. If the running directory is not version controlled or libgit2 isn’t installed (see Section 3.1.2 [Optional dependencies], page 77) then this keyword will not be present. The printed value is equivalent to the output of the following command:

\begin{verbatim}
git describe --dirty --always
\end{verbatim}

If the running directory contains non-committed work, then the stored value will have a ‘\texttt{-dirty}’ suffix. This can be very helpful to let you know that the data is not ready to be shared with collaborators or submitted to a journal. You should only share results that are produced after all your work is committed (safely stored in the version controlled history and thus reproducible).

At first sight, version control appears to be mainly a tool for software developers. However progress in a scientific research is almost identical to progress in software development: first you have a rough idea that starts with handful of easy steps. But as the first results appear to be promising, you will have to extend, or generalize, it to make it more robust and work in all the situations your research covers, not just your first test samples. Slowly you will find wrong assumptions or bad implementations that need to be fixed (‘bugs’ in software development parlance). Finally, when you submit the research to your collaborators or a journal, many comments and suggestions will come in, and you have to address them.

Software developers have created version control systems precisely for this kind of activity. Each significant moment in the project’s history is called a “commit”, see Section 3.2.2 [Version controlled source], page 85. A snapshot of the project in each “commit” is safely stored away, so you can revert back to it at a later time, or check changes/progress. This way, you can be sure that your work is reproducible and track the progress and history. With version control, experimentation in the project’s analysis is greatly facilitated, since you can easily revert back if a brainstorm test procedure fails.

One important feature of version control is that the research result (FITS image, table, report or paper) can be stamped with the unique commit information that produced it. This information will enable you to exactly reproduce that same result later, even if you have made changes/progress. For one example of a research paper’s reproduction pipeline, please see the reproduction pipeline (https://gitlab.com/makhlaghi/NoiseChisel-paper) of the paper
Chapter 4: Common program behavior


**CFITSIO**  The version of CFITSIO used (see Section 3.1.1.2 [CFITSIO], page 75).

**WCSLIB**  The version of WCSLIB used (see Section 3.1.1.3 [WCSLIB], page 76). Note that older versions of WCSLIB do not report the version internally. So this is only available if you are using more recent WCSLIB versions.

**GSL**  The version of GNU Scientific Library that was used, see Section 3.1.1.1 [GNU Scientific library], page 75.

**GNUASTRO**  The version of Gnuastro used (see Section 1.5 [Version numbering], page 7).

Here is one example of the last few lines of an example output.

```
/ Versions and date
DATE = '...' / file creation date
COMMIT = 'v0-8-g547f6eb' / Commit description in running dir.
CFITSIO = '3.45 ' / CFITSIO version.
WCSLIB = '5.19 ' / WCSLIB version.
GSL = '2.5 ' / GNU Scientific Library version.
GNUASTRO= '0.7 ' / GNU Astronomy Utilities version.
END
```
5 Data containers

The most low-level and basic property of a dataset is how it is stored. To process, archive and transmit the data, you need a container to store it first. From the start of the computer age, different formats have been defined to store data, optimized for particular applications. One format/container can never be useful for all applications: the storage defines the application and vice-versa. In astronomy, the Flexible Image Transport System (FITS) standard has become the most common format of data storage and transmission. It has many useful features, for example multiple sub-containers (also known as extensions or header data units, HDUs) within one file, or support for tables as well as images. Each HDU can store an independent dataset and its corresponding meta-data. Therefore, Gnuastro has one program (see Section 5.1 [Fits], page 146) specifically designed to manipulate FITS HDUs and the meta-data (header keywords) in each HDU.

Your astronomical research does not just involve data analysis (where the FITS format is very useful). For example you want to demonstrate your raw and processed FITS images or spectra as figures within slides, reports, or papers. The FITS format is not defined for such applications. Thus, Gnuastro also comes with the ConvertType program (see Section 5.3 [ConvertType], page 162) which can be used to convert a FITS image to and from (where possible) other formats like plain text and JPEG (which allow two way conversion), along with EPS and PDF (which can only be created from FITS, not the other way round).

Finally, the FITS format is not just for images, it can also store tables. Binary tables in particular can be very efficient in storing catalogs that have more than a few tens of columns and rows. However, unlike images (where all elements/pixels have one data type), tables contain multiple columns and each column can have different properties: independent data types (see Section 4.6 [Numeric data types], page 130) and meta-data. In practice, each column can be viewed as a separate container that is grouped with others in the table. The only shared property of the columns in a table is thus the number of elements they contain. To allow easy inspection/manipulation of table columns, Gnuastro has the Table program (see Section 5.4 [Table], page 171). It can be used to select certain table columns in a FITS table and see them as a human readable output on the command-line, or to save them into another plain text or FITS table.

5.1 Fits

The “Flexible Image Transport System”, or FITS, is by far the most common data container format in astronomy and in constant use since the 1970s. Archiving (future usage, simplicity) has been one of the primary design principles of this format. In the last few decades it has proved so useful and robust that the Vatican Library has also chosen FITS for its “long-term digital preservation” project\(^1\).

Although the full name of the standard invokes the idea that it is only for images, it also contains complete and robust features for tables. It started off in the 1970s and was formally published as a standard in 1981, it was adopted by the International Astronomical Union (IAU) in 1982 and an IAU working group to maintain its future was defined in 1988. The FITS 2.0 and 3.0 standards were approved in 2000 and 2008 respectively, and the 4.0 draft has also been released recently, please see the FITS standard document webpage (https:// www.vaticanlibrary.va/home.php?pag=progettodigit

\(^1\) https://www.vaticanlibrary.va/home.php?pag=progettodigit
fits.gsfc.nasa.gov/fits_standard.html) for the full text of all versions. Also see the FITS 3.0 standard paper (https://doi.org/10.1051/0004-6361/201015362) for a nice introduction and history along with the full standard.

Many common image formats, for example a JPEG, only have one image/dataset per file, however one great advantage of the FITS standard is that it allows you to keep multiple datasets (images or tables along with their separate meta-data) in one file. In the FITS standard, each data + metadata is known as an extension, or more formally a header data unit or HDU. The HDUs in a file can be completely independent: you can have multiple images of different dimensions/sizes or tables as separate extensions in one file. However, while the standard doesn’t impose any constraints on the relation between the datasets, it is strongly encouraged to group data that are contextually related with each other in one file. For example an image and the table/catalog of objects and their measured properties in that image. Other examples can be images of one patch of sky in different colors (filters), or one raw telescope image along with its calibration data (tables or images).

As discussed above, the extensions in a FITS file can be completely independent. To keep some information (meta-data) about the group of extensions in the FITS file, the community has adopted the following convention: put no data in the first extension, so it is just meta-data. This extension can thus be used to store Meta-data regarding the whole file (grouping of extensions). Subsequent extensions may contain data along with their own separate meta-data. All of Gnuastro’s programs also follow this convention: the main output dataset(s) are placed in the second (or later) extension(s). The first extension contains no data the program’s configuration (input file name, along with all its option values) are stored as its meta-data, see Section 4.11 [Output FITS files], page 143.

The meta-data contain information about the data, for example which region of the sky an image corresponds to, the units of the data, what telescope, camera, and filter the data were taken with, its observation date, or the software that produced it and its configuration. Without the meta-data, the raw dataset is practically just a collection of numbers and really hard to understand, or connect with the real world (other datasets). It is thus strongly encouraged to supplement your data (at any level of processing) with as much meta-data about your processing/science as possible.

The meta-data of a FITS file is in ASCII format, which can be easily viewed or edited with a text editor or on the command-line. Each meta-data element (known as a keyword generally) is composed of a name, value, units and comments (the last two are optional). For example below you can see three FITS meta-data keywords for specifying the world coordinate system (WCS, or its location in the sky) of a dataset:

LATPOLE = -27.805089 / [deg] Native latitude of celestial pole
RADESYS = 'FK5' / Equatorial coordinate system
EQUINOX = 2000.0 / [yr] Equinox of equatorial coordinates

However, there are some limitations which discourage viewing/editing the keywords with text editors. For example there is a fixed length of 80 characters for each keyword (its name, value, units and comments) and there are no new-line characters, so on a text editor all the keywords are seen in one line. Also, the meta-data keywords are immediately followed by the data which are commonly in binary format and will show up as strange looking characters on a text editor, and significantly slowing down the processor.
Gnuastro’s Fits program was designed to allow easy manipulation of FITS extensions and meta-data keywords on the command-line while conforming fully with the FITS standard. For example you can copy or cut (copy and remove) HDUs/extensions from one FITS file to another, or completely delete them. It also has features to delete, add, or edit meta-data keywords within one HDU.

5.1.1 Invoking Fits

Fits can print or manipulate the FITS file HDUs (extensions), meta-data keywords in a given HDU. The executable name is astfits with the following general template

```
$ astfits [OPTION...] ASTRdata
```

One line examples:

```
## View general information about every extension:
$ astfits image.fits

## Print the header keywords in the second HDU (counting from 0):
$ astfits image.fits -h1

## Only print header keywords that contain ‘NAXIS’:
$ astfits image.fits -h1 | grep NAXIS

## Only print the WCS standard PC matrix elements
$ astfits image.fits -h1 | grep 'PC._.'

## Copy a HDU from input.fits to out.fits:
$ astfits input.fits --copy=hdu-name --output=out.fits

## Update the OLDKEY keyword value to 153.034:
$ astfits --update=OLDKEY,153.034,"Old keyword comment"

## Delete one COMMENT keyword and add a new one:
$ astfits --delete=COMMENT --comment="Anything you like ;-)"

## Write two new keywords with different values and comments:
$ astfits --write=MYKEY1,20.00,"An example keyword" --write=MYKEY2,fd
```

When no action is requested (and only a file name is given), Fits will print a list of information about the extension(s) in the file. This information includes the HDU number, HDU name (EXTNAME keyword), type of data (see Section 4.6 [Numeric data types], page 130, and the number of data elements it contains (size along each dimension for images and table rows and columns). You can use this to get a general idea of the contents of the FITS file and what HDU to use for further processing, either with the Fits program or any other Gnuastro program.

Here is one example of information about a FITS file with four extensions: the first extension has no data, it is a purely meta-data HDU (commonly used to keep meta-data about the whole file, or grouping of extensions, see Section 5.1 [Fits], page 146). The second extension is an image with name IMAGE and single precision floating point type (float32, see Section 4.6 [Numeric data types], page 130), it has 4287 pixels along its first (horizontal)
axis and 4286 pixels along its second (vertical) axis. The third extension is also an image with name MASK. It is in 2-byte integer format (int16) which is commonly used to keep information about pixels (for example to identify which ones were saturated, or which ones had cosmic rays and so on), note how it has the same size as the IMAGE extension. The third extension is a binary table called CATALOG which has 12371 rows and 5 columns (it probably contains information about the sources in the image).

GNU Astronomy Utilities X.X
Run on Day Month DD HH:MM:SS YYYY
-----
HDU (extension) information: ‘image.fits’.
Column 1: Index (counting from 0).
Column 2: Name (‘EXTNAME’ in FITS standard).
Column 3: Image data type or ‘table’ format (ASCII or binary).
Column 4: Size of data in HDU.
-----
0 n/a uint8 0
1 IMAGE float32 4287x4286
2 MASK int16 4287x4286
3 CATALOG table_binary 12371x5

If a specific HDU is identified on the command-line with the --hdu (or -h option) and no operation requested, then the full list of header keywords in that HDU will be printed (as if the --printallkeys was called, see below). It is important to remember that this only occurs when --hdu is given on the command-line. The --hdu value given in a configuration file will only be used when a specific operation on keywords requested. Therefore as described in the paragraphs above, when no explicit call to the --hdu option is made on the command-line and no operation is requested (on the command-line or configuration files), the basic information of each HDU/extension is printed.

The operating mode and input/output options to Fits are similar to the other programs and fully described in Section 4.1.2 [Common options], page 109. The options particular to Fits can be divided into two groups: 1) those related to modifying HDUs or extensions (see Section 5.1.1.1 [HDU information and manipulation], page 149), and 2) those related to viewing/modifying meta-data keywords (see Section 5.1.1.2 [Keyword manipulation], page 152). These two classes of options cannot be called together in one run: you can either work on the extensions or meta-data keywords in any instance of Fits.

5.1.1.1 HDU information and manipulation

Each FITS file header data unit, or HDU (also known as an extension) is an independent dataset (data + meta-data). Multiple HDUs can be stored in one FITS file, see Section 5.1 [Fits], page 146. The general HDU-related options to the Fits program are listed below as two general classes: the first group below focus on HDU information while the latter focus on manipulating (moving or deleting) the HDUs.

The options below print information about the given HDU on the command-line. Thus they cannot be called together in one command (each has its own independent output).
-n
--numhdus

Print the number of extensions/HDUs in the given file. Note that this option must be called alone and will only print a single number. It is thus useful in scripts, for example when you need to do check the number of extensions in a FITS file.

For a complete list of basic meta-data on the extensions in a FITS file, don’t use any of the options in this section or in Section 5.1.1.2 [Keyword manipulation], page 152. For more, see Section 5.1.1 [Invoking Fits], page 148.

--pixelscale

Print the HDU’s pixel-scale (change in world coordinate for one pixel along each dimension) and pixel area or voxel volume. Without the --quiet option, the output of --pixelscale has multiple lines and explanations, thus being more human-friendly. It prints the file/HDU name, number of dimensions, and the units along with the actual pixel scales. Also, when any of the units are in degrees, the pixel scales and area/volume are also printed in units of arcsecs. For 3D datasets, the pixel area (on each 2D slice of the 3D cube) is printed as well as the voxel volume.

However, in scripts (that are to be run automatically), this human-friendly format is annoying, so when called with the --quiet option, only the pixel-scale value(s) along each dimension is(are) printed in one line. These numbers are followed by the pixel area (in the raw WCS units). For 3D datasets, this will be area on each 2D slice. Finally, for 3D datasets, a final number (the voxel volume) is printed. As a summary, in --quiet mode, for 2D datasets three numbers are printed and for 3D datasets, 5 numbers are printed.

--skycoverage

Print the rectangular area (or 3D cube) covered by the given image/datacube HDU over the Sky in the WCS units. The covered area is reported in two ways: 1) the center and full width in each dimension, 2) the minimum and maximum sky coordinates in each dimension. This is option is thus useful when you want to get a general feeling of a new image/dataset, or prepare the inputs to query external databases in the region of the image (for example with Section 5.5 [Query], page 183).

If run without the --quiet option, the values are given with a human-friendly description. For example here is the output of this option on an image taken near the star Castor:

$ astfits castor.fits --skycoverage

Input file: castor.fits (hdu: 1)

Sky coverage by center and (full) width:
  Center: 113.9149075  31.93759664
  Width:  2.41762045   2.67945253

Sky coverage by range along dimensions:
  RA    112.7235592    115.1411797
With the --quiet option, the values are more machine-friendly (easy to parse). It has two lines, where the first line contains the center/width values and the second line shows the coordinate ranges in each dimension.

$ astfits castor.fits --skycoverage --quiet

113.9149075  31.93759664  2.41762045  2.67945253
112.7235592  115.1411797  30.59262123  33.27207376

Note that this is a simple rectangle (cube in 3D) definition, so if the image is rotated in relation to the celestial coordinates a general polygon is necessary to exactly describe the coverage. Hence when there is rotation, the reported area will be larger than the actual area containing data, you can visually see the area with the --align option of Section 6.4 [Warp], page 238.

--datasum
Calculate and print the given HDU's "datasum" to stdout. The given HDU is specified with the --hdu (or -h) option. This number is calculated by parsing all the bytes of the given HDU's data records (excluding keywords). This option ignores any possibly existing DATASUM keyword in the HDU. For more on the datasum feature of the FITS standard, see Section 5.1.1.2 [Keyword manipulation], page 152, (under the checksum component of --write).

You can use this option to confirm that the data in two different HDUs (possibly with different keywords) is identical. Its advantage over --write=datasum (which writes the DATASUM keyword into the given HDU) is that it doesn't require write permissions.

The following options manipulate (move/delete) the HDUs in one FITS file or to another FITS file. These options may be called multiple times in one run. If so, the extensions will be copied from the input FITS file to the output FITS file in the given order (on the command-line and also in configuration files, see Section 4.2.2 [Configuration file precedence], page 121). If the separate classes are called together in one run of Fits, then first --copy is run (on all specified HDUs), followed by --cut (again on all specified HDUs), and then --remove (on all specified HDUs).

The --copy and --cut options need an output FITS file (specified with the --output option). If the output file exists, then the specified HDU will be copied following the last extension of the output file (the existing HDUs in it will be untouched). Thus, after Fits finishes, the copied HDU will be the last HDU of the output file. If no output file name is given, then automatic output will be used to store the HDUs given to this option (see Section 4.10 [Automatic output], page 142).

-C STR
--copy=STR

Copy the specified extension into the output file, see explanations above.

-k STR
--cut=STR

Cut (copy to output, remove from input) the specified extension into the output file, see explanations above.
-R STR
--remove=STR
Remove the specified HDU from the input file.
The first (zero-th) HDU cannot be removed with this option. Consider using
--copy or --cut in combination with primaryimghdu to not have an empty
zero-th HDU. From CFITSIO: “In the case of deleting the primary array (the
first HDU in the file) then [it] will be replaced by a null primary array containing
the minimum set of required keywords and no data.”. So in practice, any
existing data (array) and meta-data in the first extension will be removed, but
the number of extensions in the file won’t change. This is because of the unique
position the first FITS extension has in the FITS standard (for example it
cannot be used to store tables).

--primaryimghdu
Copy or cut an image HDU to the zero-th HDU/extension a file that doesn’t
yet exist. This option is thus irrelevant if the output file already exists or the
copied/cut extension is a FITS table. For example with the commands below,
first we make sure that out.fits doesn’t exist, then we copy the first extension
of in.fits to the zero-th extension of out.fits.

```bash
$ rm -f out.fits
$ astfits in.fits --copy=1 --primaryimghdu --output=out.fits
```
If we hadn’t used --primaryimghdu, then the zero-th extension of out.fits
would have no data, and its second extension would host the copied image (just
like any other output of Gnuastro).

5.1.1.2 Keyword manipulation
The meta-data in each header data unit, or HDU (also known as extension, see Section 5.1
[Fits], page 146) is stored as “keyword”s. Each keyword consists of a name, value, unit, and
comments. The Fits program (see Section 5.1 [Fits], page 146) options related to viewing
and manipulating keywords in a FITS HDU are described below.

To see the full list of keywords in a FITS HDU, you can use the --printallkeys option.
If any of the keywords are to be modified, the headers of the input file will be changed. If
you want to keep the original FITS file or HDU, it is easiest to create a copy first and then
run Fits on that. In the FITS standard, keywords are always uppercase. So case does not
matter in the input or output keyword names you specify.

Most of the options can accept multiple instances in one command. For example you
can add multiple keywords to delete by calling --delete multiple times, since repeated
keywords are allowed, you can even delete the same keyword multiple times. The action of
such options will start from the top most keyword.

The precedence of operations are described below. Note that while the order within each
class of actions is preserved, the order of individual actions is not. So irrespective of what
order you called --delete and --update. First, all the delete operations are going to take
effect then the update operations.

1. --delete
2. --rename
3. --update
4. --write
5. --asis
6. --history
7. --comment
8. --date
9. --printallkeys
10. --verify
11. --copykeys

All possible syntax errors will be reported before the keywords are actually written. FITS errors during any of these actions will be reported, but Fits won’t stop until all the operations are complete. If --quitonerror is called, then Fits will immediately stop upon the first error.

If you want to inspect only a certain set of header keywords, it is easiest to pipe the output of the Fits program to GNU Grep. Grep is a very powerful and advanced tool to search strings which is precisely made for such situations. For example if you only want to check the size of an image FITS HDU, you can run:

```
$ astfits input.fits | grep NAXIS
```

**FITS STANDARD KEYWORDS:** Some header keywords are necessary for later operations on a FITS file, for example BITPIX or NAXIS, see the FITS standard for their full list. If you modify (for example remove or rename) such keywords, the FITS file extension might not be usable any more. Also be careful for the world coordinate system keywords, if you modify or change their values, any future world coordinate system (like RA and Dec) measurements on the image will also change.

The keyword related options to the Fits program are fully described below.

-a STR
--asis=STR

Write STR exactly into the FITS file header with no modifications. If it does not conform to the FITS standards, then it might cause trouble, so please be very careful with this option. If you want to define the keyword from scratch, it is best to use the --write option (see below) and let CFITSIO worry about the standards. The best way to use this option is when you want to add a keyword from one FITS file to another unchanged and untouched. Below is an example of such a case that can be very useful sometimes (on the command-line or in scripts):

```
$ key=$(astfits firstimage.fits | grep KEYWORD)
$ astfits --asis="$key" secondimage.fits
```

In particular note the double quotation signs (") around the reference to the key shell variable ($key). FITS keywords usually have lots of space characters, if this variable is not quoted, the shell will only give the first word in the full keyword to this option, which will definitely be a non-standard FITS keyword.
and will make it hard to work on the file afterwords. See the “Quoting” section of the GNU Bash manual for more information if your keyword has the special characters $, ‘, or \\.

-d STR
--delete=STR
Delete one instance of the STR keyword from the FITS header. Multiple instances of --delete can be given (possibly even for the same keyword, when its repeated in the meta-data). All keywords given will be removed from the headers in the same given order. If the keyword doesn't exist, Fits will give a warning and return with a non-zero value, but will not stop. To stop as soon as an error occurs, run with --quitonerror.

-r STR
--rename=STR
Rename a keyword to a new value. STR contains both the existing and new names, which should be separated by either a comma (,) or a space character. Note that if you use a space character, you have to put the value to this option within double quotation marks (") so the space character is not interpreted as an option separator. Multiple instances of --rename can be given in one command. The keywords will be renamed in the specified order. If the keyword doesn't exist, Fits will give a warning and return with a non-zero value, but will not stop. To stop as soon as an error occurs, run with --quitonerror.

-u STR
--update=STR
Update a keyword, its value, its comments and its units in the format described below. If there are multiple instances of the keyword in the header, they will be changed from top to bottom (with multiple --update options).

The format of the values to this option can best be specified with an example:

--update=KEYWORD,value,"comments for this keyword",unit

If there is a writing error, Fits will give a warning and return with a non-zero value, but will not stop. To stop as soon as an error occurs, run with --quitonerror.

The value can be any numerical or string value. Other than the KEYWORD, all the other values are optional. To leave a given token empty, follow the preceding comma (,) immediately with the next. If any space character is present around the commas, it will be considered part of the respective token. So if more than one token has space characters within it, the safest method to specify a value to this option is to put double quotation marks around each individual token.

2 Some tricky situations arise with values like ‘87095e5’, if this was intended to be a number it will be kept in the header as 8709500000 and there is no problem. But this can also be a shortened Git commit hash. In the latter case, it should be treated as a string and stored as it is written. Commit hashes are very important in keeping the history of a file during your research and such values might arise without you noticing them in your reproduction pipeline. One solution is to use git describe instead of the short hash alone. A less recommended solution is to add a space after the commit hash and Fits will write the value as ‘87095e5 ’ in the header. If you later compare the strings on the shell, the space character will be ignored by the shell in the latter solution and there will be no problem.
that needs it. Note that without double quotation marks, space characters will be seen as option separators and can lead to undefined behavior.

-\texttt{w STR}
-\texttt{--write=STR}

Write a keyword to the header. For the possible value input formats, comments and units for the keyword, see the \texttt{--update} option above. The special names (first string) below will cause a special behavior:

\texttt{/} Write a “title” to the list of keywords. A title consists of one blank line and another which is blank for several spaces and starts with a slash (/). The second string given to this option is the “title” or string printed after the slash. For example with the command below you can add a “title” of ‘My keywords’ after the existing keywords and add the subsequent K1 and K2 keywords under it (note that keyword names are not case sensitive).

\begin{verbatim}$ astfits test.fits -h1 --write=/,"My keywords" \--write=k1,1.23,"My first keyword" \--write=k2,4.56,"My second keyword"$ astfits test.fits -h1
[[[ ... truncated ... ]]]
\end{verbatim}

/ My keywords
K1 = 1.23 / My first keyword
K2 = 4.56 / My second keyword
END

Adding a “title” before each contextually separate group of header keywords greatly helps in readability and visual inspection of the keywords. So generally, when you want to add new FITS keywords, its good practice to also add a title before them.

The reason you need to use / as the keyword name for setting a title is that / is the first non-white character.

The title(s) is(are) written into the FITS with the same order that \texttt{--write} is called. Therefore in one run of the Fits program, you can specify many different titles (with their own keywords under them). For example the command below that builds on the previous example and adds another group of keywords named A1 and A2.

\begin{verbatim}$ astfits test.fits -h1 --write=/,"My keywords" \--write=k1,1.23,"My first keyword" \--write=k2,4.56,"My second keyword" \--write=/,"My second group of keywords" \--write=a1,7.89,"First keyword" \--write=a2,0.12,"Second keyword"$ astfits test.fits -h1
[[[ ... truncated ... ]]]
\end{verbatim}

/ My keywords
K1 = 1.23 / My first keyword
K2 = 4.56 / My second keyword
A1 = 7.89 / First keyword
A2 = 0.12 / Second keyword
END

\textbf{checksum} When nothing is given afterwards, the header integrity keywords DATASUM and CHECKSUM will be calculated and written/updated. This is calculation and writing is done fully by CFITSIO. They thus
comply with the FITS standard 4.0\(^3\) that defines these keywords (its Appendix J).

If a value is given (e.g., `--write=checksum,MyOwnCheckSum`), then CFITSIO won’t be called to calculate these two keywords and the value (as well as possible comment and unit) will be written just like any other keyword. This is generally not recommended, but necessary in special circumstances (for example when the checksum needs to be manually updated).

**DATASUM** only depends on the data section of the HDU/extension, so it is not changed when you update the keywords. But **CHECKSUM** also depends on the header and will not be valid if you make any further changes to the header. This includes any further keyword modification options in the same call to the Fits program. Therefore it is recommended to write these keywords as the last keywords that are written/modified in the extension. You can use the **--verify** option (described below) to verify the values of these two keywords.

**datasum** Similar to checksum, but only write the DATASUM keyword (that doesn’t depend on the header keywords, only the data).

**-H STR**

**--history STR**

Add a HISTORY keyword to the header with the given value. A new HISTORY keyword will be created for every instance of this option. If the string given to this option is longer than 70 characters, it will be separated into multiple keyword cards. If there is an error, Fits will give a warning and return with a non-zero value, but will not stop. To stop as soon as an error occurs, run with **--quitonerror**.

**-c STR**

**--comment STR**

Add a COMMENT keyword to the header with the given value. Similar to the explanation for **--history** above.

**-t**

**--date**

Put the current date and time in the header. If the DATE keyword already exists in the header, it will be updated. If there is a writing error, Fits will give a warning and return with a non-zero value, but will not stop. To stop as soon as an error occurs, run with **--quitonerror**.

**-p**

**--printallkeys**

Print all the keywords in the specified FITS extension (HDU) on the command-line. If this option is called along with any of the other keyword editing commands, as described above, all other editing commands take precedence to this. Therefore, it will print the final keywords after all the editing has been done.

\(^3\) https://fits.gsfc.nasa.gov/standard40/fits_standard40aa-le.pdf
-v
--verify Verify the DATASUM and CHECKSUM data integrity keywords of the FITS standard. See the description under the checksum (under --write, above) for more on these keywords.

This option will print Verified for both keywords if they can be verified. Otherwise, if they don’t exist in the given HDU/extension, it will print NOT-PRESENT, and if they cannot be verified it will print INCORRECT. In the latter case (when the keyword values exist but can’t be verified), the Fits program will also return with a failure.

By default this function will also print a short description of the DATASUM AND CHECKSUM keywords. You can suppress this extra information with --quiet option.

--copykeys=INT:INT
Copy the input’s keyword records in the given range (inclusive) to the output HDU (specified with the --output and --outhdu options, for the filename and HDU/extension respectively).

The given string to this option must be two integers separated by a colon (:). The first integer must be positive (counting of the keyword records starts from 1). The second integer may be negative (zero is not acceptable) or an integer larger than the first.

A negative second integer means counting from the end. So -1 is the last copy-able keyword (not including the END keyword).

To see the header keywords of the input with a number before them, you can pipe the output of the FITS program (when it prints all the keywords in an extension) into the cat program like below:

```bash
$ astfits input.fits -h1 | cat -n
```

--outhdu The HDU/extension to write the output keywords of --copykeys.

-Q
--quitonerror Quit if any of the operations above are not successful. By default if an error occurs, Fits will warn the user of the faulty keyword and continue with the rest of actions.

-s STR
--datetosec STR
Interpret the value of the given keyword in the FITS date format (most generally: YYYY-MM-DDThh:mm:ss.ddd...) and return the corresponding Unix epoch time (number of seconds that have passed since 00:00:00 Thursday, January 1st, 1970). The Thh:mm:ss.ddd... section (specifying the time of day), and also the .ddd... (specifying the fraction of a second) are optional. The value to this option must be the FITS keyword name that contains the requested date, for example --datetosec=DATE-OBS.

This option can also interpret the older FITS date format (DD/MM/YYThh:mm:ss.ddd...) where only two characters are given to the year. In this case (following the GNU C Library), this option will make
the following assumption: values 68 to 99 correspond to the years 1969 to 1999, and values 0 to 68 as the years 2000 to 2068.

This is a very useful option for operations on the FITS date values, for example sorting FITS files by their dates, or finding the time difference between two FITS files. The advantage of working with the Unix epoch time is that you don’t have to worry about calendar details (for example the number of days in different months, or leap years, etc).

--wcsdistortion STR

If the argument has a WCS distortion, the output (file given with the --output option) will have the distortion given to this option (for example SIP, TPV). With this option, the FITS program will read the minimal set of keywords from the input HDU and the HDU data, it will then write them into the file given to the --output option but with a newly created set of WCS-related keywords corresponding to the desired distortion standard.

If no --output file is specified, an automatically generated output name will be used which is composed of the input’s name but with the -DDD.fits suffix, see Section 4.10 [Automatic output], page 142. Where DDD is the value given to this option (desired output distortion).

Note that all possible conversions between all standards are not yet supported. If the requested conversion is not supported, an informative error message will be printed. If this happens, please let us know and we’ll try our best to add the respective conversions.

For example with the command below, you can be sure that if in.fits has a distortion in its WCS, the distortion of out.fits will be in the SIP standard.

```
$ astfits in.fits --wcsdistortion=SIP --output=out.fits
```

5.2 Sort FITS files by night

FITS images usually contain (several) keywords for preserving important dates. In particular, for lower-level data, this is usually the observation date and time (for example, stored in the DATE-OBS keyword value). When analyzing observed datasets, many calibration steps (like the dark, bias or flat-field), are commonly calculated on a per-observing-night basis.

However, the FITS standard’s date format (YYYY-MM-DDTh:mm:ss.ddd) is based on the western (Gregorian) calendar. Dates that are stored in this format are complicated for automatic processing: a night starts in the final hours of one calendar day, and extends to the early hours of the next calendar day. As a result, to identify datasets from one night, we commonly need to search for two dates. However calendar peculiarities can make this identification very difficult. For example when an observation is done on the night separating two months (like the night starting on March 31st and going into April 1st), or two years (like the night starting on December 31st 2018 and going into January 1st, 2019). To account for such situations, it is necessary to keep track of how many days are in a month, and leap years, etc.

Gnuastro’s astscript-sort-by-night script is created to help in such important scenarios. It uses Section 5.1 [Fits], page 146, to convert the FITS date format into the Unix epoch time (number of seconds since 00:00:00 of January 1st, 1970), using the --datetosec
option. The Unix epoch time is a single number (integer, if not given in sub-second precision), enabling easy comparison and sorting of dates after January 1st, 1970.

You can use this script as a basis for making a much more highly customized sorting script. Here are some examples

- If you need to copy the files, but only need a single extension (not the whole file), you can add a step just before the making of the symbolic links, or copies, and change it to only copy a certain extension of the FITS file using the Fits program's --copy option, see Section 5.1.1.1 [HDU information and manipulation], page 149.

- If you need to classify the files with finer detail (for example the purpose of the dataset), you can add a step just before the making of the symbolic links, or copies, to specify a file-name prefix based on other certain keyword values in the files. For example when the FITS files have a keyword to specify if the dataset is a science, bias, or flat-field image. You can read it and to add a sci-, bias-, or flat- to the created file (after the --prefix) automatically.

For example, let's assume the observing mode is stored in the hypothetical MODE keyword, which can have three values of BIAS-IMAGE, SCIENCE-IMAGE and FLAT-EXP. With the step below, you can generate a mode-prefix, and add it to the generated link/copy names (just correct the filename and extension of the first line to the script's variables):

```
modepref=$(astfits infile.fits -h1 / 
| sed -e"s/'/ /g" / 
| awk '{if($1=="MODE") 
if($3=="BIAS-IMAGE") print "bias-"; 
else if($3=="SCIENCE-IMAGE") print "sci-"; 
else if($3==FLAT-EXP) print "flat-"; 
else print $3, "NOT recognized"; exit 1}')
```

Here is a description of it. We first use astfits to print all the keywords in extension 1 of infile.fits. In the FITS standard, string values (that we are assuming here) are placed in single quotes (' ') which are annoying in this context/use-case. Therefore, we pipe the output of astfits into sed to remove all such quotes (substituting them with a blank space). The result is then piped to AWK for giving us the final mode-prefix: with $1=="MODE", we ask AWK to only consider the line where the first column is MODE. There is an equal sign between the key name and value, so the value is the third column ($3 in AWK). We thus use a simple if-else structure to look into this value and print our custom prefix based on it. The output of AWK is then stored in the modepref shell variable which you can add to the link/copy name.

With the solution above, the increment of the file counter for each night will be independent of the mode. If you want the counter to be mode-dependent, you can add a different counter for each mode and use that counter instead of the generic counter for each night (based on the value of modepref). But we'll leave the implementation of this step to you as an exercise.

### 5.2.1 Invoking astscript-sort-by-night

This installed script will read a FITS date formatted value from the given keyword, and classify the input FITS files into individual nights. For more on installed scripts please see
(see Section 4.4 [Installed scripts], page 126). This script can be used with the following general template:

```
$ astscript-sort-by-night [OPTION...] FITS-files
```

One line examples:

```
## Use the DATE-OBS keyword
$ astscript-sort-by-night --key=DATE-OBS /path/to/data/*.fits

## Make links to the input files with the 'img-' prefix
$ astscript-sort-by-night --link --prefix=img- /path/to/data/*.fits
```

This script will look into a HDU/extension (`--hdu`) for a keyword (`--key`) in the given FITS files and interpret the value as a date. The inputs will be separated by "night"s (9:00 a.m. to next day’s 8:59:59 a.m, spanning two calendar days, exact hour can be set with `--hour`).

The default output is a list of all the input files along with the following two columns: night number and file number in that night (sorted by time). With `--link` a symbolic link will be made (one for each input) that contains the night number, and number of file in that night (sorted by time), see the description of `--link` for more. When `--copy` is used instead of a link, a copy of the inputs will be made instead of symbolic link.

Below you can see one example where all the `target-*.fits` files in the `data` directory should be separated by observing night according to the `DATE-OBS` keyword value in their second extension (number 1, recall that HDU counting starts from 0). You can see the output after the `ls` command.

```
$ astscript-sort-by-night -p img- -h1 -k DATE-OBS data/target-*.fits
$ ls
  img-n1-1.fits img-n1-2.fits img-n2-1.fits ...
```

The outputs can be placed in a different (already existing) directory by including that directory’s name in the `--prefix` value, for example `--prefix=sorted/img-` will put them all under the `sorted` directory.

This script can be configured like all Gnuastro’s programs (through command-line options, see Section 4.1.2 [Common options], page 109), with some minor differences that are described in Section 4.4 [Installed scripts], page 126. The particular options to this script are listed below:

- `h STR`  
  `--hdu=STR`
  
  The HDU/extension to use in all the given FITS files. All of the given FITS files must have this extension.

- `k STR`  
  `--key=STR`
  
  The keyword name that contains the FITS date format to classify/sort by.

- `H FLT`  
  `--hour=FLT`
  
  The hour that defines the next “night”. By default, all times before 9:00 a.m. are considered to belong to the previous calendar night. If a sub-hour value
is necessary, it should be given in units of hours, for example \texttt{--hour=9.5} corresponds to 9:30 a.m.

\begin{mdframed}[backgroundcolor=white]
\textbf{Dealing with time zones:} The time that is recorded in \texttt{--key} may be in UTC (Universal Time Coordinate). However, the organization of the images taken during the night depends on the local time. It is possible to take this into account by setting the \texttt{--hour} option to the local time in UTC.

For example, consider a set of images taken in Auckland (New Zealand, UTC+12) during different nights. If you want to classify these images by night, you have to know at which time (in UTC time) the Sun rises (or any other separator/definition of a different night). In this particular example, you can use \texttt{--hour=21}. Because in Auckland, a night finishes (roughly) at the local time of 9:00, which corresponds to 21:00 UTC.
\end{mdframed}

- \texttt{l} \texttt{--link}

Create a symbolic link for each input FITS file. This option cannot be used with \texttt{--copy}. The link will have a standard name in the following format (variable parts are written in \textsc{capital} letters and described after it):

\begin{verbatim}
PnN-I.fits
\end{verbatim}

\texttt{P} \quad This is the value given to \texttt{--prefix}. By default, its value is ./ (to store the links in the directory this script was run in). See the description of \texttt{--prefix} for more.

\texttt{N} \quad This is the night-counter: starting from 1. \texttt{N} is just incremented by 1 for the next night, no matter how many nights (without any dataset) there are between two subsequent observing nights (its just an identifier for each night which you can easily map to different calendar nights).

\texttt{I} \quad File counter in that night, sorted by time.

- \texttt{c} \texttt{--copy}

Make a copy of each input FITS file with the standard naming convention described in \texttt{--link}. With this option, instead of making a link, a copy is made. This option cannot be used with \texttt{--link}.

- \texttt{p STR} \texttt{--prefix=STR}

Prefix to append before the night-identifier of each newly created link or copy. This option is thus only relevant with the \texttt{--copy} or \texttt{--link} options. See the description of \texttt{--link} for how its used. For example, with \texttt{--prefix=img-}, all the created file names in the current directory will start with \texttt{img-}, making outputs like \texttt{img-n1-1.fits} or \texttt{img-n3-42.fits}.

\texttt{--prefix} can also be used to store the links/copies in another directory relative to the directory this script is being run (it must already exist). For example \texttt{--prefix=/path/to/processing/img-} will put all the links/copies in the \texttt{/path/to/processing} directory, and the files (in that directory) will all start with \texttt{img-}. 

5.3 ConvertType

The FITS format used in astronomy was defined mainly for archiving, transmission, and processing. In other situations, the data might be useful in other formats. For example, when you are writing a paper or report, or if you are making slides for a talk, you can’t use a FITS image. Other image formats should be used. In other cases you might want your pixel values in a table format as plain text for input to other programs that don’t recognize FITS. ConvertType is created for such situations. The various types will increase with future updates and based on need.

The conversion is not only one way (from FITS to other formats), but two ways (except the EPS and PDF formats⁴). So you can also convert a JPEG image or text file into a FITS image. Basically, other than EPS/PDF, you can use any of the recognized formats as different color channel inputs to get any of the recognized outputs. So before explaining the options and arguments (in Section 5.3.3 [Invoking ConvertType], page 166), we’ll start with a short description of the recognized files types in Section 5.3.1 [Recognized file formats], page 162, followed a short introduction to digital color in Section 5.3.2 [Color], page 165.

5.3.1 Recognized file formats

The various standards and the file name extensions recognized by ConvertType are listed below. Currently Gnuastro uses the file name’s suffix to identify the format.

FITS or IMH
Astronomical data are commonly stored in the FITS format (or the older data IRAF .imh format), a list of file name suffixes which indicate that the file is in this format is given in Section 4.1.1.1 [Arguments], page 107.

Each image extension of a FITS file only has one value per pixel/element. Therefore, when used as input, each input FITS image contributes as one color channel. If you want multiple extensions in one FITS file for different color channels, you have to repeat the file name multiple times and use the --hdu, --hdu2, --hdu3 or --hdu4 options to specify the different extensions.

JPEG
The JPEG standard was created by the Joint photographic experts group. It is currently one of the most commonly used image formats. Its major advantage is the compression algorithm that is defined by the standard. Like the FITS standard, this is a raster graphics format, which means that it is pixelated.

A JPEG file can have 1 (for gray-scale), 3 (for RGB) and 4 (for CMYK) color channels. If you only want to convert one JPEG image into other formats, there is no problem, however, if you want to use it in combination with other input files, make sure that the final number of color channels does not exceed four. If it does, then ConvertType will abort and notify you.

The file name endings that are recognized as a JPEG file for input are: .jpg, .JPG, .jpeg, .JPEG, .jpe, .jif, .jfif and .jfi.

TIFF
TIFF (or Tagged Image File Format) was originally designed as a common format for scanners in the early 90s and since then it has grown to become very general. In many aspects, the TIFF standard is similar to the FITS image standard: it can allow data of many types (see Section 4.6 [Numeric data types],

⁴ Because EPS and PDF are vector, not raster/pixelated formats
page 130), and also allows multiple images to be stored in a single file (each image in the file is called a ‘directory’ in the TIFF standard). However, unlike FITS, it can only store images, it has no constructs for tables. Another (inconvenient) difference with the FITS standard is that keyword names are stored as numbers, not human-readable text.

However, outside of astronomy, because of its support of different numeric data types, many fields use TIFF images for accurate (for example 16-bit integer or floating point for example) imaging data.

Currently ConvertType can only read TIFF images, if you are interested in writing TIFF images, please get in touch with us.

**EPS**
The Encapsulated PostScript (EPS) format is essentially a one page PostScript file which has a specified size. PostScript also includes non-image data, for example lines and texts. It is a fully functional programming language to describe a document. Therefore in ConvertType, EPS is only an output format and cannot be used as input. Contrary to the FITS or JPEG formats, PostScript is not a raster format, but is categorized as vector graphics.

The Portable Document Format (PDF) is currently the most common format for documents. Some believe that PDF has replaced PostScript and that PostScript is now obsolete. This view is wrong, a PostScript file is an actual plain text file that can be edited like any program source with any text editor. To be able to display its programmed content or print, it needs to pass through a processor or compiler. A PDF file can be thought of as the processed output of the compiler on an input PostScript file. PostScript, EPS and PDF were created and are registered by Adobe Systems.

With these features in mind, you can see that when you are compiling a document with \TeX{} or \LaTeX{}, using an EPS file is much more low level than a JPEG and thus you have much greater control and therefore quality. Since it also includes vector graphic lines we also use such lines to make a thin border around the image to make its appearance in the document much better. No matter the resolution of the display or printer, these lines will always be clear and not pixelated. In the future, addition of text might be included (for example labels or object IDs) on the EPS output. However, this can be done better with tools within \TeX{} or \LaTeX{} such as PGF/Tikz\(^5\).

If the final input image (possibly after all operations on the flux explained below) is a binary image or only has two colors of black and white (in segmentation maps for example), then PostScript has another great advantage compared to other formats. It allows for 1 bit pixels (pixels with a value of 0 or 1), this can decrease the output file size by 8 times. So if a gray-scale image is binary, ConvertType will exploit this property in the EPS and PDF (see below) outputs.

The standard formats for an EPS file are .eps, .EPS, .epsf and .epsi. The EPS outputs of ConvertType have the .eps suffix.

\(^5\) [http://sourceforge.net/projects/pgf/]
**PDF**  
As explained above, a PDF document is a static document description format, viewing its result is therefore much faster and more efficient than PostScript. To create a PDF output, ConvertType will make a PostScript page description and convert that to PDF using GPL Ghostscript. The suffixes recognized for a PDF file are: `.pdf`, `.PDF`. If GPL Ghostscript cannot be run on the PostScript file, it will remain and a warning will be printed.

**blank**  
This is not actually a file type! But can be used to fill one color channel with a blank value. If this argument is given for any color channel, that channel will not be used in the output.

**Plain text**  
Plain text files have the advantage that they can be viewed with any text editor or on the command-line. Most programs also support input as plain text files. As input, each plain text file is considered to contain one color channel.

In ConvertType, the recognized extensions for plain text files are `.txt` and `.dat`. As described in Section 5.3.3 [Invoking ConvertType], page 166, if you just give these extensions, (and not a full filename) as output, then automatic output will be preformed to determine the final output name (see Section 4.10 [Automatic output], page 142). Besides these, when the format of a file cannot be recognized from its name, ConvertType will fall back to plain text mode. So you can use any name (even without an extension) for a plain text input or output. Just note that when the suffix is not recognized, automatic output will not be preformed.

The basic input/output on plain text images is very similar to how tables are read/written as described in Section 4.8.2 [Gnuastro text table format], page 137. Simply put, the restrictions are very loose, and there is a convention to define a name, units, data type (see Section 4.6 [Numeric data types], page 130), and comments for the data in a commented line. The only difference is that as a table, a text file can contain many datasets (columns), but as a 2D image, it can only contain one dataset. As a result, only one information comment line is necessary for a 2D image, and instead of the starting `# Column N` (N is the column number), the information line for a 2D image must start with `# Image 1`. When ConvertType is asked to output to plain text file, this information comment line is written before the image pixel values.

When converting an image to plain text, consider the fact that if the image is large, the number of columns in each line will become very large, possibly making it very hard to open in some text editors.

**Standard output (command-line)**  
This is very similar to the plain text output, but instead of creating a file to keep the printed values, they are printed on the command line. This can be very useful when you want to redirect the results directly to another program in one command with no intermediate file. The only difference is that only the pixel values are printed (with no information comment line). To print to the standard output, set the output name to `stdout`.
5.3.2 Color

Color is defined by mixing various measurements/filters. In digital monitors or common digital cameras, colors are displayed/stored by mixing the three basic colors of red, green and blue (RGB) with various proportions. When printing on paper, standard printers use the cyan, magenta, yellow and key (CMYK, key=black) color space. In other words, for each displayed/printed pixel of a color image, the dataset/image has three or four values.

To store/show the three values for each pixel, cameras and monitors allocate a certain fraction of each pixel’s area to red, green and blue filters. These three filters are thus built into the hardware at the pixel level. However, because measurement accuracy is very important in scientific instruments, and we want to do measurements (take images) with various/custom filters (without having to order a new expensive detector!), scientific detectors use the full area of the pixel to store one value for it in a single mono-channel dataset. To make measurements in different filters, we just place a filter in the light path before the detector. Therefore, the FITS format that is used to store astronomical datasets is inherently a mono-channel format (see Section 5.3.1 [Recognized file formats], page 162, or Section 5.1 [Fits], page 146).

When a subject has been imaged in multiple filters, you can feed each different filter into the red, green and blue channels and obtain a colored visualization. In ConvertType, you can do this by giving each separate single-channel dataset (for example in the FITS image format) as an argument (in the proper order), then asking for the output in a format that supports multi-channel datasets (for example JPEG or PDF, see the examples in Section 5.3.3 [Invoking ConvertType], page 166).

As discussed above, color is not defined when a dataset/image contains a single value for each pixel. However, we interact with scientific datasets through monitors or printers (which allow multiple values per pixel and produce color with them). As a result, there is a lot of freedom in visualizing a single-channel dataset. The most basic is to use shades of black (because of its strong contrast with white). This scheme is called grayscale. To help in visualization, more complex mappings can be defined. For example, the values can be scaled to a range of 0 to 360 and used as the “Hue” term of the Hue-Saturation-Value (HSV) color space (while fixing the “Saturation” and “Value” terms). In ConvertType, you can use the --colormap option to choose between different mappings of mono-channel inputs, see Section 5.3.3 [Invoking ConvertType], page 166.

Since grayscale is a commonly used mapping of single-valued datasets, we’ll continue with a closer look at how it is stored. One way to represent a gray-scale image in different color spaces is to use the same proportions of the primary colors in each pixel. This is the common way most FITS image viewers work: for each pixel, they fill all the channels with the single value. While this is necessary for displaying a dataset, there are downsides when storing/saving this type of grayscale visualization (for example in a paper).

- Three (for RGB) or four (for CMYK) values have to be stored for every pixel, this makes the output file very heavy (in terms of bytes).
- If printing, the printing errors of each color channel can make the printed image slightly more blurred than it actually is.
To solve both these problems when storing grayscale visualization, the best way is to save a single-channel dataset into the black channel of the CMYK color space. The JPEG standard is the only common standard that accepts CMYK color space.

The JPEG and EPS standards set two sizes for the number of bits in each channel: 8-bit and 12-bit. The former is by far the most common and is what is used in ConvertType. Therefore, each channel should have values between 0 to \(2^8 - 1 = 255\). From this we see how each pixel in a gray-scale image is one byte (8 bits) long, in an RGB image, it is 3 bytes long and in CMYK it is 4 bytes long. But thanks to the JPEG compression algorithms, when all the pixels of one channel have the same value, that channel is compressed to one pixel. Therefore a Grayscale image and a CMYK image that has only the K-channel filled are approximately the same file size.

### 5.3.3 Invoking ConvertType

ConvertType will convert any recognized input file type to any specified output type. The executable name is `astconvertt` with the following general template

```
$ astconvertt [OPTION...] InputFile [InputFile2] ... [InputFile4]
```

One line examples:

```
## Convert an image in FITS to PDF:
$ astconvertt image.fits --output=pdf

## Similar to before, but use the Viridis color map:
$ astconvertt image.fits --colormap=viridis --output=pdf

## Convert an image in JPEG to FITS (with multiple extensions
## if its color):
$ astconvertt image.jpg -oimage.fits

## Use three plain text 2D arrays to create an RGB JPEG output:
$ astconvertt f1.txt f2.txt f3.fits -o.jpg

## Use two images and one blank for an RGB EPS output:
$ astconvertt M31_r.fits M31_g.fits blank -oeps

## Directly pass input from output of another program through Standard
## input (not a file).
$ cat 2darray.txt | astconvertt -oimg.fits
```

The output’s file format will be interpreted from the value given to the `--output` option. It can either be given on the command-line or in any of the configuration files (see Section 4.2 [Configuration files], page 120). Note that if the output suffix is not recognized, it will default to plain text format, see Section 5.3.1 [Recognized file formats], page 162.

At most four input files (one for each color channel for formats that allow it) are allowed in ConvertType. The first input dataset can either be a file or come from Standard input (see Section 4.1.3 [Standard input], page 118). The order of multiple input files is important. After reading the input file(s) the number of color channels in all the inputs will be used to define which color space to use for the outputs and how each color channel is interpreted.
Some formats can allow more than one color channel (for example in the JPEG format, see Section 5.3.1 [Recognized file formats], page 162). If there is one input dataset (color channel) the output will be gray-scale, if three input datasets (color channels) are given, they are respectively considered to be the red, green and blue color channels. Finally, if there are four color channels they will be be cyan, magenta, yellow and black (CMYK colors).

The value to --output (or -o) can be either a full file name or just the suffix of the desired output format. In the former case, it will used for the output. In the latter case, the name of the output file will be set based on the automatic output guidelines, see Section 4.10 [Automatic output], page 142. Note that the suffix name can optionally start a . (dot), so for example --output=.jpg and --output=jpg are equivalent. See Section 5.3.1 [Recognized file formats], page 162.

Besides the common set of options explained in Section 4.1.2 [Common options], page 109, the options to ConvertType can be classified into input, output and flux related options. The majority of the options are to do with the flux range. Astronomical data usually have a very large dynamic range (difference between maximum and minimum value) and different subjects might be better demonstrated with a limited flux range.

Input:

-h STR/INT
--hdu=STR/INT

In ConvertType, it is possible to call the HDU option multiple times for the different input FITS or TIFF files in the same order that they are called on the command-line. Note that in the TIFF standard, one ‘directory’ (similar to a FITS HDU) may contain multiple color channels (for example when the image is in RGB).

Except for the fact that multiple calls are possible, this option is identical to the common --hdu in Section 4.1.2.1 [Input/Output options], page 109. The number of calls to this option cannot be less than the number of input FITS or TIFF files, but if there are more, the extra HDUs will be ignored, note that they will be read in the order described in Section 4.2.2 [Configuration file precedence], page 121.

Unlike CFITSIO, libtiff (which is used to read TIFF files) only recognizes numbers (counting from zero, similar to CFITSIO) for ‘directory’ identification. Hence the concept of names is not defined for the directories and the values to this option for TIFF files must be numbers.

Output:

-w FLT
--widthincm=FLT

The width of the output in centimeters. This is only relevant for those formats that accept such a width (not plain text for example). For most digital purposes, the number of pixels is far more important than the value to this parameter because you can adjust the absolute width (in inches or centimeters) in your document preparation program.
-b INT
--borderwidth=INT
The width of the border to be put around the EPS and PDF outputs in units of PostScript points. There are 72 or 28.35 PostScript points in an inch or centimeter respectively. In other words, there are roughly 3 PostScript points in every millimeter. If you are planning on adding a border, its significance is highly correlated with the value you give to the --widthin cm parameter.
Unfortunately in the document structuring convention of the PostScript language, the “bounding box” has to be in units of PostScript points with no fractions allowed. So the border values only have to be specified in integers. To have a final border that is thinner than one PostScript point in your document, you can ask for a larger width in ConvertType and then scale down the output EPS or PDF file in your document preparation program. For example by setting width in your includegraphics command in $\LaTeX$ or $\mathrm{LATEX}$. Since it is vector graphics, the changes of size have no effect on the quality of your output quality (pixels don’t get different values).

-x
--hex
Use Hexadecimal encoding in creating EPS output. By default the ASCII85 encoding is used which provides a much better compression ratio. When converted to PDF (or included in $\LaTeX$ or $\mathrm{LATEX}$ which is finally saved as a PDF file), an efficient binary encoding is used which is far more efficient than both of them. The choice of EPS encoding will thus have no effect on the final PDF.
So if you want to transfer your EPS files (for example if you want to submit your paper to arXiv or journals in PostScript), their storage might become important if you have large images or lots of small ones. By default ASCII85 encoding is used which offers a much better compression ratio (nearly 40 percent) compared to Hexadecimal encoding.

-u INT
--quality=INT
The quality (compression) of the output JPEG file with values from 0 to 100 (inclusive). For other formats the value to this option is ignored. Note that only in gray-scale (when one input color channel is given) will this actually be the exact quality (each pixel will correspond to one input value). If it is in color mode, some degradation will occur. While the JPEG standard does support loss-less graphics, it is not commonly supported.

--colormap=STR[,FLT,...]
The color map to visualize a single channel. The first value given to this option is the name of the color map, which is shown below. Some color maps can be configured. In this case, the configuration parameters are optionally given as numbers following the name of the color map for example see hsv. The table below contains the usable names of the color maps that are currently supported:

<table>
<thead>
<tr>
<th>Color Map</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>gray</td>
<td>Grayscale color map. This color map doesn’t have any parameters. The full dataset range will be scaled to 0 and $2^8 - 1 = 255$ to be stored in the requested format.</td>
</tr>
</tbody>
</table>
**hsv**

Hue, Saturation, Value\(^6\) color map. If no values are given after the name (**colormap=hsv**), the dataset will be scaled to 0 and 360 for hue covering the full spectrum of colors. However, you can limit the range of hue (to show only a special color range) by explicitly requesting them after the name (for example **colormap=hsv,20,240**).

The mapping of a single-channel dataset to HSV is done through the Hue and Value elements: Lower dataset elements have lower “value” and lower “hue”. This creates darker colors for fainter parts, while also respecting the range of colors.

**viridis**

Viridis is the default colormap of the popular Matplotlib module of Python and available in many other visualization tools like PGFPlots.

**sls**

The SLS color range, taken from the commonly used SAO DS9 ([http://ds9.si.edu](http://ds9.si.edu)). The advantage of this color range is that it starts with black, going into dark blue and finishes with the brighter colors of red and white. So unlike the HSV color range, it includes black and white and brighter colors (like yellow, red) show the larger values.

**sls-inverse**

The inverse of the SLS color map (see above), where the lowest value corresponds to white and the highest value is black. While SLS is good for visualizing on the monitor, SLS-inverse is good for printing.

**--rgbtohsv**

When there are three input channels and the output is in the FITS format, interpret the three input channels as red, green and blue channels (RGB) and convert them to the hue, saturation, value (HSV) color space.

The currently supported output formats of ConvertType don’t have native support for HSV. Therefore this option is only supported when the output is in FITS format and each of the hue, saturation and value arrays can be saved as one FITS extension in the output for further analysis (for example to select a certain color).

Flux range:

**-c STR**

**--change=STR**

(=STR) Change pixel values with the following format "from1:to1, from2:to2,...". This option is very useful in displaying labeled pixels (not actual data images which have noise) like segmentation maps. In labeled images, usually a group of pixels have a fixed integer value. With this option, you can manipulate the labels before the image is displayed to get a better output for print or to emphasize on a particular set of labels and ignore the

rest. The labels in the images will be changed in the same order given. By default first the pixel values will be converted then the pixel values will be truncated (see \texttt{--fluxlow} and \texttt{--fluxhigh}).

You can use any number for the values irrespective of your final output, your given values are stored and used in the double precision floating point format. So for example if your input image has labels from 1 to 20000 and you only want to display those with labels 957 and 11342 then you can run ConvertType with these options:

\begin{verbatim}
$ astconvertt --change=957:50000,11342:50001 --fluxlow=5e4 \ 
   --fluxhigh=1e5 segmentationmap.fits --output=jpg
\end{verbatim}

While the output JPEG format is only 8 bit, this operation is done in an intermediate step which is stored in double precision floating point. The pixel values are converted to 8-bit after all operations on the input fluxes have been complete. By placing the value in double quotes you can use as many spaces as you like for better readability.

\texttt{-C}

\texttt{--changeaftertrunc}

Change pixel values (with \texttt{--change}) after truncation of the flux values, by default it is the opposite.

\texttt{-L FLT}

\texttt{--fluxlow=FLT}

The minimum flux (pixel value) to display in the output image, any pixel value below this value will be set to this value in the output. If the value to this option is the same as \texttt{--fluxhigh}, then no flux truncation will be applied. Note that when multiple channels are given, this value is used for all the color channels.

\texttt{-H FLT}

\texttt{--fluxhigh=FLT}

The maximum flux (pixel value) to display in the output image, see \texttt{--fluxlow}.

\texttt{-m INT}

\texttt{--maxbyte=INT}

This is only used for the JPEG and EPS output formats which have an 8-bit space for each channel of each pixel. The maximum value in each pixel can therefore be \(2^8 - 1 = 255\). With this option you can change (decrease) the maximum value. By doing so you will decrease the dynamic range. It can be useful if you plan to use those values for other purposes.

\texttt{-A INT}

\texttt{--forcemin=INT}

Enforce the value of \texttt{--fluxlow} (when its given), even if its smaller than the minimum of the dataset and the output is format supporting color. This is particularly useful when you are converting a number of images to a common image format like JPEG or PDF with a single command and want them all to have the same range of colors, independent of the contents of the dataset. Note that if the minimum value is smaller than \texttt{--fluxlow}, then this option is redundant.
By default, when the dataset only has two values, and the output format is PDF or EPS, ConvertType will use the PostScript optimization that allows setting the pixel values per bit, not byte (Section 5.3.1 [Recognized file formats], page 162). This can greatly help reduce the file size. However, when \texttt{--fluxlow} or \texttt{--fluxhigh} are called, this optimization is disabled: even though there are only two values (is binary), the difference between them does not correspond to the full contrast of black and white.

\texttt{-B INT}
\texttt{--forcemax=INT}

Similar to \texttt{--forcemin}, but for the maximum.

\texttt{-i}
\texttt{--invert}

For 8-bit output types (JPEG, EPS, and PDF for example) the final value that is stored is inverted so white becomes black and vice versa. The reason for this is that astronomical images usually have a very large area of blank sky in them. The result will be that a large area of the image will be black. Note that this behavior is ideal for gray-scale images, if you want a color image, the colors are going to be mixed up.

\section*{5.4 Table}

Tables are the products of processing astronomical images and spectra. For example in Gnuastro, MakeCatalog will process the defined pixels over an object and produce a catalog (see Section 7.4 [MakeCatalog], page 295). For each identified object, MakeCatalog can print its position on the image or sky, its total brightness and many other information that is deducible from the given image. Each one of these properties is a column in its output catalog (or table) and for each input object, we have a row.

When there are only a small number of objects (rows) and not too many properties (columns), then a simple plain text file is mainly enough to store, transfer, or even use the produced data. However, to be more efficient in all these aspects, astronomers have defined the FITS binary table standard to store data in a binary (0 and 1) format, not plain text. This can offer major advantages in all those aspects: the file size will be greatly reduced and the reading and writing will be faster (because the RAM and CPU also work in binary).

The FITS standard also defines a standard for ASCII tables, where the data are stored in the human readable ASCII format, but within the FITS file structure. These are mainly useful for keeping ASCII data along with images and possibly binary data as multiple (conceptually related) extensions within a FITS file. The acceptable table formats are fully described in Section 4.8 [Tables], page 135.

Binary tables are not easily readable by human eyes. There is no fixed/unified standard on how the zero and ones should be interpreted. The Unix-like operating systems have flourished because of a simple fact: communication between the various tools is based on human readable characters\textsuperscript{7}. So while the FITS table standards are very beneficial for the

\textsuperscript{7} In “The art of Unix programming”, Eric Raymond makes this suggestion to programmers: “When you feel the urge to design a complex binary file format, or a complex binary application protocol, it is generally wise to lie down until the feeling passes.”. This is a great book and strongly recommended, give it a look if you want to truly enjoy your work/life in this environment.
tools that recognize them, they are hard to use in the vast majority of available software. This creates limitations for their generic use.

‘Table’ is Gnuastro’s solution to this problem. With Table, FITS tables (ASCII or binary) are directly accessible to the Unix-like operating systems power-users (those working the command-line or shell, see Section 1.6.1 [Command-line interface], page 9). With Table, a FITS table (in binary or ASCII formats) is only one command away from AWK (or any other tool you want to use). Just like a plain text file that you read with the cat command. You can pipe the output of Table into any other tool for higher-level processing, see the examples in Section 5.4.2 [Invoking Table], page 176, for some simple examples.

5.4.1 Column arithmetic
After reading the requested columns from the input table, you can also do operations/arithmetic on the columns and save the resulting values as new column(s) in the output table (possibly in between other requested columns). To enable column arithmetic, the first 6 characters of the value to --column (-c) should be the arithmetic activation word ‘arith’ (note the space character in the end, after ‘arith’).

After the activation word, you can use the reverse polish notation to identify the operators and their operands, see Section 6.2.1 [Reverse polish notation], page 199. Just note that white-space characters are used between the tokens of the arithmetic expression and that they are meaningful to the command-line environment. Therefore the whole expression (including the activation word) has to be quoted on the command-line or in a shell script (see the examples below).

To identify a column you can directly use its name, or specify its number (counting from one, see Section 4.8.3 [Selecting table columns], page 140). When you are giving a column number, it is necessary to prefix the number with a $, similar to AWK. Otherwise the number is not distinguishable from a constant number to use in the arithmetic operation.

For example with the command below, the first two columns of table.fits will be printed along with a third column that is the result of multiplying the first column with $10^{10}$ (for example to convert wavelength from Meters to Angstroms). Note that without the ‘$’, it is not possible to distinguish between “1” as a column-counter, or as a constant number to use in the arithmetic operation. Also note that because of the significance of $ for the command-line environment, the single-quotes are used here (as in an AWK expression), not double-quotes.

```bash
$ asttable table.fits -c1,2 -c'arith $1 1e10 x'
```
**Single quotes when string contains $**: On the command-line, or in shell-scripts, $ is used to expand variables, for example `echo $PATH` prints the value (a string of characters) in the variable PATH, it will not simply print $PATH. This operation is also permitted within double quotes, so `echo "$PATH"` will produce the same output. This is good when printing values, for example in the command below, $PATH will expand to the value within it.

```
$ echo "My path is: $PATH"
```

If you actually want to return the literal string $PATH, not the value in the PATH variable (like the scenario here in column arithmetic), you should put it in single quotes like below. The printed value here will include the $, please try it to see for your self and compare to above.

```
$ echo 'My path is: $PATH'
```

Therefore, when your column arithmetic involves the $ sign (to specify columns by number), quote your arith string with a single quotation mark. Otherwise you can use both single or double quotes.

Alternatively, if the columns have meta-data and the first two are respectively called AWAV and SPECTRUM, the command above is equivalent to the command below. Note that the character ‘$’ is no longer necessary in this scenario (because names will not be confused with numbers):

```
$ asttable table.fits -cAWAV,SPECTRUM -c'arith AWAV 1e10 x'
```

Comparison of the two commands above clearly shows why it is recommended to use column names instead of numbers. When the columns have descriptive names, the command/script actually becomes much more readable, describing the intent of the operation. It is also independent of the low-level table structure: for the second command, the position of the AWAV and SPECTRUM columns in table.fits is irrelevant.

By nature, column arithmetic changes the values of the data within the column. So the old column meta data can’t be used any more. By default the new column created for the arithmetic operation will be given generic metadata (for example its name will be ARITH_1, which is hardly useful!). But meta data are critically important and it is good practice to always have short, but descriptive, names for each columns, units and also some comments for more explanation. To add metadata to a column, you can use the --colmetadata option that is described in Section 5.4.2 [Invoking Table], page 176.

Finally, since the arithmetic expressions are a value to --column, it doesn’t necessarily have to be a separate option, so the commands above are also identical to the command below (note that this only has one -c option). Just be very careful with the quoting!

```
$ asttable table.fits -cAWAV,SPECTRUM,'arith AWAV 1e10 x'
```

Almost all the arithmetic operators of Section 6.2.2 [Arithmetic operators], page 200, are also supported for column arithmetic in Table. In particular, the few that are not present in the Gnuastro library aren’t yet supported. For a list of the Gnuastro library arithmetic operators, please see the macros starting with GAL_ARITHMETIC_OP and ending with the operator name in Section 10.3.14 [Arithmetic on datasets (arithmetic.h)], page 454. Besides the operators in Section 6.2.2 [Arithmetic operators], page 200, several operators are only available in Table to use on table columns.

`wcstoimg` Convert the given WCS positions to image/dataset coordinates based on the number of dimensions in the WCS structure of --wcshdu extension/HDU in
--wcsfile. It will output the same number of columns. The first popped operand is the last FITS dimension.

For example the two commands below (which have the same output) will produce 5 columns. The first three columns are the input table’s ID, RA and Dec columns. The fourth and fifth columns will be the pixel positions in image.fits that correspond to each RA and Dec.

```
$ asttable table.fits -cID,RA,DEC,'arith RA DEC wcstoimg' \\
   --wcsfile=image.fits
$ asttable table.fits -cID,RA -cDEC \\
   -c’arith RA DEC wcstoimg’ --wcsfile=image.fits
```

imgtowcs Similar to wcstoimg, except that image/dataset coordinates are converted to WCS coordinates.

distance-flat

Return the distance between two points assuming they are on a flat surface. Note that each point needs two coordinates, so this operator needs four operands (currently it only works for 2D spaces). The first and second popped operands are considered to belong to one point and the third and fourth popped operands to the second point.

Each of the input points can be a single coordinate or a full table column (containing many points). In other words, the following commands are all valid:

```
$ asttable table.fits \\
   -c’arith X1 Y1 X2 Y2 distance-flat’
$ asttable table.fits \\
   -c’arith X Y 12.345 6.789 distance-flat’
$ asttable table.fits \\
   -c’arith 12.345 6.789 X Y distance-flat’
```

In the first case we are assuming that table.fits has the following four columns X1, Y1, X2, Y2. The returned column by this operator will be the difference between two points in each row with coordinates like the following (X1, Y1) and (X2, Y2). In other words, for each row, the distance between different points is calculated. In the second and third cases (which are identical), it is assumed that table.fits has the two columns X and Y. The returned column by this operator will be the difference of each row with the fixed point at (12.345, 6.789).

distance-on-sphere

Return the spherical angular distance (along a great circle, in degrees) between the given two points. Note that each point needs two coordinates (in degrees), so this operator needs four operands. The first and second popped operands are considered to belong to one point and the third and fourth popped operands to the second point.

Each of the input points can be a single coordinate or a full table column (containing many points). In other words, the following commands are all valid:

```
$ asttable table.fits \\
```


In the first case we are assuming that table.fits has the following four columns RA1, DEC1, RA2, DEC2. The returned column by this operator will be the difference between two points in each row with coordinates like the following (RA1, DEC1) and (RA2, DEC2). In other words, for each row, the angular distance between different points is calculated. In the second and third cases (which are identical), it is assumed that table.fits has the two columns RA and DEC. The returned column by this operator will be the difference of each row with the fixed point at (9.876, 5.432).

The distance (along a great circle) on a sphere between two points is calculated with the equation below, where \( r_1 \), \( r_2 \), \( d_1 \) and \( d_2 \) are the right ascensions and declinations of points 1 and 2.

\[
\cos(d) = \sin(d_1) \sin(d_2) + \cos(d_1) \cos(d_2) \cos(r_1 - r_2)
\]

ra-to-degree
Convert the hour-wise Right Ascension (RA) string, in the sexagesimal format of \_h\_m\_s or \:_:_:\_, to degrees. Note that the input column has to have a string format. In FITS tables, string columns are well-defined. For plain-text tables, please follow the standards defined in Section 4.8.2 [Gnuastro text table format], page 137, otherwise the string column won't be read.

```
$ asttable catalog.fits -c'arith RA ra-to-degree'
$ asttable catalog.fits -c'arith $5 ra-to-degree'
```

dec-to-degree
Convert the sexagesimal Declination (Dec) string, in the format of \_d\_m\_s or \:_:_:\_, to degrees (a single floating point number). For more details please see the ra-to-degree operator.

degree-to-ra
Convert degrees (a column with a single floating point number) to the Right Ascension, RA, string (in the sexagesimal format hours, minutes and seconds, written as \_h\_m\_s). The output will be a string column so no further mathematical operations can be done on it. The output file can be in any format (for example FITS or plain-text). If it is plain-text, the string column will be written following the standards described in Section 4.8.2 [Gnuastro text table format], page 137.

degree-to-dec
Convert degrees (a column with a single floating point number) to the Declination, Dec, string (in the format of \_d\_m\_s). See the degree-to-ra for more on the format of the output.
5.4.2 Invoking Table

Table will read/write, select, convert, or show the information of the columns in FITS ASCII table, FITS binary table and plain text table files, see Section 4.8 [Tables], page 135. Output columns can also be determined by number or regular expression matching of column names, units, or comments. The executable name is asttable with the following general template

$ asttable [OPTION...] InputFile

One line examples:

## Get the table column information (name, data type, or units):
$ asttable bintab.fits --information

## Print columns named RA and DEC, followed by all the columns where
## the name starts with "MAG_":
$ asttable bintab.fits --column=RA --column=DEC --column=/^MAG_/

## Similar to the above, but with one call to ‘--column’ (or ‘-c’),
## also sort the rows by the input’s photometric redshift (‘Z_PHOT’)
## column. To confirm the sort, you can add ‘Z_PHOT’ to the columns
## to print.
$ asttable bintab.fits -cRA,DEC,/^MAG_/ --sort=Z_PHOT

## Similar to the above, but only print rows that have a photometric
## redshift between 2 and 3.
$ asttable bintab.fits -cRA,DEC,/^MAG_/ --range=Z_PHOT,2:3

## Only print rows with a value in the 10th column above 100000:
$ asttable bintab.fits --range=10,10e5,inf

## Only print the 2nd column, and the third column multiplied by 5,
## Save the resulting two columns in ‘table.txt’
$ asttable bintab.fits -c2,’arith $2 5 x’ -otable.fits

## Sort the output columns by the third column, save output:
$ asttable bintab.fits --sort=3 -ooutput.txt

## Subtract the first column from the second in ‘cat.fits’ (can also
## be a text table) and keep the third and fourth columns.
$ asttable cat.txt -c’arith $2 $1 -’,3,4 -ocat.fits

## Convert sexagesimal coordinates to degrees (same can be done in a
## large table given as argument).
$ echo "7h34m35.5498 31d53m14.352s" | asttable

## Convert RA and Dec in degrees to sexagesimal (same can be done in a
## large table given as argument).
echo "113.6481241667 31.88732" \
    | asttable -c’arith $1 degree-to-ra $2 degree-to-dec'
Table’s input dataset can be given either as a file or from Standard input (see Section 4.1.3 [Standard input], page 118). In the absence of selected columns, all the input’s columns and rows will be written to the output. If any output file is explicitly requested (with \(--output\) the output table will be written in it. When no output file is explicitly requested the output table will be written to the standard output.

If the specified output is a FITS file, the type of FITS table (binary or ASCII) will be determined from the \(--tabletype\) option. If the output is not a FITS file, it will be printed as a plain text table (with space characters between the columns). When the columns are accompanied by meta-data (like column name, units, or comments), this information will also printed in the plain text file before the table, as described in Section 4.8.2 [Gnuastro text table format], page 137.

For the full list of options common to all Gnuastro programs please see Section 4.1.2 [Common options], page 109. Options can also be stored in directory, user or system-wide configuration files to avoid repeating on the command-line, see Section 4.2 [Configuration files], page 120. Table does not follow Automatic output that is common in most Gnuastro programs, see Section 4.10 [Automatic output], page 142. Thus, in the absence of an output file, the selected columns will be printed on the command-line with no column information, ready for redirecting to other tools like AWK or sort, similar to the examples above.

**Sexagesimal coordinates as floats in plain-text tables:** When a column is determined to be a floating point type (32-bit or 64-bit) in a plain-text table, it can contain sexagesimal values in the format of ‘\(_h_m_s\)’ (for RA) and ‘\(_d_m_s\)’ (for Dec). In this case, the string will be immediately converted to a single floating point number (in units of degrees) and stored in memory with the rest of the column or table. Besides being useful in large tables, with this feature, conversion to sexagesimal coordinates to degrees becomes very easy, for example:

```
    echo "7h34m35.5498 31d53m14.352s" | asttable
```

The inverse can also be done with the more general column arithmetic operators:

```
    echo "113.64812416667 31.88732" \ 
    | asttable -c'arith $1 degree-to-ra $2 degree-to-dec'
```

\(-i\)

\(--information\)

Only print the column information in the specified table on the command-line and exit. Each column’s information (number, name, units, data type, and comments) will be printed as a row on the command-line. Note that the FITS standard only requires the data type (see Section 4.6 [Numeric data types], page 130), and in plain text tables, no meta-data/information is mandatory. Gnuastro has its own convention in the comments of a plain text table to store and transfer this information as described in Section 4.8.2 [Gnuastro text table format], page 137.

This option will take precedence over the \(--column\) option, so when it is called along with requested columns, the latter will be ignored. This can be useful if you forget the identifier of a column after you have already typed some on the command-line. You can simply add a \(-i\) and run Table to see the whole list and remember. Then you can use the shell history (with the up arrow key
on the keyboard), and retrieve the last command with all the previously typed columns present, delete -i and add the identifier you had forgot.

-c STR/INT
--column=STR/INT
Set the output columns either by specifying the column number, or name. For more on selecting columns, see Section 4.8.3 [Selecting table columns], page 140. If a value of this option starts with ‘arith’, this option will do the requested operations/arithmetic on the specified columns and output the result in that place (among other requested columns). For more on column arithmetic see Section 5.4.1 [Column arithmetic], page 172.

To ask for multiple columns this option can be used in two way: 1) multiple calls to this option, 2) using a comma between each column specifier in one call to this option. These different solutions may be mixed in one call to Table: for example, -cRA,DEC -cMAG, or -cRA -cDEC -cMAG are both equivalent to -cRA -cDEC -cMAG. The order of the output columns will be the same order given to the option or in the configuration files (see Section 4.2.2 [Configuration file precedence], page 121).

This option is not mandatory, if no specific columns are requested, all the input table columns are output. When this option is called multiple times, it is possible to output one column more than once.

-w STR
--wcsfile=STR
FITS file that contains the WCS to be used in the wcstoimg and imgtowcs operators of --column (see above). The extension name/number within the FITS file can be specified with --wcshdu.

If the value to this option is none, no WCS will be written in the output.

-W STR
--wcshdu=STR
FITS extension/HDU that contains the WCS to be used in the wcstoimg and imgtowcs operators of --column (see above). The FITS file name can be specified with --wcsfile.

-L STR
--catcolumnfile=STR
Concatenate (or add, or append) the columns of this option’s value (a filename) to the output columns. This option may be called multiple times (to add columns from more than one file into the final output), the columns from each file will be added in the same order that this option is called.

By default all the columns of the given file will be appended, if you only want certain columns to be appended, use the --catcolumns option to specify their name or number (see Section 4.8.3 [Selecting table columns], page 140). Note that the columns given to --catcolumns must be present in all the given files (if this option is called more than once).

The concatenation is done after any column selection (for example with --column) or row selection (for example with --range) is applied to the main
input table given to Table. The number of rows in the file(s) given to this option has to be the same as the final output table if this option wasn’t given. If the file given to this option is a FITS file, it’s necessary to also define the corresponding HDU/extension with \texttt{--catcolumnhdu}. Also note that no operation (for example row selection, arithmetic or etc) is applied to the table given to this option.

If the appended columns have a name, the column names of each file will be appended with a \texttt{-N}, where \texttt{N} is a counter starting from 1 for each appended file. This is done because when concatenating columns from multiple tables (more than two) into one, they may have the same name, and it’s not good practice to have multiple columns with the same name. You can disable this feature with \texttt{--catcolumnrawname}. To have full control over the concatenated column names, you can use the \texttt{--colmetadata} option described below.

For example, let’s assume you have two catalogs of the same objects (same number of rows) in different filters. Such that \texttt{f160w-cat.fits} has a \texttt{MAGNITUDE} column that has the magnitude of each object in the F160W filter and similarly \texttt{f105w-cat.fits}, also has a \texttt{MAGNITUDE} column, but for the F105W filter. You can use column concatenation like below to import the \texttt{MAGNITUDE} column from the F105W catalog into the F160W catalog, while giving each magnitude column a different name:

\begin{verbatim}
asttable f160w-cat.fits --output=both.fits \
  --catcolumnfile=f105w-cat.fits --catcolumns=MAGNITUDE \
  --colmetadata=MAGNITUDE,MAG-F160W,log,"Magnitude in F160W" \
  --colmetadata=MAGNITUDE-1,MAG-F105W,log,"Magnitude in F105W"
\end{verbatim}

\texttt{-u STR/INT}
\texttt{--catcolumnhdu=STR/INT}

The HDU/extension of the FITS file(s) that should be concatenated, or appended, with \texttt{--catcolumnfile}. If \texttt{--catcolumn} is called more than once with more than one FITS file, it’s necessary to call this option more than once. The HDUs will be loaded in the same order as the FITS files given to \texttt{--catcolumnfile}.

\texttt{-C STR/INT}
\texttt{--catcolumns=STR/INT}

The column(s) in the file(s) given to \texttt{--catcolumnfile} to append. When this option is not given, all the columns will be concatenated. See \texttt{--catcolumnfile} for more.

\texttt{--catcolumnrawname}

Don’t modify the names of the concatenated (appended) columns, see description in \texttt{--catcolumnfile}.

\texttt{-O}
\texttt{--colinfoinstdout}

Add column metadata when the output is printed in the standard output. Usually the standard output is used for a fast visual check or to pipe into other program for further processing. So by default meta-data aren’t included.
-r STR,FLT:FLT
--range=STR,FLT:FLT
Only output rows that have a value within the given range in the STR column (can be a name or counter). Note that the range is only inclusive in the lower-limit. For example with --range=sn,5:20 the output's columns will only contain rows that have a value in the sn column (not case-sensitive) that is greater or equal to 5, and less than 20.
This option can be called multiple times (different ranges for different columns) in one run of the Table program. This is very useful for selecting the final rows from multiple criteria/columns.
The chosen column doesn’t have to be in the output columns. This is good when you just want to select using one column’s values, but don’t need that column anymore afterwards.
For one example of using this option, see the example under --sigclip-median in Section 7.1.5 [Invoking Statistics], page 257.

--inpolygon=STR1,STR2
Only return rows where the given coordinates are inside the polygon specified by the --polygon option. The coordinate columns are the given STR1 and STR2 columns, they can be a column name or counter (see Section 4.8.3 [Selecting table columns], page 140).
Note that the chosen columns doesn’t have to be in the output columns (which are specified by the --column option). For example if we want to select rows in the polygon specified in Section 2.2.4 [Dataset inspection and cropping], page 27, this option can be used like this (you can remove the double quotations and write them all in one line if you remove the white-spaces around the colon separating the column vertices):

```
asttable table.fits --inpolygon=RA,DEC
--polygon="53.187414,-27.779152
: 53.159507,-27.759633
: 53.134517,-27.787144
: 53.161906,-27.807208"
```

Flat/Euclidean space: The --inpolygon option assumes a flat/Euclidean space so it is only correct for RA and Dec when the polygon size is very small like the example above. If your polygon is a degree or larger, it may not return correct results. We are working on other options for this.

--outpolygon=STR1,STR2
Only return rows where the given coordinates are outside the polygon specified by the --polygon option. This option is very similar to the --inpolygon option, so see the description there for more.

--polygon=FLT:FLT,...
The polygon to use for the --inpolygon and --outpolygon options. The values to this option is parsed in the same way that the Crop program, see its description there for more: Section 6.1.4.1 [Crop options], page 193.
-e STR,INT/FLT,...
--equal=STR,INT/FLT,...
Only output rows that are equal to the given number(s) in the given column. The first argument is the column identifier (name or number, see Section 4.8.3 [Selecting table columns], page 140), after that you can specify any number of values. For example --equal=ID,5,6,8 will only print the rows that have a value of 5, 6, or 8 in the ID column. This option can also be called multiple times, so --equal=ID,4,5 --equal=ID,6,7 has the same effect as --equal=4,5,6,7.

The --equal and --notequal options also work when the given column has a string type. In this case the given value to the option will also be parsed as a string, not as a number. When dealing with string columns, be careful with trailing white space characters (the actual value maybe adjusted to the right, left, or center of the column’s width). If you need to account for such white spaces, you can use shell quoting. For example --equal=NAME," myname ".

### Equality and floating point numbers:
Floating point numbers are only approximate values (see Section 4.6 [Numeric data types], page 130). In this context, their equality depends on how the the input table was originally stored (as a plain text table or as an ASCII/binary FITS table). If you want to select floating point numbers, it is strongly recommended to use the --range option and set a very small interval around your desired number, don’t use --equal or --notequal.

-n STR,INT/FLT,...
--notequal=STR,INT/FLT,...
Only output rows that are not equal to the given number(s) in the given column. The first argument is the column identifier (name or number, see Section 4.8.3 [Selecting table columns], page 140), after that you can specify any number of values. For example --notequal=ID,5,6,8 will only print the rows where the ID column doesn’t have value of 5, 6, or 8. This option can also be called multiple times, so --notequal=ID,4,5 --notequal=ID,6,7 has the same effect as --notequal=4,5,6,7.

Be very careful if you want to use the non-equality with floating point numbers, see the special note under --equal for more. This option also works when the given column has a string type, see the description under --equal (above) for more.

-s STR
--sort=STR
Sort the output rows based on the values in the STR column (can be a column name or number). By default the sort is done in ascending/increasing order, to sort in a descending order, use --descending.

The chosen column doesn’t have to be in the output columns. This is good when you just want to sort using one column’s values, but don’t need that column anymore afterwards.
-d
--descending
When called with --sort, rows will be sorted in descending order.

-H INT
--head=INT
Only print the given number of rows from the top of the final table. Note that this option only affects the output table. For example if you use --sort, or --range, the printed rows are the first after applying the sort sorting, or selecting a range of the full input.

If the given value to --head is 0, the output columns won’t have any rows and if its larger than the number of rows in the input table, all the rows are printed (this option is effectively ignored). This behavior is taken from the head program in GNU Coreutils.

-t INT
--tail=INT
Only print the given number of rows from the bottom of the final table. See --head for more.

-b STR[,STR[,STR]]
--noblank=STR[,STR[,STR]]
Remove all rows in the given output columns that have a blank value. Like above, the columns can be specified by their name or number (counting from 1). --noblank is applied just before writing the final table (after --colmetadata has finished). So in case you changed the column metadata, or added new columns, you can use the new names, or the newly defined column numbers.

For example if table.fits has blank values (NaN in floating point types) in the magnitude and sn columns, with --noblank=magnitude,sn, the output will not contain any rows with blank values in these columns.

-m STR/INT,STR[,STR[,STR]]
--colmetadata=STR/INT,STR[,STR[,STR]]
Update the specified column metadata in the output table. This option is applied after all other column-related operations are complete, for example column arithmetic, or column concatenation. The first value (before the first comma) given to this option is the column’s identifier. It can either be a counter (positive integer, counting from 1), or a name (the column’s name in the output if this option wasn’t called).

After the to-be-updated column is identified, at least one other string should be given, with a maximum of three strings. The first string after the original name will the the selected column’s new name. The next (optional) string will be the selected column’s unit and the third (optional) will be its comments. If the two optional strings aren’t given, the original column’s units or comments will remain unchanged. Some examples of this option are available in the tutorials, in particular Section 2.2.14 [Working with catalogs (estimating colors)], page 46. Here are some more specific examples
--colmetadata=MAGNITUDE,MAG_F160W
This will convert name of the original MAGNITUDE column to MAG_F160W, leaving the unit and comments unchanged.

--colmetadata=3,MAG_F160W,mag
This will convert name of the third column of the final output to MAG_F160W and the units to mag, while leaving the comments untouched.

--colmetadata=MAGNITUDE,MAG_F160W,mag,"Magnitude in F160W filter"
This will convert name of the original MAGNITUDE column to MAG_F160W, and the units to mag and the comments to Magnitude in F160W filter. Note the double quotations around the comment string, they are necessary to preserve the white-space characters within the column comment from the command-line, into the program (otherwise, upon reaching a white-space character, the shell will consider this option to be finished and cause un-expected behavior).

If your table is large and generated by a script, you can first do all your operations on your table’s data and write it into a temporary file (maybe called temp.fits). Then, look into that file’s metadata (with asttable temp.fits -i) to see the exact column positions and possible names, then add the necessary calls to this option to your previous call to asttable, so it writes proper metadata in the same run (for example in a script or Makefile). Recall that when a name is given, this option will update the metadata of the first column that matches, so if you have multiple columns with the same name, you can call this options multiple times with the same first argument to change them all to different names.

Finally, if you already have a FITS table by other means (for example by downloading) and you merely want to update the column metadata and leave the data intact, it is much more efficient to directly modify the respective FITS header keywords with astfits, using the keyword manipulation features described in Section 5.1.1.2 [Keyword manipulation], page 152. --colmetadata is mainly intended for scenarios where you want to edit the data so it will always load the full/partial dataset into memory, then write out the resulting datasets with updated/corrected metadata.

5.5 Query
There are many astronomical databases available for downloading astronomical data. Each has its own interface, which is usually very well documented in their own webpages. However, remembering the exact URLs and interface of each database is not easily possible and using the graphic web interface (which is commonly easier to use), is not an automatic process.

Gnuastro's Query program is designed to address these problems: it has a common high-level interface for general operations that are common between its recognized databases. For example, importing a catalog of objects within a certain distance of a given coordinate.
5.5.1 Invoking Query

Query provides a high-level interface to downloading subsets of data from databases. The executable name is `astquery` with the following general template

```
$ astquery [OPTION...] ...
```

One line examples:

```
## Import all the columns of all entries in the Gaia DR2 catalog within
## 20 arc-minutes of the given coordinate.
$ astquery --database=gaia --dataset=dr2 --output=my-gaia.fits \
   --center=113.8729761,31.9027152 --radius=20/60

## Similar to above, but return all objects within a square box of
## 30 arcminutes (can also be rectangular, see '--width').
$ astquery --database=gaia --dataset=dr2 --output=my-gaia.fits \
   --center=113.8729761,31.9027152 --width=30/60

## Similar to above, but for objects with magnitude range 10 to 15
$ astquery --database=gaia --dataset=dr2 --output=my-gaia.fits \
   --center=113.8729761,31.9027152 --width=30/60 \
   --range=phot_g_mean_mag,10:15

## Similar to first example, but only import the ID, RA, Dec and G-band
## magnitude of the sources (not all the columns).
$ astquery --database=gaia --dataset=dr2 --output=my-gaia.fits \
   --center=113.8729761,31.9027152 --radius=0.1 \
   --column=source_id,ra,dec,phot_g_mean_mag

## Find the ID, RA and Dec of all Gaia sources within an image.
$ astquery --database=gaia --dataset=dr2 --overlapwith=image.fits \
   --csource_id,ra,dec

## Use a custom query to extract entries in the Gaia DR2 catalog.
## The 'XXXX YYYY' can be a query of any size on the command-line.
$ astquery --database=gaia --query="XXXX YYYY" --output=my-gaia.fits
```

Query doesn’t take any input argument, because the main goal is to retrieve data from external sources. The main input to Query is the `--database` option which specifies which database should be contacted for submitting the query. The name of the downloaded output file can optionally be set with `--output`. If `--output` is not set, an automatically generated name will be used.

There are two methods to query the database: 1) with `--query` you can directly give a raw query statement that is recognized by the database, 2) with the `--center` and `--radius`, the low-level query will constructed automatically for the particular database. The former is very low level and will require some knowledge of the database’s query language, but of course, it is much more powerful. The latter is much more limited in terms of capabilities (the only constraint is the location of the objects compared to the given center), but doesn’t require any knowledge of the database’s query language.
Under development, request for feedback: Query is a new member of the Gnuastro family of programs. It currently requires that the curl executable (for the cURL downloading program) to be present on the host and the number of databases it supports is still limited, see the list under the --database option below. More downloader tools, and databases will be added in the near future as it is used more often, so please don’t hesitate to suggest any that you may need.

-d STR
--database=STR
  Identifier for the database for sending the query. The current list of databases are listed here:

  gaia  The Gaia project (https://www.cosmos.esa.int/web/gaia) database which is a large collection of star positions on the celestial sphere, as well as peculiar velocities, parallaxes and magnitudes in some bands among many others. Besides scientific studies (like studying resolved stellar populations in the Galaxy and its halo), Gaia is also invaluable for raw data calibrations, like astrometry. The query given to this database will be submitted to https://gea.esac.esa.int/tap-server/tap-sync.

-Q "STR"
--query="STR"
  Directly specify the query to be passed onto the database. The queries will generally contain space and other meta-characters, so we recommend placing the query within quotations.

-s STR
--dataset=STR
  The dataset to query within the database for the automatically generated query (not compatible with --query). The reason for this is that many databases have different types of datasets, for example different data releases (DRs), or various high-level calculations on subsets of the database elements. For example when --database=gaia, you can set --dataset=dr2 to only select objects within the second data release (DR2).

You can either use the database’s official name of the datasets, for example gaiadr2.gaia_source for the second data release of the Gaia database, or a simplified version that maps to it (dr2) for easy typing on the command-line. Below is a list of the simplified names for the databases that have them.

  gaia
    • dr2 --> gaiadr2.gaia_source
    • dr2 --> gaiadr1.gaia_source
    • tyco2 --> public.tyco2
    • hipparcos --> public.hipparcos

-v STR
--overlapwith=STR
  File name containing image (in the HDU given by --hdu) to use for identifying the region to query in the give database and dataset. Based on the image’s
WCS, the area it covers is estimated and values to the --center, --width will be calculated internally. Hence this option cannot be used with --center, --width or --radius. Also, since it internally generates the query, it can’t be used with --query.

-C FLT,FLT
--center=FLT,FLT
The center to use for the automatically generated query (not compatible with --query). All objects within a certain distance of the requested center position will be requested from the dataset. The distance can be specified with the --radius option.

-r FLT
--radius=FLT
The radius about the requested center to use for the automatically generated query (not compatible with --query). The radius is in units of degrees, but you can use simple division with this option directly on the command-line. For example if you want a radius of 20 arc-minutes or 20 arc-seconds, you can use --radius=20/60 or --radius=20/3600 respectively (which is much more human-friendly than 0.3333 or 0.005556).

-w FLT[,FLT]
--width=FLT[,FLT]
The square (or rectangle) side length (width) about the requested center to use for the automatically generated query (not compatible with --query). If only one value is given to --width the region will be a square, but if two values are given, the widths of the query box along each dimension will be different. The value(s) is(are) in units of degrees, but you can use simple division for each value directly on the command-line, see the description of --radius for more on using division.

-g STR,FLT,FLT
--range=STR,FLT,FLT
The column name and numerical range (inclusive) of acceptable values in that column (not compatible with --query). This option can be called multiple times for applying range limits on many columns in one call (thus greatly reducing the download size). For example --range=phot_g_mean_mag,10:15 will only query for rows that have a value between 10 and 15 (inclusive) in the phot_g_mean_mag column (from the Gaia catalog).
If you want the interval to not be inclusive on both sides, you can run astquery once and get the command that it executes. Then you can edit it to be non-inclusive on one side.

-c STR
--column=STR[,STR[,...]]
The optional column name(s) to retrieve from the dataset in the automatically generated query (not compatible with --query). If not given, all the dataset’s columns for the selected rows will be used (which can be large!). This option can take multiple values in one instance (for example --column=ra,dec,mag),
or in multiple instances (for example `-cra -cd dec -cmag`), or mixed (for example `-cra,dec -cmag`).

In case, you don’t know the full list of the dataset’s column names, one solution is to run this program once without any `--column` and setting `--radius=0` (to have few, or no, rows and download fast). You can then inspect the column names with Section 5.4 [Table], page 171. In case the database doesn’t support a search radius of 0, or can’t return a table with no rows, you can increase the radius. Here is an example on the Gaia DR2 catalog to show the full list of available columns:

```
$ astquery --database=gaia --dataset=dr2 --center=0,0 \\
  --radius=0 --output=gaia-dr2-cols.fits
$ asttable gaia-dr2-cols.fits --info
```
6 Data manipulation

Images are one of the major formats of data that is used in astronomy. The functions in this chapter explain the GNU Astronomy Utilities which are provided for their manipulation. For example cropping out a part of a larger image or convolving the image with a given kernel or applying a transformation to it.

6.1 Crop

Astronomical images are often very large, filled with thousands of galaxies. It often happens that you only want a section of the image, or you have a catalog of sources and you want to visually analyze them in small postage stamps. Crop is made to do all these things. When more than one crop is required, Crop will divide the crops between multiple threads to significantly reduce the run time.

Astronomical surveys are usually extremely large. So large in fact, that the whole survey will not fit into a reasonably sized file. Because of this, surveys usually cut the final image into separate tiles and store each tile in a file. For example the COSMOS survey’s Hubble space telescope, ACS F814W image consists of 81 separate FITS images, with each one having a volume of 1.7 Giga bytes.

Even though the tile sizes are chosen to be large enough that too many galaxies/targets don’t fall on the edges of the tiles, inevitably some do. So when you simply crop the image of such targets from one tile, you will miss a large area of the surrounding sky (which is essential in estimating the noise). Therefore in its WCS mode, Crop will stitch parts of the tiles that are relevant for a target (with the given width) from all the input images that cover that region into the output. Of course, the tiles have to be present in the list of input files.

Besides cropping postage stamps around certain coordinates, Crop can also crop arbitrary polygons from an image (or a set of tiles by stitching the relevant parts of different tiles within the polygon), see \texttt{--polygon} in Section 6.1.4 [Invoking Crop], page 192. Alternatively, it can crop out rectangular regions through the \texttt{--section} option from one image, see Section 6.1.2 [Crop section syntax], page 191.

6.1.1 Crop modes

In order to be comprehensive, intuitive, and easy to use, there are two ways to define the crop:

1. From its center and side length. For example if you already know the coordinates of an object and want to inspect it in an image or to generate postage stamps of a catalog containing many such coordinates.

2. The vertices of the crop region, this can be useful for larger crops over many targets, for example to crop out a uniformly deep, or contiguous, region of a large survey.

Irrespective of how the crop region is defined, the coordinates to define the crop can be in Image (pixel) or World Coordinate System (WCS) standards. All coordinates are read as floating point numbers (not integers, except for the \texttt{--section} option, see below). By setting the \texttt{mode} in Crop, you define the standard that the given coordinates must be interpreted. Here, the different ways to specify the crop region are discussed within each standard. For the full list options, please see Section 6.1.4 [Invoking Crop], page 192.
Chapter 6: Data manipulation

When the crop is defined by its center, the respective (integer) central pixel position will be found internally according to the FITS standard. To have this pixel positioned in the center of the cropped region, the final cropped region will have an add number of pixels (even if you give an even number to \texttt{--width} in image mode).

Furthermore, when the crop is defined as by its center, Crop allows you to only keep crops what don’t have any blank pixels in the vicinity of their center (your primary target). This can be very convenient when your input catalog/coordinates originated from another survey/filter which is not fully covered by your input image, to learn more about this feature, please see the description of the \texttt{--checkcenter} option in Section 6.1.4 [Invoking Crop], page 192.

Image coordinates

In image mode (\texttt{--mode=img}), Crop interprets the pixel coordinates and widths in units of the input data-elements (for example pixels in an image, not world coordinates). In image mode, only one image may be input. The output crop(s) can be defined in multiple ways as listed below.

Center of multiple crops (in a catalog)

The center of (possibly multiple) crops are read from a text file. In this mode, the columns identified with the \texttt{--coordcol} option are interpreted as the center of a crop with a width of \texttt{--width} pixels along each dimension. The columns can contain any floating point value. The value to \texttt{--output} option is seen as a directory which will host (the possibly multiple) separate crop files, see Section 6.1.4.2 [Crop output], page 198, for more. For a tutorial using this feature, please see Section 2.2.17 [Finding reddest clumps and visual inspection], page 53.

Center of a single crop (on the command-line)

The center of the crop is given on the command-line with the \texttt{--center} option. The crop width is specified by the \texttt{--width} option along each dimension. The given coordinates and width can be any floating point number.

Vertices of a single crop

In Image mode there are two options to define the vertices of a region to crop: \texttt{--section} and \texttt{--polygon}. The former is lower-level (doesn’t accept floating point vertices, and only a rectangular region can be defined), it is also only available in Image mode. Please see Section 6.1.2 [Crop section syntax], page 191, for a full description of this method.

The latter option (\texttt{--polygon}) is a higher-level method to define any polygon (with any number of vertices) with floating point values. Please see the description of this option in Section 6.1.4 [Invoking Crop], page 192, for its syntax.

WCS coordinates

In WCS mode (\texttt{--mode=wcs}), the coordinates and widths are interpreted using the World Coordinate System (WCS, that must accompany the dataset),
not pixel coordinates. In WCS mode, Crop accepts multiple datasets as input. When the cropped region (defined by its center or vertices) overlaps with multiple of the input images/tiles, the overlapping regions will be taken from the respective input (they will be stitched when necessary for each output crop).

In this mode, the input images do not necessarily have to be the same size, they just need to have the same orientation and pixel resolution. Currently only orientation along the celestial coordinates is accepted, if your input has a different orientation you can use Warp’s --align option to align the image before cropping it (see Section 6.4 [Warp], page 238).

Each individual input image/tile can even be smaller than the final crop. In any case, any part of any of the input images which overlaps with the desired region will be used in the crop. Note that if there is an overlap in the input images/tiles, the pixels from the last input image read are going to be used for the overlap. Crop will not change pixel values, so it assumes your overlapping tiles were cutout from the same original image. There are multiple ways to define your cropped region as listed below.

Center of multiple crops (in a catalog)

Similar to catalog inputs in Image mode (above), except that the values along each dimension are assumed to have the same units as the dataset’s WCS information. For example, the central RA and Dec value for each crop will be read from the first and second calls to the --coordcol option. The width of the cropped box (in units of the WCS, or degrees in RA and Dec mode) must be specified with the --width option.

Center of a single crop (on the command-line)

You can specify the center of only one crop box with the --center option. If it exists in the input images, it will be cropped similar to the catalog mode, see above also for --width.

Vertices of a single crop

The --polygon option is a high-level method to define any convex polygon (with any number of vertices). Please see the description of this option in Section 6.1.4 [Invoking Crop], page 192, for its syntax.

**CAUTION:** In WCS mode, the image has to be aligned with the celestial coordinates, such that the first FITS axis is parallel (opposite direction) to the Right Ascension (RA) and the second FITS axis is parallel to the declination. If these conditions aren’t met for an image, Crop will warn you and abort. You can use Warp’s --align option to align the input image with these coordinates, see Section 6.4 [Warp], page 238.

As a summary, if you don’t specify a catalog, you have to define the cropped region manually on the command-line. In any case the mode is mandatory for Crop to be able to interpret the values given as coordinates or widths.
6.1.2 Crop section syntax

When in image mode, one of the methods to crop only one rectangular section from the input image is to use the `--section` option. Crop has a powerful syntax to read the box parameters from a string of characters. If you leave certain parts of the string to be empty, Crop can fill them for you based on the input image sizes.

To define a box, you need the coordinates of two points: the first \((X_1, Y_1)\) and the last pixel \((X_2, Y_2)\) pixel positions in the image, or four integer numbers in total. The four coordinates can be specified with one string in this format: ‘\(X_1:X_2,Y_1:Y_2\)’. This string is given to the `--section` option. Therefore, the pixels along the first axis that are \(\geq X_1\) and \(\leq X_2\) will be included in the cropped image. The same goes for the second axis. Note that each different term will be read as an integer, not a float.

The reason it only accepts integers is that `--section` is a low-level option (which is also very fast!). For a higher-level way to specify region (any polygon, not just a box), please see the `--polygon` option in Section 6.1.4.1 [Crop options], page 193. Also note that in the FITS standard, pixel indexes along each axis start from unity(1) not zero(0).

You can omit any of the values and they will be filled automatically. The left hand side of the colon (:) will be filled with 1, and the right side with the image size. So, \(2:;\) will include the full range of pixels along the second axis and only those with a first axis index larger than 2 in the first axis. If the colon is omitted for a dimension, then the full range is automatically used. So the same string is also equal to \(2;\), or \(2:\) or even 2. If you want such a case for the second axis, you should set it to: \(,2\).

If you specify a negative value, it will be seen as before the indexes of the image which are outside the image along the bottom or left sides when viewed in SAO ds9. In case you want to count from the top or right sides of the image, you can use an asterisk (*). When confronted with a *, Crop will replace it with the maximum length of the image in that dimension. So \(*-10:**10,*-20:**20\) will mean that the crop box will be 20 \(\times\) 40 pixels in size and only include the top corner of the input image with 3/4 of the image being covered by blank pixels, see Section 6.1.3 [Blank pixels], page 191.

If you feel more comfortable with space characters between the values, you can use as many space characters as you wish, just be careful to put your value in double quotes, for example `--section="5:200, 123:854"`. If you forget the quotes, anything after the first space will not be seen by `--section` and you will most probably get an error because the rest of your string will be read as a filename (which most probably doesn’t exist). See Section 4.1 [Command-line], page 105, for a description of how the command-line works.

6.1.3 Blank pixels

The cropped box can potentially include pixels that are beyond the image range. For example when a target in the input catalog was very near the edge of the input image. The parts of the cropped image that were not in the input image will be filled with the following two values depending on the data type of the image. In both cases, SAO ds9 will not color code those pixels.

- If the data type of the image is a floating point type (float or double), IEEE NaN (Not a number) will be used.
- For integer types, pixels out of the image will be filled with the value of the `BLANK` keyword in the cropped image header. The value assigned to it is the lowest value
possible for that type, so you will probably never need it any way. Only for the unsigned character type (BITPIX=8 in the FITS header), the maximum value is used because it is unsigned, the smallest value is zero which is often meaningful.

You can ask for such blank regions to not be included in the output crop image using the --noblank option. In such cases, there is no guarantee that the image size of your outputs are what you asked for.

In some survey images, unfortunately they do not use the BLANK FITS keyword. Instead they just give all pixels outside of the survey area a value of zero. So by default, when dealing with float or double image types, any values that are 0.0 are also regarded as blank regions. This can be turned off with the --zeroisnotblank option.

### 6.1.4 Invoking Crop

Crop will crop a region from an image. If in WCS mode, it will also stitch parts from separate images in the input files. The executable name is astcrop with the following general template

\[
\text{astcrop [OPTION...] [ASCIIcatalog] ASTRdata ...}
\]

One line examples:

- Crop all objects in cat.txt from image.fits:
  
  $ astcrop --catalog=cat.txt image.fits

- Crop all options in catalog (with RA,DEC) from all the files ending in ‘.drz.fits’ in ‘/mnt/data/COSMOS/’:
  
  $ astcrop --mode=wcs --catalog=cat.txt /mnt/data/COSMOS/*_drz.fits

- Crop the outer 10 border pixels of the input image:
  
  $ astcrop --section=10:*-10,10:*-10 --hdu=2 image.fits

- Crop region around RA and Dec of (189.16704, 62.218203):
  
  $ astcrop --mode=wcs --center=189.16704,62.218203 goodsnorth.fits

- Crop region around pixel coordinate (568.342, 2091.719):
  
  $ astcrop --mode=img --center=568.342,2091.719 --width=201 image.fits

Crop has one mandatory argument which is the input image name(s), shown above with ASTRdata .... You can use shell expansions, for example * for this if you have lots of images in WCS mode. If the crop box centers are in a catalog, you can use the --catalog option. In other cases, you have to provide the single cropped output parameters must be given with command-line options. See Section 6.1.4.2 [Crop output], page 198, for how the output file name(s) can be specified. For the full list of general options to all Gnuastro programs (including Crop), please see Section 4.1.2 [Common options], page 109.

Floating point numbers can be used to specify the crop region (except the --section option, see Section 6.1.2 [Crop section syntax], page 191). In such cases, the floating point values will be used to find the desired integer pixel indices based on the FITS standard. Hence, Crop ultimately doesn’t do any sub-pixel cropping (in other words, it doesn’t change pixel values). If you need such crops, you can use Section 6.4 [Warp], page 238, to first warp the image to the a new pixel grid, then crop from that. For example, let’s assume
you want a crop from pixels 12.982 to 80.982 along the first dimension. You should first translate the image by \(-0.482\) (note that the edge of a pixel is at integer multiples of 0.5). So you should run Warp with \(--\text{translate}=-0.482,0\) and then crop the warped image with \(--\text{section}=13:81\).

There are two ways to define the cropped region: with its center or its vertices. See Section 6.1.1 [Crop modes], page 188, for a full description. In the former case, Crop can check if the central region of the cropped image is indeed filled with data or is blank (see Section 6.1.3 [Blank pixels], page 191), and not produce any output when the center is blank, see the description under \(--\text{checkcenter}\) for more.

When in catalog mode, Crop will run in parallel unless you set \(--\text{numthreads}=1\), see Section 4.5 [Multi-threaded operations], page 127. Note that when multiple outputs are created with threads, the outputs will not be created in the same order. This is because the threads are asynchronous and thus not started in order. This has no effect on each output, see Section 2.2.17 [Finding reddest clumps and visual inspection], page 53, for a tutorial on effectively using this feature.

### 6.1.4.1 Crop options

The options can be classified into the following contexts: Input, Output and operating mode options. Options that are common to all Gnuastro program are listed in Section 4.1.2 [Common options], page 109, and will not be repeated here.

When you are specifying the crop vertices yourself (through \(--\text{section}\), or \(--\text{polygon}\)), on relatively small regions (depending on the resolution of your images) the outputs from image and WCS mode can be approximately equivalent. However, as the crop sizes get large, the curved nature of the WCS coordinates have to be considered. For example, when using \(--\text{section}\), the right ascension of the bottom left and top left corners will not be equal. If you only want regions within a given right ascension, use \(--\text{polygon}\) in WCS mode.

**Input image parameters:**

\(--\text{hstartwcs}=\text{INT}\)

Specify the first keyword card (line number) to start finding the input image world coordinate system information. Distortions were only recently included in WCSLIB (from version 5). Therefore until now, different telescope would apply their own specific set of WCS keywords and put them into the image header along with those that WCSLIB does recognize. So now that WCSLIB recognizes most of the standard distortion parameters, they will get confused with the old ones and give completely wrong results. For example in the CANDELS-GOODS South images\(^1\).

The two \(--\text{hstartwcs}\) and \(--\text{hendwcs}\) are thus provided so when using older datasets, you can specify what region in the FITS headers you want to use to read the WCS keywords. Note that this is only relevant for reading the WCS information, basic data information like the image size are read separately. These two options will only be considered when the value to \(--\text{hendwcs}\) is larger than that of \(--\text{hstartwcs}\). So if they are equal or \(--\text{hstartwcs}\) is larger

\(^1\) [https://archive.stsci.edu/pub/hlsp/candels/goods-s/gs-tot/v1.0/](https://archive.stsci.edu/pub/hlsp/candels/goods-s/gs-tot/v1.0/)
than --hendwcs, then all the input keywords will be parsed to get the WCS
information of the image.

--hendwcs=INT
Specify the last keyword card to read for specifying the image world coordinate
system on the input images. See --hstartwcs

Crop box parameters:
-c FLT[,FLT[,...]]
-center=FLT[,FLT[,...]]
The central position of the crop in the input image. The positions along each
dimension must be separated by a comma (,) and fractions are also acceptable.
The number of values given to this option must be the same as the dimensions
of the input dataset. The width of the crop should be set with --width. The
units of the coordinates are read based on the value to the --mode option, see
below.

-w FLT[,FLT[,...]]
-width=FLT[,FLT[,...]]
Width of the cropped region about its center. --width may take either a single
value (to be used for all dimensions) or multiple values (a specific value for each
dimension). If in WCS mode, value(s) given to this option will be read in the
same units as the dataset’s WCS information along this dimension. The final
output will have an odd number of pixels to allow easy identification of the
pixel which keeps your requested coordinate (from --center or --catalog).
The --width option also accepts fractions. For example if you want the width
of your crop to be 3 by 5 arcseconds along RA and Dec respectively, you can

If you want an even sided crop, you can run Crop afterwards with
-section=":*-1,:*-1" or --section=2:,2: (depending on which side you
don’t need), see Section 6.1.2 [Crop section syntax], page 191.

-l STR
--polygon=STR
String of vertices to define a polygon to crop. The vertices are used to define
the polygon in the same order given to this option. When the vertices are not
necessarily ordered in the proper order (for example one vertice in a square
comes after its diagonal opposite), you can add the --polygonsort option
which will attempt to sort the vertices before cropping. Note that for concave
polygons, sorting is not recommended because there is no unique solution, for
more, see the description under --polygonsort.

This option can be used both in the image and WCS modes, see Section 6.1.1
[Crop modes], page 188. The cropped image will be the size of the rectangular
region that completely encompasses the polygon. By default all the pixels that
are outside of the polygon will be set as blank values (see Section 6.1.3 [Blank
pixels], page 191). However, if --polygonout is called all pixels internal to
the vertices will be set to blank. In WCS-mode, you may provide many FITS
images/tiles: Crop will stitch them to produce this cropped region, then apply the polygon.

The syntax for the polygon vertices is similar to, and simpler than, that for --section. In short, the dimensions of each coordinate are separated by a comma (,) and each vertex is separated by a colon (:). You can define as many vertices as you like. If you would like to use space characters between the dimensions and vertices to make them more human-readable, then you have to put the value to this option in double quotation marks.

For example, let’s assume you want to work on the deepest part of the WFC3/IR images of Hubble Space Telescope eXtreme Deep Field (HST-XDF). According to the webpage (https://archive.stsci.edu/prepds/xdf/) the deepest part is contained within the coordinates:

\[
[ (53.187414,-27.779152), (53.159507,-27.759633), \\
  (53.134517,-27.787144), (53.161906,-27.807208) ]
\]

They have provided mask images with only these pixels in the WFC3/IR images, but what if you also need to work on the same region in the full resolution ACS images? Also what if you want to use the CANDELS data for the shallow region? Running Crop with --polygon will easily pull out this region of the image for you, irrespective of the resolution. If you have set the operating mode to WCS mode in your nearest configuration file (see Section 4.2 [Configuration files], page 120), there is no need to call --mode=wcs on the command line.

\[
\text{\$ astcrop --mode=wcs desired-filter-image(s).fits} \\
\text{\hspace{1cm}--polygon="53.187414,-27.779152 : 53.159507,-27.759633 : \\
\hspace{2cm}53.134517,-27.787144 : 53.161906,-27.807208"}
\]

In other cases, you have an image and want to define the polygon yourself (it isn’t already published like the example above). As the number of vertices increases, checking the vertex coordinates on a FITS viewer (for example SAO ds9) and typing them in one by one can be very tedious and prone to typo errors.

You can take the following steps to avoid the frustration and possible typos:

Open the image with ds9 and activate its “region” mode with Edit→Region. Then define the region as a polygon with Region→Shape→Polygon. Click on the approximate center of the region you want and a small square will appear. By clicking on the vertices of the square you can shrink or expand it, clicking and dragging anywhere on the edges will enable you to define a new vertex. After the region has been nicely defined, save it as a file with Region→Save Regions. You can then select the name and address of the output file, keep the format as REG and press “OK”. In the next window, keep format as “ds9” and “Coordinate System” as “fk5”. A plain text file (let’s call it ds9.reg) is now created.

You can now convert this plain text file to Crop’s polygon format with this command (when typing on the command-line, ignore the “\" at the end of the first and second lines along with the extra spaces, these are only for nice printing):

\[
2 \text{https://archive.stsci.edu/prepds/xdf/}
\]
$ v=$(awk 'NR==4' ds9.reg | sed -e's/polygon//' -e's/\([^,]*,[^,]*\),/\1:/g' -e's/)//' )
$ astcrop --mode=wcs image.fits --polygon=$v

--polygonout
Keep all the regions outside the polygon and mask the inner ones with blank pixels (see Section 6.1.3 [Blank pixels], page 191). This is practically the inverse of the default mode of treating polygons. Note that this option only works when you have only provided one input image. If multiple images are given (in WCS mode), then the full area covered by all the images has to be shown and the polygon excluded. This can lead to a very large area if large surveys like COSMOS are used. So Crop will abort and notify you. In such cases, it is best to crop out the larger region you want, then mask the smaller region with this option.

--polygonsort
Sort the given set of vertices to the --polygon option. For a concave polygon it will sort the vertices correctly, however for a convex polygon it there is no unique sorting, so be careful because the crop may not be what you expected.

Polygons come in two classes: convex and concave (or generally, non-convex!), see below for a demonstration. Convex polygons are those where all inner angles are less than 180 degrees. By contrast, a convex polygon is one where an inner angle may be more than 180 degrees.

<table>
<thead>
<tr>
<th>Concave Polygon</th>
<th>Convex Polygon</th>
</tr>
</thead>
<tbody>
<tr>
<td>D -------- C</td>
<td>D------------ C</td>
</tr>
<tr>
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<td>\E</td>
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<tr>
<td>/</td>
<td>/</td>
</tr>
<tr>
<td>A-------- B</td>
<td>A ---------- B</td>
</tr>
</tbody>
</table>

-s STR
--section=STR
Section of the input image which you want to be cropped. See Section 6.1.2 [Crop section syntax], page 191, for a complete explanation on the syntax required for this input.

-x STR/INT
--coordcol=STR/INT
The column in a catalog to read as a coordinate. The value can be either the column number (starting from 1), or a match/search in the table meta-data, see Section 4.8.3 [Selecting table columns], page 140. This option must be called multiple times, depending on the number of dimensions in the input dataset. If it is called more than necessary, the extra columns (later calls to this option on the command-line or configuration files) will be ignored, see Section 4.2.2 [Configuration file precedence], page 121.
-n STR/INT
--namecol=STR/INT
Column selection of crop file name. The value can be either the column number (starting from 1), or a match/search in the table meta-data, see Section 4.8.3 [Selecting table columns], page 140. This option can be used both in Image and WCS modes, and not a mandatory. When a column is given to this option, the final crop base file name will be taken from the contents of this column. The directory will be determined by the --output option (current directory if not given) and the value to --suffix will be appended. When this column isn’t given, the row number will be used instead.

Output options:

-c FLT/INT
--checkcenter=FLT/INT
Square box width of region in the center of the image to check for blank values. If any of the pixels in this central region of a crop (defined by its center) are blank, then it will not be stored in an output file. If the value to this option is zero, no checking is done. This check is only applied when the cropped region(s) are defined by their center (not by the vertices, see Section 6.1.1 [Crop modes], page 188).

The units of the value are interpreted based on the --mode value (in WCS or pixel units). The ultimate checked region size (in pixels) will be an odd integer around the center (converted from WCS, or when an even number of pixels are given to this option). In WCS mode, the value can be given as fractions, for example if the WCS units are in degrees, \(0.1/3600\) will correspond to a check size of 0.1 arcseconds.

Because survey regions don’t often have a clean square or rectangle shape, some of the pixels on the sides of the survey FITS image don’t commonly have any data and are blank (see Section 6.1.3 [Blank pixels], page 191). So when the catalog was not generated from the input image, it often happens that the image does not have data over some of the points.

When the given center of a crop falls in such regions or outside the dataset, and this option has a non-zero value, no crop will be created. Therefore with this option, you can specify a width of a small box (3 pixels is often good enough) around the central pixel of the cropped image. You can check which crops were created and which weren’t from the command-line (if --quiet was not called, see Section 4.1.2.3 [Operating mode options], page 114), or in Crop’s log file (see Section 6.1.4.2 [Crop output], page 198).

-p STR
--suffix=STR
The suffix (or post-fix) of the output files for when you want all the cropped images to have a special ending. One case where this might be helpful is when besides the science images, you want the weight images (or exposure maps, which are also distributed with survey images) of the cropped regions too. So in one run, you can set the input images to the science images and --suffix=...
s.fits. In the next run you can set the weight images as input and --suffix=_w.fits.

-b
--noblank
Pixels outside of the input image that are in the crop box will not be used. By default they are filled with blank values (depending on type), see Section 6.1.3 [Blank pixels], page 191. This option only applies only in Image mode, see Section 6.1.1 [Crop modes], page 188.

-z
--zeroisnotblank
In float or double images, it is common to give the value of zero to blank pixels. If the input image type is one of these two types, such pixels will also be considered as blank. You can disable this behavior with this option, see Section 6.1.3 [Blank pixels], page 191.

Operating mode options:

-0 STR
--mode=STR
Operate in Image mode or WCS mode when the input coordinates can be both image or WCS. The value must either be img or wcs, see Section 6.1.1 [Crop modes], page 188, for a full description.

6.1.4.2 Crop output

The string given to --output option will be interpreted depending on how many crops were requested, see Section 6.1.1 [Crop modes], page 188:

- When a catalog is given, the value of the --output (see Section 4.1.2 [Common options], page 109) will be read as the directory to store the output cropped images. Hence if it doesn’t already exist, Crop will abort with an error of a “No such file or directory” error.

  The crop file names will consist of two parts: a variable part (the row number of each target starting from 1) along with a fixed string which you can set with the --suffix option. Optionally, you may also use the --namecol option to define a column in the input catalog to use as the file name instead of numbers.

- When only one crop is desired, the value of the --output option will be read as a file name. If no output is specified or if it is a directory, the output file name will follow the automatic output names of Gnuastro, see Section 4.10 [Automatic output], page 142: The string given to --suffix will be replaced with the .fits suffix of the input.

  The header of each output cropped image will contain the names of the input image(s) it was cut from. If a name is longer than the 70 character space that the FITS standard allows for header keyword values, the name will be cut into several keywords from the nearest slash (/). The keywords have the following format: ICFn_m (for Crop File). Where n is the number of the image used in this crop and m is the part of the name (it can be broken into multiple keywords). Following the name is another keyword named ICFnPIX which shows the pixel range from that input image in the same syntax as Section 6.1.2
[Crop section syntax], page 191. So this string can be directly given to the \texttt{--section} option later.

Once done, a log file can be created in the current directory with the \texttt{--log} option. This file will have three columns and the same number of rows as the number of cropped images. There are also comments on the top of the log file explaining basic information about the run and descriptions for the columns. A short description of the columns is also given below:

1. The cropped image file name for that row.
2. The number of input images that were used to create that image.
3. A 0 if the central few pixels (value to the \texttt{--checkcenter} option) are blank and 1 if they aren’t. When the crop was not defined by its center (see Section 6.1.1 [Crop modes], page 188), or \texttt{--checkcenter} was given a value of 0 (see Section 6.1.4 [Invoking Crop], page 192), the center will not be checked and this column will be given a value of -1.

### 6.2 Arithmetic

It is commonly necessary to do operations on some or all of the elements of a dataset independently (pixels in an image). For example, in the reduction of raw data it is necessary to subtract the Sky value (Section 7.1.4 [Sky value], page 252) from each image image. Later (once the images as warped into a single grid using Warp for example, see Section 6.4 [Warp], page 238), the images are co-added (the output pixel grid is the average of the pixels of the individual input images). Arithmetic is Gnuastro’s program for such operations on your datasets directly from the command-line. It currently uses the reverse polish or post-fix notation, see Section 6.2.1 [Reverse polish notation], page 199, and will work on the native data types of the input images/data to reduce CPU and RAM resources, see Section 4.6 [Numeric data types], page 130. For more information on how to run Arithmetic, please see Section 6.2.3 [Invoking Arithmetic], page 212.

#### 6.2.1 Reverse polish notation

The most common notation for arithmetic operations is the infix notation (https://en.wikipedia.org/wiki/Infix_notation) where the operator goes between the two operands, for example $4 + 5$. While the infix notation is the preferred way in most programming languages, currently the Gnuastro’s program (in particular Arithmetic and Table, when doing column arithmetic) do not use it. This is because it will require parenthesis which can complicate the implementation of the code. In the near future we do plan to also allow this notation$^3$, but for the time being (due to time constraints on the developers), arithmetic operations can only be done in the post-fix notation (also known as reverse polish notation (https://en.wikipedia.org/wiki/Reverse_Polish_notation)). The Wikipedia article provides some excellent explanation on this notation but here we will give a short summary here for self-sufficiency.

In the post-fix notation, the operator is placed after the operands, as we will see below this removes the need to define parenthesis for most ordinary operators. For example, instead of writing $5 \times 6$, we write $5 \ 6 \ +$. To easily understand how this notation works, you can think of each operand as a node in a “last-in-first-out” stack. Every time an operator

is confronted, the operator pops the number of operands it needs from the top of the stack
(so they don’t exist in the stack any more), does its operation and pushes the result back
on top of the stack. So if you want the average of 5 and 6, you would write: 5 6 + 2 /. The
operations that are done are:
1. 5 is an operand, so it is pushed to the top of the stack (which is initially empty).
2. 6 is an operand, so it is pushed to the top of the stack.
3. + is a binary operator, so it will pop the top two elements of the stack out of it, and
perform addition on them (the order is 5 + 6 in the example above). The result is 11
which is pushed to the top of the stack.
4. 2 is an operand so push it onto the top of the stack.
5. / is a binary operator, so pull out the top two elements of the stack (top-most is 2,
then 11) and divide the second one by the first.

In the Arithmetic program, the operands can be FITS images or numbers (see
Section 6.2.3 [Invoking Arithmetic], page 212). In Table’s column arithmetic, they can be
any column or a number (see Section 5.4.1 [Column arithmetic], page 172).

With this notation, very complicated procedures can be created without the need for
parenthesis or worrying about precedence. Even functions which take an arbitrary number
of arguments can be defined in this notation. This is a very powerful notation and is used
in languages like Postscript\(^4\) which produces PDF files when compiled.

### 6.2.2 Arithmetic operators

The recognized operators in Arithmetic are listed below. See Section 6.2.1 [Reverse polish
notation], page 199, for more on how the operators and operands should be ordered on the
command-line. The operands to all operators can be a data array (for example a FITS
image) or a number, the output will be an array or number according to the inputs. For
example a number multiplied by an array will produce an array. The conditional operators
will return pixel, or numerical values of 0 (false) or 1 (true) and stored in an unsigned char
data type (see Section 4.6 [Numeric data types], page 130).

<table>
<thead>
<tr>
<th>Operator</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>+</td>
<td>Addition, so “4 5 +” is equivalent to 4 + 5.</td>
</tr>
<tr>
<td>-</td>
<td>Subtraction, so “4 5 -” is equivalent to 4 − 5.</td>
</tr>
<tr>
<td>x</td>
<td>Multiplication, so “4 5 x” is equivalent to 4 × 5.</td>
</tr>
<tr>
<td>/</td>
<td>Division, so “4 5 /” is equivalent to 4/5.</td>
</tr>
</tbody>
</table>
| %        | Modulo (remainder), so “3 2 %” is equivalent to 1. Note that the modulo oper-

\(^4\) See the EPS and PDF part of Section 5.3.1 [Recognized file formats], page 162, for a little more on the
Postscript language.
Otherwise, the output will be 32-bit floating point (see Section 4.6 [Numeric data types], page 130, for the respective precision). Therefore if you require 64-bit precision in estimating the square root, convert the input to 64-bit floating point first, for example with \texttt{5 float64 sqrt}.

\textbf{log} \quad \text{Natural logarithm of first operand, so “4 log” is equivalent to } ln(4). \text{ The output type is determined from the input, see the explanation under } sqrt \text{ for more.}

\textbf{log10} \quad \text{Base-10 logarithm of first operand, so “4 log10” is equivalent to } log(4). \text{ The output type is determined from the input, see the explanation under } sqrt \text{ for more.}

\textbf{minvalue} \quad \text{Minimum (non-blank) value in the top operand on the stack, so “a.fits minvalue” will push the minimum pixel value in this image onto the stack. Therefore this operator is mainly intended for data (for example images), if the top operand is a number, this operator just returns it without any change. So note that when this operator acts on a single image, the output will no longer be an image, but a number. The output of this operand is in the same type as the input.}

\textbf{maxvalue} \quad \text{Maximum (non-blank) value of first operand in the same type, similar to } minvalue.

\textbf{numbervalue} \quad \text{Number of non-blank elements in first operand in the } uint64 \text{ type, similar to } minvalue.

\textbf{sumvalue} \quad \text{Sum of non-blank elements in first operand in the } float32 \text{ type, similar to } minvalue.

\textbf{meanvalue} \quad \text{Mean value of non-blank elements in first operand in the } float32 \text{ type, similar to } minvalue.

\textbf{stdvalue} \quad \text{Standard deviation of non-blank elements in first operand in the } float32 \text{ type, similar to } minvalue.

\textbf{medianvalue} \quad \text{Median of non-blank elements in first operand with the same type, similar to } minvalue.

\textbf{min} \quad \text{For each pixel, find the minimum value in all given datasets. The output will have the same type as the input.}

The first popped operand to this operator must be a positive integer number which specifies how many further operands should be popped from the stack. All the subsequently popped operands must have the same type and size. This operator (and all the variable-operand operators similar to it that are discussed below) will work in multi-threaded mode unless Arithmetic is called with the \texttt{--numthreads=1} option, see Section 4.5 [Multi-threaded operations], page 127.

Each pixel of the output of the \texttt{min} operator will be given the minimum value of the same pixel from all the popped operands/images. For example the following command will produce an image with the same size and type as the three inputs,
but each output pixel value will be the minimum of the same pixel's values in all three input images.

```
$ astarithmetic a.fits b.fits c.fits 3 min
```

Important notes:
- NaN/blank pixels will be ignored, see Section 6.1.3 [Blank pixels], page 191.
- The output will have the same type as the inputs. This is natural for the `min` and `max` operators, but for other similar operators (for example `sum`, or `average`) the per-pixel operations will be done in double precision floating point and then stored back in the input type. Therefore, if the input was an integer, C’s internal type conversion will be used.

### max
For each pixel, find the maximum value in all given datasets. The output will have the same type as the input. This operator is called similar to the `min` operator, please see there for more.

### number
For each pixel count the number of non-blank pixels in all given datasets. The output will be an unsigned 32-bit integer datatype (see Section 4.6 [Numeric data types], page 130). This operator is called similar to the `min` operator, please see there for more.

### sum
For each pixel, calculate the sum in all given datasets. The output will have the a single-precision (32-bit) floating point type. This operator is called similar to the `min` operator, please see there for more.

### mean
For each pixel, calculate the mean in all given datasets. The output will have the a single-precision (32-bit) floating point type. This operator is called similar to the `min` operator, please see there for more.

### std
For each pixel, find the standard deviation in all given datasets. The output will have the a single-precision (32-bit) floating point type. This operator is called similar to the `min` operator, please see there for more.

### median
For each pixel, find the median in all given datasets. The output will have the a single-precision (32-bit) floating point type. This operator is called similar to the `min` operator, please see there for more.

### quantile
For each pixel, find the quantile from all given datasets. The output will have the same numeric data type and size as the input datasets. Besides the input datasets, the quantile operator also needs a single parameter (the requested quantile). The parameter should be the first popped operand, with a value between (and including) 0 and 1. The second popped operand must be the number of datasets to use.

In the example below, the first-popped operand (0.7) is the quantile, the second-popped operand (3) is the number of datasets to pop.

```
astarithmetic a.fits b.fits c.fits 3 0.7 quantile
```

### sigclip-number
For each pixel, find the sigma-clipped number (after removing outliers) in all given datasets. The output will have the an unsigned 32-bit integer type (see Section 4.6 [Numeric data types], page 130).
This operator will combine the specified number of inputs into a single output that contains the number of remaining elements after $\sigma$-clipping on each element/pixel (for more on $\sigma$-clipping, see Section 7.1.3 [Sigma clipping], page 251). This operator is very similar to $\text{min}$, with the exception that it expects two operands (parameters for sigma-clipping) before the total number of inputs. The first popped operand is the termination criteria and the second is the multiple of $\sigma$.

For example in the command below, the first popped operand (0.2) is the sigma clipping termination criteria. If the termination criteria is larger than, or equal to, 1 it is interpreted as the number of clips to do. But if it is between 0 and 1, then it is the tolerance level on the standard deviation (see Section 7.1.3 [Sigma clipping], page 251). The second popped operand (5) is the multiple of sigma to use in sigma-clipping. The third popped operand (10) is number of datasets that will be used (similar to the first popped operand to $\text{min}$).

```
astarithmetic a.fits b.fits c.fits 3 5 0.2 sigclip-number
```

**sigclip-median**

For each pixel, find the sigma-clipped median in all given datasets. The output will have the a single-precision (32-bit) floating point type. This operator is called similar to the `sigclip-number` operator, please see there for more.

**sigclip-mean**

For each pixel, find the sigma-clipped mean in all given datasets. The output will have the a single-precision (32-bit) floating point type. This operator is called similar to the `sigclip-number` operator, please see there for more.

**sigclip-std**

For each pixel, find the sigma-clipped standard deviation in all given datasets. The output will have the a single-precision (32-bit) floating point type. This operator is called similar to the `sigclip-number` operator, please see there for more.

**filter-mean**

Apply mean filtering (or moving average ([https://en.wikipedia.org/wiki/Moving_average](https://en.wikipedia.org/wiki/Moving_average))) on the input dataset. During mean filtering, each pixel (data element) is replaced by the mean value of all its surrounding pixels (excluding blank values). The number of surrounding pixels in each dimension (to calculate the mean) is determined through the earlier operands that have been pushed onto the stack prior to the input dataset. The number of necessary operands is determined by the dimensions of the input dataset (first popped operand). The order of the dimensions on the command-line is the order in FITS format. Here is one example:

```
$ astarithmetic 5 4 image.fits filter-mean
```

In this example, each pixel is replaced by the mean of a 5 by 4 box around it. The box is 5 pixels along the first FITS dimension (horizontal when viewed in ds9) and 4 pixels along the second FITS dimension (vertical).

Each pixel will be placed in the center of the box that the mean is calculated on. If the given width along a dimension is even, then the center is assumed to be
between the pixels (not in the center of a pixel). When the pixel is close to the edge, the pixels of the box that fall outside the image are ignored. Therefore, on the edge, less points will be used in calculating the mean.

The final effect of mean filtering is to smooth the input image, it is essentially a convolution with a kernel that has identical values for all its pixels (is flat), see Section 6.3.1.1 [Convolution process], page 217.

Note that blank pixels will also be affected by this operator: if there are any non-blank elements in the box surrounding a blank pixel, in the filtered image, it will have the mean of the non-blank elements, therefore it won’t be blank any more. If blank elements are important for your analysis, you can use the isblank with the where operator to set them back to blank after filtering.

**filter-median**

Apply median filtering (https://en.wikipedia.org/wiki/Median_filter) on the input dataset. This is very similar to filter-mean, except that instead of the mean value of the box pixels, the median value is used to replace a pixel value. For more on how to use this operator, please see filter-mean.

The median is less susceptible to outliers compared to the mean. As a result, after median filtering, the pixel values will be more discontinuous than mean filtering.

**filter-sigclip-mean**

Apply a σ-clipped mean filtering onto the input dataset. This is very similar to filter-mean, except that all outliers (identified by the σ-clipping algorithm) have been removed, see Section 7.1.3 [Sigma clipping], page 251, for more on the basics of this algorithm. As described there, two extra input parameters are necessary for σ-clipping: the multiple of σ and the termination criteria. filter-sigclip-mean therefore needs to pop two other operands from the stack after the dimensions of the box.

For example the line below uses the same box size as the example of filter-mean. However, all elements in the box that are iteratively beyond 3σ of the distribution’s median are removed from the final calculation of the mean until the change in σ is less than 0.2.

$$\text{astarithmetic 3 0.2 5 4 image.fits filter-sigclip-mean}$$

The median (which needs a sorted dataset) is necessary for σ-clipping, therefore filter-sigclip-mean can be significantly slower than filter-mean. However, if there are strong outliers in the dataset that you want to ignore (for example emission lines on a spectrum when finding the continuum), this is a much better solution.

**filter-sigclip-median**

Apply a σ-clipped median filtering onto the input dataset. This operator and its necessary operands are almost identical to filter-sigclip-mean, except that after σ-clipping, the median value (which is less affected by outliers than the mean) is added back to the stack.
**interpolate-medianngb**
Interpolate all the blank elements of the second popped operand with the median of its nearest non-blank neighbors. The number of the nearest non-blank neighbors used to calculate the median is given by the first popped operand. Note that the distance of the nearest non-blank neighbors is irrelevant in this interpolation.

**interpolate-minngb**
Similar to **interpolate-medianngb**, but will fill the blank values of the dataset with the minimum value of the nearest neighbors.

**interpolate-maxngb**
Similar to **interpolate-medianngb**, but will fill the blank values of the dataset with the maximum value of the nearest neighbors. One useful implementation of this operator is to fill the saturated pixels of stars in images.

**collapse-sum**
Collapse the given dataset (second popped operand), by summing all elements along the first popped operand (a dimension in FITS standard: counting from one, from fastest dimension). The returned dataset has one dimension less compared to the input.

The output will have a double-precision floating point type irrespective of the input dataset’s type. Doing the operation in double-precision (64-bit) floating point will help the collapse (summation) be affected less by floating point errors. But afterwards, single-precision floating points are usually enough in real (noisy) datasets. So depending on the type of the input and its nature, it is recommended to use one of the type conversion operators on the returned dataset.

If any WCS is present, the returned dataset will also lack the respective dimension in its WCS matrix. Therefore, when the WCS is important for later processing, be sure that the input is aligned with the respective axes: all non-diagonal elements in the WCS matrix are zero.

One common application of this operator is the creation of pseudo broad-band or narrow-band 2D images from 3D data cubes. For example integral field unit (IFU) data products that have two spatial dimensions (first two FITS dimensions) and one spectral dimension (third FITS dimension). The command below will collapse the whole third dimension into a 2D array the size of the first two dimensions, and then convert the output to single-precision floating point (as discussed above).

```
$ astarithmetic cube.fits 3 collapse-sum float32
```

**collapse-mean**
Similar to **collapse-sum**, but the returned dataset will be the mean value along the collapsed dimension, not the sum.

**collapse-number**
Similar to **collapse-sum**, but the returned dataset will be the number of non-blank values along the collapsed dimension. The output will have a 32-bit signed integer type. If the input dataset doesn’t have blank values, all the elements
in the returned dataset will have a single value (the length of the collapsed dimension). Therefore this is mostly relevant when there are blank values in the dataset.

**collapse-min**
Similar to **collapse-sum**, but the returned dataset will have the same numeric type as the input and will contain the minimum value for each pixel along the collapsed dimension.

**collapse-max**
Similar to **collapse-sum**, but the returned dataset will have the same numeric type as the input and will contain the maximum value for each pixel along the collapsed dimension.

**add-dimension**
Build a higher-dimensional dataset from all the input datasets stacked after one another (along the slowest dimension). The first popped operand has to be a single number. It is used by the operator to know how many operands it should pop from the stack (and the size of the output in the new dimension). The rest of the operands must have the same size and numerical data type. This operator currently only works for 2D input operands, please contact us if you want inputs to have different dimensions.

The output’s WCS (which should have a different dimensionality compared to the inputs) can be read from another file with the **--wcsfile** option. If no file is specified for the WCS, the first dataset’s WCS will be used, you can later add/change the necessary WCS keywords with the FITS keyword modification features of the Fits program (see Section 5.1 [Fits], page 146).

If your datasets don’t have the same type, you can use the type transformation operators of Arithmetic that are discussed below. Just beware of overflow if you are transforming to a smaller type, see Section 4.6 [Numeric data types], page 130.

For example if you want to put the three **img1.fits**, **img2.fits** and **img3.fits** images (each a 2D dataset) into one 3D datacube, you can use this command:

```bash
$ astarithmetic img1.fits img2.fits img3.fits 3 add-dimension
```

**unique**
Remove all duplicate (and blank) elements from the first popped operand. The unique elements of the dataset will be stored in a single-dimensional dataset. Recall that by default, single-dimensional datasets are stored as a table column in the output. But you can use **--onedasimage** or **--onedonstdout** to respectively store them as a single-dimensional FITS array/image, or to print them on the standard output.

**erode**
Erode the foreground pixels (with value 1) of the input dataset (second popped operand). The first popped operand is the connectivity (see description in **connected-components**). Erosion is simply a flipping of all foreground pixels (with value 1) to background (with value 0) that are “touching” background pixels. “Touching” is defined by the connectivity. In effect, this carves off the outer borders of the foreground, making them thinner. This operator assumes a binary dataset (all pixels are 0 and 1).
dilate
Dilate the foreground pixels (with value 1) of the input dataset (second popped operand). The first popped operand is the connectivity (see description in connected-components). Dilation is simply a flipping of all background pixels (with value 0) to foreground (with value 1) that are “touching” foreground pixels. “Touching” is defined by the connectivity. In effect, this expands the outer borders of the foreground. This operator assumes a binary dataset (all pixels are 0 and 1).

connected-components
Find the connected components in the input dataset (second popped operand). The first popped is the connectivity used in the connected components algorithm. The second popped operand is the dataset where connected components are to be found. It is assumed to be a binary image (with values of 0 or 1). It must have an 8-bit unsigned integer type which is the format produced by conditional operators. This operator will return a labeled dataset where the non-zero pixels in the input will be labeled with a counter (starting from 1).

The connectivity is a number between 1 and the number of dimensions in the dataset (inclusive). 1 corresponds to the weakest (symmetric) connectivity between elements and the number of dimensions the strongest. For example on a 2D image, a connectivity of 1 corresponds to 4-connected neighbors and 2 corresponds to 8-connected neighbors.

One example usage of this operator can be the identification of regions above a certain threshold, as in the command below. With this command, Arithmetic will first separate all pixels greater than 100 into a binary image (where pixels with a value of 1 are above that value). Afterwards, it will label all those that are connected.

\$ astarithmetic in.fits 100 gt 2 connected-components

If your input dataset doesn’t have a binary type, but you know all its values are 0 or 1, you can use the uint8 operator (below) to convert it to binary.

fill-holes
Flip background (0) pixels surrounded by foreground (1) in a binary dataset. This operator takes two operands (similar to connected-components): the first popped operand is the connectivity (to define a hole) and the second is the binary (0 or 1 valued) dataset to fill holes in.

invert
Invert an unsigned integer dataset. This is the only operator that ignores blank values (which are set to be the maximum values in the unsigned integer types). This is useful in cases where the target(s) has(have) been imaged in absorption as raw formats (which are unsigned integer types). With this option, the maximum value for the given type will be subtracted from each pixel value, thus “inverting” the image, so the target(s) can be treated as emission. This can be useful when the higher-level analysis methods/tools only work on emission (positive skew in the noise, not negative).

lt
Less than: If the second popped (or left operand in infix notation, see Section 6.2.1 [Reverse polish notation], page 199) value is smaller than the first popped operand, then this function will return a value of 1, otherwise it
will return a value of 0. If both operands are images, then all the pixels will be compared with their counterparts in the other image. If only one operand is an image, then all the pixels will be compared with the single value (number) of the other operand. Finally if both are numbers, then the output is also just one number (0 or 1). When the output is not a single number, it will be stored as an unsigned char type.

le  Less or equal: similar to lt (‘less than’ operator), but returning 1 when the second popped operand is smaller or equal to the first.

gt  Greater than: similar to lt (‘less than’ operator), but returning 1 when the second popped operand is greater than the first.

ge  Greater or equal: similar to lt (‘less than’ operator), but returning 1 when the second popped operand is larger or equal to the first.

eq  Equality: similar to lt (‘less than’ operator), but returning 1 when the two popped operands are equal (to double precision floating point accuracy).

e  Non-Equality: similar to lt (‘less than’ operator), but returning 1 when the two popped operands are not equal (to double precision floating point accuracy).

and Logical AND: returns 1 if both operands have a non-zero value and 0 if both are zero. Both operands have to be the same kind: either both images or both numbers.

or Logical OR: returns 1 if either one of the operands is non-zero and 0 only when both operators are zero. Both operands have to be the same kind: either both images or both numbers.

not Logical NOT: returns 1 when the operand is zero and 0 when the operand is non-zero. The operand can be an image or number, for an image, it is applied to each pixel separately.

isblank Test for a blank value (see Section 6.1.3 [Blank pixels], page 191). In essence, this is very similar to the conditional operators: the output is either 1 or 0 (see the ‘less than’ operator above). The difference is that it only needs one operand. Because of the definition of a blank pixel, a blank value is not even equal to itself, so you cannot use the equal operator above to select blank pixels. See the “Blank pixels” box below for more on Blank pixels in Arithmetic.

where Change the input (pixel) value where/if a certain condition holds. The conditional operators above can be used to define the condition. Three operands are required for where. The input format is demonstrated in this simplified example:

```bash
$ astarithmetic modify.fits binary.fits if-true.fits where
```

The value of any pixel in modify.fits that corresponds to a non-zero and non-blank pixel of binary.fits will be changed to the value of the same pixel in if-true.fits (this may also be a number). The 3rd and 2nd popped operands (modify.fits and binary.fits respectively, see Section 6.2.1 [Reverse polish notation], page 199) have to have the same dimensions/size. if-true.fits can be either a number, or have the same dimension/size as the other two.
The 2nd popped operand (*binary.fits*) has to have *uint8* (or *unsigned char* in standard C) type (see Section 4.6 [Numeric data types], page 130). It is treated as a binary dataset (with only two values: zero and non-zero, hence the name *binary.fits* in this example). However, commonly you won’t be dealing with an actual FITS file of a condition/binary image. You will probably define the condition in the same run based on some other reference image and use the conditional and logical operators above to make a true/false (or one/zero) image for you internally. For example the case below:

```bash
$ astarithmetric in.fits reference.fits 100 gt new.fits
```

In the example above, any of the *in.fits* pixels that has a value in *reference.fits* greater than 100, will be replaced with the corresponding pixel in *new.fits*. Effectively the *reference.fits 100 gt* part created the condition/binary image which was added to the stack (in memory) and later used by *where*. The command above is thus equivalent to these two commands:

```bash
$ astarithmetric reference.fits 100 gt --output=binary.fits
$ astarithmetric in.fits binary.fits new.fits
```

Finally, the input operands are read and used independently, so you can use the same file more than once as any of the operands.

When the 1st popped operand to *where (if-true.fits)* is a single number, it may be a NaN value (or any blank value, depending on its type) like the example below (see Section 6.1.3 [Blank pixels], page 191). When the number is blank, it will be converted to the blank value of the type of the 3rd popped operand (*in.fits*). Hence, in the example below, all the pixels in *reference.fits* that have a value greater than 100, will become blank in the natural data type of *in.fits* (even though NaN values are only defined for floating point types).

```bash
$ astarithmetric in.fits reference.fits 100 gt nan
```

### bitand

Bitwise AND operator: only bits with values of 1 in both popped operands will get the value of 1, the rest will be set to 0. For example (assuming numbers can be written as bit strings on the command-line): 00101000 00100010 *bitand* will give 00100000. Note that the bitwise operators only work on integer type datasets.

### bitor

Bitwise inclusive OR operator: The bits where at least one of the two popped operands has a 1 value get a value of 1, the others 0. For example (assuming numbers can be written as bit strings on the command-line): 00101000 00100010 *bitand* will give 00101010. Note that the bitwise operators only work on integer type datasets.

### bitxor

Bitwise exclusive OR operator: A bit will be 1 if it differs between the two popped operands. For example (assuming numbers can be written as bit strings on the command-line): 00101000 00100010 *bitand* will give 00001010. Note that the bitwise operators only work on integer type datasets.

### lshift

Bitwise left shift operator: shift all the bits of the first operand to the left by a number of times given by the second operand. For example (assuming numbers can be written as bit strings on the command-line): 00101000 2 *lshift* will
give 10100000. This is equivalent to multiplication by 4. Note that the bitwise operators only work on integer type datasets.

**rshift**  
Bitwise right shift operator: shift all the bits of the first operand to the right by a number of times given by the second operand. For example (assuming numbers can be written as bit strings on the command-line): 00101000 2 **rshift** will give 00001010. Note that the bitwise operators only work on integer type datasets.

**bitnot**  
Bitwise not (more formally known as one’s complement) operator: flip all the bits of the popped operand (note that this is the only unary, or single operand, bitwise operator). In other words, any bit with a value of 0 is changed to 1 and vice-versa. For example (assuming numbers can be written as bit strings on the command-line): 00101000 **bitnot** will give 11010111. Note that the bitwise operators only work on integer type datasets/numbers.

**uint8**  
Convert the type of the popped operand to 8-bit unsigned integer type (see Section 4.6 [Numeric data types], page 130). The internal conversion of C will be used.

**int8**  
Convert the type of the popped operand to 8-bit signed integer type (see Section 4.6 [Numeric data types], page 130). The internal conversion of C will be used.

**uint16**  
Convert the type of the popped operand to 16-bit unsigned integer type (see Section 4.6 [Numeric data types], page 130). The internal conversion of C will be used.

**int16**  
Convert the type of the popped operand to 16-bit signed integer (see Section 4.6 [Numeric data types], page 130). The internal conversion of C will be used.

**uint32**  
Convert the type of the popped operand to 32-bit unsigned integer type (see Section 4.6 [Numeric data types], page 130). The internal conversion of C will be used.

**int32**  
Convert the type of the popped operand to 32-bit signed integer type (see Section 4.6 [Numeric data types], page 130). The internal conversion of C will be used.

**uint64**  
Convert the type of the popped operand to 64-bit unsigned integer (see Section 4.6 [Numeric data types], page 130). The internal conversion of C will be used.

**float32**  
Convert the type of the popped operand to 32-bit (single precision) floating point (see Section 4.6 [Numeric data types], page 130). The internal conversion of C will be used.

**float64**  
Convert the type of the popped operand to 64-bit (double precision) floating point (see Section 4.6 [Numeric data types], page 130). The internal conversion of C will be used.

**size**  
Size of the dataset along a given FITS/Fortran dimension (counting from 1). The desired dimension should be the first popped operand and the dataset must be the second popped operand. The output will be a single unsigned integer
(dimensions cannot be negative). For example, the following command will produce the size of the first extension/HDU (the default HDU) of a.fits along the second FITS axis:

```
astarithmetic a.fits 2 size
```

**makenew** Create a new dataset that only has zero values. The number of dimensions is read as the first popped operand and the number of elements along each dimension are the next popped operand (in reverse of the popping order). The type of the new dataset is an unsigned 8-bit integer and all pixel values have a value of zero. For example, if you want to create a new 100 by 200 pixel image, you can run this command:

```
astarithmetic 100 200 2 makenew
```

**set-AAA** Set the characters after the dash (AAA in the case shown here) as a name for the first popped operand on the stack. The named dataset will be freed from memory as soon as it is no longer needed, or if the name is reset to refer to another dataset later in the command. This operator thus enables re-usability of a dataset without having to re-read it from a file every time it is necessary during a process. When a dataset is necessary more than once, this operator can thus help simplify reading/writing on the command-line (thus avoiding potential bugs), while also speeding up the processing.

Like all operators, this operator pops the top operand off of the main processing stack, but unlike other operands, it won’t add anything back to the stack immediately. It will keep the popped dataset in memory through a separate list of named datasets (not on the main stack). That list will be used to add/copy any requested dataset to the main processing stack when the name is called.

The name to give the popped dataset is part of the operator’s name. For example the `set-a` operator of the command below, gives the name “a” to the contents of image.fits. This name is then used instead of the actual filename to multiply the dataset by two.

```
$ astarithmetic image.fits set-a a 2 x
```

The name can be any string, but avoid strings ending with standard filename suffixes (for example `.fits`).

One example of the usefulness of this operator is in the where operator. For example, let’s assume you want to mask all pixels larger than 5 in image.fits (extension number 1) with a NaN value. Without setting a name for the dataset, you have to read the file two times from memory in a command like this:

```
$ astarithmetic image.fits image.fits 5 gt nan where -g1
```

But with this operator you can simply give image.fits the name `i` and simplify the command above to the more readable one below (which greatly helps when the filename is long):

```
$ astarithmetic image.fits set-i i i 5 gt nan where
```

---

5 A dataset name like a.fits (which can be set with set-a.fits) will cause confusion in the initial parser of Arithmetic. It will assume this name is a FITS file, and if it is used multiple times, Arithmetic will abort, complaining that you haven’t provided enough HDUs.
tofile-AAA
Write the top operand on the operands stack into a file called AAA (can be any FITS file name) without changing the operands stack. If you don’t need the dataset any more and would like to free it, see the tofilefree operator below. By default, any file that is given to this operator is deleted before Arithmetic actually starts working on the input datasets. The deletion can be deactivated with the --dontdelete option (as in all Gnuastro programs, see Section 4.1.2.1 [Input/Output options], page 109). If the same FITS file is given to this operator multiple times, it will contain multiple extensions (in the same order that it was called).

For example the operator tofile-check.fits will write the top operand to check.fits. Since it doesn’t modify the operands stack, this operator is very convenient when you want to debug, or understanding, a string of operators and operands given to Arithmetic: simply put tofile-AAA anywhere in the process to see what is happening behind the scenes without modifying the overall process.

tofilefree-AAA
Similar to the tofile operator, with the only difference that the dataset that is written to a file is popped from the operand stack and freed from memory (cannot be used any more).

### Blank pixels in Arithmetic:
Blank pixels in the image (see Section 6.1.3 [Blank pixels], page 191) will be stored based on the data type. When the input is floating point type, blank values are NaN. One aspect of NaN values is that by definition they will fail on any comparison. Hence both equal and not-equal operators will fail when both their operands are NaN! Therefore, the only way to guarantee selection of blank pixels is through the isblank operator explained above.

One way you can exploit this property of the NaN value to your advantage is when you want a fully zero-valued image (even over the blank pixels) based on an already existing image (with same size and world coordinate system settings). The following command will produce this for you:

```
$ astarithmetic input.fits nan eq --output=all-zeros.fits
```

Note that on the command-line you can write NaN in any case (for example NaN or NAN are also acceptable). Reading NaN as a floating point number in Gnuastro isn’t case-sensitive.

### 6.2.3 Invoking Arithmetic
Arithmetic will do pixel to pixel arithmetic operations on the individual pixels of input data and/or numbers. For the full list of operators with explanations, please see Section 6.2.2 [Arithmetic operators], page 200. Any operand that only has a single element (number, or single pixel FITS image) will be read as a number, the rest of the inputs must have the same dimensions. The general template is:

```
$ astarithmetic [OPTION...] ASTRdata1 [ASTRdata2] OPERATOR ...
```

One line examples:

```
## Calculate (10.32-3.84)^2.7 quietly (will just print 155.329):
```

$ astarithmetic -q 10.32 3.84 - 2.7 pow

## Inverse the input image (1/pixel):
$ astarithmetic 1 image.fits / --out=inverse.fits

## Multiply each pixel in image by -1:
$ astarithmetic image.fits -1 x --out=negative.fits

## Subtract extension 4 from extension 1 (counting from zero):
$ astarithmetic image.fits image.fits - --out=skysub.fits
   --hdu=1 --hdu=4

## Add two images, then divide them by 2 (2 is read as floating point):
## Note that without the '.0', the '2' will be read/used as an integer.
$ astarithmetic image1.fits image2.fits + 2.0 / --out=average.fits

## Use Arithmetic's average operator:
$ astarithmetic image1.fits image2.fits average --out=average.fits

## Calculate the median of three images in three separate extensions:
$ astarithmetic img1.fits img2.fits img3.fits median
   -h0 -h1 -h2 --out=median.fits

Arithmetic’s notation for giving operands to operators is fully described in Section 6.2.1 [Reverse polish notation], page 199. The output dataset is last remaining operand on the stack. When the output dataset a single number, it will be printed on the command-line. When the output is an array, it will be stored as a file.

The name of the final file can be specified with the --output option, but if its not given, Arithmetic will use “automatic output” on the name of the first FITS image encountered to generate an output file name, see Section 4.10 [Automatic output], page 142. By default, if the output file already exists, it will be deleted before Arithmetic starts operation. However, this can be disabled with the --dontdelete option (see below). At any point during Arithmetic’s operation, you can also write the top operand on the stack to a file, using the tofile or tofilefree operators, see Section 6.2.2 [Arithmetic operators], page 200.

By default, the world coordinate system (WCS) information of the output dataset will be taken from the first input image (that contains a WCS) on the command-line. This can be modified with the --wcsfile and --wcshdu options described below. When the --quiet option isn’t given, the name and extension of the dataset used for the output’s WCS is printed on the command-line.

Through operators like those starting with collapse-, the dimensionality of the inputs may not be the same as the outputs. By default, when the output is 1D, Arithmetic will write it as a table, not an image/array. The format of the output table (plain text or FITS ASCII or binary) can be set with the --tableformat option, see Section 4.1.2.1 [Input/Output options], page 109). You can disable this feature (write 1D arrays as FITS images/arrays, or to the standard output) with the --onedasimage or --onедonstdout options.
See Section 4.1.2 [Common options], page 109, for a review of the options in all Gnuastro programs. Arithmetic just redefines the --hdu and --dontdelete options as explained below.

-h INT/STR
--hdu INT/STR

The header data unit of the input FITS images, see Section 4.1.2.1 [Input/Output options], page 109. Unlike most options in Gnuastro (which will ultimately only have one value for this option), Arithmetic allows --hdu to be called multiple times and the value of each invocation will be stored separately (for the unlimited number of input images you would like to use). Recall that for other programs this (common) option only takes a single value. So in other programs, if you specify it multiple times on the command-line, only the last value will be used and in the configuration files, it will be ignored if it already has a value.

The order of the values to --hdu has to be in the same order as input FITS images. Options are first read from the command-line (from left to right), then top-down in each configuration file, see Section 4.2.2 [Configuration file precedence], page 121.

If the number of HDUs is less than the number of input images, Arithmetic will abort and notify you. However, if there are more HDUs than FITS images, there is no problem: they will be used in the given order (every time a FITS image comes up on the stack) and the extra HDUs will be ignored in the end. So there is no problem with having extra HDUs in the configuration files and by default several HDUs with a value of 0 are kept in the system-wide configuration file when you install Gnuastro.

-g INT/STR
--globalhdu INT/STR

Use the value to this option as the HDU of all input FITS files. This option is very convenient when you have many input files and the dataset of interest is in the same HDU of all the files. When this option is called, any values given to the --hdu option (explained above) are ignored and will not be used.

-w STR
--wcsfile STR

FITS Filename containing the WCS structure that must be written to the output. The HDU/extension should be specified with --wcshdu.

When this option is used, the respective WCS will be read before any processing is done on the command-line and directly used in the final output. If the given file doesn’t have any WCS, then the default WCS (first file on the command-line with WCS) will be used in the output.

This option will mostly be used when the default file (first of the set of inputs) is not the one containing your desired WCS. But with this option, you can also use Arithmetic to rewrite/change the WCS of an existing FITS dataset from another file:

```
$ astarithmetic data.fits --wcsfile=other.fits -ofinal.fits
```
-W STR
--wcs hdr STR
    HDU/extension to read the WCS within the file given to --wcsfile. For more, see the description of --wcsfile.

-O
--onedasimage
    When final dataset to write as output only has one dimension, write it as a FITS image/array. By default, if the output is 1D, it will be written as a table, see above.

-s
--onedonstdout
    When final dataset to write as output only has one dimension, print it on the standard output, not in a file. By default, if the output is 1D, it will be written as a table, see above.

-D
--dontdelete
    Don’t delete the output file, or files given to the tofile or tofilefree operators, if they already exist. Instead append the desired datasets to the extensions that already exist in the respective file. Note it doesn’t matter if the final output file name is given with the --output option, or determined automatically.

Arithmetic treats this option differently from its default operation in other Gnuastro programs (see Section 4.1.2.1 [Input/Output options], page 109). If the output file exists, when other Gnuastro programs are called with --dontdelete, they simply complain and abort. But when Arithmetic is called with --dontdelete, it will appended the dataset(s) to the existing extension(s) in the file.

Arithmetic accepts two kinds of input: images and numbers. Images are considered to be any of the inputs that is a file name of a recognized type (see Section 4.1.1.1 [Arguments], page 107) and has more than one element/pixel. Numbers on the command-line will be read into the smallest type (see Section 4.6 [Numeric data types], page 130) that can store them, so -2 will be read as a char type (which is signed on most systems and can thus keep negative values), 2500 will be read as an unsigned short (all positive numbers will be read as unsigned), while 3.1415926535897 will be read as a double and 3.14 will be read as a float. To force a number to be read as float, put a . after it (possibly followed by a zero for easier readability), or add an f after it. Hence while 5 will be read as an integer, 5., 5.0 or 5f will be added to the stack as float (see Section 6.2.1 [Reverse polish notation], page 199).

Unless otherwise stated (in Section 6.2.2 [Arithmetic operators], page 200), the operators can deal with numeric multiple data types (see Section 4.6 [Numeric data types], page 130). For example in “a.fits b.fits +”, the image types can be long and float. In such cases, C’s internal type conversion will be used. The output type will be set to the higher-ranking type of the two inputs. Unsigned integer types have smaller ranking than their signed counterparts and floating point types have higher ranking than the integer types. So the internal C type conversions done in the example above are equivalent to this piece of C:

        size_t i;
long a[100];
float b[100], out[100];
for(i=0;i<100;++i) out[i]=a[i]+b[i];

Relying on the default C type conversion significantly speeds up the processing and also requires less RAM (when using very large images).

Some operators can only work on integer types (of any length, for example bitwise operators) while others only work on floating point types, (currently only the \texttt{pow} operator). In such cases, if the operand type(s) are different, an error will be printed. Arithmetic also comes with internal type conversion operators which you can use to convert the data into the appropriate type, see Section 6.2.2 \cite{Arithmetic operators}, page 200.

The hyphen (\texttt{-}) can be used both to specify options (see Section 4.1.1.2 \cite{Options}, page 107) and also to specify a negative number which might be necessary in your arithmetic. In order to enable you to do this, Arithmetic will first parse all the input strings and if the first character after a hyphen is a digit, then that hyphen is temporarily replaced by the vertical tab character which is not commonly used. The arguments are then parsed and these strings will not be specified as an option. Then the given arguments are parsed and any vertical tabs are replaced back with a hyphen so they can be read as negative numbers. Therefore, as long as the names of the files you want to work on, don’t start with a vertical tab followed by a digit, there is no problem. An important consequence of this implementation is that you should not write negative fractions like this: \texttt{-.3}, instead write them as \texttt{-0.3}.

Without any images, Arithmetic will act like a simple calculator and print the resulting output number on the standard output like the first example above. If you really want such calculator operations on the command-line, AWK (GNU AWK is the most common implementation) is much faster, easier and much more powerful. For example, the numerical one-line example above can be done with the following command. In general AWK is a fantastic tool and GNU AWK has a wonderful manual (\url{https://www.gnu.org/software/gawk/manual/}). So if you often confront situations like this, or have to work with large text tables/catalogs, be sure to checkout AWK and simplify your life.

\begin{verbatim}
$ echo "" | awk '{print (10.32-3.84)^2.7}'
155.329
\end{verbatim}

\section{6.3 Convolve}

On an image, convolution can be thought of as a process to blur or remove the contrast in an image. If you are already familiar with the concept and just want to run Convolve, you can jump to Section 6.3.4 \cite{Convolution kernel}, page 235, and Section 6.3.5 \cite{Invoking Convolve}, page 236, and skip the lengthy introduction on the basic definitions and concepts of convolution.

There are generally two methods to convolve an image. The first and more intuitive one is in the “spatial domain” or using the actual image pixel values, see Section 6.3.1 \cite{Spatial domain convolution}, page 217. The second method is when we manipulate the “frequency domain”, or work on the magnitudes of the different frequencies that constitute the image, see Section 6.3.2 \cite{Frequency domain and Fourier operations}, page 219. Understanding convolution in the spatial domain is more intuitive and thus recommended if you are just starting to learn about convolution. However, getting a good grasp of the
frequency domain is a little more involved and needs some concentration and some mathematical proofs. However, its reward is a faster operation and more importantly a very fundamental understanding of this very important operation.

Convolution of an image will generally result in blurring the image because it mixes pixel values. In other words, if the image has sharp differences in neighboring pixel values\(^\text{6}\), those sharp differences will become smoother. This has very good consequences in detection of signal in noise for example. In an actual observed image, the variation in neighboring pixel values due to noise can be very high. But after convolution, those variations will decrease and we have a better hope in detecting the possible underlying signal. Another case where convolution is extensively used is in mock images and modeling in general, convolution can be used to simulate the effect of the atmosphere or the optical system on the mock profiles that we create, see Section 8.1.1.2 [Point spread function], page 334. Convolution is a very interesting and important topic in any form of signal analysis (including astronomical observations). So we have thoroughly\(^\text{7}\) explained the concepts behind it in the following sub-sections.

### 6.3.1 Spatial domain convolution

The pixels in an input image represent different “spatial” positions, therefore when convolution is done only using the actual input pixel values, we name the process as being done in the “Spatial domain”. In particular this is in contrast to the “frequency domain” that we will discuss later in Section 6.3.2 [Frequency domain and Fourier operations], page 219. In the spatial domain (and in realistic situations where the image and the convolution kernel don’t extend to infinity), convolution is the process of changing the value of one pixel to the *weighted* average of all the pixels in its *neighborhood*.

The ‘neighborhood’ of each pixel (how many pixels in which direction) and the ‘weight’ function (how much each neighboring pixel should contribute depending on its position) are given through a second image which is known as a “kernel”\(^\text{8}\).

#### 6.3.1.1 Convolution process

In convolution, the kernel specifies the weight and positions of the neighbors of each pixel. To find the convolved value of a pixel, the central pixel of the kernel is placed on that pixel. The values of each overlapping pixel in the kernel and image are multiplied by each other and summed for all the kernel pixels. To have one pixel in the center, the sides of the convolution kernel have to be an odd number. This process effectively mixes the pixel values of each pixel with its neighbors, resulting in a blurred image compared to the sharper input image.

Formally, convolution is one kind of linear ‘spatial filtering’ in image processing texts. If we assume that the kernel has \(2a + 1\) and \(2b + 1\) pixels on each side, the convolved value of a pixel placed at \(x\) and \(y\) \((C_{x,y})\) can be calculated from the neighboring pixel values in the input image \((I)\) and the kernel \((K)\) from

---

\(^6\) In astronomy, the only major time we confront such sharp borders in signal are cosmic rays. All other sources of signal in an image are already blurred by the atmosphere or the optics of the instrument.

\(^7\) A mathematician will certainly consider this explanation is incomplete and inaccurate. However this text is written for an understanding on the operations that are done on a real (not complex, discrete and noisy) astronomical image, not any general form of abstract function.

\(^8\) Also known as filter, here we will use ‘kernel’.
\[ C_{x,y} = \sum_{s=-a}^{a} \sum_{t=-b}^{b} K_{s,t} \times I_{x+s,y+t}. \]

Any pixel coordinate that is outside of the image in the equation above will be considered to be zero. When the kernel is symmetric about its center the blurred image has the same orientation as the original image. However, if the kernel is not symmetric, the image will be affected in the opposite manner, this is a natural consequence of the definition of spatial filtering. In order to avoid this we can rotate the kernel about its center by 180 degrees so the convolved output can have the same original orientation. Technically speaking, only if the kernel is flipped the process is known Convolution. If it isn’t it is known as Correlation.

To be a weighted average, the sum of the weights (the pixels in the kernel) have to be unity. This will have the consequence that the convolved image of an object and unconvolved object will have the same brightness (see Section 8.1.3 [Brightness, Flux, Magnitude and Surface brightness], page 338), which is natural, because convolution should not eat up the object photons, it only disperses them.

### 6.3.1.2 Edges in the spatial domain

In purely ‘linear’ spatial filtering (convolution), there are problems on the edges of the input image. Here we will explain the problem in the spatial domain. For a discussion of this problem from the frequency domain perspective, see Section 6.3.2.10 [Edges in the frequency domain], page 233. The problem originates from the fact that on the edges, in practice\(^9\), the sum of the weights we use on the actual image pixels is not unity. For example, as discussed above, a profile in the center of an image will have the same brightness before and after convolution. However, for partially imaged profile on the edge of the image, the brightness (sum of its pixel fluxes within the image, see Section 8.1.3 [Brightness, Flux, Magnitude and Surface brightness], page 338) will not be equal, some of the flux is going to be ‘eaten’ by the edges.

If you ran \$ make check on the source files of Gnuastro, you can see the this effect by comparing the convolve_frequency.fits with convolve_spatial.fits in the ./tests/ directory. In the spatial domain, by default, no assumption will be made about pixels outside of the image or any blank pixels in the image. The problem explained above will also occur on the sides of blank regions (see Section 6.1.3 [Blank pixels], page 191). The solution to this edge effect problem is only possible in the spatial domain. For pixels near the edge, we have to abandon the assumption that the sum of the kernel pixels is unity during the convolution process\(^{10}\). So taking \(W\) as the sum of the kernel pixels that overlapped with non-blank and in-image pixels, the equation in Section 6.3.1.1 [Convolution process], page 217, will become:

\[ C_{x,y} = \frac{\sum_{s=-a}^{a} \sum_{t=-b}^{b} K_{s,t} \times I_{x+s,y+t}}{W}. \]

\(^9\) Because we assumed the overlapping pixels outside the input image have a value of zero.

\(^{10}\) of course the sum of the kernel pixels still have to be unity in general.
In this manner, objects which are near the edges of the image or blank pixels will also have the same brightness (within the image) before and after convolution. This correction is applied by default in Convolve when convolving in the spatial domain. To disable it, you can use the \texttt{--noedgecorrection} option. In the frequency domain, there is no way to avoid this loss of flux near the edges of the image, see Section 6.3.2.10 [Edges in the frequency domain], page 233, for an interpretation from the frequency domain perspective.

Note that the edge effect discussed here is different from the one in Section 8.1.2 [If convolving afterwards], page 338. In making mock images we want to simulate a real observation. In a real observation the images of the galaxies on the sides of the CCD are first blurred by the atmosphere and instrument, then imaged. So light from the parts of a galaxy which are immediately outside the CCD will affect the parts of the galaxy which are covered by the CCD. Therefore in modeling the observation, we have to convolve an image that is larger than the input image by exactly half of the convolution kernel. We can hence conclude that this correction for the edges is only useful when working on actual observed images (where we don’t have any more data on the edges) and not in modeling.

6.3.2 Frequency domain and Fourier operations

Getting a good grip on the frequency domain is usually not an easy job! So we have decided to give the issue a complete review here. Convolution in the frequency domain (see Section 6.3.2.6 [Convolution theorem], page 227) heavily relies on the concepts of Fourier transform (Section 6.3.2.4 [Fourier transform], page 224) and Fourier series (Section 6.3.2.3 [Fourier series], page 223) so we will be investigating these important operations first. It has become something of a cliché for people to say that the Fourier series “is a way to represent a (wave-like) function as the sum of simple sine waves” (from Wikipedia). However, sines themselves are abstract functions, so this statement really adds no extra layer of physical insight.

Before jumping head-first into the equations and proofs, we will begin with a historical background to see how the importance of frequencies actually roots in our ancient desire to see everything in terms of circles. A short review of how the complex plane should be interpreted is then given. Having paved the way with these two basics, we define the Fourier series and subsequently the Fourier transform. The final aim is to explain discrete Fourier transform, however some very important concepts need to be solidified first: The Dirac comb, convolution theorem and sampling theorem. So each of these topics are explained in their own separate sub-sub-section before going on to the discrete Fourier transform. Finally we revisit (after Section 6.3.1.2 [Edges in the spatial domain], page 218) the problem of convolution on the edges, but this time in the frequency domain. Understanding the sampling theorem and the discrete Fourier transform is very important in order to be able to pull out valuable science from the discrete image pixels. Therefore we have included the mathematical proofs and figures so you can have a clear understanding of these very important concepts.

6.3.2.1 Fourier series historical background

Ever since the ancient times, the circle has been (and still is) the simplest shape for abstract comprehension. All you need is a center point and a radius and you are done. All the points on a circle are at a fixed distance from the center. However, the moment you try to connect this elegantly simple and beautiful abstract construct (the circle) with the real
world (for example compute its area or its circumference), things become really hard (ideally, impossible) because the irrational number $\pi$ gets involved.

The key to understanding the Fourier series (thus the Fourier transform and finally the Discrete Fourier Transform) is our ancient desire to express everything in terms of circles or the most exceptionally simple and elegant abstract human construct. Most people prefer to say the same thing in a more ahistorical manner: to break a function into sines and cosines. As the term “ancient” in the previous sentence implies, Jean-Baptiste Joseph Fourier (1768 – 1830 A.D.) was not the first person to do this. The main reason we know this process by his name today is that he came up with an ingenious method to find the necessary coefficients (radius of) and frequencies (“speed” of rotation on) the circles for any generic (integrable) function.

Figure 6.1: Epicycles and the Fourier series. Left: A demonstration of Mercury’s epicycles relative to the “center of the world” by Qutb al-Din al-Shirazi (1236 – 1311 A.D.) retrieved from Wikipedia (https://commons.wikimedia.org/wiki/File:Ghotb2.jpg). Middle (https://commons.wikimedia.org/wiki/File:Fourier_series_square_wave_circles_animation.gif) and Right: How adding more epicycles (or terms in the Fourier series) will approximate functions. The right (https://commons.wikimedia.org/wiki/File:Fourier_series_sawtooth_wave_circles_animation.gif) animation is also available.

Like most aspects of mathematics, this process of interpreting everything in terms of circles, began for astronomical purposes. When astronomers noticed that the orbit of Mars and other outer planets, did not appear to be a simple circle (as everything should have been in the heavens). At some point during their orbit, the revolution of these planets would become slower, stop, go back a little (in what is known as the retrograde motion) and then continue going forward again.

The correction proposed by Ptolemy (90 – 168 A.D.) was the most agreed upon. He put the planets on Epicycles or circles whose center itself rotates on a circle whose center is the earth. Eventually, as observations became more and more precise, it was necessary to add more and more epicycles in order to explain the complex motions of the planets\textsuperscript{11}.

\textsuperscript{11} See the Wikipedia page on “Deferent and epicycle” for a more complete historical review.
Figure 6.1 (Left) shows an example depiction of the epicycles of Mercury in the late 13th century.

Of course we now know that if they had abdicated the Earth from its throne in the center of the heavens and allowed the Sun to take its place, everything would become much simpler and true. But there wasn’t enough observational evidence for changing the “professional consensus” of the time to this radical view suggested by a small minority\textsuperscript{12}. So the pre-Galilean astronomers chose to keep Earth in the center and find a correction to the models (while keeping the heavens a purely “circular” order).

The main reason we are giving this historical background which might appear off topic is to give historical evidence that while such “approximations” do work and are very useful for pragmatic reasons (like measuring the calendar from the movement of astronomical bodies), they offer no physical insight. The astronomers who were involved with the Ptolemaic world view had to add a huge number of epicycles during the centuries after Ptolemy in order to explain more accurate observations. Finally the death knell of this world-view was Galileo’s observations with his new instrument (the telescope). So the physical insight, which is what Astronomers and Physicists are interested in (as opposed to Mathematicians and Engineers who just like proving and optimizing or calculating!) comes from being creative and not limiting our selves to such approximations. Even when they work.

### 6.3.2.2 Circles and the complex plane

Before going onto the derivation, it is also useful to review how the complex numbers and their plane relate to the circles we talked about above. The two schematics in the middle and right of Figure 6.1 show how a 1D function of time can be made using the 2D real and imaginary surface. Seeing the animation in Wikipedia will really help in understanding this important concept. At each point in time, we take the vertical coordinate of the point and use it to find the value of the function at that point in time. Figure 6.2 shows this relation with the axes marked.

Leonhard Euler\textsuperscript{13} (1707 – 1783 A.D.) showed that the complex exponential ($e^{iv}$ where $v$ is real) is periodic and can be written as: $e^{iv} = \cos v + isin v$. Therefore $e^{i(v+2\pi)} = e^{iv}$. Later, Caspar Wessel (mathematician and cartographer 1745 – 1818 A.D.) showed how complex numbers can be displayed as vectors on a plane. Euler’s identity might seem counter intuitive at first, so we will try to explain it geometrically (for deeper physical insight). On the real-imaginary 2D plane (like the left hand plot in each box of Figure 6.2), multiplying a number by $i$ can be interpreted as rotating the point by 90 degrees (for example the value 3 on the real axis becomes $3i$ on the imaginary axis). On the other hand, $e \equiv \lim_{n \to \infty} (1 + \frac{1}{n})^n$, therefore, defining $m \equiv nu$, we get:

\[
e^u = \lim_{n \to \infty} \left(1 + \frac{1}{n}\right)^{nu} = \lim_{n \to \infty} \left(1 + \frac{u}{nu}\right)^{nu} = \lim_{m \to \infty} \left(1 + \frac{u}{m}\right)^m
\]

\textsuperscript{12} Aristarchus of Samos (310 – 230 B.C.) appears to be one of the first people to suggest the Sun being in the center of the universe. This approach to science (that the standard model is defined by consensus) and the fact that this consensus might be completely wrong still applies equally well to our models of particle physics and cosmology today.

\textsuperscript{13} Other forms of this equation were known before Euler. For example in 1707 A.D. (the year of Euler’s birth) Abraham de Moivre (1667 – 1754 A.D.) showed that $(\cos x + i \sin x)^n = \cos(nx) + i \sin(nx)$. In 1714 A.D., Roger Cotes (1682 – 1716 A.D. a colleague of Newton who proofread the second edition of Principia) showed that: $ix = \ln(\cos x + i \sin x)$. 
Taking \( u \equiv iv \) the result can be written as a generic complex number (a function of \( v \)):

\[
e^{iv} = \lim_{m \to \infty} \left( 1 + \frac{iv}{m} \right)^m = a(v) + ib(v)
\]

For \( v = \pi \), a nice geometric animation of going to the limit can be seen on Wikipedia (https://commons.wikimedia.org/wiki/File:ExpIPi.gif). We see that \( \lim_{m \to \infty} a(\pi) = -1 \), while \( \lim_{m \to \infty} b(\pi) = 0 \), which gives the famous \( e^{i\pi} = -1 \) equation. The final value is the real number \(-1\), however the distance of the polygon points traversed as \( m \to \infty \) is half the circumference of a circle or \( \pi \), showing how \( v \) in the equation above can be interpreted as an angle in units of radians and therefore how \( a(v) = \cos(v) \) and \( b(v) = \sin(v) \).

Since \( e^{iv} \) is periodic (let’s assume with a period of \( T \)), it is more clear to write it as \( v \equiv \frac{2\pi}{T} t \) (where \( n \) is an integer), so \( e^{iv} = e^{i\frac{2\pi n}{T}} \). The advantage of this notation is that the period \( (T) \) is clearly visible and the frequency \( (\frac{2\pi n}{T}, \text{in units of 1/cycle}) \) is defined through the integer \( n \). In this notation, \( t \) is in units of “cycle”s.

As we see from the examples in Figure 6.1 and Figure 6.2, for each constituting frequency, we need a respective ‘magnitude’ or the radius of the circle in order to accurately approximate the desired 1D function. The concepts of “period” and “frequency” are relatively easy to grasp when using temporal units like time because this is how we define them in every-day life. However, in an image (astronomical data), we are dealing with spatial units like distance. Therefore, by one “period” we mean the distance at which the signal is identical and frequency is defined as the inverse of that spatial “period”. The complex circle of Figure 6.2 can be thought of the Moon rotating about Earth which is rotating around the Sun; so the “Real (signal)” axis shows the Moon’s position as seen by a distant observer on the Sun as time goes by. Because of the scalar (not having any direction or vector) nature of time, Figure 6.2 is easier to understand in units of time. When thinking about spatial units, mentally replace the “Time (sec)” axis with “Distance (meters)”. Because length has direction and is a vector, visualizing the rotation of the imaginary circle and the advance along the “Distance (meters)” axis is not as simple as temporal units like time.

![Figure 6.2: Relation between the real (signal), imaginary (i \equiv \sqrt{-1}) and time axes at two snapshots of time.](https://commons.wikimedia.org/wiki/File:ExpIPi.gif)
6.3.2.3 Fourier series

In astronomical images, our variable (brightness, or number of photo-electrons, or signal to be more generic) is recorded over the 2D spatial surface of a camera pixel. However to make things easier to understand, here we will assume that the signal is recorded in 1D (assume one row of the 2D image pixels). Also for this section and the next (Section 6.3.2.4 [Fourier transform], page 224) we will be talking about the signal before it is digitized or pixelated.

Let’s assume that we have the continuous function \( f(l) \) which is integrable in the interval \([l_0, l_0 + L]\) (always true in practical cases like images). Take \( l_0 \) as the position of the first pixel in the assumed row of the image and \( L \) as the width of the image along that row. The units of \( l_0 \) and \( L \) can be in any spatial units (for example meters) or an angular unit (like radians) multiplied by a fixed distance which is more common.

To approximate \( f(l) \) over this interval, we need to find a set of frequencies and their corresponding ‘magnitude’s (see Section 6.3.2.2 [Circles and the complex plane], page 221). Therefore our aim is to show \( f(l) \) as the following sum of periodic functions:

\[
f(l) = \sum_{n=-\infty}^{\infty} c_n e^{i \frac{2\pi}{L} nl}
\]

Note that the different frequencies (\(2\pi n/L\), in units of cycles per meters for example) are not arbitrary. They are all integer multiples of the fundamental frequency of \( \omega_0 = 2\pi/L \). Recall that \( L \) was the length of the signal we want to model. Therefore, we see that the smallest possible frequency (or the frequency resolution) in the end, depends on the length we observed the signal or \( L \). In the case of each dimension on an image, this is the size of the image in the respective dimension. The frequencies have been defined in this “harmonic” fashion to insure that the final sum is periodic outside of the \([l_0, l_0 + L]\) interval too. At this point, you might be thinking that the sky is not periodic with the same period as my camera’s view angle. You are absolutely right! The important thing is that since your camera’s observed region is the only region we are “observing” and will be using, the rest of the sky is irrelevant; so we can safely assume the sky is periodic outside of it. However, this working assumption will haunt us later in Section 6.3.2.10 [Edges in the frequency domain], page 233.

The frequencies are thus determined by definition. So all we need to do is to find the coefficients \( (c_n) \), or magnitudes, or radii of the circles for each frequency which is identified with the integer \( n \). Fourier’s approach was to multiply both sides with a fixed term:

\[
f(l) e^{-i \frac{2\pi m}{L} l} = \sum_{n=-\infty}^{\infty} c_n e^{i \frac{2\pi (n-m)}{L} l}
\]

where \( m > 0 \)\(^{14}\). We can then integrate both sides over the observation period:

\[
\int_{l_0}^{l_0+L} f(l) e^{-i \frac{2\pi m}{L} l} dl = \int_{l_0}^{l_0+L} \sum_{n=-\infty}^{\infty} c_n e^{i \frac{2\pi (n-m)}{L} l} dl = \sum_{n=-\infty}^{\infty} c_n \int_{l_0}^{l_0+L} e^{i \frac{2\pi (n-m)}{L} l} dl
\]

\(^{14}\) We could have assumed \( m < 0 \) and set the exponential to positive, but this is more clear.
Both $n$ and $m$ are positive integers. Also, we know that a complex exponential is periodic so after one period ($L$) it comes back to its starting point. Therefore $\int_{l_0}^{l_0+L} e^{2\pi k/L} dl = 0$ for any $k > 0$. However, when $k = 0$, this integral becomes: $\int_{l_0}^{l_0+T} e^0 dt = \int_{l_0}^{l_0+T} dt = T$. Hence since the integral will be zero for all $n \neq m$, we get:

$$\sum_{n=-\infty}^{\infty} c_n \int_{l_0}^{l_0+T} e^{i \frac{2\pi (n-m)}{L} l} dl = L c_m$$

The origin of the axis is fundamentally an arbitrary position. So let’s set it to the start of the image such that $l_0 = 0$. So we can find the “magnitude” of the frequency $2\pi m/L$ within $f(l)$ through the relation:

$$c_m = \frac{1}{L} \int_{0}^{L} f(l) e^{-i \frac{2\pi m}{L} l} dl$$

### 6.3.2.4 Fourier transform

In Section 6.3.2.3 [Fourier series], page 223, we had to assume that the function is periodic outside of the desired interval with a period of $L$. Therefore, assuming that $L \to \infty$ will allow us to work with any function. However, with this approximation, the fundamental frequency ($\omega_0$) or the frequency resolution that we discussed in Section 6.3.2.3 [Fourier series], page 223, will tend to zero: $\omega_0 \to 0$. In the equation to find $c_m$, every $m$ represented a frequency (multiple of $\omega_0$) and the integration on $l$ removes the dependence of the right side of the equation on $l$, making it only a function of $m$ or frequency. Let’s define the following two variables:

$$\omega \equiv m \omega_0 = \frac{2\pi m}{L}$$

$$F(\omega) \equiv L c_m$$

The equation to find the coefficients of each frequency in Section 6.3.2.3 [Fourier series], page 223, thus becomes:

$$F(\omega) = \int_{-\infty}^{\infty} f(l) e^{-i \omega l} dl.$$  

The function $F(\omega)$ is thus the Fourier transform of $f(l)$ in the frequency domain. So through this transformation, we can find (analyze) the magnitudes of the constituting frequencies or the value in the frequency space$^{15}$ of our spatial input function. The great thing is that we

---

$^{15}$ As we discussed before, this ‘magnitude’ can be interpreted as the radius of the circle rotating at this frequency in the epicyclic interpretation of the Fourier series, see Figure 6.1 and Figure 6.2.
can also do the reverse and later synthesize the input function from its Fourier transform. Let’s do it: with the approximations above, multiply the right side of the definition of the Fourier Series (Section 6.3.2.3 [Fourier series], page 223) with \( 1 = L/L = (\omega_0 L)/(2\pi) \):

\[
f(l) = \frac{1}{2\pi} \sum_{n=-\infty}^{\infty} L c_n e^{\frac{2\pi in}{\lambda}} = \frac{1}{2\pi} \sum_{n=-\infty}^{\infty} F(\omega)e^{i\omega l} \Delta \omega
\]

To find the right most side of this equation, we renamed \( \omega_0 \) as \( \Delta \omega \) because it was our resolution, \( 2\pi n/L \) was written as \( \omega \) and finally, \( L c_n \) was written as \( F(\omega) \) as we defined above. Now, as \( L \to \infty \), \( \Delta \omega \to 0 \) so we can write:

\[
f(l) = \frac{1}{2\pi} \int_{-\infty}^{\infty} F(\omega)e^{i\omega l} d\omega
\]

Together, these two equations provide us with a very powerful set of tools that we can use to process (analyze) and recreate (synthesize) the input signal. Through the first equation, we can break up our input function into its constituent frequencies and analyze it, hence it is also known as analysis. Using the second equation, we can synthesize or make the input function from the known frequencies and their magnitudes. Thus it is known as synthesis. Here, we symbolize the Fourier transform (analysis) and its inverse (synthesis) of a function \( f(l) \) and its Fourier Transform \( F(\omega) \) as \( F[f] \) and \( F^{-1}[F] \).

**6.3.2.5 Dirac delta and comb**

The Dirac \( \delta \) (delta) function (also known as an impulse) is the way that we convert a continuous function into a discrete one. It is defined to satisfy the following integral:

\[
\int_{-\infty}^{\infty} \delta(l)dl = 1
\]

When integrated with another function, it gives that function’s value at \( l = 0 \):

\[
\int_{-\infty}^{\infty} f(l)\delta(l)dt = f(0)
\]

An impulse positioned at another point (say \( l_0 \)) is written as \( \delta(l - l_0) \):

\[
\int_{-\infty}^{\infty} f(l)\delta(l - l_0)dt = f(l_0)
\]

The Dirac \( \delta \) function also operates similarly if we use summations instead of integrals. The Fourier transform of the delta function is:

\[
F[\delta(l)] = \int_{-\infty}^{\infty} \delta(l)e^{-i\omega l} dl = e^{-i\omega 0} = 1
\]
\[ \mathcal{F}[\delta(l - l_0)] = \int_{-\infty}^{\infty} \delta(l - l_0)e^{-i\omega l} dl = e^{-i\omega l_0} \]

From the definition of the Dirac \( \delta \) we can also define a Dirac comb (III\(_P\)) or an impulse train with infinite impulses separated by \( P \):

\[ \text{III}_P(l) \equiv \sum_{k=-\infty}^{\infty} \delta(l - kP) \]

\( P \) is chosen to represent “pixel width” later in Section 6.3.2.7 [Sampling theorem], page 228. Therefore the Dirac comb is periodic with a period of \( P \). We have intentionally used a different name for the period of the Dirac comb compared to the input signal’s length of observation that we showed with \( L \) in Section 6.3.2.3 [Fourier series], page 223. This difference is highlighted here to avoid confusion later when these two periods are needed together in Section 6.3.2.8 [Discrete Fourier transform], page 231. The Fourier transform of the Dirac comb will be necessary in Section 6.3.2.7 [Sampling theorem], page 228, so let’s derive it. By its definition, it is periodic, with a period of \( P \), so the Fourier coefficients of its Fourier Series (Section 6.3.2.3 [Fourier series], page 223) can be calculated within one period:

\[ \text{III}_P = \sum_{n=-\infty}^{\infty} c_n e^{i\frac{2\pi n}{P} l} \]

We can now find the \( c_n \) from Section 6.3.2.3 [Fourier series], page 223:

\[ c_n = \frac{1}{P} \int_{-P/2}^{P/2} \delta(l)e^{-i\frac{2\pi n}{P} l} dl = \frac{1}{P} \rightarrow \text{III}_P = \frac{1}{P} \sum_{n=-\infty}^{\infty} e^{i\frac{2\pi n}{P} l} \]

So we can write the Fourier transform of the Dirac comb as:

\[ \mathcal{F}[\text{III}_P] = \int_{-\infty}^{\infty} \text{III}_P e^{-i\omega l} dl = \frac{1}{P} \sum_{n=-\infty}^{\infty} \int_{-\infty}^{\infty} e^{-i(\omega - \frac{2\pi n}{P}) l} dl = \frac{1}{P} \sum_{n=-\infty}^{\infty} \delta \left( \omega - \frac{2\pi n}{P} \right) \]

In the last step, we used the fact that the complex exponential is a periodic function, that \( n \) is an integer and that as we defined in Section 6.3.2.4 [Fourier transform], page 224, \( \omega \equiv mw_0 \), where \( m \) was an integer. The integral will be zero for any \( \omega \) that is not equal to \( 2\pi n/P \), a more complete explanation can be seen in Section 6.3.2.3 [Fourier series], page 223. Therefore, while in the spatial domain the impulses had spacing of \( P \) (meters for example), in the frequency space, the spacing between the different impulses are \( 2\pi/P \) cycles per meters.
6.3.2.6 Convolution theorem

The convolution (shown with the * operator) of the two functions $f(l)$ and $h(l)$ is defined as:

$$ c(l) \equiv [f * h](l) = \int_{-\infty}^{\infty} f(\tau) h(l - \tau) d\tau $$

See Section 6.3.1.1 [Convolution process], page 217, for a more detailed physical (pixel based) interpretation of this definition. The Fourier transform of convolution ($C(\omega)$) can be written as:

$$ C(\omega) = \int_{-\infty}^{\infty} [f * h](l) e^{-i\omega l} dl = \int_{-\infty}^{\infty} f(\tau) \left[ \int_{-\infty}^{\infty} h(l - \tau) e^{-i\omega l} dl \right] d\tau $$

To solve the inner integral, let’s define $s \equiv l - \tau$, so that $ds = dl$ and $l = s + \tau$ then the inner integral becomes:

$$ \int_{-\infty}^{\infty} h(l - \tau)e^{-i\omega l} dl = \int_{-\infty}^{\infty} h(s)e^{-i\omega(s + \tau)} ds = e^{-i\omega \tau} \int_{-\infty}^{\infty} h(s)e^{-i\omega s} ds = H(\omega) e^{-i\omega \tau} $$

where $H(\omega)$ is the Fourier transform of $h(l)$. Substituting this result for the inner integral above, we get:

$$ C(\omega) = H(\omega) \int_{-\infty}^{\infty} f(\tau)e^{-i\omega \tau} d\tau = H(\omega) F(\omega) = F(\omega) H(\omega) $$

where $F(\omega)$ is the Fourier transform of $f(l)$. So multiplying the Fourier transform of two functions individually, we get the Fourier transform of their convolution. The convolution theorem also proves a relation between the convolutions in the frequency space. Let’s define:

$$ D(\omega) \equiv F(\omega) * H(\omega) $$

Applying the inverse Fourier Transform or synthesis equation (Section 6.3.2.4 [Fourier transform], page 224) to both sides and following the same steps above, we get:

$$ d(l) = f(l) h(l) $$

Where $d(l)$ is the inverse Fourier transform of $D(\omega)$. We can therefore re-write the two equations above formally as the convolution theorem:

$$ \mathcal{F}[f * h] = \mathcal{F}[f] \mathcal{F}[h] $$
\[ \mathcal{F}[fh] = \mathcal{F}[f] \ast \mathcal{F}[h] \]

Besides its usefulness in blurring an image by convolving it with a given kernel, the convolution theorem also enables us to do another very useful operation in data analysis: to match the blur (or PSF) between two images taken with different telescopes/cameras or under different atmospheric conditions. This process is also known as de-convolution. Let’s take \( f(l) \) as the image with a narrower PSF (less blurry) and \( c(l) \) as the image with a wider PSF which appears more blurred. Also let’s take \( h(l) \) to represent the kernel that should be convolved with the sharper image to create the more blurry image. Above, we proved the relation between these three images through the convolution theorem. But there, we assumed that \( f(l) \) and \( h(l) \) are known (given) and the convolved image is desired.

In de-convolution, we have \( f(l) \) –the sharper image– and \( f \ast h(l) \) –the more blurry image– and we want to find the kernel \( h(l) \). The solution is a direct result of the convolution theorem:

\[ F[h] = \frac{F[f \ast h]}{F[f]} \quad \text{or} \quad h(l) = F^{-1} \left[ \frac{F[f \ast h]}{F[f]} \right] \]

While this works really nice, it has two problems:

- If \( F[f] \) has any zero values, then the inverse Fourier transform will not be a number!
- If there is significant noise in the image, then the high frequencies of the noise are going to significantly reduce the quality of the final result.

A standard solution to both these problems is the Weiner de-convolution algorithm\(^{16}\).

\subsection*{6.3.2.7 Sampling theorem}

Our mathematical functions are continuous, however, our data collecting and measuring tools are discrete. Here we want to give a mathematical formulation for digitizing the continuous mathematical functions so that later, we can retrieve the continuous function from the digitized recorded input. Assuming that we have a continuous function \( f(l) \), then we can define \( f_s(l) \) as the ‘sampled’ \( f(l) \) through the Dirac comb (see Section 6.3.2.5 [Dirac delta and comb], page 225):

\[ f_s(l) = f(l) \Pi_p = \sum_{n=-\infty}^{\infty} f(l) \delta(l - nP) \]

The discrete data-element \( f_k \) (for example, a pixel in an image), where \( k \) is an integer, can thus be represented as:

\[ f_k = \int_{-\infty}^{\infty} f_s(l) dl = \int_{-\infty}^{\infty} f(l) \delta(l - kP) dl = f(kP) \]

\(^{16}\) https://en.wikipedia.org/wiki/Wiener_deconvolution
Note that in practice, our discrete data points are not found in this fashion. Each detector pixel (in an image for example) has an area and averages the signal it receives over that area, not a mathematical point as the Dirac $\delta$ function defines. However, as long as the variation in the signal over one detector pixel is not significant, this can be a good approximation. Having put this issue to the side, we can now try to find the relation between the Fourier transforms of the un-sampled $f(l)$ and the sampled $f_s(l)$. For a more clear notation, let’s define:

$$F_s(\omega) \equiv \mathcal{F}[f_s]$$

$$D(\omega) \equiv \mathcal{F}[\Pi_P]$$

Then using the Convolution theorem (see Section 6.3.2.6 [Convolution theorem], page 227), $F_s(\omega)$ can be written as:

$$F_s(\omega) = \mathcal{F}[f(l)\Pi_P] = F(\omega) * D(\omega)$$

Finally, from the definition of convolution and the Fourier transform of the Dirac comb (see Section 6.3.2.5 [Dirac delta and comb], page 225), we get:

$$F_s(\omega) = \int_{-\infty}^{\infty} F(\omega)D(\omega - \mu)d\mu$$

$$= \frac{1}{P} \sum_{n=-\infty}^{\infty} \int_{-\infty}^{\infty} F(\omega)\delta(\omega - \mu - \frac{2\pi n}{P})d\mu$$

$$= \frac{1}{P} \sum_{n=-\infty}^{\infty} F\left(\omega - \frac{2\pi n}{P}\right).$$

$F(\omega)$ was only a simple function, see Figure 6.3(left). However, from the sampled Fourier transform function we see that $F_s(\omega)$ is the superposition of infinite copies of $F(\omega)$ that have been shifted, see Figure 6.3(right). From the equation, it is clear that the shift in each copy is $2\pi/P$. 
Figure 6.3: Sampling causes infinite repetition in the frequency domain. FT is an abbreviation for ‘Fourier transform’. \( \omega_m \) represents the maximum frequency present in the input. \( F(\omega) \) is only symmetric on both sides of 0 when the input is real (not complex). In general \( F(\omega) \) is complex and thus cannot be simply plotted like this. Here we have assumed a real Gaussian \( f(t) \) which has produced a Gaussian \( F(\omega) \).

The input \( f(l) \) can have any distribution of frequencies in it. In the example of Figure 6.3(left), the input consisted of a range of frequencies equal to \( \Delta \omega = 2\omega_m \). Fortunately as Figure 6.3(right) shows, the assumed pixel size \( (P) \) we used to sample this hypothetical function was such that \( 2\pi/P > \Delta \omega \). The consequence is that each copy of \( F(\omega) \) has become completely separate from the surrounding copies. Such a digitized (sampled) data set is thus called \textit{over-sampled}. When \( 2\pi/P = \Delta \omega \), \( P \) is just small enough to finely separate even the largest frequencies in the input signal and thus it is known as \textit{critically-sampled}. Finally if \( 2\pi/P < \Delta \omega \) we are dealing with an \textit{under-sampled} data set. In an under-sampled data set, the separate copies of \( F(\omega) \) are going to overlap and this will deprive us of recovering high constituent frequencies of \( f(l) \). The effects of under-sampling in an image with high rates of change (for example a brick wall imaged from a distance) can clearly be visually seen and is known as \textit{aliasing}.

When the input \( f(l) \) is composed of a finite range of frequencies, \( f(l) \) is known as a \textit{band-limited} function. The example in Figure 6.3(left) was a nice demonstration of such a case: for all \( \omega < -\omega_m \) or \( \omega > \omega_m \), we have \( F(\omega) = 0 \). Therefore, when the input function is band-limited and our detector’s pixels are placed such that we have critically (or over-) sampled it, then we can exactly reproduce the continuous \( f(l) \) from the discrete or digitized samples. To do that, we just have to isolate one copy of \( F(\omega) \) from the infinite copies and take its inverse Fourier transform.

This ability to exactly reproduce the continuous input from the sampled or digitized data leads us to the \textit{sampling theorem} which connects the inherent property of the continuous signal (its maximum frequency) to that of the detector (the spacing between its pixels). The sampling theorem states that the full (continuous) signal can be recovered when the pixel size \( (P) \) and the maximum constituent frequency in the signal \( (\omega_m) \) have the following relation:\footnote{This equation is also shown in some places without the \( 2\pi \). Whether \( 2\pi \) is included or not depends on how you define the frequency}\(^\text{17}\):

\[
\frac{2\pi}{P} > 2\omega_m
\]
This relation was first formulated by Harry Nyquist (1889 – 1976 A.D.) in 1928 and formally proved in 1949 by Claude E. Shannon (1916 – 2001 A.D.) in what is now known as the Nyquist-Shannon sampling theorem. In signal processing, the signal is produced (synthesized) by a transmitter and is received and de-coded (analyzed) by a receiver. Therefore producing a band-limited signal is necessary.

In astronomy, we do not produce the shapes of our targets, we are only observers. Galaxies can have any shape and size, therefore ideally, our signal is not band-limited. However, since we are always confined to observing through an aperture, the aperture will cause a point source (for which $\omega_m = \infty$) to be spread over several pixels. This spread is quantitatively known as the point spread function or PSF. This spread does blur the image which is undesirable; however, for this analysis it produces the positive outcome that there will be a finite $\omega_m$. Though we should caution that any detector will have noise which will add lots of very high frequency (ideally infinite) changes between the pixels. However, the coefficients of those noise frequencies are usually exceedingly small.

### 6.3.2.8 Discrete Fourier transform

As we have stated several times so far, the input image is a digitized, pixelated or discrete array of values ($f_s(l)$, see Section 6.3.2.7 [Sampling theorem], page 228). The input is not a continuous function. Also, all our numerical calculations can only be done on a sampled, or discrete Fourier transform. Note that $F_s(\omega)$ is not discrete, it is continuous. One way would be to find the analytic $F_s(\omega)$, then sample it at any desired “freq-pixel”$^{18}$ spacing. However, this process would involve two steps of operations and computers in particular are not too good at analytic operations for the first step. So here, we will derive a method to directly find the ‘freq-pixel’ated $F_s(\omega)$ from the pixelated $f_s(l)$. Let’s start with the definition of the Fourier transform (see Section 6.3.2.4 [Fourier transform], page 224):

$$F_s(\omega) = \int_{-\infty}^{\infty} f_s(l) e^{-i\omega l} dl$$

From the definition of $f_s(\omega)$ (using $x$ instead of $n$) we get:

$$F_s(\omega) = \sum_{x=-\infty}^{\infty} \int_{-\infty}^{\infty} f(l) \delta(l - xP) e^{-i\omega l} dl$$

$$= \sum_{x=-\infty}^{\infty} f_x e^{-i\omega xP}$$

Where $f_x$ is the value of $f(l)$ on the point $x$ or the value of the $x$th pixel. As shown in Section 6.3.2.7 [Sampling theorem], page 228, this function is infinitely periodic with a period of $2\pi/P$. So all we need is the values within one period: $0 < \omega < 2\pi/P$, see Figure 6.3. We want $X$ samples within this interval, so the frequency difference between each frequency sample or freq-pixel is $1/XP$. Hence we will evaluate the equation above on the points at:

$^{18}$ We are using the made-up word “freq-pixel” so they are not confused with spatial domain “pixels”.

\[ \omega = \frac{u}{XP} \quad u = 0, 1, 2, ..., X - 1 \]

Therefore the value of the freq-pixel \( u \) in the frequency domain is:

\[ F_u = \sum_{x=0}^{X-1} f_x e^{-i \frac{2\pi}{X} x} \]

Therefore, we see that for each freq-pixel in the frequency domain, we are going to need all the pixels in the spatial domain\(^{19}\). If the input (spatial) pixel row is also \( X \) pixels wide, then we can exactly recover the \( x \)th pixel with the following summation:

\[ f_x = \frac{1}{X} \sum_{u=0}^{X-1} F_u e^{i \frac{2\pi}{X} x} \]

When the input pixel row (we are still only working on 1D data) has \( X \) pixels, then it is \( L = XP \) spatial units wide. \( L \), or the length of the input data was defined in Section 6.3.2.3 [Fourier series], page 223, and \( P \) or the space between the pixels in the input was defined in Section 6.3.2.5 [Dirac delta and comb], page 225. As we saw in Section 6.3.2.7 [Sampling theorem], page 228, the input (spatial) pixel spacing \( (P) \) specifies the range of frequencies that can be studied and in Section 6.3.2.3 [Fourier series], page 223, we saw that the length of the (spatial) input, \( (L) \) determines the resolution (or size of the freq-pixels) in our discrete Fourier transformed image. Both result from the fact that the frequency domain is the inverse of the spatial domain.

### 6.3.2.9 Fourier operations in two dimensions

Once all the relations in the previous sections have been clearly understood in one dimension, it is very easy to generalize them to two or even more dimensions since each dimension is by definition independent. Previously we defined \( l \) as the continuous variable in 1D and the inverse of the period in its direction to be \( \omega \). Let’s show the second spatial direction with \( m \) the inverse of the period in the second dimension with \( \nu \). The Fourier transform in 2D (see Section 6.3.2.4 [Fourier transform], page 224) can be written as:

\[ F(\omega, \nu) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(l, m) e^{-i(\omega l + \nu m)} dl \]

\[ f(l, m) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} F(\omega, \nu) e^{i(\omega l + \nu m)} dl \]

The 2D Dirac \( \delta(l, m) \) is non-zero only when \( l = m = 0 \). The 2D Dirac comb (or Dirac brush! See Section 6.3.2.5 [Dirac delta and comb], page 225) can be written in units of the

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\(^{19}\) So even if one pixel is a blank pixel (see Section 6.1.3 [Blank pixels], page 191), all the pixels in the frequency domain will also be blank.
2D Dirac $\delta$. For most image detectors, the sides of a pixel are equal in both dimensions. So $P$ remains unchanged, if a specific device is used which has non-square pixels, then for each dimension a different value should be used.

$$\Pi_P(l, m) \equiv \sum_{j=-\infty}^{\infty} \sum_{k=-\infty}^{\infty} \delta(l-jP, m-kP)$$

The Two dimensional Sampling theorem (see Section 6.3.2.7 [Sampling theorem], page 228) is thus very easily derived as before since the frequencies in each dimension are independent. Let’s take $\nu_m$ as the maximum frequency along the second dimension. Therefore the two dimensional sampling theorem says that a 2D band-limited function can be recovered when the following conditions hold:\footnote{If the pixels are not a square, then each dimension has to use the respective pixel size, but since most detectors have square pixels, we assume so here too.}

$$\frac{2\pi}{P} > 2\omega_m \quad \text{and} \quad \frac{2\pi}{P} > 2\nu_m$$

Finally, let’s represent the pixel counter on the second dimension in the spatial and frequency domains with $y$ and $v$ respectively. Also let’s assume that the input image has $Y$ pixels on the second dimension. Then the two dimensional discrete Fourier transform and its inverse (see Section 6.3.2.8 [Discrete Fourier transform], page 231) can be written as:

$$F_{u,v} = \sum_{x=0}^{X-1} \sum_{y=0}^{Y-1} f_{x,y} e^{-i\left(\frac{ux}{X} + \frac{vy}{Y}\right)}$$

$$f_{x,y} = \frac{1}{XY} \sum_{u=0}^{X-1} \sum_{v=0}^{Y-1} F_{u,v} e^{i\left(\frac{ux}{X} + \frac{vy}{Y}\right)}$$

### 6.3.2.10 Edges in the frequency domain

With a good grasp of the frequency domain, we can revisit the problem of convolution on the image edges, see Section 6.3.1.2 [Edges in the spatial domain], page 218. When we apply the convolution theorem (see Section 6.3.2.6 [Convolution theorem], page 227) to convolve an image, we first take the discrete Fourier transforms (DFT, Section 6.3.2.8 [Discrete Fourier transform], page 231) of both the input image and the kernel, then we multiply them with each other and then take the inverse DFT to construct the convolved image. Of course, in order to multiply them with each other in the frequency domain, the two images have to be the same size, so let’s assume that we pad the kernel (it is usually smaller than the input image) with zero valued pixels in both dimensions so it becomes the same size as the input image before the DFT.

Having multiplied the two DFTs, we now apply the inverse DFT which is where the problem is usually created. If the DFT of the kernel only had values of 1 (unrealistic condition!) then there would be no problem and the inverse DFT of the multiplication would
be identical with the input. However in real situations, the kernel’s DFT has a maximum of 1 (because the sum of the kernel has to be one, see Section 6.3.1.1 [Convolution process], page 217) and decreases something like the hypothetical profile of Figure 6.3. So when multiplied with the input image’s DFT, the coefficients or magnitudes (see Section 6.3.2.2 [Circles and the complex plane], page 221) of the smallest frequency (or the sum of the input image pixels) remains unchanged, while the magnitudes of the higher frequencies are significantly reduced.

As we saw in Section 6.3.2.7 [Sampling theorem], page 228, the Fourier transform of a discrete input will be infinitely repeated. In the final inverse DFT step, the input is in the frequency domain (the multiplied DFT of the input image and the kernel DFT). So the result (our output convolved image) will be infinitely repeated in the spatial domain. In order to accurately reconstruct the input image, we need all the frequencies with the correct magnitudes. However, when the magnitudes of higher frequencies are decreased, longer periods (shorter frequencies) will dominate in the reconstructed pixel values. Therefore, when constructing a pixel on the edge of the image, the newly empowered longer periods will look beyond the input image edges and will find the repeated input image there. So if you convolve an image in this fashion using the convolution theorem, when a bright object exists on one edge of the image, its blurred wings will be present on the other side of the convolved image. This is often termed as circular convolution or cyclic convolution.

So, as long as we are dealing with convolution in the frequency domain, there is nothing we can do about the image edges. The least we can do is to eliminate the ghosts of the other side of the image. So, we add zero valued pixels to both the input image and the kernel in both dimensions so the image that will be convolved has a size equal to the sum of both images in each dimension. Of course, the effect of this zero-padding is that the sides of the output convolved image will become dark. To put it another way, the edges are going to drain the flux from nearby objects. But at least it is consistent across all the edges of the image and is predictable. In Convolve, you can see the padded images when inspecting the frequency domain convolution steps with the --viewfreqsteps option.

6.3.3 Spatial vs. Frequency domain

With the discussions above it might not be clear when to choose the spatial domain and when to choose the frequency domain. Here we will try to list the benefits of each.

The spatial domain,
- Can correct for the edge effects of convolution, see Section 6.3.1.2 [Edges in the spatial domain], page 218.
- Can operate on blank pixels.
- Can be faster than frequency domain when the kernel is small (in terms of the number of pixels on the sides).

The frequency domain,
- Will be much faster when the image and kernel are both large.

As a general rule of thumb, when working on an image of modeled profiles use the frequency domain and when working on an image of real (observed) objects use the spatial domain (corrected for the edges). The reason is that if you apply a frequency domain convolution to a real image, you are going to lose information on the edges and generally you don’t want
large kernels. But when you have made the profiles in the image yourself, you can just make
a larger input image and crop the central parts to completely remove the edge effect, see
Section 8.1.2 [If convolving afterwards], page 338. Also due to oversampling, both the kernels
and the images can become very large and the speed boost of frequency domain convolution
will significantly improve the processing time, see Section 8.1.1.6 [Oversampling], page 337.

6.3.4 Convolution kernel

All the programs that need convolution will need to be given a convolution kernel file and
extension. In most cases (other than Convolve, see Section 6.3 [Convolve], page 216) the
kernel file name is optional. However, the extension is necessary and must be specified either
on the command-line or at least one of the configuration files (see Section 4.2 [Configuration
files], page 120). Within Gnuastro, there are two ways to create a kernel image:

- MakeProfiles: You can use MakeProfiles to create a parametric (based on a radial
  function) kernel, see Section 8.1 [MakeProfiles], page 332. By default MakeProfiles will
  make the Gaussian and Moffat profiles in a separate file so you can feed it into any of
  the programs.

- ConvertType: You can write your own desired kernel into a text file table and convert
  it to a FITS file with ConvertType, see Section 5.3 [ConvertType], page 162. Just be
  careful that the kernel has to have an odd number of pixels along its two axes, see
  Section 6.3.1.1 [Convolution process], page 217. All the programs that do convolution
  will normalize the kernel internally, so if you choose this option, you don’t have to
  worry about normalizing the kernel. Only within Convolve, there is an option to
  disable normalization, see Section 6.3.5 [Invoking Convolve], page 236.

The two options to specify a kernel file name and its extension are shown below. These are
common between all the programs that will do convolution.

-k STR
   --kernel=STR
   The convolution kernel file name. The BITPIX (data type) value of this file can
   be any standard type and it does not necessarily have to be normalized. Several
   operations will be done on the kernel image prior to the program’s processing:
   • It will be converted to floating point type.
   • All blank pixels (see Section 6.1.3 [Blank pixels], page 191) will be set to
     zero.
   • It will be normalized so the sum of its pixels equal unity.
   • It will be flipped so the convolved image has the same orientation. This is
     only relevant if the kernel is not circular. See Section 6.3.1.1 [Convolution
     process], page 217.

-U STR
   --khdu=STR
   The convolution kernel HDU. Although the kernel file name is optional, before
   running any of the programs, they need to have a value for --khdu even if the
default kernel is to be used. So be sure to keep its value in at least one of the
configuration files (see Section 4.2 [Configuration files], page 120). By default,
the system configuration file has a value.
6.3.5 Invoking Convolve

Convolve an input dataset (2D image or 1D spectrum for example) with a known kernel, or make the kernel necessary to match two PSFs. The general template for Convolve is:

$ astconvolve [OPTION...] ASTRdata

One line examples:

## Convolve mockimg.fits with psf.fits:
$ astconvolve --kernel=psf.fits mockimg.fits

## Convolve in the spatial domain:
$ astconvolve observedimg.fits --kernel=psf.fits --domain=spatial

## Find the kernel to match sharper and blurry PSF images:
$ astconvolve --kernel=sharperimage.fits --makekernel=10 \ blurryimage.fits

## Convolve a Spectrum (column 14 in the FITS table below) with a
## custom kernel (the kernel will be normalized internally, so only
## the ratios are important). Sed is used to replace the spaces with
## new line characters so Convolve sees them as values in one column.
$ echo "1 3 10 3 1" | sed 's/ /\n/g' | astconvolve spectra.fits -c14

The only argument accepted by Convolve is an input image file. Some of the options are the same between Convolve and some other Gnuastro programs. Therefore, to avoid repetition, they will not be repeated here. For the full list of options shared by all Gnuastro programs, please see Section 4.1.2 [Common options], page 109. In particular, in the spatial domain, on a multi-dimensional datasets, convolve uses Gnuastro’s tessellation to speed up the run, see Section 4.9 [Tessellation], page 141. Common options related to tessellation are described in in Section 4.1.2.2 [Processing options], page 112.

1-dimensional datasets (for example spectra) are only read as columns within a table (see Section 4.8 [Tables], page 135, for more on how Gnuastro programs read tables). Note that currently 1D convolution is only implemented in the spatial domain and thus kernel-matching is also not supported.

Here we will only explain the options particular to Convolve. Run Convolve with --help in order to see the full list of options Convolve accepts, irrespective of where they are explained in this book.

--kernelcolumn
Column containing the 1D kernel. When the input dataset is a 1-dimensional column, and the host table has more than one column, use this option to specify which column should be used.

--nokernelflip
Do not flip the kernel after reading it the spatial domain convolution. This can be useful if the flipping has already been applied to the kernel.

--nokernelnormx
Do not normalize the kernel after reading it, such that the sum of its pixels is unity.
The domain to use for the convolution. The acceptable values are ‘spatial’ and ‘frequency’, corresponding to the respective domain.

For large images, the frequency domain process will be more efficient than convolving in the spatial domain. However, the edges of the image will lose some flux (see Section 6.3.1.2 [Edges in the spatial domain], page 218) and the image must not contain any blank pixels, see Section 6.3.3 [Spatial vs. Frequency domain], page 234.

--checkfreqsteps
With this option a file with the initial name of the output file will be created that is suffixed with _freqsteps.fits, all the steps done to arrive at the final convolved image are saved as extensions in this file. The extensions in order are:

1. The padded input image. In frequency domain convolution the two images (input and convolved) have to be the same size and both should be padded by zeros.
2. The padded kernel, similar to the above.
3. The Fourier spectrum of the forward Fourier transform of the input image. Note that the Fourier transform is a complex operation (and not viewable in one image!) So we either have to show the ‘Fourier spectrum’ or the ‘Phase angle’. For the complex number \( a + ib \), the Fourier spectrum is defined as \( \sqrt{a^2 + b^2} \) while the phase angle is defined as \( \arctan(b/a) \).
4. The Fourier spectrum of the forward Fourier transform of the kernel image.
5. The Fourier spectrum of the multiplied (through complex arithmetic) transformed images.
6. The inverse Fourier transform of the multiplied image. If you open it, you will see that the convolved image is now in the center, not on one side of the image as it started with (in the padded image of the first extension). If you are working on a mock image which originally had pixels of precisely 0.0, you will notice that in those parts that your convolved profile(s) did not convert, the values are now \( \sim 10^{-18} \), this is due to floating-point round off errors. Therefore in the final step (when cropping the central parts of the image), we also remove any pixel with a value less than \( 10^{-17} \).

--noedgecorrection
Do not correct the edge effect in spatial domain convolution. For a full discussion, please see Section 6.3.1.2 [Edges in the spatial domain], page 218.

-m INT
--makekernel=INT
\( (=\text{INT}) \) If this option is called, Convolve will do de-convolution (see Section 6.3.2.6 [Convolution theorem], page 227). The image specified by the --kernel option is assumed to be the sharper (less blurry) image and the input image is assumed to be the more blurry image. The value given to this option will be used as the maximum radius of the kernel. Any pixel in the
final kernel that is larger than this distance from the center will be set to zero. The two images must have the same size.

Noise has large frequencies which can make the result less reliable for the higher frequencies of the final result. So all the frequencies which have a spectrum smaller than the value given to the `--minsharpspec` option in the sharper input image are set to zero and not divided. This will cause the wings of the final kernel to be flatter than they would ideally be which will make the convolved image result unreliable if it is too high. Some notes to take into account for a good result:

- Choose a bright (unsaturated) star and use a region box (with Crop for example, see Section 6.1 [Crop], page 188) that is sufficiently above the noise.
- Use Warp (see Section 6.4 [Warp], page 238) to warp the pixel grid so the star’s center is exactly on the center of the central pixel in the cropped image. This will certainly slightly degrade the result, however, it is necessary. If there are multiple good stars, you can shift all of them, then normalize them (so the sum of each star’s pixels is one) and then take their average to decrease this effect.
- The shifting might move the center of the star by one pixel in any direction, so crop the central pixel of the warped image to have a clean image for the de-convolution.

Note that this feature is not yet supported in 1-dimensional datasets.

`--minsharpspec` *(=FLT)* The minimum frequency spectrum (or coefficient, or pixel value in the frequency domain image) to use in deconvolution, see the explanations under the `--makekernel` option for more information.

### 6.4 Warp

Image warping is the process of mapping the pixels of one image onto a new pixel grid. This process is sometimes known as transformation, however following the discussion of Heckbert 1989\(^{21}\) we will not be using that term because it can be confused with only pixel value or flux transformations. Here we specifically mean the pixel grid transformation which is better conveyed with ‘warp’.

Image wrapping is a very important step in astronomy, both in observational data analysis and in simulating modeled images. In modeling, warping an image is necessary when we want to apply grid transformations to the initial models, for example in simulating gravitational lensing (Radial warpings are not yet included in Warp). Observational reasons for warping an image are listed below:

- **Noise:** Most scientifically interesting targets are inherently faint (have a very low Signal to noise ratio). Therefore one short exposure is not enough to detect such objects that

are drowned deeply in the noise. We need multiple exposures so we can add them together and increase the objects’ signal to noise ratio. Keeping the telescope fixed on one field of the sky is practically impossible. Therefore very deep observations have to put into the same grid before adding them.

- **Resolution:** If we have multiple images of one patch of the sky (hopefully at multiple orientations) we can warp them to the same grid. The multiple orientations will allow us to ‘guess’ the values of pixels on an output pixel grid that has smaller pixel sizes and thus increase the resolution of the output. This process of merging multiple observations is known as Mosaicing.

- **Cosmic rays:** Cosmic rays can randomly fall on any part of an image. If they collide vertically with the camera, they are going to create a very sharp and bright spot that in most cases can be separated easily. However, depending on the depth of the camera pixels, and the angle that a cosmic rays collides with it, it can cover a line-like larger area on the CCD which makes the detection using their sharp edges very hard and error prone. One of the best methods to remove cosmic rays is to compare multiple images of the same field. To do that, we need all the images to be on the same pixel grid.

- **Optical distortion:** (Not yet included in Warp) In wide field images, the optical distortion that occurs on the outer parts of the focal plane will make accurate comparison of the objects at various locations impossible. It is therefore necessary to warp the image and correct for those distortions prior to the analysis.

- **Detector not on focal plane:** In some cases (like the Hubble Space Telescope ACS and WFC3 cameras), the CCD might be tilted compared to the focal plane, therefore the recorded CCD pixels have to be projected onto the focal plane before further analysis.

### 6.4.1 Warping basics

Let’s take \([u \ v]\) as the coordinates of a point in the input image and \([x \ y]\) as the coordinates of that same point in the output image. The simplest form of coordinate transformation (or warping) is the scaling of the coordinates, let’s assume we want to scale the first axis by \(M\) and the second by \(N\), the output coordinates of that point can be calculated by

\[
\begin{bmatrix}
    x \\
    y 
\end{bmatrix} = \begin{bmatrix}
    Mu \\
    Nv 
\end{bmatrix} = \begin{bmatrix}
    M & 0 \\
    0 & N 
\end{bmatrix} \begin{bmatrix}
    u \\
    v 
\end{bmatrix}
\]

Note that these are matrix multiplications. We thus see that we can represent any such grid warping as a matrix. Another thing we can do with this \(2 \times 2\) matrix is to rotate the output coordinate around the common center of both coordinates. If the output is rotated anticlockwise by \(\theta\) degrees from the positive (to the right) horizontal axis, then the warping matrix should become:

\[
\begin{bmatrix}
    x \\
    y 
\end{bmatrix} = \begin{bmatrix}
    ucos\theta - vsin\theta \\
    usin\theta + vcos\theta 
\end{bmatrix} = \begin{bmatrix}
    cos\theta & -sin\theta \\
    sin\theta & cos\theta 
\end{bmatrix} \begin{bmatrix}
    u \\
    v 
\end{bmatrix}
\]

---

22 All astronomical targets are blurred with the PSF, see Section 8.1.1.2 [Point spread function], page 334, however a cosmic ray is not and so it is very sharp (it suddenly stops at one pixel).

23 These can be any real number, we are not necessarily talking about integer pixels here.
We can also flip the coordinates around the first axis, the second axis and the coordinate center with the following three matrices respectively:

\[
\begin{bmatrix}
1 & 0 \\
0 & -1
\end{bmatrix} \quad \begin{bmatrix}
-1 & 0 \\
0 & 1
\end{bmatrix} \quad \begin{bmatrix}
-1 & 0 \\
0 & -1
\end{bmatrix}
\]

The final thing we can do with this definition of a $2 \times 2$ warping matrix is shear. If we want the output to be sheared along the first axis with $A$ and along the second with $B$, then we can use the matrix:

\[
\begin{bmatrix}
1 & A \\
B & 1
\end{bmatrix}
\]

To have one matrix representing any combination of these steps, you use matrix multiplication, see Section 6.4.2 [Merging multiple warpings], page 241. So any combinations of these transformations can be displayed with one $2 \times 2$ matrix:

\[
\begin{bmatrix}
a & b \\
c & d
\end{bmatrix}
\]

The transformations above can cover a lot of the needs of most coordinate transformations. However they are limited to mapping the point $[0 \ 0]$ to $[0 \ 0]$. Therefore they are useless if you want one coordinate to be shifted compared to the other one. They are also space invariant, meaning that all the coordinates in the image will receive the same transformation. In other words, all the pixels in the output image will have the same area if placed over the input image. So transformations which require varying output pixel sizes like projections cannot be applied through this $2 \times 2$ matrix either (for example for the tilted ACS and WFC3 camera detectors on board the Hubble space telescope).

To add these further capabilities, namely translation and projection, we use the homogeneous coordinates. They were defined about 200 years ago by August Ferdinand Möbius (1790 – 1868). For simplicity, we will only discuss points on a 2D plane and avoid the complexities of higher dimensions. We cannot provide a deep mathematical introduction here, interested readers can get a more detailed explanation from Wikipedia\(^{24}\) and the references therein.

By adding an extra coordinate to a point we can add the flexibility we need. The point $[x \ y]$ can be represented as $[xZ \ yZ \ Z]$ in homogeneous coordinates. Therefore multiplying all the coordinates of a point in the homogeneous coordinates with a constant will give the same point. Put another way, the point $[x \ y \ Z]$ corresponds to the point $[x/Z \ y/Z]$ on the constant $Z$ plane. Setting $Z = 1$, we get the input image plane, so $[u \ v \ 1]$ corresponds to $[u \ v]$. With this definition, the transformations above can be generally written as:

We thus acquired 4 extra degrees of freedom. By giving non-zero values to the zero valued elements of the last column we can have translation (try the matrix multiplication!). In general, any coordinate transformation that is represented by the matrix below is known as an affine transformation:\footnote{http://en.wikipedia.org/wiki/Affine_transformation}:

\[
\begin{bmatrix}
    a & b & c \\
    d & e & f \\
    0 & 0 & 1
\end{bmatrix}
\]

We can now consider translation, but the affine transform is still spatially invariant. Giving non-zero values to the other two elements in the matrix above gives us the projective transformation or Homography\footnote{http://en.wikipedia.org/wiki/Homography} which is the most general type of transformation with the \(3 \times 3\) matrix:

\[
\begin{bmatrix}
    x' \\
    y' \\
    w
\end{bmatrix}
= \begin{bmatrix}
    a & b & c \\
    d & e & f \\
    g & h & 1
\end{bmatrix}
\begin{bmatrix}
    u \\
    v \\
    1
\end{bmatrix}
\]

So the output coordinates can be calculated from:

\[
x = \frac{x'}{w} = \frac{au + bv + c}{gu + hv + 1} \quad \quad \quad y = \frac{y'}{w} = \frac{dv + ev + f}{gu + hv + 1}
\]

Thus with Homography we can change the sizes of the output pixels on the input plane, giving a ‘perspective’-like visual impression. This can be quantitatively seen in the two equations above. When \(g = h = 0\), the denominator is independent of \(u\) or \(v\) and thus we have spatial invariance. Homography preserves lines at all orientations. A very useful fact about Homography is that its inverse is also a Homography. These two properties play a very important role in the implementation of this transformation. A short but instructive and illustrated review of affine, projective and also bi-linear mappings is provided in Heckbert\footnote{Paul S. Heckbert. 1989. *Fundamentals of Texture mapping and Image Warping*, Master’s thesis at University of California, Berkeley. Note that since points are defined as row vectors there, the matrix is the transpose of the one discussed here.} 1989.}

### 6.4.2 Merging multiple warpings

In Section 6.4.1 [Warping basics], page 239, we saw how a basic warp/transformation can be represented with a matrix. To make more complex warpings (for example to define a translation, rotation and scale as one warp) the individual matrices have to be multiplied
Chapter 6: Data manipulation

through matrix multiplication. However matrix multiplication is not commutative, so the
order of the set of matrices you use for the multiplication is going to be very important.

The first warping should be placed as the left-most matrix. The second warping to
the right of that and so on. The second transformation is going to occur on the warped
coordinates of the first. As an example for merging a few transforms into one matrix, the
multiplication below represents the rotation of an image about a point $[U \ V]$ anticlockwise
from the horizontal axis by an angle of $\theta$. To do this, first we take the origin to $[U \ V]$ through translation. Then we rotate the image, then we translate it back to where it was
initially. These three operations can be merged in one operation by calculating the matrix
multiplication below:

$$
\begin{bmatrix}
1 & 0 & U \\
0 & 1 & V \\
0 & 0 & 1
\end{bmatrix}
\begin{bmatrix}
cos\theta & -sin\theta & 0 \\
sin\theta & cos\theta & 0 \\
0 & 0 & 1
\end{bmatrix}
\begin{bmatrix}
1 & 0 & -U \\
0 & 1 & -V \\
0 & 0 & 1
\end{bmatrix}
$$

6.4.3 Resampling

A digital image is composed of discrete ‘picture elements’ or ‘pixels’. When a real image is
created from a camera or detector, each pixel’s area is used to store the number of photo-
electrons that were created when incident photons collided with that pixel’s surface area.
This process is called the ‘sampling’ of a continuous or analog data into digital data. When
we change the pixel grid of an image or warp it as we defined in Section 6.4.1 [Warping
basics], page 239, we have to ‘guess’ the flux value of each pixel on the new grid based on
the old grid, or re-sample it. Because of the ‘guessing’, any form of warping on the data
is going to degrade the image and mix the original pixel values with each other. So if an
analysis can be done on an unwarped data image, it is best to leave the image untouched
and pursue the analysis. However as discussed in Section 6.4 [Warp], page 238, this is not
possible most of the times, so we have to accept the problem and re-sample the image.

In most applications of image processing, it is sufficient to consider each pixel to be a
point and not an area. This assumption can significantly speed up the processing of an
image and also the simplicity of the code. It is a fine assumption when the signal to noise
ratio of the objects are very large. The question will then be one of interpolation because
you have multiple points distributed over the output image and you want to find the values
at the pixel centers. To increase the accuracy, you might also sample more than one point
from within a pixel giving you more points for a more accurate interpolation in the output
grid.

However, interpolation has several problems. The first one is that it will depend on the
type of function you want to assume for the interpolation. For example you can choose a
bi-linear or bi-cubic (the ‘bi’s are for the 2 dimensional nature of the data) interpolation
method. For the latter there are various ways to set the constants\textsuperscript{28}. Such functional
interpolation functions can fail seriously on the edges of an image. They will also need
normalization so that the flux of the objects before and after the warpings are comparable.
The most basic problem with such techniques is that they are based on a point while
a detector pixel is an area. They add a level of subjectivity to the data (make more

\textsuperscript{28} see http://entropymine.com/imageworsener/bicubic/ for a nice introduction.
assumptions through the functions than the data can handle). For most applications this is fine, but in scientific applications where detection of the faintest possible galaxies or fainter parts of bright galaxies is our aim, we cannot afford this loss. Because of these reasons Warp will not use such interpolation techniques.

Warp will do interpolation based on “pixel mixing”\(^{29}\) or “area resampling”. This is also what the Hubble Space Telescope pipeline calls “Drizzling”\(^{30}\). This technique requires no functions, it is thus non-parametric. It is also the closest we can get (make least assumptions) to what actually happens on the detector pixels. The basic idea is that you reverse-transform each output pixel to find which pixels of the input image it covers and what fraction of the area of the input pixels are covered. To find the output pixel value, you simply sum the value of each input pixel weighted by the overlap fraction (between 0 to 1) of the output pixel and that input pixel. Through this process, pixels are treated as an area not as a point (which is how detectors create the image), also the brightness (see Section 8.1.3 [Brightness, Flux, Magnitude and Surface brightness], page 338) of an object will be left completely unchanged.

If there are very high spatial-frequency signals in the image (for example fringes) which vary on a scale smaller than your output image pixel size, pixel mixing can cause aliasing\(^{31}\). So if the input image has fringes, they have to be calculated and removed separately (which would naturally be done in any astronomical application). Because of the PSF no astronomical target has a sharp change in the signal so this issue is less important for astronomical applications, see Section 8.1.1.2 [Point spread function], page 334.

### 6.4.4 Invoking Warp

Warp an input dataset into a new grid. Any homographic warp (for example scaling, rotation, translation, projection) is acceptable, see Section 6.4.1 [Warping basics], page 239, for the definitions. The general template for invoking Warp is:

```
$ astwarp [OPTIONS...] InputImage
```

One line examples:

```bash
## Rotate and then scale input image:
$ astwarp --rotate=37.92 --scale=0.8 image.fits

## Scale, then translate the input image:
$ astwarp --scale 8/3 --translate 2.1 image.fits

## Align raw image with celestial coordinates:
$ astwarp --align rawimage.fits --output=aligned.fits

## Directly input a custom warping matrix (using fraction):
$ astwarp --matrix=1/5,0,4/10,0,1/5,4/10,0,0,1 image.fits

## Directly input a custom warping matrix, with final numbers:
$ astwarp --matrix="0.7071,-0.7071, 0.7071,0.7071" image.fits
```

---


If any processing is to be done, Warp can accept one file as input. As in all Gnuastro programs, when an output is not explicitly set with the \texttt{--output} option, the output filename will be set automatically based on the operation, see Section 4.10 [Automatic output], page 142. For the full list of general options to all Gnuastro programs (including Warp), please see Section 4.1.2 [Common options], page 109.

To be the most accurate, the input image will be read as a 64-bit double precision floating point dataset and all internal processing is done in this format (including the raw output type). You can use the common \texttt{--type} option to write the output in any type you want, see Section 4.6 [Numeric data types], page 130. Warps must be specified as command-line options, either as (possibly multiple) modular warpings (for example \texttt{--rotate}, or \texttt{--scale}), or directly as a single raw matrix (with \texttt{--matrix}). If specified together, the latter (direct matrix) will take precedence and all the modular warpings will be ignored. Any number of modular warpings can be specified on the command-line and configuration files. If more than one modular warping is given, all will be merged to create one warping matrix. As described in Section 6.4.2 [Merging multiple warpings], page 241, matrix multiplication is not commutative, so the order of specifying the modular warpings on the command-line, and/or configuration files makes a difference (see Section 4.2.2 [Configuration file precedence], page 121). The full list of modular warpings and the other options particular to Warp are described below.

The values to the warping options (modular warpings as well as \texttt{--matrix}), are a sequence of at least one number. Each number in this sequence is separated from the next by a comma (\texttt{,}). Each number can also be written as a single fraction (with a forward-slash / between the numerator and denominator). Space and Tab characters are permitted between any two numbers, just don’t forget to quote the whole value. Otherwise, the value will not be fully passed onto the option. See the examples above as a demonstration.

Based on the FITS standard, integer values are assigned to the center of a pixel and the coordinate \([1.0, 1.0]\) is the center of the first pixel (bottom left of the image when viewed in SAO ds9). So the coordinate center \([0.0, 0.0]\) is half a pixel away (in each axis) from the bottom left vertex of the first pixel. The resampling that is done in Warp (see Section 6.4.3 [Resampling], page 242) is done on the coordinate axes and thus directly depends on the coordinate center. In some situations this is fine, for example when rotating/aligning a real image, all the edge pixels will be similarly affected. But in other situations (for example when scaling an over-sampled mock image to its intended resolution, this is not desired: you want the center of the coordinates to be on the corner of the pixel. In such cases, you can use the \texttt{--centeroncorner} option which will shift the center by 0.5 before the main warp, then shift it back by \(-0.5\) after the main warp, see below.

\texttt{-a}

\textbf{--align}  
Align the image and celestial (WCS) axes given in the input. After it, the vertical image direction (when viewed in SAO ds9) corresponds to the declination and the horizontal axis is the inverse of the Right Ascension (RA). The inverse of the RA is chosen so the image can correspond to what you would actually see on the sky and is common in most survey images.

Align is internally treated just like a rotation (\texttt{--rotation}), but uses the input image’s WCS to find the rotation angle. Thus, if you have rotated the image
before calling --align, you might get unexpected results (because the rotation is defined on the original WCS).

--rotate=FLT

Rotate the input image by the given angle in degrees: $\theta$ in Section 6.4.1 [Warping basics], page 239. Note that commonly, the WCS structure of the image is set such that the RA is the inverse of the image horizontal axis which increases towards the right in the FITS standard and as viewed by SAO ds9. So the default center for rotation is on the right of the image. If you want to rotate about other points, you have to translate the warping center first (with --translate) then apply your rotation and then return the center back to the original position (with another call to --translate, see Section 6.4.2 [Merging multiple warpings], page 241).

--scale=FLT[,FLT]

Scale the input image by the given factor(s): $M$ and $N$ in Section 6.4.1 [Warping basics], page 239. If only one value is given, then both image axes will be scaled with the given value. When two values are given (separated by a comma), the first will be used to scale the first axis and the second will be used for the second axis. If you only need to scale one axis, use 1 for the axis you don’t need to scale. The value(s) can also be written (on the command-line or in configuration files) as a fraction.

--flip=FLT[,FLT]

Flip the input image around the given axis(s). If only one value is given, then both image axes are flipped. When two values are given (separated by a comma), you can choose which axis to flip over. --flip only takes values 0 (for no flip), or 1 (for a flip). Hence, if you want to flip by the second axis only, use --flip=0,1.

--shear=FLT[,FLT]

Shear the input image by the given value(s): $A$ and $B$ in Section 6.4.1 [Warping basics], page 239. If only one value is given, then both image axes will be sheared with the given value. When two values are given (separated by a comma), the first will be used to shear the first axis and the second will be used for the second axis. If you only need to shear along one axis, use 0 for the axis that must be untouched. The value(s) can also be written (on the command-line or in configuration files) as a fraction.

--translate=FLT[,FLT]

Translate (move the center of coordinates) the input image by the given value(s): $c$ and $f$ in Section 6.4.1 [Warping basics], page 239. If only one value is given, then both image axes will be translated by the given value. When two values are given (separated by a comma), the first will be used to translate the first axis and the second will be used for the second axis. If you only need to translate
along one axis, use 0 for the axis that must be untouched. The value(s) can also be written (on the command-line or in configuration files) as a fraction.

-p FLT[,FLT]
--project=FLT[,FLT]
Apply a projection to the input image by the given values(s): \( g \) and \( h \) in Section 6.4.1 [Warping basics], page 239. If only one value is given, then projection will apply to both axes with the given value. When two values are given (separated by a comma), the first will be used to project the first axis and the second will be used for the second axis. If you only need to project along one axis, use 0 for the axis that must be untouched. The value(s) can also be written (on the command-line or in configuration files) as a fraction.

-m STR
--matrix=STR
The warp/transformation matrix. All the elements in this matrix must be separated by commas (,) characters and as described above, you can also use fractions (a forward-slash between two numbers). The transformation matrix can be either a 2 by 2 (4 numbers), or a 3 by 3 (9 numbers) array. In the former case (if a 2 by 2 matrix is given), then it is put into a 3 by 3 matrix (see Section 6.4.1 [Warping basics], page 239).

The determinant of the matrix has to be non-zero and it must not contain any non-number values (for example infinities or NaNs). The elements of the matrix have to be written row by row. So for the general Homography matrix of Section 6.4.1 [Warping basics], page 239, it should be called with --matrix=a,b,c,d,e,f,g,h,1.

The raw matrix takes precedence over all the modular warping options listed above, so if it is called with any number of modular warps, the latter are ignored.

-c
--centeroncorer
Put the center of coordinates on the corner of the first (bottom-left when viewed in SAO ds9) pixel. This option is applied after the final warping matrix has been finalized: either through modular warpings or the raw matrix. See the explanation above for coordinates in the FITS standard to better understand this option and when it should be used.

--hstartwcs=INT
Specify the first header keyword number (line) that should be used to read the WCS information, see the full explanation in Section 6.1.4 [Invoking Crop], page 192.

--hendwcs=INT
Specify the last header keyword number (line) that should be used to read the WCS information, see the full explanation in Section 6.1.4 [Invoking Crop], page 192.
-k
--keepwcs
Do not correct the WCS information of the input image and save it untouched to
the output image. By default the WCS (World Coordinate System) information
of the input image is going to be corrected in the output image so the objects
in the image are at the same WCS coordinates. But in some cases it might be
useful to keep it unchanged (for example to correct alignments).

-C FLT
--coveredfrac=FLT
Depending on the warp, the output pixels that cover pixels on the edge of the
input image, or blank pixels in the input image, are not going to be fully covered
by input data. With this option, you can specify the acceptable covered fraction
of such pixels (any value between 0 and 1). If you only want output pixels that
are fully covered by the input image area (and are not blank), then you can set
--coveredfrac=1. Alternatively, a value of 0 will keep output pixels that are
even infinitesimally covered by the input (so the sum of the pixels in the input
and output images will be the same).
7 Data analysis

Astronomical datasets (images or tables) contain very valuable information, the tools in this section can help in analyzing, extracting, and quantifying that information. For example, getting general or specific statistics of the dataset (with Section 7.1 [Statistics], page 248), detecting signal within a noisy dataset (with Section 7.2 [NoiseChisel], page 269), or creating a catalog from an input dataset (with Section 7.4 [MakeCatalog], page 295).

7.1 Statistics

The distribution of values in a dataset can provide valuable information about it. For example, in an image, if it is a positively skewed distribution, we can see that there is significant data in the image. If the distribution is roughly symmetric, we can tell that there is no significant data in the image. In a table, when we need to select a sample of objects, it is important to first get a general view of the whole sample.

On the other hand, you might need to know certain statistical parameters of the dataset. For example, if we have run a detection algorithm on an image, and we want to see how accurate it was, one method is to calculate the average of the undetected pixels and see how reasonable it is (if detection is done correctly, the average of undetected pixels should be approximately equal to the background value, see Section 7.1.4 [Sky value], page 252). In a table, you might have calculated the magnitudes of a certain class of objects and want to get some general characteristics of the distribution immediately on the command-line (very fast!), to possibly change some parameters. The Statistics program is designed for such situations.

7.1.1 Histogram and Cumulative Frequency Plot

Histograms and the cumulative frequency plots are both used to visually study the distribution of a dataset. A histogram shows the number of data points which lie within pre-defined intervals (bins). So on the horizontal axis we have the bin centers and on the vertical, the number of points that are in that bin. You can use it to get a general view of the distribution: which values have been repeated the most? how close/far are the most significant bins? Are there more values in the larger part of the range of the dataset, or in the lower part? Similarly, many very important properties about the dataset can be deduced from a visual inspection of the histogram. In the Statistics program, the histogram can be either output to a table to plot with your favorite plotting program\(^1\), or it can be shown with ASCII characters on the command-line, which is very crude, but good enough for a fast and on-the-go analysis, see the example in Section 7.1.5 [Invoking Statistics], page 257.

The width of the bins is only necessary parameter for a histogram. In the limiting case that the bin-widths tend to zero (while assuming the number of points in the dataset tend to infinity), then the histogram will tend to the probability density function (https://en.wikipedia.org/wiki/Probability_density_function) of the distribution. When the absolute number of points in each bin is not relevant to the study (only the shape of the histogram is important), you can normalize a histogram so like the probability density function, the sum of all its bins will be one.

\(^1\) We recommend PGFPlots (http://pgfplots.sourceforge.net/) which generates your plots directly within \TeX{} (the same tool that generates your document).
In the cumulative frequency plot of a distribution, the horizontal axis is the sorted data values and the y axis is the index of each data in the sorted distribution. Unlike a histogram, a cumulative frequency plot does not involve intervals or bins. This makes it less prone to any sort of bias or error that a given bin-width would have on the analysis. When a larger number of the data points have roughly the same value, then the cumulative frequency plot will become steep in that vicinity. This occurs because on the horizontal axis, there is little change while on the vertical axis, the indexes constantly increase. Normalizing a cumulative frequency plot means to divide each index (y axis) by the total number of data points (or the last value).

Unlike the histogram which has a limited number of bins, ideally the cumulative frequency plot should have one point for every data element. Even in small datasets (for example a 200 × 200 image) this will result in an unreasonably large number of points to plot (40000)! As a result, for practical reasons, it is common to only store its value on a certain number of points (intervals) in the input range rather than the whole dataset, so you should determine the number of bins you want when asking for a cumulative frequency plot.

In Gnuastro (and thus the Statistics program), the number reported for each bin is the total number of data points until the larger interval value for that bin. You can see an example histogram and cumulative frequency plot of a single dataset under the --asciihist and --asciicfp options of Section 7.1.5 [Invoking Statistics], page 257.

So as a summary, both the histogram and cumulative frequency plot in Statistics will work with bins. Within each bin/interval, the lower value is considered to be within then bin (it is inclusive), but its larger value is not (it is exclusive). Formally, an interval/bin between a and b is represented by [a, b). When the over-all range of the dataset is specified (with the --greaterequal, --lessthan, or --qrange options), the acceptable values of the dataset are also defined with a similar inclusive-exclusive manner. But when the range is determined from the actual dataset (none of these options is called), the last element in the dataset is included in the last bin’s count.

7.1.2 2D Histograms

In Section 7.1.1 [Histogram and Cumulative Frequency Plot], page 248, the concept of histograms were introduced on a single dataset. However, especially when doing high-level science on tables, the distribution in a 2D space may be of interest (for example a color-magnitude diagram). But the number of points may be too large for a simple scatter plot to show the concentration of the points: they will all fall over each other and just make a large connected region that will hide potentially interesting behaviors. This is where 2D histograms can become very useful. The desired 2D region is broken up into 2D bins (boxes) and the number of points falling within each box is returned. Added with a color-bar, you can now clearly see the distribution.

Gnuastro’s Statistics program has the --histogram2d option for this task. Its output will be three columns that have the centers of every box in both dimensions. The first column is the central box coordinates in the first dimension, the second has values along the second dimension and the third has the number of input points that fall within each box. You can specify the number of bins along each dimension through the --numbins (for first input column) an --numbins2 (for second input column). The output file from this command can then be given to any plotting tool to visualize the distribution.
For example, you can make high-quality plots within your paper (using the same \LaTeX engine, thus blending very nicely with your text) using PGFPLOTS (https://ctan.org/pkg/pgfplots). Below you can see one such minimal example, using your favorite text editor, save it into a file, make the two small corrections in it, then run the commands shown at the top. This assumes that you have \LaTeX installed, if not the steps to install a minimally sufficient \LaTeX package on your system, see the respective section in Section 3.1.3 [Bootstrapping dependencies], page 79.

The two parts that need to be corrected are marked with ‘%% <-’: the first one (XXXXXXXXX) should be replaced by the value to the --numbins option which is the number of bins along the first dimension. The second one (FILE.txt) should be replaced with the name of the file generated by Statistics.

%% Replace 'XXXXXXXXX' with your selected number of bins in the first
%% dimension.
%%
%% Then run these commands to build the plot in a LaTeX command.
%% mkdir tikz
%% pdflatex -shell-escape -halt-on-error plot.tex
\documentclass{article}
\usepackage{pgfplots}
\usetikzlibrary{external}
\tikzexternalize\tikzsetexternalprefix{tikz/}
\begin{document}
You can actually write a full paper here and include many figures! Feel free to change this text.

%% Define the colormap.
\pgfplotstikzset{
/pgfplots/colormap={coldredux}{
[1cm]
 rgb255(0cm)=(255,255,255)
 rgb255(2cm)=(0,192,255)
 rgb255(4cm)=(0,0,255)
 rgb255(6cm)=(0,0,0)
}
}
\begin{tikzpicture}
\small
\begin{axis}[
width=\linewidth,
view={0}{90},
colorbar horizontal,
xlabel=X axis,
ylabel=Y axis,
ylabel shift=-0.1cm,
colorbar style={at={(0,1.01)}, anchor=south west,
xticklabel pos=upper},
]
\addplot3[
surf,
shader=flat corner,
mesh/ordering=rowwise,
mesh/cols=XXXXXXXXX, \% <-- Number of bins in 1st column.
] file {FILE.txt}; \% <-- Name of aststatistics output.
\end{axis}
\end{tikzpicture}

7.1.3 Sigma clipping

Let’s assume that you have pure noise (centered on zero) with a clear Gaussian distribution (https://en.wikipedia.org/wiki/Normal_distribution), or see Section 8.2.1.1 [Photon counting noise], page 353. Now let’s assume you add very bright objects (signal) on the image which have a very sharp boundary. By a sharp boundary, we mean that there is a clear cutoff (from the noise) at the pixels the objects finish. In other words, at their boundaries, the objects do not fade away into the noise. In such a case, when you plot the histogram (see Section 7.1.1 [Histogram and Cumulative Frequency Plot], page 248) of the distribution, the pixels relating to those objects will be clearly separate from pixels that belong to parts of the image that did not have any signal (were just noise). In the cumulative frequency plot, after a steady rise (due to the noise), you would observe a long flat region were for a certain range of data (horizontal axis), there is no increase in the index (vertical axis).

Outliers like the example above can significantly bias the measurement of noise statistics. $\sigma$-clipping is defined as a way to avoid the effect of such outliers. In astronomical applications, cosmic rays (when they collide at a near normal incidence angle) are a very good example of such outliers. The tracks they leave behind in the image are perfectly immune to the blurring caused by the atmosphere and the aperture. They are also very energetic and so their borders are usually clearly separated from the surrounding noise. So $\sigma$-clipping is very useful in removing their effect on the data. See Figure 15 in Akhlaghi and Ichikawa, 2015 (https://arxiv.org/abs/1505.01664).
\(\sigma\)-clipping is defined as the very simple iteration below. In each iteration, the range of input data might decrease and so when the outliers have the conditions above, the outliers will be removed through this iteration. The exit criteria will be discussed below.

1. Calculate the standard deviation \((\sigma)\) and median \((m)\) of a distribution.
2. Remove all points that are smaller or larger than \(m \pm \alpha \sigma\).
3. Go back to step 1, unless the selected exit criteria is reached.

The reason the median is used as a reference and not the mean is that the mean is too significantly affected by the presence of outliers, while the median is less affected, see Section 7.1.4.3 [Quantifying signal in a tile], page 255. As you can tell from this algorithm, besides the condition above (that the signal have clear high signal to noise boundaries) \(\sigma\)-clipping is only useful when the signal does not cover more than half of the full data set. If they do, then the median will lie over the outliers and \(\sigma\)-clipping might remove the pixels with no signal.

There are commonly two exit criteria to stop the \(\sigma\)-clipping iteration:

- When a certain number of iterations has taken place (second value to the \texttt{--sclipparams} option is larger than 1).
- When the new measured standard deviation is within a certain tolerance level of the old one (second value to the \texttt{--sclipparams} option is less than 1). The tolerance level is defined by:

\[
\frac{\sigma_{\text{old}} - \sigma_{\text{new}}}{\sigma_{\text{new}}}
\]

The standard deviation is used because it is heavily influenced by the presence of outliers. Therefore the fact that it stops changing between two iterations is a sign that we have successfully removed outliers. Note that in each clipping, the dispersion in the distribution is either less or equal. So \(\sigma_{\text{old}} \geq \sigma_{\text{new}}\).

When working on astronomical images, objects like galaxies and stars are blurred by the atmosphere and the telescope aperture, therefore their signal sinks into the noise very gradually. Galaxies in particular do not appear to have a clear high signal to noise cutoff at all. Therefore \(\sigma\)-clipping will not be useful in removing their effect on the data.

To gauge if \(\sigma\)-clipping will be useful for your dataset, look at the histogram (see Section 7.1.1 [Histogram and Cumulative Frequency Plot], page 248). The ASCII histogram that is printed on the command-line with \texttt{--asciihist} is good enough in most cases.

### 7.1.4 Sky value

One of the most important aspects of a dataset is its reference value: the value of the dataset where there is no signal. Without knowing, and thus removing the effect of, this value it is impossible to compare the derived results of many high-level analyses over the dataset with other datasets (in the attempt to associate our results with the “real” world).

In astronomy, this reference value is known as the “Sky” value: the value that noise fluctuates around: where there is no signal from detectable objects or artifacts (for example
galaxies, stars, planets or comets, star spikes or internal optical ghost). Depending on the
dataset, the Sky value maybe a fixed value over the whole dataset, or it may vary based on
location. For an example of the latter case, see Figure 11 in Akhlaghi and Ichikawa (2015)

Because of the significance of the Sky value in astronomical data analysis, we have
devoted this subsection to it for a thorough review. We start with a thorough discussion on its
definition (Section 7.1.4.1 [Sky value definition], page 253). In the astronomical literature,
researchers use a variety of methods to estimate the Sky value, so in Section 7.1.4.2 [Sky
value misconceptions], page 254) we review those and discuss their biases. From the defini-
tion of the Sky value, the most accurate way to estimate the Sky value is to run a detection
algorithm (for example Section 7.2 [NoiseChisel], page 269) over the dataset and use the
undetected pixels. However, there is also a more crude method that maybe useful when
good direct detection is not initially possible (for example due to too many cosmic rays in
a shallow image). A more crude (but simpler method) that is usable in such situations is
discussed in Section 7.1.4.3 [Quantifying signal in a tile], page 255.

7.1.4.1 Sky value definition

01664). Let’s assume that all instrument defects – bias, dark and flat – have been corrected
and the brightness (see Section 8.1.3 [Brightness, Flux, Magnitude and Surface brightness],
page 338) of a detected object, $O$, is desired. The sources of flux on pixel $i$ of the image
can be written as follows:

• Contribution from the target object ($O_i$).
• Contribution from other detected objects ($D_i$).
• Undetected objects or the fainter undetected regions of bright objects ($U_i$).
• A cosmic ray ($C_i$).
• The background flux, which is defined to be the count if none of the others exists on
that pixel ($B_i$).

The total flux in this pixel ($T_i$) can thus be written as:

$$T_i = B_i + D_i + U_i + C_i + O_i.$$  

By definition, $D_i$ is detected and it can be assumed that it is correctly estimated (deblended)
and subtracted, we can thus set $D_i = 0$. There are also methods to detect and remove
cosmic rays, for example the method described in van Dokkum (2001)$^3$, or by comparing
multiple exposures. This allows us to set $C_i = 0$. Note that in practice, $D_i$ and $U_i$ are
correlated, because they both directly depend on the detection algorithm and its input
parameters. Also note that no detection or cosmic ray removal algorithm is perfect. With
these limitations in mind, the observed Sky value for this pixel ($S_i$) can be defined as

---

$^2$ For this analysis the dimension of the data (image) is irrelevant. So if the data is an image (2D) with
width of $w$ pixels, then a pixel located on column $x$ and row $y$ (where all counting starts from zero and
$(0, 0)$ is located on the bottom left corner of the image), would have an index: $i = x + y \times w$.

\[ S_i \equiv B_i + U_i. \]

Therefore, as the detection process (algorithm and input parameters) becomes more accurate, or \( U_i \to 0 \), the Sky value will tend to the background value or \( S_i \to B_i \). Hence, we see that while \( B_i \) is an inherent property of the data (pixel in an image), \( S_i \) depends on the detection process. Over a group of pixels, for example in an image or part of an image, this equation translates to the average of undetected pixels (Sky= \( \sum S_i \)). With this definition of Sky, the object flux in the data can be calculated, per pixel, with

\[ T_i = S_i + O_i \quad \rightarrow \quad O_i = T_i - S_i. \]

In the fainter outskirts of an object, a very small fraction of the photo-electrons in a pixel actually belongs to objects, the rest is caused by random factors (noise), see Figure 1b in Akhlaghi and Ichikawa (2015) (https://arxiv.org/abs/1505.01664). Therefore even a small over estimation of the Sky value will result in the loss of a very large portion of most galaxies. Besides the lost area/brightness, this will also cause an over-estimation of the Sky value and thus even more under-estimation of the object’s brightness. It is thus very important to detect the diffuse flux of a target, even if they are not your primary target.

In summary, the more accurately the Sky is measured, the more accurately the brightness (sum of pixel values) of the target object can be measured (photometry). Any under/over-estimation in the Sky will directly translate to an over/under-estimation of the measured object’s brightness.

The **Sky value** is only correctly found when all the detected objects \( (D_i \text{ and } C_i) \) have been removed from the data.

### 7.1.4.2 Sky value misconceptions

As defined in Section 7.1.4 [Sky value], page 252, the sky value is only accurately defined when the detection algorithm is not significantly reliant on the sky value. In particular its detection threshold. However, most signal-based detection tools\(^4\) use the sky value as a reference to define the detection threshold. These older techniques therefore had to rely on approximations based on other assumptions about the data. A review of those other techniques can be seen in Appendix A of Akhlaghi and Ichikawa (2015) (https://arxiv.org/abs/1505.01664).

These methods were extensively used in astronomical data analysis for several decades, therefore they have given rise to a lot of misconceptions, ambiguities and disagreements about the sky value and how to measure it. As a summary, the major methods used until now were an approximation of the mode of the image pixel distribution and \( \sigma \)-clipping.

\(^4\) According to Akhlaghi and Ichikawa (2015), signal-based detection is a detection process that relies heavily on assumptions about the to-be-detected objects. This method was the most heavily used technique prior to the introduction of NoiseChisel in that paper.
• To find the mode of a distribution those methods would either have to assume (or find) a certain probability density function (PDF) or use the histogram. But astronomical datasets can have any distribution, making it almost impossible to define a generic function. Also, histogram-based results are very inaccurate (there is a large dispersion) and it depends on the histogram bin-widths. Generally, the mode of a distribution also shifts as signal is added. Therefore, even if it is accurately measured, the mode is a biased measure for the Sky value.

• Another approach was to iteratively clip the brightest pixels in the image (which is known as $\sigma$-clipping). See Section 7.1.3 [Sigma clipping], page 251, for a complete explanation. $\sigma$-clipping is useful when there are clear outliers (an object with a sharp edge in an image for example). However, real astronomical objects have diffuse and faint wings that penetrate deeply into the noise, see Figure 1 in Akhlaghi and Ichikawa (2015) (https://arxiv.org/abs/1505.01664).

As discussed in Section 7.1.4 [Sky value], page 252, the sky value can only be correctly defined as the average of undetected pixels. Therefore all such approaches that try to approximate the sky value prior to detection are ultimately poor approximations.

### 7.1.4.3 Quantifying signal in a tile

Put simply, noise can be characterized with a certain spread about the measured value. In the Gaussian distribution (most commonly used to model noise) the spread is defined by the standard deviation about the characteristic mean.

Let’s start by clarifying some definitions first: *Data* is defined as the combination of signal and noise (so a noisy image is one dataset). *Signal* is defined as the mean of the noise on each element. We’ll also assume that the background (see Section 7.1.4.1 [Sky value definition], page 253) is subtracted and is zero.

When a data set doesn’t have any signal (only noise), the mean, median and mode of the distribution are equal within statistical errors and approximately equal to the background value. Signal always has a positive value and will never become negative, see Figure 1 in Akhlaghi and Ichikawa (2015) (https://arxiv.org/abs/1505.01664). Therefore, as more signal is added, the mean, median and mode of the dataset shift to the positive. The mean’s shift is the largest. The median shifts less, since it is defined based on an ordered distribution and so is not affected by a small number of outliers. The distribution’s mode shifts the least to the positive.

Inverting the argument above gives us a robust method to quantify the significance of signal in a dataset. Namely, when the mean and median of a distribution are approximately equal, or the mean’s quantile is around 0.5, we can argue that there is no significant signal.

To allow for gradients (which are commonly present in ground-based images), we can consider the image to be made of a grid of tiles (see Section 4.9 [Tessellation], page 141). Hence, from the difference of the mean and median on each tile, we can estimate the significance of signal in it. The median of a distribution is defined to be the value of the distribution’s middle point after sorting (or 0.5 quantile). Thus, to estimate the presence of signal, we’ll compare with the quantile of the mean with 0.5. If the absolute difference in a tile is larger than the value given to the --meanmedqdiff option, that tile will be ignored. You can read this option as “mean-median-quantile-difference”.

---

5 The options to customize the tessellation are discussed in Section 4.1.2.2 [Processing options], page 112.
The raw dataset’s distribution is noisy, so using the argument above on the raw input will give a noisy result. To decrease the noise/error in estimating the mode, we will use convolution (see Section 6.3.1.1 [Convolution process], page 217). Convolution decreases the range of the dataset and enhances its skewness, See Section 3.1.1 and Figure 4 in Akhlaghi and Ichikawa (2015) (https://arxiv.org/abs/1505.01664). This enhanced skewness can be interpreted as an increase in the Signal to noise ratio of the objects buried in the noise. Therefore, to obtain an even better measure of the presence of signal in a tile, the mean and median discussed above are measured on the convolved image.

Through the difference of the mean and median we have actually ‘detected’ data in the distribution. However this “detection” was only based on the total distribution of the data in each tile (a much lower resolution). This is the main limitation of this technique. The best approach is thus to do detection over the dataset, mask all the detected pixels and use the undetected regions to estimate the sky and its standard deviation (possibly over a tessellation). This is how NoiseChisel works: it uses the argument above to find tiles that are used to find its thresholds. Several higher-level steps are done on the thresholded pixels to define the higher-level detections (see Section 7.2 [NoiseChisel], page 269).

There is one final hurdle: raw astronomical datasets are commonly peppered with Cosmic rays. Images of Cosmic rays aren’t smoothed by the atmosphere or telescope aperture, so they have sharp boundaries. Also, since they don’t occupy too many pixels, they don’t affect the mode and median calculation. But their very high values can greatly bias the calculation of the mean (recall how the mean shifts the fastest in the presence of outliers), for example see Figure 15 in Akhlaghi and Ichikawa (2015) (https://arxiv.org/abs/1505.01664).

The effect of outliers like cosmic rays on the mean and standard deviation can be removed through $\sigma$-clipping, see Section 7.1.3 [Sigma clipping], page 251, for a complete explanation. Therefore, after asserting that the mode and median are approximately equal in a tile (see Section 4.9 [Tessellation], page 141), the final Sky value and its standard deviation are determined after $\sigma$-clipping with the --sigmaclip option.

In the end, some of the tiles will pass the mean and median quantile difference test. However, prior to interpolating over the failed tiles, another point should be considered: large and extended galaxies, or bright stars, have wings which sink into the noise very gradually. In some cases, the gradient over these wings can be on scales that is larger than the tiles. The mean-median distance test will pass on such tiles and will cause a strong peak in the interpolated tile grid, see Section 2.3 [Detecting large extended targets], page 61.

The tiles that exist over the wings of large galaxies or bright stars are outliers in the distribution of tiles that passed the mean-median quantile distance test. Therefore, the final step of “quantifying signal in a tile” is to look at this distribution and remove the outliers. $\sigma$-clipping is a good solution for removing a few outliers, but the problem with outliers of this kind is that there may be many such tiles (depending on the large/bright stars/galaxies in the image). Therefore a novel outlier rejection algorithm will be used.

To identify the first outlier, we’ll use the distribution of distances between sorted elements. If there are $N$ successful tiles, for every tile, the distance between the adjacent $N/2$ previous elements is found, giving a distribution containing $N/2 − 1$ points. The $\sigma$-clipped median and standard deviation of this distribution is then found ($\sigma$-clipping is configured with --outliersclip). Finally, if the distance between the element and its previous element is more than --outlierssigma multiples of the $\sigma$-clipped standard deviation added
with the $\sigma$-clipped median, that element is considered an outlier and all tiles larger than that value are ignored.

Formally, if we assume there are $N$ elements. They are first sorted. Searching for the outlier starts on element $N/2$ (integer division). Let’s take $v_i$ to be the $i$-th element of the sorted input (with no blank values) and $m$ and $\sigma$ as the $\sigma$-clipped median and standard deviation from the distances of the previous $N/2 - 1$ elements (not including $v_i$). If the value given to --outliersigma is displayed with $s$, the $i$-th element is considered as an outlier when the condition below is true.

$$\frac{(v_i - v_{i-1}) - m}{\sigma} > s$$

Since $i$ begins from the median, the outlier has to be larger than the median. You can use the check images (for example --checksky in the Statistics program or --checkqthresh, --checkdetsky and --checksky options in NoiseChisel for any of its steps that uses this outlier rejection) to inspect the steps and see which tiles have been discarded as outliers prior to interpolation.

### 7.1.5 Invoking Statistics

Statistics will print statistical measures of an input dataset (table column or image). The executable name is `aststatistics` with the following general template

```
$ aststatistics [OPTION ...] InputImage.fits
```

One line examples:

```bash
## Print some general statistics of input image:
$ aststatistics image.fits

## Print some general statistics of column named MAG_F160W:
$ aststatistics catalog.fits -h1 --column=MAG_F160W

## Make the histogram of the column named MAG_F160W:
$ aststatistics table.fits -cMAG_F160W --histogram

## Find the Sky value on image with a given kernel:
$ aststatistics image.fits --sky --kernel=kernel.fits

## Print Sigma-clipped results of records with a MAG_F160W
## column value between 26 and 27:
$ aststatistics cat.fits -cMAG_F160W -g26 -l27 --sigmaclip=3,0.2

## Print the median value of all records in column MAG_F160W that
## have a value larger than 3 in column PHOTO_Z:
$ aststatistics tab.txt -rPHOTO_Z -g3 -cMAG_F160W --median

## Calculate the median of the third column in the input table, but only
## for rows where the mean of the first and second columns is >5.
$ awk '($1+$2)/2 > 5 {print $3}' table.txt | aststatistics --median
```
Statistics can take its input dataset either from a file (image or table) or the Standard input (see Section 4.1.3 [Standard input], page 118). If any output file is to be created, the value to the --output option, is used as the base name for the generated files. Without --output, the input name will be used to generate an output name, see Section 4.10 [Automatic output], page 142. The options described below are particular to Statistics, but for general operations, it shares a large collection of options with the other Gnuastro programs, see Section 4.1.2 [Common options], page 109, for the full list. For more on reading from standard input, please see the description of --stdintimeout option in Section 4.1.2.1 [Input/Output options], page 109. Options can also be given in configuration files, for more, please see Section 4.2 [Configuration files], page 120.

The input dataset may have blank values (see Section 6.1.3 [Blank pixels], page 191), in this case, all blank pixels are ignored during the calculation. Initially, the full dataset will be read, but it is possible to select a specific range of data elements to use in the analysis of each run. You can either directly specify a minimum and maximum value for the range of data elements to use (with --greaterequal or --lessthan), or specify the range using quantiles (with --qrange). If a range is specified, all pixels outside of it are ignored before any processing.

The following set of options are for specifying the input/outputs of Statistics. There are many other input/output options that are common to all Gnuastro programs including Statistics, see Section 4.1.2.1 [Input/Output options], page 109, for those.

-c STR/INT
--column=STR/INT
The column to use when the input file is a table with more than one column. See Section 4.8.3 [Selecting table columns], page 140, for a full description of how to use this option. For more on how tables are read in Gnuastro, please see Section 4.8 [Tables], page 135.

-r STR/INT
--refcol=STR/INT
The reference column selector when the input file is a table. When a reference column is given, the range options below will be applied to this column and only elements in the input column that have a reference value in the correct range will be used. In practice this option allows you to select a subset of the input column based on values in another (the reference) column. All the statistical calculations will be done on the selected input column, not the reference column.

-g FLT
--greaterequal=FLT
Limit the range of inputs into those with values greater and equal to what is given to this option. None of the values below this value will be used in any of the processing steps below.

-l FLT
--lessthan=FLT
Limit the range of inputs into those with values less-than what is given to this option. None of the values greater or equal to this value will be used in any of the processing steps below.
Specify the range of usable inputs using the quantile. This option can take one or two quantiles to specify the range. When only one number is input (let’s call it $Q$), the range will be those values in the quantile range $Q$ to $1 - Q$. So when only one value is given, it must be less than 0.5. When two values are given, the first is used as the lower quantile range and the second is used as the larger quantile range.

The quantile of a given element in a dataset is defined by the fraction of its index to the total number of values in the sorted input array. So the smallest and largest values in the dataset have a quantile of 0.0 and 1.0. The quantile is a very useful non-parametric (making no assumptions about the input) relative measure to specify a range. It can best be understood in terms of the cumulative frequency plot, see Section 7.1.1 [Histogram and Cumulative Frequency Plot], page 248. The quantile of each horizontal axis value in the cumulative frequency plot is the vertical axis value associate with it.

When no operation is requested, Statistics will print some general basic properties of the input dataset on the command-line like the example below (ran on one of the output images of make check\(^6\)). This default behavior is designed to help give you a general feeling of how the data are distributed and help in narrowing down your analysis.

```
$ aststatistics convolve_spatial_scaled_noised.fits --greaterequal=9500 --lessthan=11000
```

```
Statistics (GNU Astronomy Utilities) X.X
-------
Input: convolve_spatial_scaled_noised.fits (hdu: 0)
Range: from (inclusive) 9500, upto (exclusive) 11000.
Unit: Brightness
-------
Number of elements: 9074
Minimum: 9622.35
Maximum: 10999.7
Mode: 10055.45996
Mode quantile: 0.4001983908
Median: 10093.7
Mean: 10143.98257
Standard deviation: 221.80834
-------
Histogram:
| **
| *****
| *****
| ********
|
```

\(^6\) You can try it by running the command in the tests directory, open the image with a FITS viewer and have a look at it to get a sense of how these statistics relate to the input image/dataset.
Gnuastro’s Statistics is a very general purpose program, so to be able to easily understand this diversity in its operations (and how to possibly run them together), we’ll divided the operations into two types: those that don’t respect the position of the elements and those that do (by tessellating the input on a tile grid, see Section 4.9 [Tessellation], page 141). The former treat the whole dataset as one and can re-arrange all the elements (for example sort them), but the former do their processing on each tile independently. First, we’ll review the operations that work on the whole dataset.

The group of options below can be used to get single value measurement(s) of the whole dataset. They will print only the requested value as one field in a line/row, like the --mean, --median options. These options can be called any number of times and in any order. The outputs of all such options will be printed on one line following each other (with a space character between them). This feature makes these options very useful in scripts, or to redirect into programs like GNU AWK for higher-level processing. These are some of the most basic measures, Gnuastro is still under heavy development and this list will grow. If you want another statistical parameter, please contact us and we will do our best to add it to this list, see Section 1.8 [Suggest new feature], page 12.

-n
--number Print the number of all used (non-blank and in range) elements.

--minimum
Print the minimum value of all used elements.

--maximum
Print the maximum value of all used elements.

--sum
Print the sum of all used elements.

-m
--mean
Print the mean (average) of all used elements.

-t
--std
Print the standard deviation of all used elements.

-E
--median
Print the median of all used elements.

-u FLT[,FLT[,...]]
--quantile=FLT[,FLT[,...]]
Print the values at the given quantiles of the input dataset. Any number of quantiles may be given and one number will be printed for each. Values can either be written as a single number or as fractions, but must be between zero and one (inclusive). Hence, in effect --quantile=0.25 --quantile=0.75 is equivalent to --quantile=0.25,3/4, or -u1/4,3/4.
The returned value is one of the elements from the dataset. Taking \( q \) to be your desired quantile, and \( N \) to be the total number of used (non-blank and within the given range) elements, the returned value is at the following position in the sorted array: \( \text{round}(q \times N) \).

\[ \text{--quantfunc=FLT[,FLT[,...]]} \]
Print the quantiles of the given values in the dataset. This option is the inverse of the \text{--quantile} and operates similarly except that the acceptable values are within the range of the dataset, not between 0 and 1. Formally it is known as the “Quantile function”.
Since the dataset is not continuous this function will find the nearest element of the dataset and use its position to estimate the quantile function.

\[ \text{--mode} \]
Print the mode of all used elements. The mode is found through the mirror distribution which is fully described in Appendix C of Akhlaghi and Ichikawa 2015 (https://arxiv.org/abs/1505.01664). See that section for a full description. This mode calculation algorithm is non-parametric, so when the dataset is not large enough (larger than about 1000 elements usually), or doesn’t have a clear mode it can fail. In such cases, this option will return a value of \text{nan} (for the floating point NaN value).
As described in that paper, the easiest way to assess the quality of this mode calculation method is to use it’s symmetricity (see \text{--modesym} below). A better way would be to use the \text{--mirror} option to generate the histogram and cumulative frequency tables for any given mirror value (the mode in this case) as a table. If you generate plots like those shown in Figure 21 of that paper, then your mode is accurate.

\[ \text{--modequant} \]
Print the quantile of the mode. You can get the actual mode value from the \text{--mode} described above. In many cases, the absolute value of the mode is irrelevant, but its position within the distribution is important. In such cases, this option will become handy.

\[ \text{--modesym} \]
Print the symmetricity of the calculated mode. See the description of \text{--mode} for more. This mode algorithm finds the mode based on how symmetric it is, so if the symmetricity returned by this option is too low, the mode is not too accurate. See Appendix C of Akhlaghi and Ichikawa 2015 (https://arxiv.org/abs/1505.01664) for a full description. In practice, symmetricity values larger than 0.2 are mostly good.

\[ \text{--modesymvalue} \]
Print the value in the distribution where the mirror and input distributions are no longer symmetric, see \text{--mode} and Appendix C of Akhlaghi and Ichikawa 2015 (https://arxiv.org/abs/1505.01664) for more.

\[ \text{--sigclip-number} \]
Number of elements after applying \( \sigma \)-clipping (see Section 7.1.3 [Sigma clipping], page 251). \( \sigma \)-clipping configuration is done with the \text{--sigclippars} option.
--sigclip-median
Median after applying $\sigma$-clipping (see Section 7.1.3 [Sigma clipping], page 251). $\sigma$-clipping configuration is done with the --sigclipparams option.

Here is one scenario where this can be useful: assume you have a table and you would like to remove the rows that are outliers (not within the $\sigma$-clipping range). Let’s assume your table is called table.fits and you only want to keep the rows that have a value in COLUMN within the $\sigma$-clipped range (to $3\sigma$, with a tolerance of 0.1). This command will return the $\sigma$-clipped median and standard deviation (used to define the range later).

```
$ aststatistics table.fits -cCOLUMN --sclipparams=3,0.1
   --sigclip-median --sigclip-std
```

You can then use the --range option of Table (see Section 5.4 [Table], page 171) to select the proper rows. But for that, you need the actual starting and ending values of the range ($m \pm s\sigma$; where $m$ is the median and $s$ is the multiple of sigma to define an outlier). Therefore, the raw outputs of Statistics in the command above aren’t enough.

To get the starting and ending values of the non-outlier range (and put a ‘,’ between them, ready to be used in --range), pipe the result into AWK. But in AWK, we’ll also need the multiple of $\sigma$, so we’ll define it as a shell variable ($s$) before calling Statistics (note how $s$ is used two times now):

```
$ s=3
$ aststatistics table.fits -cCOLUMN --sclipparams=$s,0.1
   --sigclip-median --sigclip-std
   | awk '{s='$s'; printf("%f,%f\n", $1-s*$2, $1+s*$2)}'
```

To pass it onto Table, we’ll need to keep the printed output from the command above in another shell variable ($r$), not print it. In Bash, can do this by putting the whole statement within a $()$:

```
$ s=3
$ r=$(aststatistics table.fits -cCOLUMN --sclipparams=$s,0.1
   --sigclip-median --sigclip-std
   | awk '{s='$s'; printf("%f,%f\n", $1-s*$2, $1+s*$2)}')
$ echo $r # Just to confirm.
```

Now you can use Table with the --range option to only print the rows that have a value in COLUMN within the desired range:

```
$ asttable table.fits --range=COLUMN,$r
```

To save the resulting table (that is clean of outliers) in another file (for example named cleaned.fits, it can also have a .txt suffix), just add --output=cleaned.fits to the command above.

--sigclip-mean
Mean after applying $\sigma$-clipping (see Section 7.1.3 [Sigma clipping], page 251). $\sigma$-clipping configuration is done with the --sigclipparams option.

--sigclip-std
Standard deviation after applying $\sigma$-clipping (see Section 7.1.3 [Sigma clipping], page 251). $\sigma$-clipping configuration is done with the --sigclipparams option.
The list of options below are for those statistical operations that output more than one value. So while they can be called together in one run, their outputs will be distinct (each one’s output will usually be printed in more than one line).

-A
--asciistat

Print an ASCII histogram of the usable values within the input dataset along with some basic information like the example below (from the UVUDF catalog7). The width and height of the histogram (in units of character widths and heights on your command-line terminal) can be set with the --numasciibins (for the width) and --asciiheight options.

For a full description of the histogram, please see Section 7.1.1 [Histogram and Cumulative Frequency Plot], page 248. An ASCII plot is certainly very crude and cannot be used in any publication, but it is very useful for getting a general feeling of the input dataset very fast and easily on the command-line without having to take your hands off the keyboard (which is a major distraction!). If you want to try it out, you can write it all in one line and ignore the \ and extra spaces.

$ aststatistics uvudf_rafelski_2015.fits.gz --hdu=1 --column=MAG_F160W --lessthan=40 --asciistat --numasciibins=55

ASCII Histogram:
Number: 8593
Y: (linear: 0 to 660)
X: (linear: 17.7735 -- 31.4679, in 55 bins)

---

--asciicfp

Print the cumulative frequency plot of the usable elements in the input dataset. Please see descriptions under --asciistat for more, the example below is from the same input table as that example. To better understand the cumulative frequency plot, please see Section 7.1.1 [Histogram and Cumulative Frequency Plot], page 248.

$ aststatistics uvudf_rafelski_2015.fits.gz --hdu=1 --column=MAG_F160W --lessthan=40

7 https://asd.gsfc.nasa.gov/UVUDF/uvudf_rafelski_2015.fits.gz
--asciicfp --numasciibins=55

ASCII Cumulative frequency plot:
Y: (linear: 0 to 8593)
X: (linear: 17.7735 -- 31.4679, in 55 bins)

---

-H
--histogram
Save the histogram of the usable values in the input dataset into a table. The first column is the value at the center of the bin and the second is the number of points in that bin. If the --cumulative option is also called with this option in a run, then the table will have three columns (the third is the cumulative frequency plot). Through the --numbins, --onebinstart, or --manualbinrange, you can modify the first column values and with --normalize and --maxbinone you can modify the second columns. See below for the description of each.

By default (when no --output is specified) a plain text table will be created, see Section 4.8.2 [Gnuastro text table format], page 137. If a FITS name is specified, you can use the common option --tableformat to have it as a FITS ASCII or FITS binary format, see Section 4.1.2 [Common options], page 109. This table can then be fed into your favorite plotting tool and get a much more clean and nice histogram than what the raw command-line can offer you (with the --asciihist option).

--histogram2d
Save the 2D histogram of two input columns into an output file, see Section 7.1.2 [2D Histograms], page 249. The output will have three columns: the first two are the coordinates of each box’s center in the first and second dimensions/columns. The third will be number of input points that fall within that box.

-C
--cumulative
Save the cumulative frequency plot of the usable values in the input dataset into a table, similar to --histogram.
--sigmaclip
Do $\sigma$-clipping on the usable pixels of the input dataset. See Section 7.1.3
[Sigma clipping], page 251, for a full description on $\sigma$-clipping and also to
better understand this option. The $\sigma$-clipping parameters can be set through
the --sclipparams option (see below).

--mirror=FLT
Make a histogram and cumulative frequency plot of the mirror distribution for
the given dataset when the mirror is located at the value to this option. The
mirror distribution is fully described in Appendix C of Akhlaghi and Ichikawa
2015 (https://arxiv.org/abs/1505.01664) and currently it is only used to
calculate the mode (see --mode).

Just note that the mirror distribution is a discrete distribution like the input,
so while you may give any number as the value to this option, the actual mirror
value is the closest number in the input dataset to this value. If the two numbers
are different, Statistics will warn you of the actual mirror value used.

This option will make a table as output. Depending on your selected name
for the output, it will be either a FITS table or a plain text table (which is
the default). It contains three columns: the first is the center of the bins,
the second is the histogram (with the largest value set to 1) and the third is
the normalized cumulative frequency plot of the mirror distribution. The bins
will be positioned such that the mode is on the starting interval of one of the
bins to make it symmetric around the mirror. With this output file and the
input histogram (that you can generate in another run of Statistics, using the
--onebinvalue), it is possible to make plots like Figure 21 of Akhlaghi and

The list of options below allow customization of the histogram and cumulative frequency
plots (for the --histogram, --cumulative, --asciihist, and --asciicfp options).

--numbins
The number of bins (rows) to use in the histogram and the cumulative frequency
plot tables (outputs of --histogram and --cumulative).

--numasciibins
The number of bins (characters) to use in the ASCII plots when printing the
histogram and the cumulative frequency plot (outputs of --asciihist and
--asciicfp).

--asciheight
The number of lines to use when printing the ASCII histogram and cumulative
frequency plot on the command-line (outputs of --asciihist and --asciicfp).

-n
--normalize
Normalize the histogram or cumulative frequency plot tables (outputs of
--histogram and --cumulative). For a histogram, the sum of all bins will
become one and for a cumulative frequency plot the last bin value will be one.
--maxbinone

Divide all the histogram values by the maximum bin value so it becomes one and the rest are similarly scaled. In some situations (for example if you want to plot the histogram and cumulative frequency plot in one plot) this can be very useful.

--onebinstart=FLT

Make sure that one bin starts with the value to this option. In practice, this will shift the bins used to find the histogram and cumulative frequency plot such that one bin’s lower interval becomes this value.

For example when a histogram range includes negative and positive values and zero has a special significance in your analysis, then zero might fall somewhere in one bin. As a result that bin will have counts of positive and negative.

By setting --onebinstart=0, you can make sure that one bin will only count negative values in the vicinity of zero and the next bin will only count positive ones in that vicinity.

Note that by default, the first row of the histogram and cumulative frequency plot show the central values of each bin. So in the example above you will not see the 0.000 in the first column, you will see two symmetric values.

If the value is not within the usable input range, this option will be ignored.

When it is, this option is the last operation before the bins are finalized, therefore it has a higher priority than options like --manualbinrange.

--manualbinrange

Use the values given to the --greaterequal and --lessthan to define the range of all bin-based calculations like the histogram. This option itself doesn’t take any value, but just tells the program to use the values of those two options instead of the minimum and maximum values of a plot. If any of the two options are not given, then the minimum or maximum will be used respectively. Therefore, if none of them are called calling this option is redundant.

The --onebinstart option has a higher priority than this option. In other words, --onebinstart takes effect after the range has been finalized and the initial bins have been defined, therefore it has the power to (possibly) shift the bins. If you want to manually set the range of the bins and have one bin on a special value, it is thus better to avoid --onebinstart.

--numbins2=INT

Similar to --numbins, but for the second column when a 2D histogram is requested, see --histogram2d.

--greaterequal2=FLT

Similar to --greaterequal, but for the second column when a 2D histogram is requested, see --histogram2d.

--lessthan2=FLT

Similar to --lessthan, but for the second column when a 2D histogram is requested, see --histogram2d.
--onebinstart2=FLT
Similar to --onebinstart, but for the second column when a 2D histogram is requested, see --histogram2d.

All the options described until now were from the first class of operations discussed above: those that treat the whole dataset as one. However, it often happens that the relative position of the dataset elements over the dataset is significant. For example you don’t want one median value for the whole input image, you want to know how the median changes over the image. For such operations, the input has to be tessellated (see Section 4.9 [Tessellation], page 141). Thus this class of options can’t currently be called along with the options above in one run of Statistics.

-t
--ontile Do the respective single-valued calculation over one tile of the input dataset, not the whole dataset. This option must be called with at least one of the single valued options discussed above (for example --mean or --quantile). The output will be a file in the same format as the input. If the --oneelempertile option is called, then one element/pixel will be used for each tile (see Section 4.1.2.2 [Processing options], page 112). Otherwise, the output will have the same size as the input, but each element will have the value corresponding to that tile’s value. If multiple single valued operations are called, then for each operation there will be one extension in the output FITS file.

-R FLT[,FLT[,FLT...]]
--contour=FLT[,FLT[,FLT...]]
Write the contours for the requested levels in a file ending with _contour.txt. It will have three columns: the first two are the coordinates of each point and the third is the level it belongs to (one of the input values). Each disconnected contour region will be separated by a blank line. This is the requested format for adding contours with PGFPLOTS in LATEX. If any other format can be useful for your work please let us know so we can add it. If the image has World Coordinate System information, the written coordinates will be in RA and Dec, otherwise, they will be in pixel coordinates.

Note that currently, this is a very crude/simple implementation, please let us know if you find problematic situations so we can fix it.

-y
--sky Estimate the Sky value on each tile as fully described in Section 7.1.4.3 [Quantifying signal in a tile], page 255. As described in that section, several options are necessary to configure the Sky estimation which are listed below. The output file will have two extensions: the first is the Sky value and the second is the Sky standard deviation on each tile. Similar to --ontile, if the --oneelempertile option is called, then one element/pixel will be used for each tile (see Section 4.1.2.2 [Processing options], page 112).

The parameters for estimating the sky value can be set with the following options, except for the --sclippars option (which is also used by the --sigmaclip), the rest are only used for the Sky value estimation.
-k=STR
--kernel=STR
File name of kernel to help in estimating the significance of signal in a tile, see Section 7.1.4.3 [Quantifying signal in a tile], page 255.

--khdu=STR
Kernel HDU to help in estimating the significance of signal in a tile, see Section 7.1.4.3 [Quantifying signal in a tile], page 255.

--meanmedqdiff=FLT
The maximum acceptable distance between the quantiles of the mean and median, see Section 7.1.4.3 [Quantifying signal in a tile], page 255. The initial Sky and its standard deviation estimates are measured on tiles where the quantiles of their mean and median are less distant than the value given to this option. For example --meanmedqdiff=0.01 means that only tiles where the mean’s quantile is between 0.49 and 0.51 (recall that the median’s quantile is 0.5) will be used.

--sclipparams=FLT,FLT
The $\sigma$-clipping parameters, see Section 7.1.3 [Sigma clipping], page 251. This option takes two values which are separated by a comma (,). Each value can either be written as a single number or as a fraction of two numbers (for example 3,1/10). The first value to this option is the multiple of $\sigma$ that will be clipped ($\alpha$ in that section). The second value is the exit criteria. If it is less than 1, then it is interpreted as tolerance and if it is larger than one it is a specific number. Hence, in the latter case the value must be an integer.

--outliersclip=FLT,FLT
$\sigma$-clipping parameters for the outlier rejection of the Sky value (similar to --sclipparams).
Outlier rejection is useful when the dataset contains a large and diffuse (almost flat within each tile) signal. The flatness of the profile will cause it to successfully pass the mean-median quantile difference test, so we’ll need to use the distribution of successful tiles for removing these false positive. For more, see the latter half of Section 7.1.4.3 [Quantifying signal in a tile], page 255.

--outliersigma=FLT
Multiple of sigma to define an outlier in the Sky value estimation. If this option is given a value of zero, no outlier rejection will take place. For more see --outliersclip and the latter half of Section 7.1.4.3 [Quantifying signal in a tile], page 255.

--smoothwidth=INT
Width of a flat kernel to convolve the interpolated tile values. Tile interpolation is done using the median of the --interpnumngb neighbors of each tile (see Section 4.1.2.2 [Processing options], page 112). If this option is given a value of zero or one, no smoothing will be done. Without smoothing, strong boundaries will probably be created between the values estimated for each tile. It is thus good to smooth the interpolated image so strong discontinuities do not show up in the final Sky values. The smoothing is done through convolution (see
Section 6.3.1.1 [Convolution process], page 217) with a flat kernel, so the value
to this option must be an odd number.

--ignoreblankintiles
Don’t set the input’s blank pixels to blank in the tiled outputs (for example Sky
and Sky standard deviation extensions of the output). This is only applicable
when the tiled output has the same size as the input, in other words, when
--oneelempertile isn’t called.

By default, blank values in the input (commonly on the edges which are outside
the survey/field area) will be set to blank in the tiled outputs also. But in other
scenarios this default behavior is not desired: for example if you have masked
something in the input, but want the tiled output under that also.

--checksky
Create a multi-extension FITS file showing the steps that were used to estimate
the Sky value over the input, see Section 7.1.4.3 [Quantifying signal in a tile],
page 255. The file will have two extensions for each step (one for the Sky and
one for the Sky standard deviation).

7.2 NoiseChisel

Once instrumental signatures are removed from the raw data (image) in the initial reduc-
tion process (see Chapter 6 [Data manipulation], page 188). You are naturally eager to
start answering the scientific questions that motivated the data collection in the first place.
However, the raw dataset/image is just an array of values/pixels, that is all! These raw
values cannot directly be used to answer your scientific questions: for example “how many
galaxies are there in the image?”.

The first high-level step in the analysis of your dataset will thus be to classify, or label,
the dataset elements (pixels) into two classes: 1) Noise, where random effects are the major
contributor to the value, and 2) Signal, where non-random factors (for example light from
a distant galaxy) are present. This classification of the elements in a dataset is formally
known as detection.

In an observational/experimental dataset, signal is always buried in noise: only
mock/simulated datasets are free of noise. Therefore detection, or the process of separating
signal from noise, determines the number of objects you study and the accuracy of
any higher-level measurement you do on them. Detection is thus the most important
step of any analysis and is not trivial. In particular, the most scientifically interesting
astronomical targets are faint, can have a large variety of morphologies, along with a large
distribution in brightness and size. Therefore when noise is significant, proper detection of
your targets is a uniquely decisive step in your final scientific analysis/result.

NoiseChisel is Gnuastro’s program for detection of targets that don’t have a sharp border
(almost all astronomical objects). When the targets have sharp edges/borders (for example
cells in biological imaging), a simple threshold is enough to separate them from noise and
each other (if they are not touching). To detect such sharp-edged targets, you can use
Gnuastro’s Arithmetic program in a command like below (assuming the threshold is 100,
see Section 6.2 [Arithmetic], page 199):

$ astarithmetic in.fits 100 gt 2 connected-components
Since almost no astronomical target has such sharp edges, we need a more advanced
detection methodology. NoiseChisel uses a new noise-based paradigm for detection of very
extended and diffuse targets that are drowned deeply in the ocean of noise. It was initially
introduced in Akhlaghi and Ichikawa [2015] (https://arxiv.org/abs/1505.01664) and
improvements after the first four were published in Akhlaghi [2019] (https://arxiv.org/
abs/1909.11230). Please take the time to go through these papers to most effectively use
NoiseChisel.

The name of NoiseChisel is derived from the first thing it does after thresholding the
dataset: to erode it. In mathematical morphology, erosion on pixels can be pictured as
carving-off boundary pixels. Hence, what NoiseChisel does is similar to what a wood chisel
or stone chisel do. It is just not a hardware, but a software. In fact, looking at it as a
chisel and your dataset as a solid cube of rock will greatly help in effectively understanding
and optimally using it: with NoiseChisel you literally carve your targets out of the noise.
Try running it with the --checkdetection option, and open the temporary output as a
multi-extension cube, to see each step of the carving process on your input dataset (see
Section B.1.1 [Viewing multiextension FITS images], page 540).

NoiseChisel’s primary output is a binary detection map with the same size as the input
but its pixels only have two values: 0 (background) and 1 (foreground). Pixels that don’t
harbor any detected signal (noise) are given a label (or value) of zero and those with a value
of 1 have been identified as hosting signal.

Segmentation is the process of classifying the signal into higher-level constructs. For
example if you have two separate galaxies in one image, NoiseChisel will give a value of
1 to the pixels of both (each forming an “island” of touching foreground pixels). After
segmentation, the connected foreground pixels will get separate labels, enabling you to study
them individually. NoiseChisel is only focused on detection (separating signal from noise), to
segment the signal (into separate galaxies for example), Gnuastro has a separate specialized
program Section 7.3 [Segment], page 284. NoiseChisel’s output can be directly/readily fed
into Segment.

For more on NoiseChisel’s output format and its benefits (especially in conjunction with
Section 7.3 [Segment], page 284, and later Section 7.4 [MakeCatalog], page 295), please see
was published, Segment was not yet spun-off into a separate program, and NoiseChisel done
both detection and segmentation.

NoiseChisel’s output is designed to be generic enough to be easily used in any higher-
level analysis. If your targets are not touching after running NoiseChisel and you aren’t
interested in their sub-structure, you don’t need the Segment program at all. You can ask
NoiseChisel to find the connected pixels in the output with the --label option. In this
case, the output won’t be a binary image any more, the signal will have counters/labels
starting from 1 for each connected group of pixels. You can then directly feed NoiseChisel’s
output into MakeCatalog for measurements over the detections and the production of a
catalog (see Section 7.4 [MakeCatalog], page 295).

Thanks to the published papers mentioned above, there is no need to provide a more
complete introduction to NoiseChisel in this book. In Section 7.2.1 [Invoking NoiseChisel],
page 271, the details of running NoiseChisel and its options are discussed.
As discussed above, detection is one of the most important steps for your scientific result. It is therefore very important to obtain a good understanding of NoiseChisel (and afterwards Section 7.3 [Segment], page 284, and Section 7.4 [MakeCatalog], page 295). We strongly recommend reviewing two tutorials of Section 2.2 [General program usage tutorial], page 24, and Section 2.3 [Detecting large extended targets], page 61. They are designed to show how to most effectively use NoiseChisel for the detection of small faint objects and large extended objects. In the meantime, they also show the modular principle behind Gnuastro’s programs and how they are built to complement, and build upon, each other.

Section 2.2 [General program usage tutorial], page 24, culminates in using NoiseChisel to detect galaxies and use its outputs to find the galaxy colors. Defining colors is a very common process in most science-cases. Therefore it is also recommended to (patiently) complete that tutorial for optimal usage of NoiseChisel in conjunction with all the other Gnuastro programs. Section 2.3 [Detecting large extended targets], page 61, shows you can optimize NoiseChisel’s settings for very extended objects to successfully carve out to signal-to-noise ratio levels of below 1/10. After going through those tutorials, play a little with the settings (in the order presented in the paper and Section 7.2.1 [Invoking NoiseChisel], page 271) on a dataset you are familiar with and inspect all the check images (options starting with `--check`) to see the effect of each parameter.

Below, in Section 7.2.1 [Invoking NoiseChisel], page 271, we will review NoiseChisel’s input, detection, and output options in Section 7.2.1.1 [NoiseChisel input], page 273, Section 7.2.1.2 [Detection options], page 275, and Section 7.2.1.3 [NoiseChisel output], page 282. If you have used NoiseChisel within your research, please run it with `--cite` to list the papers you should cite and how to acknowledge its funding sources.

### 7.2.1 Invoking NoiseChisel

NoiseChisel will detect signal in noise producing a multi-extension dataset containing a binary detection map which is the same size as the input. Its output can be readily used for input into Section 7.3 [Segment], page 284, for higher-level segmentation, or Section 7.4 [MakeCatalog], page 295, to do measurements and generate a catalog. The executable name is `astnoisechisel` with the following general template

```
$ astnoisechisel [OPTION ...] InputImage.fits
```

One line examples:

```
## Detect signal in `input.fits`.
$ astnoisechisel input.fits

## Inspect all the detection steps after changing a parameter.
$ astnoisechisel input.fits --qthresh=0.4 --checkdetection

## Detect signal assuming input has 4 amplifier channels along first
## dimension and 1 along the second. Also set the regular tile size
## to 100 along both dimensions:
$ astnoisechisel --numchannels=4,1 --tilesize=100,100 input.fits
```

If NoiseChisel is to do processing (for example you don’t want to get help, or see the values to each input parameter), an input image should be provided with the recognized extensions (see Section 4.1.1.1 [Arguments], page 107). NoiseChisel shares a large set of
common operations with other Gnuastro programs, mainly regarding input/output, general processing steps, and general operating modes. To help in a unified experience between all of Gnuastro’s programs, these operations have the same command-line options, see Section 4.1.2 [Common options], page 109, for a full list/description (they are not repeated here).

As in all Gnuastro programs, options can also be given to NoiseChisel in configuration files. For a thorough description on Gnuastro’s configuration file parsing, please see Section 4.2 [Configuration files], page 120. All of NoiseChisel’s options with a short description are also always available on the command-line with the --help option, see Section 4.3 [Getting help], page 123. To inspect the option values without actually running NoiseChisel, append your command with --printparams (or -P).

NoiseChisel’s input image may contain blank elements (see Section 6.1.3 [Blank pixels], page 191). Blank elements will be ignored in all steps of NoiseChisel. Hence if your dataset has bad pixels which should be masked with a mask image, please use Gnuastro’s Section 6.2 [Arithmetic], page 199, program (in particular its where operator) to convert those pixels to blank pixels before running NoiseChisel. Gnuastro’s Arithmetic program has bitwise operators helping you select specific kinds of bad-pixels when necessary.

A convolution kernel can also be optionally given. If a value (file name) is given to --kernel on the command-line or in a configuration file (see Section 4.2 [Configuration files], page 120), then that file will be used to convolve the image prior to thresholding. Otherwise a default kernel will be used. The default kernel is a 2D Gaussian with a FWHM of 2 pixels truncated at 5 times the FWHM. This choice of the default kernel is discussed in Section 3.1.1 of Akhlaghi and Ichikawa [2015] (https://arxiv.org/abs/1505.01664). See Section 6.3.4 [Convolution kernel], page 235, for kernel related options. Passing none to --kernel will disable convolution. On the other hand, through the --convolved option, you may provide an already convolved image, see descriptions below for more.

NoiseChisel defines two tessellations over the input (see Section 4.9 [Tessellation], page 141). This enables it to deal with possible gradients in the input dataset and also significantly improve speed by processing each tile on different threads simultaneously. Tessellation related options are discussed in Section 4.1.2.2 [Processing options], page 112. In particular, NoiseChisel uses two tessellations (with everything between them identical except the tile sizes): a fine-grained one with smaller tiles (used in thresholding and Sky value estimations) and another with larger tiles which is used for pseudo-detections over non-detected regions of the image. The common Tessellation options described in Section 4.1.2.2 [Processing options], page 112, define all parameters of both tessellations. The large tile size for the latter tessellation is set through the --largetilesize option. To inspect the tessellations on your input dataset, run NoiseChisel with --checktiles.

Usage TIP: Frequently use the options starting with --check. Since the noise properties differ between different datasets, you can often play with the parameters/options for a better result than the default parameters. You can start with --checkdetection for the main steps. For the full list of NoiseChisel’s checking options please run:

```
$ astnoisechisel --help | grep check
```

Below, we’ll discuss NoiseChisel’s options, classified into two general classes, to help in easy navigation. Section 7.2.1.1 [NoiseChisel input], page 273, mainly discusses the
basic options relating to inputs and prior to the detection process detection. Afterwards, Section 7.2.1.2 [Detection options], page 275, fully describes every configuration parameter (option) related to detection and how they affect the final result. The order of options in this section follow the logical order within NoiseChisel. On first reading (while you are still new to NoiseChisel), it is therefore strongly recommended to read the options in the given order below. The output of \texttt{--printparams} (or \texttt{-P}) also has this order. However, the output of \texttt{--help} is sorted alphabetically. Finally, in Section 7.2.1.3 [NoiseChisel output], page 282, the format of NoiseChisel’s output is discussed.

7.2.1.1 NoiseChisel input

The options here can be used to configure the inputs and output of NoiseChisel, along with some general processing options. Recall that you can always see the full list of Gnuastro’s options with the \texttt{--help} (see Section 4.3 [Getting help], page 123), or \texttt{--printparams} (or \texttt{-P}) to see their values (see Section 4.1.2.3 [Operating mode options], page 114).

\texttt{-k STR}  \texttt{--kernel=STR}

File name of kernel to smooth the image before applying the threshold, see Section 6.3.4 [Convolution kernel], page 235. If no convolution is needed, give this option a value of \texttt{none}. The first step of NoiseChisel is to convolve/smooth the image and use the convolved image in multiple steps including the finding and applying of the quantile threshold (see \texttt{--qthresh}).

The \texttt{--kernel} option is not mandatory. If not called, a 2D Gaussian profile with a FWHM of 2 pixels truncated at 5 times the FWHM is used. This choice of the default kernel is discussed in Section 3.1.1 of Akhlaghi and Ichikawa [2015]. You can use MakeProfiles to build a kernel with any of its recognized profile types and parameters. For more details, please see Section 8.1.5.3 [MakeProfiles output dataset], page 348. For example, the command below will make a Moffat kernel (with $\beta = 2.8$) with FWHM of 2 pixels truncated at 10 times the FWHM.

\begin{verbatim}
$ astmkprof --oversample=1 --kernel=moffat,2,2.8,10
\end{verbatim}

Since convolution can be the slowest step of NoiseChisel, for large datasets, you can convolve the image once with Gnuastro’s Convolve (see Section 6.3 [Convolve], page 216), and use the \texttt{--convolved} option to feed it directly to NoiseChisel. This can help getting faster results when you are playing/testing the higher-level options.

\texttt{--khdu=STR}

HDU containing the kernel in the file given to the \texttt{--kernel} option.

\texttt{--convolved=STR}

Use this file as the convolved image and don’t do convolution (ignore \texttt{--kernel}). NoiseChisel will just check the size of the given dataset is the same as the input’s size. If a wrong image (with the same size) is given to this option, the results (errors, bugs, etc) are unpredictable. So please use this option with care and in a highly controlled environment, for example in the scenario discussed below.

In almost all situations, as the input gets larger, the single most CPU (and time) consuming step in NoiseChisel (and other programs that need a con-
volved image) is convolution. Therefore minimizing the number of convolutions can save a significant amount of time in some scenarios. One such scenario is when you want to segment NoiseChisel’s detections using the same kernel (with Section 7.3 [Segment], page 284, which also supports this --convolve option). This scenario would require two convolutions of the same dataset: once by NoiseChisel and once by Segment. Using this option in both programs, only one convolution (prior to running NoiseChisel) is enough.

Another common scenario where this option can be convenient is when you are testing NoiseChisel (or Segment) for the best parameters. You have to run NoiseChisel multiple times and see the effect of each change. However, once you are happy with the kernel, re-convolving the input on every change of higher-level parameters will greatly hinder, or discourage, further testing. With this option, you can convolve the input image with your chosen kernel once before running NoiseChisel, then feed it to NoiseChisel on each test run and thus save valuable time for better/more tests.

To build your desired convolution kernel, you can use Section 8.1 [MakeProfiles], page 332. To convolve the image with a given kernel you can use Section 6.3 [Convolve], page 216. Spatial domain convolution is mandatory: in the frequency domain, blank pixels (if present) will cover the whole image and gradients will appear on the edges, see Section 6.3.3 [Spatial vs. Frequency domain], page 234.

Below you can see an example of the second scenario: you want to see how variation of the growth level (through the --detgrowquant option) will affect the final result. Recall that you can ignore all the extra spaces, new lines, and backslash’s (\’) if you are typing in the terminal. In a shell script, remove the $ signs at the start of the lines.

```
## Make the kernel to convolve with.
$ astmkprof --oversample=1 --kernel=gaussian,2,5

## Convolve the input with the given kernel.
$ astconvolve input.fits --kernel=kernel.fits \
   --domain=spatial --output=convolved.fits

## Run NoiseChisel with seven growth quantile values.
$ for g in 60 65 70 75 80 85 90; do \
   astnoisechisel input.fits --convolved=convolved.fits \
   --detgrowquant=0.$g --output=$g.fits; \
   done

--chdu=STR
   The HDU/extension containing the convolved image in the file given to --convolved.

-w STR
   --widekernel=STR
   File name of a wider kernel to use in estimating the difference of the mode and median in a tile (this difference is used to identify the significance of signal
in that tile, see Section 7.1.4.3 [Quantifying signal in a tile], page 255). As displayed in Figure 4 of Akhlaghi and Ichikawa [2015] (https://arxiv.org/abs/1505.01664), a wider kernel will help in identifying the skewness caused by data in noise. The image that is convolved with this kernel is only used for this purpose. Once the mode is found to be sufficiently close to the median, the quantile threshold is found on the image convolved with the sharper kernel (--kernel), see --qthresh).

Since convolution will significantly slow down the processing, this feature is optional. When it isn't given, the image that is convolved with --kernel will be used to identify good tiles and apply the quantile threshold. This option is mainly useful in conditions were you have a very large, extended, diffuse signal that is still present in the usable tiles when using --kernel. See Section 2.3 [Detecting large extended targets], page 61, for a practical demonstration on how to inspect the tiles used in identifying the quantile threshold.

--whdu=STR

HDU containing the kernel file given to the --widekernel option.

-L INT[,INT]

--largetilesize=INT[,INT]

The size of each tile for the tessellation with the larger tile sizes. Except for the tile size, all the other parameters for this tessellation are taken from the common options described in Section 4.1.2.2 [Processing options], page 112. The format is identical to that of the --tilesize option that is discussed in that section.

7.2.1.2 Detection options

Detection is the process of separating the pixels in the image into two groups: 1) Signal, and 2) Noise. Through the parameters below, you can customize the detection process in NoiseChisel. Recall that you can always see the full list of NoiseChisel's options with the --help (see Section 4.3 [Getting help], page 123), or --printparams (or -P) to see their values (see Section 4.1.2.3 [Operating mode options], page 114).

-Q FLT

--meanmedqdiff=FLT

The maximum acceptable distance between the quantiles of the mean and median in each tile, see Section 7.1.4.3 [Quantifying signal in a tile], page 255. The quantile threshold estimates are measured on tiles where the quantiles of their mean and median are less distant than the value given to this option. For example --meanmedqdiff=0.01 means that only tiles where the mean's quantile is between 0.49 and 0.51 (recall that the median's quantile is 0.5) will be used.

--outliersclip=FLT,FLT

σ-clipping parameters for the outlier rejection of the quantile threshold. The format of the given values is similar to --sigmaclip below. In NoiseChisel, outlier rejection on tiles is used when identifying the quantile thresholds (--qthresh, --noerodequant, and detgrowquant).

Outlier rejection is useful when the dataset contains a large and diffuse (almost flat within each tile) signal. The flatness of the profile will cause it to success-
fully pass the mean-median quantile difference test, so we’ll need to use the
distribution of successful tiles for removing these false positives. For more, see
the latter half of Section 7.1.4.3 [Quantifying signal in a tile], page 255.

--outliersigma=FLT
Multiple of sigma to define an outlier. If this option is given a value of zero, no
outlier rejection will take place. For more see --outliersclip and the latter
half of Section 7.1.4.3 [Quantifying signal in a tile], page 255.

-t FLT
--qthresh=FLT
The quantile threshold to apply to the convolved image. The detection process
begins with applying a quantile threshold to each of the tiles in the small tessell-
ation. The quantile is only calculated for tiles that don’t have any significant
signal within them, see Section 7.1.4.3 [Quantifying signal in a tile], page 255.
Interpolation is then used to give a value to the unsuccessful tiles and it is
finally smoothed.
The quantile value is a floating point value between 0 and 1. Assume that we
have sorted the \( N \) data elements of a distribution (the pixels in each mesh on
the convolved image). The quantile \( q \) of this distribution is the value of the
element with an index of (the nearest integer to) \( q \times N \) in the sorted data set.
After thresholding is complete, we will have a binary (two valued) image. The
pixels above the threshold are known as foreground pixels (have a value of 1)
while those which lie below the threshold are known as background (have a
value of 0).

--smoothwidth=INT
Width of flat kernel used to smooth the interpolated quantile thresholds, see
--qthresh for more.

--checkqthresh
Check the quantile threshold values on the mesh grid. A file suffixed with \_qthresh.fits will be created showing each step. With this option, NoiseChisel
will abort as soon as quantile estimation has been completed, allowing you to
inspect the steps leading to the final quantile threshold, this can be disabled with --continueaftercheck. By default the output will have the same pixel
size as the input, but with the --oneelempertile option, only one pixel will
be used for each tile (see Section 4.1.2.2 [Processing options], page 112).

--blankasforeground
In the erosion and opening steps below, treat blank elements as foreground
(regions above the threshold). By default, blank elements in the dataset are
considered to be background, so if a foreground pixel is touching it, it will be
eroded. This option is irrelevant if the datasets contains no blank elements.
When there are many blank elements in the dataset, treating them as fore-
ground will systematically erode their regions less, therefore systematically cre-
ating more false positives. So use this option (when blank values are present)
with care.
-e INT
--erode=INT
The number of erosions to apply to the binary thresholded image. Erosion is simply the process of flipping (from 1 to 0) any of the foreground pixels that neighbor a background pixel. In a 2D image, there are two kinds of neighbors, 4-connected and 8-connected neighbors. You can specify which type of neighbors should be used for erosion with the --erodengb option, see below.

Erosion has the effect of shrinking the foreground pixels. To put it another way, it expands the holes. This is a founding principle in NoiseChisel: it exploits the fact that with very low thresholds, the holes in the very low surface brightness regions of an image will be smaller than regions that have no signal. Therefore by expanding those holes, we are able to separate the regions harboring signal.

--erodengb=INT
The type of neighborhood (structuring element) used in erosion, see --erode for an explanation on erosion. Only two integer values are acceptable: 4 or 8. In 4-connectivity, the neighbors of a pixel are defined as the four pixels on the top, bottom, right and left of a pixel that share an edge with it. The 8-connected neighbors on the other hand include the 4-connected neighbors along with the other 4 pixels that share a corner with this pixel. See Figure 6 (a) and (b) in Akhlaghi and Ichikawa (2015) for a demonstration.

--noerodequant
Pure erosion is going to carve off sharp and small objects completely out of the detected regions. This option can be used to avoid missing such sharp and small objects (which have significant pixels, but not over a large area). All pixels with a value larger than the significance level specified by this option will not be eroded during the erosion step above. However, they will undergo the erosion and dilation of the opening step below.

Like the --qthresh option, the significance level is determined using the quantile (a value between 0 and 1). Just as a reminder, in the normal distribution, $1\sigma$, $1.5\sigma$, and $2\sigma$ are approximately on the 0.84, 0.93, and 0.98 quantiles.

-p INT
--opening=INT
Depth of opening to be applied to the eroded binary image. Opening is a composite operation. When opening a binary image with a depth of $n$, $n$ erosions (explained in --erode) are followed by $n$ dilations. Simply put, dilation is the inverse of erosion. When dilating an image any background pixel is flipped (from 0 to 1) to become a foreground pixel. Dilation has the effect of fattening the foreground. Note that in NoiseChisel, the erosion which is part of opening is independent of the initial erosion that is done on the thresholded image (explained in --erode). The structuring element for the opening can be specified with the --openingngb option. Opening has the effect of removing the thin foreground connections (mostly noise) between separate foreground ‘islands’ (detections) thereby completely isolating them. Once opening is complete, we have initial detections.
--openingngb=INT
The structuring element used for opening, see --erodengb for more information about a structuring element.

--skyfracnoblank
Ignore blank pixels when estimating the fraction of undetected pixels for Sky estimation. NoiseChisel only measures the Sky over the tiles that have a sufficiently large fraction of undetected pixels (value given to --minskyfrac). By default this fraction is found by dividing number of undetected pixels in a tile by the tile’s area. But this default behavior ignores the possibility of blank pixels. In situations that blank/masked pixels are scattered across the image and if they are large enough, all the tiles can fail the --minskyfrac test, thus not allowing NoiseChisel to proceed. With this option, such scenarios can be fixed: the denominator of the fraction will be the number of non-blank elements in the tile, not the total tile area.

-B FLT
--minskyfrac=FLT
Minimum fraction (value between 0 and 1) of Sky (undetected) areas in a tile. Only tiles with a fraction of undetected pixels (Sky) larger than this value will be used to estimate the Sky value. NoiseChisel uses this option value twice to estimate the Sky value: after initial detections and in the end when false detections have been removed.

Because of the PSF and their intrinsic amorphous properties, astronomical objects (except cosmic rays) never have a clear cutoff and commonly sink into the noise very slowly. Even below the very low thresholds used by NoiseChisel. So when a large fraction of the area of one mesh is covered by detections, it is very plausible that their faint wings are present in the undetected regions (hence causing a bias in any measurement). To get an accurate measurement of the above parameters over the tessellation, tiles that harbor too many detected regions should be excluded. The used tiles are visible in the respective --check option of the given step.

--checkdetsky
Check the initial approximation of the sky value and its standard deviation in a FITS file ending with _detsky.fits. With this option, NoiseChisel will abort as soon as the sky value used for defining pseudo-detections is complete. This allows you to inspect the steps leading to the final quantile threshold, this behavior can be disabled with --continueaftercheck. By default the output will have the same pixel size as the input, but with the --oneelementper tile option, only one pixel will be used for each tile (see Section 4.1.2.2 [Processing options], page 112).

-s FLT,FLT
--sigmaclip=FLT,FLT
The σ-clipping parameters for measuring the initial and final Sky values from the undetected pixels, see Section 7.1.3 [Sigma clipping], page 251.
This option takes two values which are separated by a comma (,). Each value can either be written as a single number or as a fraction of two numbers (for
example 3, 1/10). The first value to this option is the multiple of \( \sigma \) that will be clipped (\( \alpha \) in that section). The second value is the exit criteria. If it is less than 1, then it is interpreted as tolerance and if it is larger than one it is assumed to be the fixed number of iterations. Hence, in the latter case the value must be an integer.

\[-R \text{ FLT}\]

\[-\text{dthresh}=\text{FLT}\]

The detection threshold: a multiple of the initial Sky standard deviation added with the initial Sky approximation (which you can inspect with \(--\text{checkdetsky}\)). This flux threshold is applied to the initially undetected regions on the unconvolved image. The background pixels that are completely engulfed in a 4-connected foreground region are converted to background (holes are filled) and one opening (depth of 1) is applied over both the initially detected and undetected regions. The Signal to noise ratio of the resulting ‘pseudo-detections’ are used to identify true vs. false detections. See Section 3.1.5 and Figure 7 in Akhlaghi and Ichikawa (2015) for a very complete explanation.

\[-\text{dopening}=\text{INT}\]

The number of openings to do after applying \(--\text{dthresh}\).

\[-\text{dopeningngb}=\text{INT}\]

The connectivity used in the opening of \(--\text{dopening}\). In a 2D image this must be either 4 or 8. The stronger the connectivity, the more smaller regions will be discarded.

\[-\text{holengb}=\text{INT}\]

The connectivity (defined by the number of neighbors) to fill holes after applying \(--\text{dthresh}\) (above) to find pseudo-detections. For example in a 2D image it must be 4 (the neighbors that are most strongly connected) or 8 (all neighbors). The stronger the connectivity, the stronger the hole will be enclosed. So setting a value of 8 in a 2D image means that the walls of the hole are 4-connected. If standard (near Sky level) values are given to \(--\text{dthresh}\), setting \(--\text{holengb}=4\), might fill the complete dataset and thus not create enough pseudo-detections.

\[-\text{pseudoconcomp}=\text{INT}\]

The connectivity (defined by the number of neighbors) to find individual pseudo-detections. If it is a weaker connectivity (4 in a 2D image), then pseudo-detections that are connected on the corners will be treated as separate.

\[-m \text{ INT}\]

\[-\text{snminarea}=\text{INT}\]

The minimum area to calculate the Signal to noise ratio on the pseudo-detections of both the initially detected and undetected regions. When the area in a pseudo-detection is too small, the Signal to noise ratio measurements will not be accurate and their distribution will be heavily skewed to the positive. So it is best to ignore any pseudo-detection that is smaller than this area. Use \(--\text{detsnhistnbins}\) to check if this value is reasonable or not.
--checksn
Save the S/N values of the pseudo-detections (and possibly grown detections if --cleangrowndet is called) into separate tables. If --tableformat is a FITS table, each table will be written into a separate extension of one file suffixed with _detsn.fits. If it is plain text, a separate file will be made for each table (ending in _detsn_sky.txt, _detsn_det.txt and _detsn_grown.txt). For more on --tableformat see Section 4.1.2.1 [Input/Output options], page 109.
You can use these to inspect the S/N values and their distribution (in combination with the --checkdetection option to see where the pseudo-detections are). You can use Gnuastro’s Section 7.1 [Statistics], page 248, to make a histogram of the distribution or any other analysis you would like for better understanding of the distribution (for example through a histogram).

--minnumfalse=INT
The minimum number of ‘pseudo-detections’ over the undetected regions to identify a Signal-to-Noise ratio threshold. The Signal to noise ratio (S/N) of false pseudo-detections in each tile is found using the quantile of the S/N distribution of the pseudo-detections over the undetected pixels in each mesh. If the number of S/N measurements is not large enough, the quantile will not be accurate (can have large scatter). For example if you set --snquant=0.99 (or the top 1 percent), then it is best to have at least 100 S/N measurements.

-c FLT
--snquant=FLT
The quantile of the Signal to noise ratio distribution of the pseudo-detections in each mesh to use for filling the large mesh grid. Note that this is only calculated for the large mesh grids that satisfy the minimum fraction of undetected pixels (value of --minbfrac) and minimum number of pseudo-detections (value of --minnumfalse).

--snthresh=FLT
Manually set the signal-to-noise ratio of true pseudo-detections. With this option, NoiseChisel will not attempt to find pseudo-detections over the noisy regions of the dataset, but will directly go onto applying the manually input value.
This option is useful in crowded images where there is no blank sky to find the sky pseudo-detections. You can get this value on a similarly reduced dataset (from another region of the Sky with more undetected regions spaces).

-d FLT
--detgrowquant=FLT
Quantile limit to “grow” the final detections. As discussed in the previous options, after applying the initial quantile threshold, layers of pixels are carved off the objects to identify true signal. With this step you can return those low surface brightness layers that were carved off back to the detections. To disable growth, set the value of this option to 1.
The process is as follows: after the true detections are found, all the non-detected pixels above this quantile will be put in a list and used to “grow” the
true detections (seeds of the growth). Like all quantile thresholds, this thres-
old is defined and applied to the convolved dataset. Afterwards, the dataset
is dilated once (with minimum connectivity) to connect very thin regions on
the boundary: imagine building a dam at the point rivers spill into an open
sea/ocean. Finally, all holes are filled. In the geography metaphor, holes can be
seen as the closed (by the dams) rivers and lakes, so this process is like turning
the water in all such rivers and lakes into soil. See `--detgrowmaxholesize` for
configuring the hole filling.

```
--detgrowmaxholesize=INT
```
The maximum hole size to fill during the final expansion of the true detections
as described in `--detgrowquant`. This is necessary when the input contains
many smaller objects and can be used to avoid marking blank sky regions as
detections.

For example multiple galaxies can be positioned such that they surround an
empty region of sky. If all the holes are filled, the Sky region in between
them will be taken as a detection which is not desired. To avoid such cases, the
integer given to this option must be smaller than the hole between such objects.
However, we should caution that unless the “hole” is very large, the combined
faint wings of the galaxies might actually be present in between them, so be
very careful in not filling such holes.

On the other hand, if you have a very large (and extended) galaxy, the diffuse
wings of the galaxy may create very large holes over the detections. In such
cases, a large enough value to this option will cause all such holes to be detected
as part of the large galaxy and thus help in detecting it to extremely low surface
brightness limits. Therefore, especially when large and extended objects are
present in the image, it is recommended to give this option (very) large values.
For one real-world example, see Section 2.3 [Detecting large extended targets],
page 61.

```
--cleangrowndet
```
After dilation, if the signal-to-noise ratio of a detection is less than the derived
pseudo-detection S/N limit, that detection will be discarded. In an ideal/clean
noise, a true detection’s S/N should be larger than its constituent pseudo-
detections because its area is larger and it also covers more signal. However,
on a false detections (especially at lower `--snquant` values), the increase in size
can cause a decrease in S/N below that threshold.

This will improve purity and not change completeness (a true detection will not
be discarded). Because a true detection has flux in its vicinity and dilation will
catch more of that flux and increase the S/N. So on a true detection, the final
S/N cannot be less than pseudo-detections.

However, in many real images bad processing creates artifacts that cannot be
accurately removed by the Sky subtraction. In such cases, this option will
decrease the completeness (will artificially discard true detections). So this
feature is not default and should to be explicitly called when you know the
noise is clean.
Chapter 7: Data analysis

--checkdetection
Every step of the detection process will be added as an extension to a file with the suffix _det.fits. Going through each would just be a repeat of the explanations above and also of those in Akhlaghi and Ichikawa (2015). The extension label should be sufficient to recognize which step you are observing. Viewing all the steps can be the best guide in choosing the best set of parameters. With this option, NoiseChisel will abort as soon as a snapshot of all the detection process is saved. This behavior can be disabled with --continueaftercheck.

--checksky
Check the derivation of the final sky and its standard deviation values on the mesh grid. With this option, NoiseChisel will abort as soon as the sky value is estimated over the image (on each tile). This behavior can be disabled with --continueaftercheck. By default the output will have the same pixel size as the input, but with the --oneelempertile option, only one pixel will be used for each tile (see Section 4.1.2.2 [Processing options], page 112).

7.2.1.3 NoiseChisel output
NoiseChisel’s output is a multi-extension FITS file. The main extension/dataset is a (binary) detection map. It has the same size as the input but with only two possible values for all pixels: 0 (for pixels identified as noise) and 1 (for those identified as signal/detections). The detection map is followed by a Sky and Sky standard deviation dataset (which are calculated from the binary image). By default (when --rawoutput isn’t called), NoiseChisel will also subtract the Sky value from the input and save the sky-subtracted input as the first extension in the output with data. The zero-th extension (that contains no data), contains NoiseChisel’s configuration as FITS keywords, see Section 4.11 [Output FITS files], page 143.

The name of the output file can be set by giving a value to --output (this is a common option between all programs and is therefore discussed in Section 4.1.2.1 [Input/Output options], page 109). If --output isn’t used, the input name will be suffixed with _detected.fits and used as output, see Section 4.10 [Automatic output], page 142. If any of the options starting with --check* are given, NoiseChisel won’t complete and will abort as soon as the respective check images are created. For more information on the different check images, see the description for the --check* options in Section 7.2.1.2 [Detection options], page 275, (this can be disabled with --continueaftercheck).

The last two extensions of the output are the Sky and its Standard deviation, see Section 7.1.4 [Sky value], page 252, for a complete explanation. They are calculated on the tile grid that you defined for NoiseChisel. By default these datasets will have the same size as the input, but with all the pixels in one tile given one value. To be more space-efficient (keep only one pixel per tile), you can use the --oneelempertile option, see Section 4.9 [Tessellation], page 141.

To inspect any of NoiseChisel’s output files, assuming you use SAO DS9, you can configure your Graphic User Interface (GUI) to open NoiseChisel’s output as a multi-extension data cube. This will allow you to flip through the different extensions and visually inspect the results. This process has been described for the GNOME GUI (most common GUI in GNU/Linux operating systems) in Section B.1.1 [Viewing multiextension FITS images], page 540.
NoiseChisel’s output configuration options are described in detail below.

```bash
--continueaftercheck
Continue NoiseChisel after any of the options starting with --check (see Section 7.2.1.2 [Detection options], page 275. NoiseChisel involves many steps and as a result, there are many checks, allowing you to inspect the status of the processing. The results of each step affect the next steps of processing. Therefore, when you want to check the status of the processing at one step, the time spent to complete NoiseChisel is just wasted/distracting time.

To encourage easier experimentation with the option values, when you use any of the NoiseChisel options that start with --check, NoiseChisel will abort once its desired extensions have been written. With --continueaftercheck option, you can disable this behavior and ask NoiseChisel to continue with the rest of the processing, even after the requested check files are complete.
```

```bash
--ignoreblankintiles
Don’t set the input’s blank pixels to blank in the tiled outputs (for example Sky and Sky standard deviation extensions of the output). This is only applicable when the tiled output has the same size as the input, in other words, when --oneelempertile isn’t called.

By default, blank values in the input (commonly on the edges which are outside the survey/field area) will be set to blank in the tiled outputs also. But in other scenarios this default behavior is not desired: for example if you have masked something in the input, but want the tiled output under that also.
```

```bash
-l
--label
Run a connected-components algorithm on the finally detected pixels to identify which pixels are connected to which. By default the main output is a binary dataset with only two values: 0 (for noise) and 1 (for signal/detections). See Section 7.2.1.3 [NoiseChisel output], page 282, for more.

The purpose of NoiseChisel is to detect targets that are extended and diffuse, with outer parts that sink into the noise very gradually (galaxies and stars for example). Since NoiseChisel digs down to extremely low surface brightness values, many such targets will commonly be detected together as a single large body of connected pixels.

To properly separate connected objects, sophisticated segmentation methods are commonly necessary on NoiseChisel’s output. Gnuastro has the dedicated Section 7.3 [Segment], page 284, program for this job. Since input images are commonly large and can take a significant volume, the extra volume necessary to store the labels of the connected components in the detection map (which will be created with this --label option, in 32-bit signed integer type) can thus be a major waste of space. Since the default output is just a binary dataset, an 8-bit unsigned dataset is enough.

The binary output will also encourage users to segment the result separately prior to doing higher-level analysis. As an alternative to --label, if you have the binary detection image, you can use the connected-components operator in Gnuastro’s Arithmetic program to identify regions that are connected with
Chapter 7: Data analysis

7.3 Segment

Once signal is separated from noise (for example with Section 7.2 [NoiseChisel], page 269), you have a binary dataset: each pixel is either signal (1) or noise (0). Signal (for example
every galaxy in your image) has been “detected”, but all detections have a label of 1. Therefore while we know which pixels contain signal, we still can’t find out how many galaxies they contain or which detected pixels correspond to which galaxy. At the lowest (most generic) level, detection is a kind of segmentation (segmenting the whole dataset into signal and noise, see Section 7.2 [NoiseChisel], page 269). Here, we’ll define segmentation only on signal: to separate sub-structure within the detections.

If the targets are clearly separated, or their detected regions aren’t touching, a simple connected components\(^8\) algorithm (very basic segmentation) is enough to separate the regions that are touching/connected. This is such a basic and simple form of segmentation that Gnuastro’s Arithmetic program has an operator for it: see connected-components in Section 6.2.2 [Arithmetic operators], page 200. Assuming the binary dataset is called binary.fits, you can use it with a command like this:

```
$ astarithmetic binary.fits 2 connected-components
```

You can even do a very basic detection (a threshold, say at value 100) \textit{and} segmentation in Arithmetic with a single command like below:

```
$ astarithmetic in.fits 100 gt 2 connected-components
```

However, in most astronomical situations our targets are not nicely separated or have a sharp boundary/edge (for a threshold to suffice): they touch (for example merging galaxies), or are simply in the same line-of-sight (which is much more common). This causes their images to overlap.

In particular, when you do your detection with NoiseChisel, you will detect signal to very low surface brightness limits: deep into the faint wings of galaxies or bright stars (which can extend very far and irregularly from their center). Therefore, it often happens that several galaxies are detected as one large detection. Since they are touching, a simple connected components algorithm will not suffice. It is therefore necessary to do a more sophisticated segmentation and break up the detected pixels (even those that are touching) into multiple target objects as accurately as possible.

Segment will use a detection map and its corresponding dataset to find sub-structure over the detected areas and use them for its segmentation. Until Gnuastro version 0.6 (released in 2018), Segment was part of Section 7.2 [NoiseChisel], page 269. Therefore, similar to NoiseChisel, the best place to start reading about Segment and understanding what it does (with many illustrative figures) is Section 3.2 of Akhlaghi and Ichikawa [2015] (https://arxiv.org/abs/1505.01664), and continue with Akhlaghi [2019] (https://arxiv.org/abs/1909.11230).

As a summary, Segment first finds true \textit{clumps} over the detections. Clumps are associated with local maxima/minima\(^9\) and extend over the neighboring pixels until they reach a local minimum/maximum (river/watershed). By default, Segment will use the distribution of clump signal-to-noise ratios over the undetected regions as reference to find “true” clumps over the detections. Using the undetected regions can be disabled by directly giving a signal-to-noise ratio to \texttt{--clumpsthresh}.

The true clumps are then grown to a certain threshold over the detections. Based on the strength of the connections (rivers/watersheds) between the grown clumps, they are

\(^8\) https://en.wikipedia.org/wiki/Connected-component_labeling

\(^9\) By default the maximum is used as the first clump pixel, to define clumps based on local minima, use the \texttt{--minima} option.
considered parts of one *object* or as separate *objects*. See Section 3.2 of Akhlaghi and Ichikawa [2015] (https://arxiv.org/abs/1505.01664) for more. Segment’s main output are thus two labeled datasets: 1) clumps, and 2) objects. See Section 7.3.1.3 [Segment output], page 293, for more.

To start learning about Segment, especially in relation to detection (Section 7.2 [NoiseChisel], page 269) and measurement (Section 7.4 [MakeCatalog], page 295), the recommended references are Akhlaghi and Ichikawa [2015] (https://arxiv.org/abs/1505.01664), Akhlaghi [2016] (https://arxiv.org/abs/1611.06387) and Akhlaghi [2019] (https://arxiv.org/abs/1909.11230). If you have used Segment within your research, please run it with --cite to list the papers you should cite and how to acknowledge its funding sources.

Those papers cannot be updated any more but the software will evolve. For example Segment became a separate program (from NoiseChisel) in 2018 (after those papers were published). Therefore this book is the definitive reference. Finally, in Section 7.3.1 [Invoking Segment], page 286, we’ll discuss Segment’s inputs, outputs and configuration options.

### 7.3.1 Invoking Segment

Segment will identify substructure within the detected regions of an input image. Segment’s output labels can be directly used for measurements (for example with Section 7.4 [MakeCatalog], page 295). The executable name is `astsegment` with the following general template

```
$ astsegment [OPTION ...] InputImage.fits
```

One line examples:

```
## Segment NoiseChisel's detected regions.
$ astsegment default-noisechisel-output.fits

## Use a hand-input S/N value for keeping true clumps
## (avoid finding the S/N using the undetected regions).
$ astsegment nc-out.fits --clumpsthresh=10

## Inspect all the segmentation steps after changing a parameter.
$ astsegment input.fits --snquant=0.9 --checksegmentation

## Use the fixed value of 0.01 for the input's Sky standard deviation
## (in the units of the input), and assume all the pixels are a
## detection (for example a large structure extending over the whole
## image), and only keep clumps with S/N>10 as true clumps.
$ astsegment in.fits --std=0.01 --detection=all --clumpsthresh=10
```

If Segment is to do processing (for example you don’t want to get help, or see the values of each option), at least one input dataset is necessary along with detection and error information, either as separate datasets (per-pixel) or fixed values, see Section 7.3.1.1 [Segment input], page 287. Segment shares a large set of common operations with other Gnuastro programs, mainly regarding input/output, general processing steps, and general operating modes. To help in a unified experience between all of Gnuastro’s programs, these common operations have the same names and defined in Section 4.1.2 [Common options], page 109.
As in all Gnuastro programs, options can also be given to Segment in configuration files. For a thorough description of Gnuastro’s configuration file parsing, please see Section 4.2 [Configuration files], page 120. All of Segment’s options with a short description are also always available on the command-line with the --help option, see Section 4.3 [Getting help], page 123. To inspect the option values without actually running Segment, append your command with --printparams (or -P).

To help in easy navigation between Segment’s options, they are separately discussed in the three sub-sections below: Section 7.3.1.1 [Segment input], page 287, discusses how you can customize the inputs to Segment. Section 7.3.1.2 [Segmentation options], page 290, is devoted to options specific to the high-level segmentation process. Finally, in Section 7.3.1.3 [Segment output], page 293, we’ll discuss options that affect Segment’s output.

7.3.1.1 Segment input

Besides the input dataset (for example astronomical image), Segment also needs to know the Sky standard deviation and the regions of the dataset that it should segment. The values dataset is assumed to be Sky subtracted by default. If it isn’t, you can ask Segment to subtract the Sky internally by calling --sky. For the rest of this discussion, we’ll assume it is already sky subtracted.

The Sky and its standard deviation can be a single value (to be used for the whole dataset) or a separate dataset (for a separate value per pixel). If a dataset is used for the Sky and its standard deviation, they must either be the size of the input image, or have a single value per tile (generated with --oneelementtile, see Section 4.1.2.2 [Processing options], page 112, and Section 4.9 [Tessellation], page 141).

The detected regions/pixels can be specified as a detection map (for example see Section 7.2.1.3 [NoiseChisel output], page 282). If --detection=all, Segment won’t read any detection map and assume the whole input is a single detection. For example when the dataset is fully covered by a large nearby galaxy/globular cluster.

When dataset are to be used for any of the inputs, Segment will assume they are multiple extensions of a single file by default (when --std or --detection aren’t called). For example NoiseChisel’s default output Section 7.2.1.3 [NoiseChisel output], page 282. When the Sky-subtracted values are in one file, and the detection and Sky standard deviation are in another, you just need to use --detection: in the absence of --std, Segment will look for both the detection labels and Sky standard deviation in the file given to --detection. Ultimately, if all three are in separate files, you need to call both --detection and --std.

The extensions of the three mandatory inputs can be specified with --hdu, --dhdu, and --stdhdu. For a full discussion on what to give to these options, see the description of --hdu in Section 4.1.2.1 [Input/Output options], page 109. To see their default values (along with all the other options), run Segment with the --printparams (or -P) option. Just recall that in the absence of --detection and --std, all three are assumed to be in the same file. If you only want to see Segment’s default values for HDUs on your system, run this command:

```
$ astsegment -P | grep hdu
```

By default Segment will convolve the input with a kernel to improve the signal-to-noise ratio of true peaks. If you already have the convolved input dataset, you can pass it directly to Segment for faster processing (using the --convolved and --chdu options). Just don’t
forget that the convolved image must also be Sky-subtracted before calling Segment. If a value/file is given to `--sky`, the convolved values will also be Sky subtracted internally. Alternatively, if you prefer to give a kernel (with `--kernel` and `--khdu`), Segment can do the convolution internally. To disable convolution, use `--kernel=none`.

`--sky=STR/FLT`

The Sky value(s) to subtract from the input. This option can either be given a constant number or a file name containing a dataset (multiple values, per pixel or per tile). By default, Segment will assume the input dataset is Sky subtracted, so this option is not mandatory.

If the value can't be read as a number, it is assumed to be a file name. When the value is a file, the extension can be specified with `--skyhdu`. When its not a single number, the given dataset must either have the same size as the output or the same size as the tessellation (so there is one pixel per tile, see Section 4.9 [Tessellation], page 141).

When this option is given, its value(s) will be subtracted from the input and the (optional) convolved dataset (given to `--convolved`) prior to starting the segmentation process.

`--skyhdu=STR/INT`

The HDU/extension containing the Sky values. This is mandatory when the value given to `--sky` is not a number. Please see the description of `--hdu` in Section 4.1.2.1 [Input/Output options], page 109, for the different ways you can identify a special extension.

`--std=STR/FLT`

The Sky standard deviation value(s) corresponding to the input. The value can either be a constant number or a file name containing a dataset (multiple values, per pixel or per tile). The Sky standard deviation is mandatory for Segment to operate.

If the value can't be read as a number, it is assumed to be a file name. When the value is a file, the extension can be specified with `--skyhdu`. When its not a single number, the given dataset must either have the same size as the output or the same size as the tessellation (so there is one pixel per tile, see Section 4.9 [Tessellation], page 141).

When this option is not called, Segment will assume the standard deviation is a dataset and in a HDU/extension (`--stdhdu`) of another one of the input file(s). If a file is given to `--detection`, it will assume that file contains the standard deviation dataset, otherwise, it will look into input filename (the main argument, without any option).

`--stdhdu=INT/STR`

The HDU/extension containing the Sky standard deviation values, when the value given to `--std` is a file name. Please see the description of `--hdu` in Section 4.1.2.1 [Input/Output options], page 109, for the different ways you can identify a special extension.
--variance
The input Sky standard deviation value/dataset is actually variance. When this option is called, the square root of input Sky standard deviation (see --std) is used internally, not its raw value(s).

-d STR
--detection=STR
Detection map to use for segmentation. If given a value of all, Segment will assume the whole dataset must be segmented, see below. If a detection map is given, the extension can be specified with --dhdu. If not given, Segment will assume the desired HDU/extension is in the main input argument (input file specified with no option).

The final segmentation (clumps or objects) will only be over the non-zero pixels of this detection map. The dataset must have the same size as the input image. Only datasets with an integer type are acceptable for the labeled image, see Section 4.6 [Numeric data types], page 130. If your detection map only has integer values, but it is stored in a floating point container, you can use Gnuastro’s Arithmetic program (see Section 6.2 [Arithmetic], page 199) to convert it to an integer container, like the example below:

$ astarithmetic float.fits int32 --output=int.fits

It may happen that the whole input dataset is covered by signal, for example when working on parts of the Andromeda galaxy, or nearby globular clusters (that cover the whole field of view). In such cases, segmentation is necessary over the complete dataset, not just specific regions (detections). By default Segment will first use the undetected regions as a reference to find the proper signal-to-noise ratio of “true” clumps (give a purity level specified with --snquant). Therefore, in such scenarios you also need to manually give a “true” clump signal-to-noise ratio with the --clumpsnthresh option to disable looking into the undetected regions, see Section 7.3.1.2 [Segmentation options], page 290. In such cases, is possible to make a detection map that only has the value 1 for all pixels (for example using Section 6.2 [Arithmetic], page 199), but for convenience, you can also use --detection=all.

--dhdu
The HDU/extension containing the detection map given to --detection.
Please see the description of --hdu in Section 4.1.2.1 [Input/Output options], page 109, for the different ways you can identify a special extension.

-k STR
--kernel=STR
The kernel used to convolve the input image. The usage of this option is identical to NoiseChisel’s --kernel option (Section 7.2.1.1 [NoiseChisel input], page 273). Please see the descriptions there for more. To disable convolution, you can give it a value of none.

--khdu
The HDU/extension containing the kernel used for convolution. For acceptable values, please see the description of --hdu in Section 4.1.2.1 [Input/Output options], page 109.
--convolved

The convolved image to avoid internal convolution by Segment. The usage of this option is identical to NoiseChisel's --convolved option. Please see Section 7.2.1.1 [NoiseChisel input], page 273, for a thorough discussion of the usefulness and best practices of using this option.

If you want to use the same convolution kernel for detection (with Section 7.2 [NoiseChisel], page 269) and segmentation, with this option, you can use the same convolved image (that is also available in NoiseChisel) and avoid two convolutions. However, just be careful to use the input to NoiseChisel as the input to Segment also, then use the --sky and --std to specify the Sky and its standard deviation (from NoiseChisel's output). Recall that when NoiseChisel is not called with --rawoutput, the first extension of NoiseChisel's output is the Sky-subtracted input (see Section 7.2.1.3 [NoiseChisel output], page 282). So if you use the same convolved image that you fed to NoiseChisel, but use NoiseChisel's output with Segment's --convolved, then the convolved image won't be Sky subtracted.

--chdu

The HDU/extension containing the convolved image (given to --convolved).
For acceptable values, please see the description of --hdu in Section 4.1.2.1 [Input/Output options], page 109.

-L INT[,INT]
--largetilesize=INT[,INT]

The size of the large tiles to use for identifying the clump S/N threshold over the undetected regions. The usage of this option is identical to NoiseChisel's --largetilesize option (Section 7.2.1.1 [NoiseChisel input], page 273). Please see the descriptions there for more.

The undetected regions can be a significant fraction of the dataset and finding clumps requires sorting of the desired regions, which can be slow. To speed up the processing, Segment finds clumps in the undetected regions over separate large tiles. This allows it to have to sort a much smaller set of pixels and also to treat them independently and in parallel. Both these issues greatly speed it up. Just be sure to not decrease the large tile sizes too much (less than 100 pixels in each dimension). It is important for them to be much larger than the clumps.

7.3.1.2 Segmentation options

The options below can be used to configure every step of the segmentation process in the Segment program. For a more complete explanation (with figures to demonstrate each step), please see Section 3.2 of Akhlaghi and Ichikawa [2015] (https://arxiv.org/abs/1505.01664), and also Section 7.3 [Segment], page 284. By default, Segment will follow the procedure described in the paper to find the S/N threshold based on the noise properties. This can be disabled by directly giving a trustable signal-to-noise ratio to the --clumpsthresh option.

Recall that you can always see the full list of Gnuastro's options with the --help (see Section 4.3 [Getting help], page 123), or --printparams (or -P) to see their values (see Section 4.1.2.3 [Operating mode options], page 114).
-B FLT
--minskyfrac=FLT
Minimum fraction (value between 0 and 1) of Sky (undetected) areas in a large
tile. Only (large) tiles with a fraction of undetected pixels (Sky) greater than
this value will be used for finding clumps. The clumps found in the undetected
areas will be used to estimate a S/N threshold for true clumps. Therefore
this is an important option (to decrease) in crowded fields. Operationally,
this is almost identical to NoiseChisel’s --minskyfrac option (Section 7.2.1.2
[Detection options], page 275). Please see the descriptions there for more.

--minima
Build the clumps based on the local minima, not maxima. By default, clumps
are built starting from local maxima (see Figure 8 of Akhlaghi and Ichikawa
[2015] (https://arxiv.org/abs/1505.01664)). Therefore, this option can be
useful when you are searching for true local minima (for example absorption
features).

-m INT
--snminarea=INT
The minimum area which a clump in the undetected regions should have in
order to be considered in the clump Signal to noise ratio measurement. If this
size is set to a small value, the Signal to noise ratio of false clumps will not be
accurately found. It is recommended that this value be larger than the value
to NoiseChisel’s --snminarea. Because the clumps are found on the convolved
(smoothed) image while the pseudo-detections are found on the input image.
You can use --checksn and --checksegmentation to see if your chosen value
is reasonable or not.

--checksn
Save the S/N values of the clumps over the sky and detected regions into sep-
arate tables. If --tableformat is a FITS format, each table will be written
into a separate extension of one file suffixed with _clumpsn.fits. If it is plain
text, a separate file will be made for each table (ending in _clumpsn_sky.txt
and _clumpsn_det.txt). For more on --tableformat see Section 4.1.2.1 [In-
put/Output options], page 109.
You can use these tables to inspect the S/N values and their distribution (in
combination with the --checksegmentation option to see where the clumps
are). You can use Gnuastro’s Section 7.1 [Statistics], page 248, to make a
histogram of the distribution (ready for plotting in a text file, or a crude ASCII-
art demonstration on the command-line).
With this option, Segment will abort as soon as the two tables are created.
This allows you to inspect the steps leading to the final S/N quantile threshold,
this behavior can be disabled with --continueaftercheck.

--minnumfalse=INT
The minimum number of clumps over undetected (Sky) regions to identify the
requested Signal-to-Noise ratio threshold. Operationally, this is almost identi-
cal to NoiseChisel’s --minnumfalse option (Section 7.2.1.2 [Detection options],
page 275). Please see the descriptions there for more.
The quantile of the signal-to-noise ratio distribution of clumps in undetected regions, used to define true clumps. After identifying all the usable clumps in the undetected regions of the dataset, the given quantile of their signal-to-noise ratios is used to define the signal-to-noise ratio of a "true" clump. Effectively, this can be seen as an inverse p-value measure. See Figure 9 and Section 3.2.1 of Akhlaghi and Ichikawa [2015] (https://arxiv.org/abs/1505.01664) for a complete explanation. The full distribution of clump signal-to-noise ratios over the undetected areas can be saved into a table with --checksn option and visually inspected with --checksegmentation.

Keep a clump whose maximum (minimum if --minima is called) flux is 8-connected to a river pixel. By default such clumps over detections are considered to be noise and are removed irrespective of their brightness (see Section 8.1.3 [Brightness, Flux, Magnitude and Surface brightness], page 338). Over large profiles, that sink into the noise very slowly, noise can cause part of the profile (which was flat without noise) to become a very large and with a very high Signal to noise ratio. In such cases, the pixel with the maximum flux in the clump will be immediately touching a river pixel.

The signal-to-noise threshold for true clumps. If this option is given, then the segmentation options above will be ignored and the given value will be directly used to identify true clumps over the detections. This can be useful if you have a large dataset with similar noise properties. You can find a robust signal-to-noise ratio based on a (sufficiently large) smaller portion of the dataset. Afterwards, with this option, you can speed up the processing on the whole dataset. Other scenarios where this option may be useful is when the image might not contain enough/any Sky regions.

Threshold (multiple of the sky standard deviation added with the sky) to stop growing true clumps. Once true clumps are found, they are set as the basis to segment the detected region. They are grown until the threshold specified by this option.

The minimum length of a river between two grown clumps for it to be considered in signal-to-noise ratio estimations. Similar to --sminarea, if the length of the river is too short, the signal-to-noise ratio can be noisy and unreliable. Any existing rivers shorter than this length will be considered as non-existent, independent of their Signal to noise ratio. The clumps are grown on the input image, therefore this value can be smaller than the value given to --sminarea.
Recall that the clumps were defined on the convolved image so `--snminarea` should be larger.

```
-0 FLT
--objbordersn=FLT
```

The maximum Signal to noise ratio of the rivers between two grown clumps in order to consider them as separate ‘objects’. If the Signal to noise ratio of the river between two grown clumps is larger than this value, they are defined to be part of one ‘object’. Note that the physical reality of these ‘objects’ can never be established with one image, or even multiple images from one broadband filter. Any method we devise to define ‘object’s over a detected region is ultimately subjective.

Two very distant galaxies or satellites in one halo might lie in the same line of sight and be detected as clumps on one detection. On the other hand, the connection (through a spiral arm or tidal tail for example) between two parts of one galaxy might have such a low surface brightness that they are broken up into multiple detections or objects. In fact if you have noticed, exactly for this purpose, this is the only Signal to noise ratio that the user gives into NoiseChisel. The ‘true’ detections and clumps can be objectively identified from the noise characteristics of the image, so you don’t have to give any hand input Signal to noise ratio.

```
--checksegmentation
```

A file with the suffix `_seg.fits` will be created. This file keeps all the relevant steps in finding true clumps and segmenting the detections into multiple objects in various extensions. Having read the paper or the steps above. Examining this file can be an excellent guide in choosing the best set of parameters. Note that calling this function will significantly slow NoiseChisel. In verbose mode (without the `--quiet` option, see Section 4.1.2.3 [Operating mode options], page 114) the important steps (along with their extension names) will also be reported.

With this option, NoiseChisel will abort as soon as the two tables are created. This behavior can be disabled with `--continueaftercheck`.

### 7.3.1.3 Segment output

The main output of Segment are two label datasets (with integer types, separating the dataset’s elements into different classes). They have HDU/extension names of `CLUMPS` and `OBJECTS`.

Similar to all Gnuastro’s FITS outputs, the zero-th extension/HDU of the main output file only contains header keywords and image or table. It contains the Segment input files and parameters (option names and values) as FITS keywords. Note that if an option name is longer than 8 characters, the keyword name is the second word. The first word is `HIERARCH`. Also note that according to the FITS standard, the keyword names must be in capital letters, therefore, if you want to use Grep to inspect these keywords, use the `-i` option, like the example below.

```
$ astfits image_segmented.fits -h0 | grep -i snquant
```
By default, besides the `CLUMPS` and `OBJECTS` extensions, Segment's output will also contain the (technically redundant) input dataset and the sky standard deviation dataset (if it wasn't a constant number). This can help in visually inspecting the result when viewing the images as a "Multi-extension data cube" in SAO DS9 for example (see Section B.1.1 [Viewing multiextension FITS images], page 540). You can simply flip through the extensions and see the same region of the image and its corresponding clumps/object labels. It also makes it easy to feed the output (as one file) into MakeCatalog when you intend to make a catalog afterwards (see Section 7.4 [MakeCatalog], page 295. To remove these redundant extensions from the output (for example when designing a pipeline), you can use `--rawoutput`.

The `OBJECTS` and `CLUMPS` extensions can be used as input into Section 7.4 [MakeCatalog], page 295, to generate a catalog for higher-level analysis. If you want to treat each clump separately, you can give a very large value (or even a NaN, which will always fail) to the `--gthresh` option (for example `--gthresh=1e10` or `--gthresh=nan`), see Section 7.3.1.2 [Segmentation options], page 290.

For a complete definition of clumps and objects, please see Section 3.2 of Akhlaghi and Ichikawa [2015] (https://arxiv.org/abs/1505.01664) and Section 7.3.1.2 [Segmentation options], page 290. The clumps are "true" local maxima (minima if `--minima` is called) and their surrounding pixels until a local minimum/maximum (caused by noise fluctuations, or another "true" clump). Therefore it may happen that some of the input detections aren't covered by clumps at all (very diffuse objects without any strong peak), while some objects may contain many clumps. Even in those that have clumps, there will be regions that are too diffuse. The diffuse regions (within the input detected regions) are given a negative label (-1) to help you separate them from the undetected regions (with a value of zero).

Each clump is labeled with respect to its host object. Therefore, if an object has three clumps for example, the clumps within it have labels 1, 2 and 3. As a result, if an initial detected region has multiple objects, each with a single clump, all the clumps will have a label of 1. The total number of clumps in the dataset is stored in the `NCLUMPS` keyword of the `CLUMPS` extension and printed in the verbose output of Segment (when `--quiet` is not called).

The `OBJECTS` extension of the output will give a positive counter/label to every detected pixel in the input. As described in Akhlaghi and Ichikawa [2015], the true clumps are grown until a certain threshold. If the grown clumps touch other clumps and the connection is strong enough, they are considered part of the same `object`. Once objects (grown clumps) are identified, they are grown to cover the whole detected area.

The options to configure the output of Segment are listed below:

`--continueaftercheck`

Don't abort Segment after producing the check image(s). The usage of this option is identical to NoiseChisel's `--continueaftercheck` option (Section 7.2.1.1 [NoiseChisel input], page 273). Please see the descriptions there for more.

`--onlyclumps`

Abort Segment after finding true clumps and don't continue with finding options. Therefore, no `OBJECTS` extension will be present in the output. Each true clump in `CLUMPS` will get a unique label, but diffuse regions will still have a negative value.
To make a catalog of the clumps, the input detection map (where all the labels are one) can be fed into Section 7.4 [MakeCatalog], page 295, along with the input detection map to Segment (that only had a value of 1 for all detected pixels) with \texttt{--clumpscat}. In this way, MakeCatalog will assume all the clumps belong to a single “object”.

\texttt{--grownclumps}

In the output \texttt{CLUMPS} extension, store the grown clumps. If a detected region contains no clumps or only one clump, then it will be fully given a label of 1 (no negative valued pixels).

\texttt{--rawoutput}

Only write the \texttt{CLUMPS} and \texttt{OBJECTS} datasets in the output file. Without this option (by default), the first and last extensions of the output will the Sky-subtracted input dataset and the Sky standard deviation dataset (if it wasn’t a number). When the datasets are small, these redundant extensions can make it convenient to inspect the results visually or feed the output to Section 7.4 [MakeCatalog], page 295, for measurements. Ultimately both the input and Sky standard deviation datasets are redundant (you had them before running Segment). When the inputs are large/numerous, these extra dataset can be a burden.

\begin{center}
\textbf{Save space:} with the \texttt{--rawoutput}, Segment’s output will only be two labeled datasets (only containing integers). Since they have no noise, such datasets can be compressed very effectively (without any loss of data) with exceptionally high compression ratios. You can use the following command to compress it with the best ratio:

\$\texttt{gzip --best segment\_output.fits}$

The resulting \texttt{.fits.gz} file can then be fed into any of Gnuastro’s programs directly, without having to decompress it separately (it will just take them a little longer, because they have to decompress it internally before use).
\end{center}

\section*{7.4 MakeCatalog}

At the lowest level, a dataset (for example an image) is just a collection of values, placed after each other in any number of dimensions (for example an image is a 2D dataset). Each data-element (pixel) just has two properties: its position (relative to the rest) and its value. In higher-level analysis, an entire dataset (an image for example) is rarely treated as a singular entity\textsuperscript{10}. You usually want to know/measure the properties of the (separate) scientifically interesting targets that are embedded in it. For example the magnitudes, positions and elliptical properties of the galaxies that are in the image.

MakeCatalog is Gnuastro’s program for localized measurements over a dataset. In other words, MakeCatalog is Gnuastro’s program to convert low-level datasets (like images), to high level catalogs. The role of MakeCatalog in a scientific analysis and the benefits of its model (where detection/segmentation is separated from measurement) is dis-

\textsuperscript{10} You can derive the over-all properties of a complete dataset (1D table column, 2D image, or 3D data-cube) treated as a single entity with Gnuastro’s Statistics program (see Section 7.1 [Statistics], page 248).
cussed in Akhlaghi [2016] (https://arxiv.org/abs/1611.06387v1)\textsuperscript{11} and summarized in Section 7.4.1 [Detection and catalog production], page 297. We strongly recommend reading this short paper for a better understanding of this methodology. Understanding the effective usage of MakeCatalog, will thus also help effective use of other (lower-level) Gnuastro’s programs like Section 7.2 [NoiseChisel], page 269, or Section 7.3 [Segment], page 284.

It is important to define your regions of interest for measurements before running MakeCatalog. MakeCatalog is specialized in doing measurements accurately and efficiently. Therefore MakeCatalog will not do detection, segmentation, or defining apertures on requested positions in your dataset. Following Gnuastro’s modularity principle, there are separate and highly specialized and customizable programs in Gnuastro for these other jobs as shown below (for a usage example in a real-world analysis, see Section 2.2 [General program usage tutorial], page 24, and Section 2.3 [Detecting large extended targets], page 61).

- Section 6.2 [Arithmetic], page 199: Detection with a simple threshold.
- Section 7.2 [NoiseChisel], page 269: Advanced detection.
- Section 7.3 [Segment], page 284: Segmentation (substructure over detections).
- Section 8.1 [MakeProfiles], page 332: Aperture creation for known positions.

These programs will/can return labeled dataset(s) to be fed into MakeCatalog. A labeled dataset for measurement has the same size/dimensions as the input, but with integer valued pixels that have the label/counter for each sub-set of pixels that must be measured together. For example all the pixels covering one galaxy in an image, get the same label.

The requested measurements are then done on similarly labeled pixels. The final result is a catalog where each row corresponds to the measurements on pixels with a specific label. For example the flux weighted average position of all the pixels with a label of 42 will be written into the 42nd row of the output catalog/table’s central position column\textsuperscript{12}. Similarly, the sum of all these pixels will be the 42nd row in the brightness column, etc. Pixels with labels equal to, or smaller than, zero will be ignored by MakeCatalog. In other words, the number of rows in MakeCatalog’s output is already known before running it (the maximum value of the labeled dataset).

Before getting into the details of running MakeCatalog (in Section 7.4.5 [Invoking MakeCatalog], page 307, we’ll start with a discussion on the basics of its approach to separating detection from measurements in Section 7.4.1 [Detection and catalog production], page 297. A very important factor in any measurement is understanding its validity range, or limits. Therefore in Section 7.4.2 [Quantifying measurement limits], page 298, we’ll discuss how to estimate the reliability of the detection and basic measurements. This section will continue with a derivation of elliptical parameters from the labeled datasets in Section 7.4.3 [Measuring elliptical parameters], page 302. For those who feel MakeCatalog’s existing measurements/columns aren’t enough and would like to add further measurements, in Section 7.4.4 [Adding new columns to MakeCatalog], page 305, a checklist of steps is provided for readily adding your own new measurements/columns.

\textsuperscript{11} A published paper cannot undergo any more change, so this manual is the definitive guide.

\textsuperscript{12} See Section 7.4.3 [Measuring elliptical parameters], page 302, for a discussion on this and the derivation of positional parameters, which includes the center.
7.4.1 Detection and catalog production

Most existing common tools in low-level astronomical data-analysis (for example SExtractor\(^{13}\)) merge the two processes of detection and measurement (catalog production) in one program. However, in light of Gnuastro’s modularized approach (modeled on the Unix system) detection is separated from measurements and catalog production. This modularity is therefore new to many experienced astronomers and deserves a short review here. Further discussion on the benefits of this methodology can be seen in Akhlaghi [2016] (https://arxiv.org/abs/1611.06387v1).

As discussed in the introduction of Section 7.4 [MakeCatalog], page 295, detection (identifying which pixels to do measurements on) can be done with different programs. Their outputs (a labeled dataset) can be directly fed into MakeCatalog to do the measurements and write the result as a catalog/table. Beyond that, Gnuastro’s modular approach has many benefits that will become clear as you get more experienced in astronomical data analysis and want to be more creative in using your valuable data for the exciting scientific project you are working on. In short the reasons for this modularity can be classified as below:

- Simplicity/robustness of independent, modular tools: making a catalog is a logically separate process from labeling (detection, segmentation, or aperture production). A user might want to do certain operations on the labeled regions before creating a catalog for them. Another user might want the properties of the same pixels/objects in another image (another filter for example) to measure the colors or SED fittings. Here is an example of doing both: suppose you have images in various broad band filters at various resolutions and orientations. The image of one color will thus not lie exactly on another or even be in the same scale. However, it is imperative that the same pixels be used in measuring the colors of galaxies.

To solve the problem, NoiseChisel can be run on the reference image to generate the labeled detection image. Afterwards, the labeled image can be warped into the grid of the other color (using Section 6.4 [Warp], page 238). MakeCatalog will then generate the same catalog for both colors (with the different labeled images). It is currently customary to warp the images to the same pixel grid, however, modification of the scientific dataset is very harmful for the data and creates correlated noise. It is much more accurate to do the transformations on the labeled image.

- Complexity of a monolith: Adding in a catalog functionality to the detector program will add several more steps (and many more options) to its processing that can equally well be done outside of it. This makes following what the program does harder for the users and developers, it can also potentially add many bugs.

As an example, if the parameter you want to measure over one profile is not provided by the developers of MakeCatalog. You can simply open this tiny little program and add your desired calculation easily. This process is discussed in Section 7.4.4 [Adding new columns to MakeCatalog], page 305. However, if making a catalog was part of NoiseChisel for example, adding a new column/measurement would require a lot of energy to understand all the steps and internal structures of that huge program. It might even be so intertwined with its processing, that adding new columns might cause problems/bugs in its primary job (detection).

\(^{13}\) https://www.astromatic.net/software/sextractor
7.4.2 Quantifying measurement limits

No measurement on a real dataset can be perfect: you can only reach a certain level/limit of accuracy. Therefore, a meaningful (scientific) analysis requires an understanding of these limits for the dataset and your analysis tools: different datasets have different noise properties and different detection methods (one method/algorithm/software that is run with a different set of parameters is considered as a different detection method) will have different abilities to detect or measure certain kinds of signal (astronomical objects) and their properties in the dataset. Hence, quantifying the detection and measurement limitations with a particular dataset and analysis tool is the most crucial/critical aspect of any high-level analysis.

Here, we’ll review some of the most general limits that are important in any astronomical data analysis and how MakeCatalog makes it easy to find them. Depending on the higher-level analysis, there are more tests that must be done, but these are relatively low-level and usually necessary in most cases. In astronomy, it is common to use the magnitude (a unit-less scale) and physical units, see Section 8.1.3 [Brightness, Flux, Magnitude and Surface brightness], page 338. Therefore the measurements discussed here are commonly used in units of magnitudes.

Surface brightness limit (of whole dataset)

As we make more observations on one region of the sky, and add the observations into one dataset, the signal and noise both increase. However, the signal increase much faster than the noise: assuming you add $N$ datasets with equal exposure times, the signal will increases as a multiple of $N$, while noise increases as $\sqrt{N}$. Thus this increases the signal-to-noise ratio. Qualitatively, fainter (per pixel) parts of the objects/signal in the image will become more visible/detectable. The noise-level is known as the dataset’s surface brightness limit.

You can think of the noise as muddy water that is completely covering a flat ground. The signal (or astronomical objects in this analogy) will be summits/hills that start from the flat sky level (under the muddy water) and can sometimes reach outside of the muddy water. Let’s assume that in your first observation the muddy water has just been stirred and you can’t see anything through it. As you wait and make more observations/exposures, the mud settles down and the depth of the transparent water increases, making the summits visible. As the depth of clear water increases, the parts of the hills with lower heights (parts with lower surface brightness) can be seen more clearly. In this analogy, height (from the ground) is surface brightness and the height of the muddy water is your surface brightness limit.

The outputs of NoiseChisel include the Sky standard deviation ($\sigma$) on every group of pixels (a mesh) that were calculated from the undetected pixels in each tile, see Section 4.9 [Tessellation], page 141, and Section 7.2.1.3 [NoiseChisel output], page 282. Let’s take $\sigma_m$ as the median $\sigma$ over the successful meshes in the image (prior to interpolation or smoothing).

---

14 The ground is the sky value in this analogy, see Section 7.1.4 [Sky value], page 252. Note that this analogy only holds for a flat sky value across the surface of the image or ground.

15 Note that this muddy water analogy is not perfect, because while the water-level remains the same all over a peak, in data analysis, the Poisson noise increases with the level of data.
On different instruments, pixels have different physical sizes (for example in micro-meters, or spatial angle over the sky). Nevertheless, a pixel is our unit of data collection. In other words, while quantifying the noise, the physical or projected size of the pixels is irrelevant. We thus define the Surface brightness limit or \( \text{depth} \), in units of magnitude/pixel, of a data-set, with zeropoint magnitude \( z \), with the \( n \)th multiple of \( \sigma_m \) as (see Section 8.1.3 [Brightness, Flux, Magnitude and Surface brightness], page 338):

\[
SB_{\text{Pixel}} = -2.5 \times \log_{10} (n\sigma_m) + z
\]

As an example, the XDF survey covers part of the sky that the Hubble space telescope has observed the most (for 85 orbits) and is consequently very small (\( \sim 4 \) arcmin\(^2\)). On the other hand, the CANDELS survey, is one of the widest multi-color surveys covering several fields (about 720 arcmin\(^2\)) but its deepest fields have only 9 orbits observation. The depth of the XDF and CANDELS-deep surveys in the near infrared WFC3/F160W filter are respectively 34.40 and 32.45 magnitudes/pixel. In a single orbit image, this same field has a depth of 31.32. Recall that a larger magnitude corresponds to less brightness.

The low-level magnitude/pixel measurement above is only useful when all the datasets you want to use belong to one instrument (telescope and camera). However, you will often find yourself using datasets from various instruments with different pixel scales (projected pixel sizes). If we know the pixel scale, we can obtain a more easily comparable surface brightness limit in units of: magnitude/arcsec\(^2\). Let’s assume that the dataset has a zeropoint value of \( z \), and every pixel is \( p \) arcsec\(^2\) (so \( A/p \) is the number of pixels that cover an area of \( A \) arcsec\(^2\)). If the surface brightness is desired at the \( n \)th multiple of \( \sigma_m \), the following equation (in units of magnitudes per \( A \) arcsec\(^2\)) can be used:

\[
SB_{\text{Projected}} = -2.5 \times \log_{10} \left( n\sigma_m \sqrt{\frac{A}{p}} \right) + z
\]

The \( \sqrt{A/p} \) term comes from the fact that noise is added in RMS: if you add three datasets with noise \( \sigma_1, \sigma_2 \) and \( \sigma_3 \), the resulting noise level is \( \sigma_t = \sqrt{\sigma_1^2 + \sigma_2^2 + \sigma_3^2} \), so when \( \sigma_1 = \sigma_2 = \sigma_3 = \sigma \), then \( \sigma_t = \sqrt{3}\sigma \). As mentioned above, there are \( A/p \) pixels in the area \( A \). Therefore, as \( A/p \) increases, the surface brightness limiting magnitude will become brighter.

It is just important to understand that the surface brightness limit is the raw noise level, not the signal-to-noise. To get a feeling for it you can try these commands on any FITS image (let’s assume its called \texttt{image.fits}):

1. The output of the first command (\texttt{zero.fits}) will be the same size as the input, but all pixels will have a value of zero.
2. We then add an ideal noise to this image and warp it to a new pixel size (such that the area of the new pixels is \texttt{area_per_pixel} times the input’s), then we print the standard deviation of the raw noise and warped noise.

Please open the output images and compare them (their sizes,
or their pixel values) to get a good feeling of what is going on. Just note that
this demo only works when `area_per_pixel` is larger than one.

```bash
area_per_pixel=25
scale=$(echo $area_per_pixel | awk '{print sqrt($1)})
astarithmetic image.fits -h0 nan + isblank not -o zero.fits
astmknoise zero.fits -onoise.fits
astwarp --scale=1/$scale,1/$scale noise.fits -onoise-w.fits
std_raw=$(aststatistics noise.fits --std)
std_warped=$(aststatistics noise-w.fits --std)
echo;
echo "(warped pixel area) = $area_per_pixel x (pixel area)"
```

As you see in this example, this is thus just an extrapolation of the per-pixel
measurement $\sigma$. So it should be used with extreme care: for example the
dataset must have an approximately flat depth or noise properties overall. A
more accurate measure for each detection is known as the upper-limit magni-
tude which actually uses random positioning of each detection’s area/footprint,
see the respective item below. The upper-limit magnitude doesn’t extrapolate
and even accounts for correlated noise patterns in relation to that detection.
Therefore, the upper-limit magnitude is a much better measure of your dataset’s
surface brightness limit for each particular object.

MakeCatalog will calculate the input dataset’s $SB_{\text{Pixel}}$ and $SB_{\text{Projected}}$ and
write them as comments/meta-data in the output catalog(s). Just note that
$SB_{\text{Projected}}$ is only calculated if the input has World Coordinate System (WCS).

Completeness limit (of each detection)

As the surface brightness of the objects decreases, the ability to detect them
will also decrease. An important statistic is thus the fraction of objects of
similar morphology and brightness that will be identified with our detection
algorithm/parameters in the given image. This fraction is known as complete-
ess. For brighter objects, completeness is 1: all bright objects that might exist
over the image will be detected. However, as we go to objects of lower overall
surface brightness, we will fail to detect some, and gradually we are not able
to detect anything any more. For a given profile, the magnitude where the
completeness drops below a certain level (usually above 90%) is known as the
completeness limit.

Another important parameter in measuring completeness is purity: the frac-
tion of true detections to all true detections. In effect purity is the measure of
contamination by false detections: the higher the purity, the lower the contam-
ination. Completeness and purity are anti-correlated: if we can allow a large
number of false detections (that we might be able to remove by other means),
we can significantly increase the completeness limit.

One traditional way to measure the completeness and purity of a given sample is
by embedding mock profiles in regions of the image with no detection. However
in such a study we must be really careful to choose model profiles as similar to the target of interest as possible.

Magnitude measurement error (of each detection)

Any measurement has an error and this includes the derived magnitude for an object. Note that this value is only meaningful when the object’s magnitude is brighter than the upper-limit magnitude (see the next items in this list). As discussed in Section 8.1.3 [Brightness, Flux, Magnitude and Surface brightness], page 338, the magnitude \( M \) of an object with brightness \( B \) and zero point magnitude \( z \) can be written as:

\[
M = -2.5 \log_{10}(B) + z
\]

Calculating the derivative with respect to \( B \), we get:

\[
\frac{dM}{dB} = - \frac{2.5}{B \times \ln(10)}
\]

From the Taylor series (\( \Delta M = dM/dB \times \Delta B \)), we can write:

\[
\Delta M = \left| - \frac{2.5}{\ln(10)} \right| \times \frac{\Delta B}{B}
\]

But, \( \Delta B/B \) is just the inverse of the Signal-to-noise ratio (\( S/N \)), so we can write the error in magnitude in terms of the signal-to-noise ratio:

\[
\Delta M = \frac{2.5}{S/N \times \ln(10)}
\]

MakeCatalog uses this relation to estimate the magnitude errors. The signal-to-noise ratio is calculated in different ways for clumps and objects (see Akhlaghi and Ichikawa [2015] ([https://arxiv.org/abs/1505.01664](https://arxiv.org/abs/1505.01664))), but this single equation can be used to estimate the measured magnitude error afterwards for any type of target.

Upper limit magnitude (of each detection)

Due to the noisy nature of data, it is possible to get arbitrarily low values for a faint object’s brightness (or arbitrarily high magnitudes). Given the scatter caused by the dataset’s noise, values fainter than a certain level are meaningless: another similar depth observation will give a radically different value.

For example, while the depth of the image is 32 magnitudes/pixel, a measurement that gives a magnitude of 36 for a \( \sim 100 \) pixel object is clearly unreliable. In another similar depth image, we might measure a magnitude of 30 for it, and yet another might give 33. Furthermore, due to the noise scatter so close to the depth of the data-set, the total brightness might actually get measured as a negative value, so no magnitude can be defined (recall that a magnitude is a
base-10 logarithm). This problem usually becomes relevant when the detection labels were not derived from the values being measured (for example when you are estimating colors, see Section 7.4 [MakeCatalog], page 295).

Using such unreliable measurements will directly affect our analysis, so we must not use the raw measurements. But how can we know how reliable a measurement on a given dataset is?

When we confront such unreasonably faint magnitudes, there is one thing we can deduce: that if something actually exists here (possibly buried deep under the noise), it’s inherent magnitude is fainter than an upper limit magnitude. To find this upper limit magnitude, we place the object’s footprint (segmentation map) over random parts of the image where there are no detections, so we only have pure (possibly correlated) noise, along with undetected objects. Doing this a large number of times will give us a distribution of brightness values. The standard deviation ($\sigma$) of that distribution can be used to quantify the upper limit magnitude.

Traditionally, faint/small object photometry was done using fixed circular apertures (for example with a diameter of $N$ arc-seconds). Hence, the upper limit was like the depth discussed above: one value for the whole image. The problem with this simplified approach is that the number of pixels in the aperture directly affects the final distribution and thus magnitude. Also the image correlated noise might actually create certain patterns, so the shape of the object can also affect the final result result. Fortunately, with the much more advanced hardware and software of today, we can make customized segmentation maps for each object.

When requested, MakeCatalog will randomly place each target’s footprint over the dataset as described above and estimate the resulting distribution’s properties (like the upper limit magnitude). The procedure is fully configurable with the options in Section 7.4.5.2 [Upper-limit settings], page 311. If one value for the whole image is required, you can either use the surface brightness limit above or make a circular aperture and feed it into MakeCatalog to request an upper-limit magnitude for it\textsuperscript{16}.

### 7.4.3 Measuring elliptical parameters

The shape or morphology of a target is one of the most commonly desired parameters of a target. Here, we will review the derivation of the most basic/simple morphological parameters: the elliptical parameters for a set of labeled pixels. The elliptical parameters are: the (semi-)major axis, the (semi-)minor axis and the position angle along with the central position of the profile. The derivations below follow the SExtractor manual derivations with some added explanations for easier reading.

\textsuperscript{16} If you intend to make apertures manually and not use a detection map (for example from Section 7.3 [Segment], page 284), don’t forget to use the --upmaskfile to give NoiseChisel’s output (or any a binary map, marking detected pixels, see Section 7.2.1.3 [NoiseChisel output], page 282) as a mask. Otherwise, the footprints may randomly fall over detections, giving highly skewed distributions, with wrong upper-limit distributions. See The description of --upmaskfile in Section 7.4.5.2 [Upper-limit settings], page 311, for more.
Let’s begin with one dimension for simplicity: Assume we have a set of \( N \) values \( B_i \) (for example showing the spatial distribution of a target’s brightness), each at position \( x_i \). The simplest parameter we can define is the geometric center of the object (\( x_g \)) (ignoring the brightness values):

\[
x_g = \frac{\sum_i x_i}{N}.
\]

Moments are defined to incorporate both the value (brightness) and position of the data. The first moment can be written as:

\[
x = \frac{\sum_i B_i x_i}{\sum_i B_i}.
\]

This is essentially the weighted (by \( B_i \)) mean position. The geometric center (\( x_g \), defined above) is a special case of this with all \( B_i = 1 \). The second moment is essentially the variance of the distribution:

\[
x^2 = \frac{\sum_i B_i (x_i - \bar{x})^2}{\sum_i B_i} = \frac{\sum_i B_i x_i^2}{\sum_i B_i} - 2\bar{x} \frac{\sum_i B_i x_i}{\sum_i B_i} + \frac{\sum_i B_i x_i^2}{\sum_i B_i} - \bar{x}^2.
\]

The last step was done from the definition of \( \bar{x} \). Hence, the square root of \( \bar{x}^2 \) is the spatial standard deviation (along the one-dimension) of this particular brightness distribution (\( B_i \)). Crudely (or qualitatively), you can think of its square root as the distance (from \( \bar{x} \)) which contains a specific amount of the flux (depending on the \( B_i \) distribution). Similar to the first moment, the geometric second moment can be found by setting all \( B_i = 1 \). So while the first moment quantified the position of the brightness distribution, the second moment quantifies how that brightness is dispersed about the first moment. In other words, it quantifies how “sharp” the object’s image is.

Before continuing to two dimensions and the derivation of the elliptical parameters, let’s pause for an important implementation technicality. You can ignore this paragraph and the next two if you don’t want to implement these concepts. The basic definition (first definition of \( \bar{x}^2 \) above) can be used without any major problem. However, using this fraction requires two runs over the data: one run to find \( \bar{x} \) and another run to find \( \bar{x}^2 \) from \( \bar{x} \), this can be slow. The advantage of the last fraction above, is that we can estimate both the first and second moments in one run (since the \( -\bar{x}^2 \) term can easily be added later).

The logarithmic nature of floating point number digitization creates a complication however: suppose the object is located between pixels 10000 and 10020. Hence the target’s pixels are only distributed over 20 pixels (with a standard deviation < 20), while the mean has a value of \( \sim 10000 \). The \( \sum_i B_i^2 x_i^2 \) will go to very very large values while the individual pixel differences will be orders of magnitude smaller. This will lower the accuracy of our calculation due to the limited accuracy of floating point operations. The variance only depends on the distance of each point from the mean, so we can shift all position by a constant/arbitrary \( K \) which is much closer to the mean: \( x - K = \bar{x} - K \). Hence we can calculate the second order moment using:

\[
\bar{x}^2 = \frac{\sum_i B_i (x_i - K)^2}{\sum_i B_i} - (\bar{x} - K)^2
\]

The closer \( K \) is to \( \bar{x} \), the better (the sums of squares will involve smaller numbers), as long as \( K \) is within the object limits (in the example above: 10000 \( \leq K \leq 10020 \)), the
floating point error induced in our calculation will be negligible. For the most simplest implementation, MakeCatalog takes $K$ to be the smallest position of the object in each dimension. Since $K$ is arbitrary and an implementation/technical detail, we will ignore it for the remainder of this discussion.

In two dimensions, the mean and variances can be written as:

$$
\bar{x} = \frac{\sum_i B_i x_i}{B}, \quad \bar{x^2} = \frac{\sum_i B_i x_i^2}{\sum_i B_i} - \bar{x}^2
$$

$$
\bar{y} = \frac{\sum_i B_i y_i}{B}, \quad \bar{y^2} = \frac{\sum_i B_i y_i^2}{\sum_i B_i} - \bar{y}^2
$$

$$
\bar{xy} = \frac{\sum_i B_i x_i y_i}{\sum_i B_i} - \bar{x} \times \bar{y}
$$

If an elliptical profile’s major axis exactly lies along the $x$ axis, then $\bar{x^2}$ will be directly proportional with the profile’s major axis, $\bar{y^2}$ with its minor axis and $\bar{xy} = 0$. However, in reality we are not that lucky and (assuming galaxies can be parameterized as an ellipse) the major axis of galaxies can be in any direction on the image (in fact this is one of the core principles behind weak-lensing by shear estimation). So the purpose of the remainder of this section is to define a strategy to measure the position angle and axis ratio of some randomly positioned ellipses in an image, using the raw second moments that we have calculated above in our image coordinates.

Let’s assume we have rotated the galaxy by $\theta$, the new second order moments are:

$$
\bar{x_\theta} = \bar{x^2} \cos^2 \theta + \bar{y^2} \sin^2 \theta - 2\bar{xy} \cos \theta \sin \theta
$$

$$
\bar{y_\theta} = \bar{x^2} \sin^2 \theta + \bar{y^2} \cos^2 \theta + 2\bar{xy} \cos \theta \sin \theta
$$

$$
\bar{xy_\theta} = \bar{x^2} \cos \theta \sin \theta - \bar{y^2} \cos \theta \sin \theta + \bar{xy}(\cos^2 \theta - \sin^2 \theta)
$$

The best $\theta$ ($\theta_0$, where major axis lies along the $x_\theta$ axis) can be found by:

$$
\frac{\partial \bar{x_\theta}}{\partial \theta} \bigg|_{\theta_0} = 0
$$

Taking the derivative, we get:

$$
2 \cos \theta_0 \sin \theta_0 (\bar{y^2} - \bar{x^2}) + 2(\cos^2 \theta_0 - \sin^2 \theta_0)\bar{xy} = 0
$$

When $\bar{x^2} \neq \bar{y^2}$, we can write:

$$
\tan 2\theta_0 = 2 \frac{\bar{xy}}{\bar{x^2} - \bar{y^2}}.
$$
Chapter 7: Data analysis

MakeCatalog uses the standard C math library’s \texttt{atan2} function to estimate $\theta_0$, which we define as the position angle of the ellipse. To recall, this is the angle of the major axis of the ellipse with the $x$ axis. By definition, when the elliptical profile is rotated by $\theta_0$, then $x y_{\theta_0} = 0$, $x^{\theta_0}$ will be the extent of the maximum variance and $y^{\theta_0}$ the extent of the minimum variance (which are perpendicular for an ellipse). Replacing $\theta_0$ in the equations above for $x$ and $y$, we can get the semi-major ($A$) and semi-minor ($B$) lengths:

\[
A^2 \equiv x^{\theta_0} = \frac{x^2 + y^2}{2} + \sqrt{\left(\frac{x^2 - y^2}{2}\right)^2 + x y^2}
\]

\[
B^2 \equiv y^{\theta_0} = \frac{x^2 + y^2}{2} - \sqrt{\left(\frac{x^2 - y^2}{2}\right)^2 + x y^2}
\]

As a summary, it is important to remember that the units of $A$ and $B$ are in pixels (the standard deviation of a positional distribution) and that they represent the spatial light distribution of the object in both image dimensions (rotated by $\theta_0$). When the object cannot be represented as an ellipse, this interpretation breaks down: $x y_{\theta_0} \neq 0$ and $y^{\theta_0}$ will not be the direction of minimum variance.

7.4.4 Adding new columns to MakeCatalog

MakeCatalog is designed to allow easy addition of different measurements over a labeled image (see Akhlaghi [2016] (https://arxiv.org/abs/1611.06387v1)). A check-list style description of necessary steps to do that is described in this section. The common development characteristics of MakeCatalog and other Gnuastro programs is explained in Chapter 11 [Developing], page 516. We strongly encourage you to have a look at that chapter to greatly simplify your navigation in the code. After adding and testing your column, you are most welcome (and encouraged) to share it with us so we can add to the next release of Gnuastro for everyone else to also benefit from your efforts.

MakeCatalog will first pass over each label’s pixels two times and do necessary raw/internal calculations. Once the passes are done, it will use the raw information for filling the final catalog’s columns. In the first pass it will gather mainly object information and in the second run, it will mainly focus on the clumps, or any other measurement that needs an output from the first pass. These two passes are designed to be raw summations: no extra processing. This will allow parallel processing and simplicity/clarity. So if your new calculation, needs new raw information from the pixels, then you will need to also modify the respective \texttt{mkcatalog_first_pass} and \texttt{mkcatalog_second_pass} functions (both in bin/mkcatalog/mkcatalog.c) and define new raw table columns in \texttt{main.h} (hopefully the comments in the code are clear enough).

In all these different places, the final columns are sorted in the same order (same order as Section 7.4.5 [Invoking MakeCatalog], page 307). This allows a particular column/option to be easily found in all steps. Therefore in adding your new option, be sure to keep it in the same relative place in the list in all the separate places (it doesn’t necessarily have to be in the end), and near conceptually similar options.
The `objectcols` and `clumpcols` enumerated variables (`enum`) define the raw/internal calculation columns. If your new column requires new raw calculations, add a row to the respective list. If your calculation requires any other settings parameters, you should add a variable to the `mkcatalogparams` structure.

If the new column needs raw calculations (an entry was added in `objectcols` and `clumpcols`), specify which inputs it needs in `ui_necessary_inputs`, similar to the other options. Afterwards, if your column includes any particular settings (you needed to add a variable to the `mkcatalogparams` structure in `main.h`), you should do the sanity checks and preparations for it here.

The `option_keys_enum` associates a unique value for each option to MakeCatalog. The options that have a short option version, the single character short comment is used for the value. Those that don't have a short option version, get a large integer automatically. You should add a variable here to identify your desired column.

This file specifies all the parameters for the GNU C library, Argp structure that is in charge of reading the user's options. To define your new column, just copy an existing set of parameters and change the first, second and 5th values (the only ones that differ between all the columns), you should use the macro you defined in `ui.h` here.

This file contains the main definition and high-level calculation of your new column through the `columns_define_alloc` and `columns_fill` functions. In the first, you specify the basic information about the column: its name, units, comments, type (see Section 4.6 [Numeric data types], page 130) and how it should be printed if the output is a text file. You should also specify the raw/internal columns that are necessary for this column here as the many existing examples show. Through the types for objects and rows, you can specify if this column is only for clumps, objects or both.

The second main function (`columns_fill`) writes the final value into the appropriate column for each object and clump. As you can see in the many existing examples, you can define your processing on the raw/internal calculations here and save them in the output.

This file contains the low-level parsing functions. To be optimized, the parsing is done in parallel through the `mkcatalog_single_object` function. This function initializes the necessary arrays and calls the lower-level `parse_objects` and `parse_clumps` for actually going over the pixels. They are all heavily commented, so you should be able to follow where to add your necessary low-level calculations.

Update this manual and add a description for the new column.
7.4.5 Invoking MakeCatalog

MakeCatalog will do measurements and produce a catalog from a labeled dataset and optional values dataset(s). The executable name is `astmkcatalog` with the following general template

```
$ astmkcatalog [OPTION ...] InputImage.fits
```

One line examples:

```
## Create catalog with RA, Dec, Magnitude and Magnitude error, 
## from Segment's output:
$ astmkcatalog --ra --dec --magnitude --magnitudeerr seg-out.fits

## Same catalog as above (using short options):
$ asmkcatalog -rdmG seg-out.fits

## Write the catalog to a text table:
$ astmkcatalog -mpQ seg-out.fits --output=cat.txt

## Output columns specified in 'columns.conf':
$ astmkcatalog --config=columns.conf seg-out.fits

## Use object and clump labels from a K-band image, but pixel values
## from an i-band image.
$ astmkcatalog K_segmented.fits --hdu=DETECTIONS --clumpscat
   \n   --clumpsfile=K_segmented.fits --clumpshdu=CLUMPS \n   --valuesfile=i_band.fits
```

If MakeCatalog is to do processing (not printing help or option values), an input labeled image should be provided. The options described in this section are those that are particular to MakeProfiles. For operations that MakeProfiles shares with other programs (mainly involving input/output or general processing steps), see Section 4.1.2 [Common options], page 109. Also see Chapter 4 [Common program behavior], page 105, for some general characteristics of all Gnuastro programs including MakeCatalog.

The various measurements/columns of MakeCatalog are requested as options, either on the command-line or in configuration files, see Section 4.2 [Configuration files], page 120. The full list of available columns is available in Section 7.4.5.3 [MakeCatalog measurements], page 313. Depending on the requested columns, MakeCatalog needs more than one input dataset, for more details, please see Section 7.4.5.1 [MakeCatalog inputs and basic settings], page 307. The upper-limit measurements in particular need several configuration options which are thoroughly discussed in Section 7.4.5.2 [Upper-limit settings], page 311. Finally, in Section 7.4.5.4 [MakeCatalog output], page 324, the output file(s) created by MakeCatalog are discussed.

7.4.5.1 MakeCatalog inputs and basic settings

MakeCatalog works by using a localized/labeled dataset (see Section 7.4 [MakeCatalog], page 295). This dataset maps/labels pixels to a specific target (row number in the final catalog) and is thus the only necessary input dataset to produce a minimal catalog in any situation. Because it only has labels/counters, it must have an integer type (see Section 4.6
When the requested measurements only need this dataset (for example \texttt{--geox}, \texttt{--geoy}, or \texttt{--geoarea}), MakeCatalog won’t read any more datasets.

Low-level measurements that only use the labeled image are rarely sufficient for any high-level science case. Therefore necessary input datasets depend on the requested columns in each run. For example, let’s assume you want the brightness/magnitude and signal-to-noise ratio of your labeled regions. For these columns, you will also need to provide an extra dataset containing values for every pixel of the labeled input (to measure brightness) and another for the Sky standard deviation (to measure error). All such auxiliary input files have to have the same size (number of pixels in each dimension) as the input labeled image. Their numeric data type is irrelevant (they will be converted to 32-bit floating point internally). For the full list of available measurements, see Section 7.4.5.3 [MakeCatalog measurements], page 313.

The “values” dataset is used for measurements like brightness/magnitude, or flux-weighted positions. If it is a real image, by default it is assumed to be already Sky-subtracted prior to running MakeCatalog. If it isn’t, you use the \texttt{--subtractsky} option to, so MakeCatalog reads and subtracts the Sky dataset before any processing. To obtain the Sky value, you can use the \texttt{--sky} option of Section 7.1 [Statistics], page 248, but the best recommended method is Section 7.2 [NoiseChisel], page 269, see Section 7.1.4 [Sky value], page 252.

MakeCatalog can also do measurements on sub-structures of detections. In other words, it can produce two catalogs. Following the nomenclature of Segment (see Section 7.3 [Segment], page 284), the main labeled input dataset is known as “object” labels and the (optional) sub-structure input dataset is known as “clumps”. If MakeCatalog is run with the \texttt{--clumpscat} option, it will also need a labeled image containing clumps, similar to what Segment produces (see Section 7.3.1.3 [Segment output], page 293). Since clumps are defined within detected regions (they exist over signal, not noise), MakeCatalog uses their boundaries to subtract the level of signal under them.

There are separate options to explicitly request a file name and HDU/extension for each of the required input datasets as fully described below (with the \texttt{--*file} format). When each dataset is in a separate file, these options are necessary. However, one great advantage of the FITS file format (that is heavily used in astronomy) is that it allows the storage of multiple datasets in one file. So in most situations (for example if you are using the outputs of Section 7.2 [NoiseChisel], page 269, or Section 7.3 [Segment], page 284), all the necessary input datasets can be in one file.

When none of the \texttt{--*file} options are given, MakeCatalog will assume the necessary input datasets are in the file given as its argument (without any option). When the Sky or Sky standard deviation datasets are necessary and the only \texttt{--*file} option called is \texttt{--valuesfile}, MakeCatalog will search for these datasets (with the default/given HDUs) in the file given to \texttt{--valuesfile} (before looking into the main argument file).

When the clumps image (necessary with the \texttt{--clumpscat} option) is used, MakeCatalog looks into the (possibly existing) \texttt{NUMLABS} keyword for the total number of clumps in the image (irrespective of how many objects there are). If its not present, it will count them and possibly re-label the clumps so the clump labels always start with 1 and finish with the total number of clumps in each object. The re-labeled clumps image will be stored with the \texttt{-clumps-relab.fits} suffix. This can slightly slow-down the run.
Note that `NUMLABS` is automatically written by Segment in its outputs, so if you are feeding Segment’s clump labels, you can benefit from the improved speed. Otherwise, if you are creating the clumps label dataset manually, it may be good to include the `NUMLABS` keyword in its header and also be sure that there is no gap in the clump labels. For example if an object has three clumps, they are labeled as 1, 2, 3. If they are labeled as 1, 3, 4, or any other combination of three positive integers that aren’t an increment of the previous, you might get unknown behavior.

It may happen that your labeled objects image was created with a program that only outputs floating point files. However, you know it only has integer valued pixels that are stored in a floating point container. In such cases, you can use Gnuastro’s Arithmetic program (see Section 6.2 [Arithmetic], page 199) to change the numerical data type of the image (`float.fits`) to an integer type image (`int.fits`) with a command like below:

```
$ astarithmetic float.fits int32 --output=int.fits
```

To summarize: if the input file to MakeCatalog is the default/full output of Segment (see Section 7.3.1.3 [Segment output], page 293) you don’t have to worry about any of the `--file` options below. You can just give Segment’s output file to MakeCatalog as described in Section 7.4.5 [Invoking MakeCatalog], page 307. To feed NoiseChisel’s output into MakeCatalog, just change the labeled dataset’s header (with `--hdul=DETECTIONS`). The full list of input dataset options and general setting options are described below.

- `l STR`
  `-l STR`
  The file containing the labeled clumps dataset when `--clumps` is called (see Section 7.4.5.4 [MakeCatalog output], page 324). When `--clumps` is called, but this option isn’t, MakeCatalog will look into the main input file (given as an argument) for the required extension/HDU (value to `--clumpshdu`).

- `--clumpshdu=STR`
  The HDU/extension of the clump labels dataset. Only pixels with values above zero will be considered. The clump labels dataset has to be an integer data type (see Section 4.6 [Numeric data types], page 130) and only pixels with a value larger than zero will be used. See Section 7.3.1.3 [Segment output], page 293, for a description of the expected format.

- `v STR`
  `-v STR`
  The file name of the (sky-subtracted) values dataset. When any of the columns need values to associate with the input labels (for example to measure the brightness/magnitude of a galaxy), MakeCatalog will look into a “values” for the respective pixel values. In most common processing, this is the actual astronomical image that the labels were defined, or detected, over. The HDU/extension of this dataset in the given file can be specified with `--valueshdu`. If this option is not called, MakeCatalog will look for the given extension in the main input file.

- `--valueshdu=STR/INT`
  The name or number (counting from zero) of the extension containing the “values” dataset, see the descriptions above and those in `--valuesfile` for more.
Sky value as a single number, or the file name containing a dataset (different values per pixel or tile). The Sky dataset is only necessary when `--subtractsky` is called or when a column directly related to the Sky value is requested (currently `--sky`). This dataset may be a tessellation, with one element per tile (see `--oneelempertile` of NoiseChisel’s Section 4.1.2.2 [Processing options], page 112).

When the Sky dataset is necessary but this option is not called, MakeCatalog will assume it is an HDU/extension (specified by `--skyhdu`) in one of the already given files. First it will look for it in the `--valuesfile` (if it is given) and then the main input file (given as an argument).

By default the values dataset is assumed to be already Sky subtracted, so this dataset is not necessary for many of the columns.

`--skyhdu=STR`
HDU/extension of the Sky dataset, see `--skyfile`.

`--subtractsky`
Subtract the sky value or dataset from the values file prior to any processing.

Sky standard deviation value as a single number, or the file name containing a dataset (different values per pixel or tile). With the `--variance` option you can tell MakeCatalog to interpret this value/dataset as a variance image, not standard deviation.

**Important note:** This must only be the SKY standard deviation or variance (not including the signal’s contribution to the error). In other words, the final standard deviation of a pixel depends on how much signal there is in it. MakeCatalog will find the amount of signal within each pixel (while subtracting the Sky, if `--subtractsky` is called) and account for the extra error due to it’s value (signal). Therefore if the input standard deviation (or variance) image also contains the contribution of signal to the error, then the final error measurements will be over-estimated.

`--stdhdu=STR`
The HDU of the Sky value standard deviation image.

`--variance`
The dataset given to `--stdfile` (and `--stdhdu` has the Sky variance of every pixel, not the Sky standard deviation.

`--forcereadstd`
Read the input STD image even if it is not required by any of the requested columns. This is because some of the output catalog’s metadata may need it, for example to calculate the dataset’s surface brightness limit (see Section 7.4.2 [Quantifying measurement limits], page 298, configured with `--sfmagarea` and `--sfmagnsigma` in Section 7.4.5.4 [MakeCatalog output], page 324).
Chapter 7: Data analysis

-z FLT
--zeropoint=FLT
The zero point magnitude for the input image, see Section 8.1.3 [Brightness, Flux, Magnitude and Surface brightness], page 338.

--sigmaclip FLT,FLT
The sigma-clipping parameters when any of the sigma-clipping related columns are requested (for example --sigclip-median or --sigclip-number).
This option takes two values: the first is the multiple of $\sigma$, and the second is the termination criteria. If the latter is larger than 1, it is read as an integer number and will be the number of times to clip. If it is smaller than 1, it is interpreted as the tolerance level to stop clipping. See Section 7.1.3 [Sigma clipping], page 251, for a complete explanation.

--fracsum=FLT[,FLT]
The fractions of summed flux in objects or clumps to be used in the --fracsumarea1 and --fracsumarea2 columns, see Section 7.4.5.3 [MakeCatalog measurements], page 313. The values must be larger than 0 and smaller than 1. When only --fracsumarea1 is requested, one value must be given to this option, but if --fracsumarea2 is also requested, two values must be given here. The values can be written as simple floating point numbers, or as fractions, for example 0.25, 0.75 and 0.25, 3/4 are the same.

7.4.5.2 Upper-limit settings
The upper-limit magnitude was discussed in Section 7.4.2 [Quantifying measurement limits], page 298. Unlike other measured values/columns in MakeCatalog, the upper limit magnitude needs several extra parameters which are discussed here. All the options specific to the upper-limit measurements start with up for "upper-limit". The only exception is --envseed that is also present in other programs and is general for any job requiring random number generation in Gnuastro (see Section 8.2.1.4 [Generating random numbers], page 355).

One very important consideration in Gnuastro is reproducibility. Therefore, the values to all of these parameters along with others (like the random number generator type and seed) are also reported in the comments of the final catalog when the upper limit magnitude column is desired. The random seed that is used to define the random positions for each object or clump is unique and set based on the (optionally) given seed, the total number of objects and clumps and also the labels of the clumps and objects. So with identical inputs, an identical upper-limit magnitude will be found. However, even if the seed is identical, when the ordering of the object/clump labels differs between different runs, the result of upper-limit measurements will not be identical.

MakeCatalog will randomly place the object/clump footprint over the dataset. When the randomly placed footprint doesn’t fall on any object or masked region (see --upmaskfile) it will be used in the final distribution. Otherwise that particular random position will be ignored and another random position will be generated. Finally, when the distribution has the desired number of successfully measured random samples (--upnum) the distribution’s properties will be measured and placed in the catalog.
When the profile is very large or the image is significantly covered by detections, it might not be possible to find the desired number of samplings in a reasonable time. MakeProfiles will continue searching until it is unable to find a successful position (since the last successful measurement\(^\text{17}\)), for a large multiple of \(--\text{upnum}\) (currently\(^\text{18}\) this is 10). If \(--\text{upnum}\) successful samples cannot be found until this limit is reached, MakeCatalog will set the upper-limit magnitude for that object to NaN (blank).

MakeCatalog will also print a warning if the range of positions available for the labeled region is smaller than double the size of the region. In such cases, the limited range of random positions can artificially decrease the standard deviation of the final distribution. If your dataset can allow it (it is large enough), it is recommended to use a larger range if you see such warnings.

\texttt{--upmaskfile=STR}

File name of mask image to use for upper-limit calculation. In some cases (especially when doing matched photometry), the object labels specified in the main input and mask image might not be adequate. In other words they do not necessarily have to cover \textit{all} detected objects: the user might have selected only a few of the objects in their labeled image. This option can be used to ignore regions in the image in these situations when estimating the upper-limit magnitude. All the non-zero pixels of the image specified by this option (in the \texttt{--upmaskhdu} extension) will be ignored in the upper-limit magnitude measurements.

For example, when you are using labels from another image, you can give NoiseChisel’s objects image output for this image as the value to this option. In this way, you can be sure that regions with data do not harm your distribution. See Section 7.4.2 [Quantifying measurement limits], page 298, for more on the upper limit magnitude.

\texttt{--upmaskhdu=STR}

The extension in the file specified by \texttt{--upmask}.

\texttt{--upnum=INT}

The number of random samples to take for all the objects. A larger value to this option will give a more accurate result (asymptotically), but it will also slow down the process. When a randomly positioned sample overlaps with a detected/masked pixel it is not counted and another random position is found until the object completely lies over an undetected region. So you can be sure that for each object, this many samples over undetected objects are made. See the upper limit magnitude discussion in Section 7.4.2 [Quantifying measurement limits], page 298, for more.

\texttt{--uprange=INT,INT}

The range/width of the region (in pixels) to do random sampling along each dimension of the input image around each object’s position. This is not a mandatory option and if not given (or given a value of zero in a dimension),

\(^{17}\) The counting of failed positions restarts on every successful measurement.

\(^{18}\) In Gnuastro’s source, this constant number is defined as the \texttt{MKCATALOG_UPPERLIMIT_MAXFAILS_MULTIP} macro in \texttt{bin/mkcatalog/main.h}, see Section 3.2 [Downloading the source], page 84.
the full possible range of the dataset along that dimension will be used. This is useful when the noise properties of the dataset vary gradually. In such cases, using the full range of the input dataset is going to bias the result. However, note that decreasing the range of available positions too much will also artificially decrease the standard deviation of the final distribution (and thus bias the upper-limit measurement).

--envseed
Read the random number generator type and seed value from the environment (see Section 8.2.1.4 [Generating random numbers], page 355). Random numbers are used in calculating the random positions of different samples of each object.

--upsigmaclip=FLT,FLT
The raw distribution of random values will not be used to find the upper-limit magnitude, it will first be $\sigma$-clipped (see Section 7.1.3 [Sigma clipping], page 251) to avoid outliers in the distribution (mainly the faint undetected wings of bright/large objects in the image). This option takes two values: the first is the multiple of $\sigma$, and the second is the termination criteria. If the latter is larger than 1, it is read as an integer number and will be the number of times to clip. If it is smaller than 1, it is interpreted as the tolerance level to stop clipping. See Section 7.1.3 [Sigma clipping], page 251, for a complete explanation.

--upnsigma=FLT
The multiple of the final ($\sigma$-clipped) standard deviation (or $\sigma$) used to measure the upper-limit brightness or magnitude.

--checkuplim=INT[,INT]
Print a table of positions and measured values for all the full random distribution used for one particular object or clump. If only one integer is given to this option, it is interpreted to be an object’s label. If two values are given, the first is the object label and the second is the ID of requested clump within it. The output is a table with three columns (its type is determined with the --tableformat option, see Section 4.1.2.1 [Input/Output options], page 109). The first two columns are the position of the first pixel in each random sampling of this particular object/clump. The third column is the measured flux over that region. If the region overlapped with a detection or masked pixel, then its measured value will be a NaN (not-a-number). The total number of rows is thus unknown, but you can be sure that the number of rows with non-NaN measurements is the number given to the --upnum option.

7.4.5.3 MakeCatalog measurements
The final group of options particular to MakeCatalog are those that specify which measurements/columns should be written into the final output table. The current measurements in MakeCatalog are those which only produce one final value for each label (for example its total brightness: a single number). All the different label’s measurements can be written as one column in a final table/catalog that contains other columns for other similar single-number measurements.
In this case, all the different label’s measurements can be written as one column in a final table/catalog that contains other columns for other similar single-number measurements. The majority of this section is devoted to MakeCatalog’s single-valued measurements. However, MakeCatalog can also do measurements that produce more than one value for each label. Currently the only such measurement is generation of spectra from 3D cubes with the \texttt{--spectrum} option and it is discussed in the end of this section.

Command-line options are used to identify which measurements you want in the final catalog(s) and in what order. If any of the options below is called on the command line or in any of the configuration files, it will be included as a column in the output catalog. The order of the columns is in the same order as the options were seen by MakeCatalog (see Section 4.2.2 [Configuration file precedence], page 121). Some of the columns apply to both “objects” and “clumps” and some are particular to only one of them (for the definition of “objects” and “clumps”, see Section 7.3 [Segment], page 284). Columns/options that are unique to one catalog (only objects, or only clumps), are explicitly marked with [Objects] or [Clumps] to specify the catalog they will be placed in.

\textbf{--i} \textbf{--ids}
This is a unique option which can add multiple columns to the final catalog(s). Calling this option will put the object IDs (\texttt{--objid}) in the objects catalog and host-object-ID (\texttt{--hostobjid}) and ID-in-host-object (\texttt{--idinhostobj}) into the clumps catalog. Hence if only object catalogs are required, it has the same effect as \texttt{--objid}.

\textbf{--objid} [Objects] ID of this object.

\textbf{-j} \textbf{--hostobjid}
[Clumps] The ID of the object which hosts this clump.

\textbf{--idinhostobj}
[Clumps] The ID of this clump in its host object.

\textbf{-x} \textbf{--x}
The flux weighted center of all objects and clumps along the first FITS axis (horizontal when viewed in SAO ds9), see \(\pi\) in Section 7.4.3 [Measuring elliptical parameters], page 302. The weight has to have a positive value (pixel value larger than the Sky value) to be meaningful! Specially when doing matched photometry, this might not happen: no pixel value might be above the Sky value. For such detections, the geometric center will be reported in this column (see \texttt{--geox}). You can use \texttt{--weightarea} to see which was used.

\textbf{-y} \textbf{--y}
The flux weighted center of all objects and clumps along the second FITS axis (vertical when viewed in SAO ds9). See \texttt{--x}.

\textbf{-z} \textbf{--z}
The flux weighted center of all objects and clumps along the third FITS axis. See \texttt{--x}.

\textbf{--geox}
The geometric center of all objects and clumps along the first FITS axis axis. The geometric center is the average pixel positions irrespective of their pixel values.
--geoy  The geometric center of all objects and clumps along the second FITS axis, see --geox.
--geoz  The geometric center of all objects and clumps along the third FITS axis, see --geox.
--minvx  Position of pixel with minimum value in objects and clumps, along the first FITS axis.
--maxvx  Position of pixel with minimum value in objects and clumps, along the first FITS axis.
--minvy  Position of pixel with minimum value in objects and clumps, along the first FITS axis.
--maxvy  Position of pixel with minimum value in objects and clumps, along the first FITS axis.
--minvz  Position of pixel with minimum value in objects and clumps, along the first FITS axis.
--maxvz  Position of pixel with minimum value in objects and clumps, along the first FITS axis.
--minx  The minimum position of all objects and clumps along the first FITS axis.
--maxx  The maximum position of all objects and clumps along the first FITS axis.
--miny  The minimum position of all objects and clumps along the second FITS axis.
--maxy  The maximum position of all objects and clumps along the second FITS axis.
--minz  The minimum position of all objects and clumps along the third FITS axis.
--maxz  The maximum position of all objects and clumps along the third FITS axis.
--clumpsx  [Objects] The flux weighted center of all the clumps in this object along the first FITS axis. See --x.
--clumpsy  [Objects] The flux weighted center of all the clumps in this object along the second FITS axis. See --x.
--clumpsz  [Objects] The flux weighted center of all the clumps in this object along the third FITS axis. See --x.
--clumpsgeox  [Objects] The geometric center of all the clumps in this object along the first FITS axis. See --geox.
--clumpsgeoy  [Objects] The geometric center of all the clumps in this object along the second FITS axis. See --geox.
--clumpsgeoz  [Objects] The geometric center of all the clumps in this object along the third FITS axis. See --geoz.
-r
--ra Flux weighted right ascension of all objects or clumps, see --x. This is just an alias for one of the lower-level --w1 or --w2 options. Using the FITS WCS keywords (CTYPE), MakeCatalog will determine which axis corresponds to the right ascension. If no CTYPE keywords start with RA, an error will be printed when requesting this column and MakeCatalog will abort.

-d
--dec Flux weighted declination of all objects or clumps, see --x. This is just an alias for one of the lower-level --w1 or --w2 options. Using the FITS WCS keywords (CTYPE), MakeCatalog will determine which axis corresponds to the declination. If no CTYPE keywords start with DEC, an error will be printed when requesting this column and MakeCatalog will abort.

--w1 Flux weighted first WCS axis of all objects or clumps, see --x. The first WCS axis is commonly used as right ascension in images.

--w2 Flux weighted second WCS axis of all objects or clumps, see --x. The second WCS axis is commonly used as declination in images.

--w3 Flux weighted third WCS axis of all objects or clumps, see --x. The third WCS axis is commonly used as wavelength in integral field unit data cubes.

--geow1 Geometric center in first WCS axis of all objects or clumps, see --geox. The first WCS axis is commonly used as right ascension in images.

--geow2 Geometric center in second WCS axis of all objects or clumps, see --geox. The second WCS axis is commonly used as declination in images.

--geow3 Geometric center in third WCS axis of all objects or clumps, see --geox. The third WCS axis is commonly used as wavelength in integral field unit data cubes.

--clumpsw1 [Objects] Flux weighted center in first WCS axis of all clumps in this object, see --x. The first WCS axis is commonly used as right ascension in images.

--clumpsw2 [Objects] Flux weighted declination of all clumps in this object, see --x. The second WCS axis is commonly used as declination in images.

--clumpsw3 [Objects] Flux weighted center in third WCS axis of all clumps in this object, see --x. The third WCS axis is commonly used as wavelength in integral field unit data cubes.

--clumpsgeow1 [Objects] Geometric center right ascension of all clumps in this object, see --geox. The first WCS axis is commonly used as right ascension in images.

--clumpsgeow2 [Objects] Geometric center declination of all clumps in this object, see --geox. The second WCS axis is commonly used as declination in images.
--clumpsgeow3
[Objects] Geometric center in third WCS axis of all clumps in this object, see --geox. The third WCS axis is commonly used as wavelength in integral field unit data cubes.

-b
--brightness
The brightness (sum of all pixel values), see Section 8.1.3 [Brightness, Flux, Magnitude and Surface brightness], page 338. For clumps, the ambient brightness (flux of river pixels around the clump multiplied by the area of the clump) is removed, see --riverave. So the sum of all the clumps brightness in the clump catalog will be smaller than the total clump brightness in the --clumpbrightness column of the objects catalog.

If no usable pixels are present over the clump or object (for example they are all blank), the returned value will be NaN (note that zero is meaningful).

--brightnesserr
The (1σ) error in measuring the brightness of objects or clumps.

--clumpbrightness
[Objects] The total brightness of the clumps within an object. This is simply the sum of the pixels associated with clumps in the object. If no usable pixels are present over the clump or object (for example they are all blank), the stored value will be NaN (note that zero is meaningful).

--brightnessnoriver
[Clumps] The Sky (not river) subtracted clump brightness. By definition, for the clumps, the average brightness of the rivers surrounding it are subtracted from it for a first order accounting for contamination by neighbors. In cases where you will be calculating the flux brightness difference later (one example below) the contamination will be (mostly) removed at that stage, which is why this column was added.

If no usable pixels are present over the clump or object (for example they are all blank), the stored value will be NaN (note that zero is meaningful).

--mean
The mean sky subtracted value of pixels within the object or clump. For clumps, the average river flux is subtracted from the sky subtracted mean.

--median
The median sky subtracted value of pixels within the object or clump. For clumps, the average river flux is subtracted from the sky subtracted median.

--maximum
The maximum value of pixels within the object or clump. When the label (object or clump) is larger than three pixels, the maximum is actually derived by the mean of the brightest three pixels, not the largest pixel value of the same label. This is because noise fluctuations can be very strong in the extreme values of the objects/clumps due to Poisson noise (which gets stronger as the mean gets higher). Simply using the maximum pixel value will create a strong scatter in results that depend on the maximum (for example the --fwhmobs option also uses this value internally).
--sigclip-number
The number of elements/pixels in the dataset after sigma-clipping the object or clump. The sigma-clipping parameters can be set with the --sigmaclip option described in Section 7.4.5.1 [MakeCatalog inputs and basic settings], page 307. For more on Sigma-clipping, see Section 7.1.3 [Sigma clipping], page 251.

--sigclip-median
The sigma-clipped median value of the object of clump’s pixel distribution. For more on sigma-clipping and how to define it, see --sigclip-number.

--sigclip-mean
The sigma-clipped mean value of the object of clump’s pixel distribution. For more on sigma-clipping and how to define it, see --sigclip-number.

--sigclip-std
The sigma-clipped standard deviation of the object of clump’s pixel distribution. For more on sigma-clipping and how to define it, see --sigclip-number.

-m
--magnitude
The magnitude of clumps or objects, see --brightness.

-e
--magnitudeerr
The magnitude error of clumps or objects. The magnitude error is calculated from the signal-to-noise ratio (see --sn and Section 7.4.2 [Quantifying measurement limits], page 298). Note that until now this error assumes uncorrelated pixel values and also does not include the error in estimating the aperture (or error in generating the labeled image).

For now these factors have to be found by other means. Task 14124 (https://savannah.gnu.org/task/index.php?14124) has been defined for work on adding these sources of error too.

--clumpsmagnitude
[Objects] The magnitude of all clumps in this object, see --clumpbrightness.

--upperlimit
The upper limit value (in units of the input image) for this object or clump. See Section 7.4.2 [Quantifying measurement limits], page 298, and Section 7.4.5.2 [Upper-limit settings], page 311, for a complete explanation. This is very important for the fainter and smaller objects in the image where the measured magnitudes are not reliable.

--upperlimitmag
The upper limit magnitude for this object or clump. See Section 7.4.2 [Quantifying measurement limits], page 298, and Section 7.4.5.2 [Upper-limit settings], page 311, for a complete explanation. This is very important for the fainter and smaller objects in the image where the measured magnitudes are not reliable.

--upperlimitonesigma
The 1σ upper limit value (in units of the input image) for this object or clump. See Section 7.4.2 [Quantifying measurement limits], page 298, and
Section 7.4.5.2 [Upper-limit settings], page 311, for a complete explanation. When --upnsigma=1, this column's values will be the same as --upperlimit.

--upperlimitsigma
The position of the total brightness measured within the distribution of randomly placed upperlimit measurements in units of the distribution's σ or standard deviation. See Section 7.4.2 [Quantifying measurement limits], page 298, and Section 7.4.5.2 [Upper-limit settings], page 311, for a complete explanation.

--upperlimitquantile
The position of the total brightness measured within the distribution of randomly placed upperlimit measurements as a quantile (value between 0 or 1). See Section 7.4.2 [Quantifying measurement limits], page 298, and Section 7.4.5.2 [Upper-limit settings], page 311, for a complete explanation. If the object is brighter than the brightest randomly placed profile, a value of inf is returned. If it is less than the minimum, a value of -inf is reported.

--upperlimitskew
This column contains the non-parametric skew of the σ-clipped random distribution that was used to estimate the upper-limit magnitude. Taking μ as the mean, ν as the median and σ as the standard deviation, the traditional definition of skewness is defined as: $(\mu - \nu)/\sigma$.

This can be a good measure to see how much you can trust the random measurements, or in other words, how accurately the regions with signal have been masked/detected. If the skewness is strong (and to the positive), then you can tell that you have a lot of undetected signal in the dataset, and therefore that the upper-limit measurement (and other measurements) are not reliable.

--riverave
[Clumps] The average brightness of the river pixels around this clump. River pixels were defined in Akhlaghi and Ichikawa 2015. In short they are the pixels immediately outside of the clumps. This value is used internally to find the brightness (or magnitude) and signal to noise ratio of the clumps. It can generally also be used as a scale to gauge the base (ambient) flux surrounding the clump. In case there was no river pixels, then this column will have the value of the Sky under the clump. So note that this value is not sky subtracted.

--rivernum
[Clumps] The number of river pixels around this clump, see --riverave.

--sn
The Signal to noise ratio (S/N) of all clumps or objects. See Akhlaghi and Ichikawa (2015) for the exact equations used.

--sky
The sky flux (per pixel) value under this object or clump. This is actually the mean value of all the pixels in the sky image that lie on the same position as the object or clump.

--std
The sky value standard deviation (per pixel) for this clump or object. This is the square root of the mean variance under the object, or the root mean square.
-C
--numclumps

[Objects] The number of clumps in this object.

-a
--area

The raw area (number of pixels/voxels) in any clump or object independent of what pixel it lies over (if it is NaN/blank or unused for example).

--areaarcsec2

The used (non-blank in values image) area of the labeled region in units of arcsec squared. This column is just the value of the --area column, multiplied by the area of each pixel in the input image (in units of arcsec^-2). Similar to the --ra or --dec columns, for this option to work, the objects extension used has to have a WCS structure.

--surfacebrightness

The surface brightness (in units of mag/arcsec^2) of the labeled region (objects or clumps). For more on the definition of the surface brightness, see Section 8.1.3 [Brightness, Flux, Magnitude and Surface brightness], page 338.

--areaxy

Similar to --area, when the clump or object is projected onto the first two dimensions. This is only available for 3-dimensional datasets. When working with Integral Field Unit (IFU) datasets, this projection onto the first two dimensions would be a narrow-band image.

--fwhmobs

The full width at half maximum (in units of pixels, along the semi-major axis) of the labeled region (object or clump). The maximum value is estimated from the mean of the top-three pixels with the highest values, see the description under --maximum. The number of pixels that have half the value of that maximum are then found (value in the --halfmaxarea column) and a radius is estimated from the area. See the description under --halfradiusobs for more on converting area to radius along major axis.

Because of its non-parametric nature, this column is most reliable on clumps and should only be used in objects with great caution. This is because objects can have more than one clump (peak with true signal) and multiple peaks are not treated separately in objects, so the result of this column will be biased.

Also, because of its non-parametric nature, this FWHM it does not account for the PSF, and it will be strongly affected by noise if the object is faint. So when half the maximum value (which can be requested using the --maximum column) is too close to the local noise level (which can be requested using the --std column), the value returned in this column is meaningless (its just noise peaks which are randomly distributed over the area). You can therefore use the --maximum and --std columns to remove unreliable FWHMs. For example if a labeled region’s maximum is less than 2 times the sky standard deviation, the value will certainly be unreliable (half of that is 1σ!). For a more reliable value, this fraction should be around 4 (so half the maximum is 2σ).
--halfmaxarea
The number of pixels containing half the maximum flux within the labeled region. This option is used to estimate --fwhmobs, so please read the notes there for the caveats and necessary precautions.

--halfmaxsum
The sum of the pixel values containing half the maximum flux within the labeled region (or those that are counted in --halfmaxarea). This option uses the pixels within --fwhmobs, so please read the notes there for the caveats and necessary precautions.

--halfmaxsb
The surface brightness (in units of mag/arcsec$^2$) within the region that contains half the maximum value of the labeled region. For more on the definition of the surface brightness, see Section 8.1.3 [Brightness, Flux, Magnitude and Surface brightness], page 338.

--halfsumarea
The number of pixels that contain half the object or clump’s total sum of pixels (half the value in the --brightness column). To count this area, all the non-blank values associated with the given label (object or clump) will be sorted and summed in order (starting from the maximum), until the sum becomes larger than half the total sum of the label’s pixels.
This option is thus good for clumps (which are defined to have a single peak in their morphology), but for objects you should be careful because if they may have multiple peaks and the sorting by value doesn’t include morphology. So if the object includes multiple peaks/clumps at roughly the same level, then the area reported by this option will be distributed over all the peaks.

--halfsumsb
Surface brightness (in units of mag/arcsec$^2$) within the area that contains half the total sum of the label’s pixels (object or clump). For more on the definition of the surface brightness, see Section 8.1.3 [Brightness, Flux, Magnitude and Surface brightness], page 338.
This column just plugs in the values of half the value of the --brightness column and the --halfsumarea column, into the surface brightness equation. Therefore please see the description in --halfsumarea to understand the systematics of this column and potential biases.

--halfradiusobs
Radius (in units of pixels) derived from the area that contains half the total sum of the label’s pixels (value reported by --halfsumarea). If the area is $A_h$ and the axis ratio is $q$, then the value returned in this column is $\sqrt{A_h/(\pi q)}$.
This option is a good measure of the concentration of the observed (after PSF convolution and noisy) object or clump, But as described below it underestimates the effective radius. Also, it should be used in caution with objects, it reliable with clumps, see the note under --halfradiusarea.
Recall that in general, for an ellipse with semi-major axis $a$, semi-minor axis $b$, and axis ratio $q = b/a$ the area ($A$) is $A = \pi ab = \pi qa^2$. For a circle (where $q = 1$), this simplifies to the familiar $A = \pi a^2$. 

The suffix obs is added to the option name to avoid confusing this with a profile’s effective radius for Sérsic profiles, commonly written as $r_e$. For more on $r_e$, please see Section 8.1.1.4 [Galaxies], page 336. Therefore, when $r_e$ is meaningful for the target (the target is elliptically symmetric and can be parametrized as a Sérsic profile), $r_e$ should be derived from fitting the profile with a Sérsic function which has been convolved with the PSF. But from the equation above, you see that this radius is derived from the raw image’s labeled values (after convolution, with no parametric profile), so this column’s value will generally be (much) smaller than $r_e$, depending on the PSF, depth of the dataset, the morphology, or if a fraction of the profile falls on the edge of the image.

--fracsumarea1
--fracsumarea2
Similar to --halffsumarea, but for user-defined fractions of total sum. The fractions are given through the --fracs option (that can take two values) and is described in Section 7.4.5.1 [MakeCatalog inputs and basic settings], page 307. Recall that in --halffsumarea, the fraction is fixed to 0.5 so added with these two columns, you can sample three parts of the profile.

--fracradiusobs1
--fracradiusobs2
Similar to --halfradiusobs, but for user-defined fractions of total sum. The fractions are given through the --fracs option (that can take two values) and is described in Section 7.4.5.1 [MakeCatalog inputs and basic settings], page 307. Recall that in --halfradiusobs, the fraction is fixed to 0.5 so added with these two columns, you can sample three parts of the profile.

--clumpsarea
[Objects] The total area of all the clumps in this object.

--weightarea
The area (number of pixels) used in the flux weighted position calculations.

--geoarea
The area of all the pixels labeled with an object or clump. Note that unlike --area, pixel values are completely ignored in this column. For example, if a pixel value is blank, it won’t be counted in --area, but will be counted here.

--geoareaxy
Similar to --geoarea, when the clump or object is projected onto the first two dimensions. This is only available for 3-dimensional datasets. When working with Integral Field Unit (IFU) datasets, this projection onto the first two dimensions would be a narrow-band image.

-A
--semimajor
The pixel-value weighted root mean square (RMS) along the semi-major axis of the profile (assuming it is an ellipse) in units of pixels. See Section 7.4.3 [Measuring elliptical parameters], page 302.
--semiminor
The pixel-value weighted root mean square (RMS) along the semi-minor axis of the profile (assuming it is an ellipse) in units of pixels. See Section 7.4.3 [Measuring elliptical parameters], page 302.

--axisratio
The pixel-value weighted axis ratio (semi-minor/semi-major) of the object or clump.

--positionangle
The pixel-value weighted angle of the semi-major axis with the first FITS axis in degrees. See Section 7.4.3 [Measuring elliptical parameters], page 302.

--geosemimajor
The geometric (ignoring pixel values) root mean square (RMS) along the semi-major axis of the profile, assuming it is an ellipse, in units of pixels.

--geosemiminor
The geometric (ignoring pixel values) root mean square (RMS) along the semi-minor axis of the profile, assuming it is an ellipse, in units of pixels.

--geoaxisratio
The geometric (ignoring pixel values) axis ratio of the profile, assuming it is an ellipse.

--geopositionangle
The geometric (ignoring pixel values) angle of the semi-major axis with the first FITS axis in degrees.

Above, all of MakeCatalog’s single-valued measurements were listed. As mentioned in the start of this section, MakeCatalog can also do multi-valued measurements per label. Currently the only such measurement is the creation of spectra from 3D data cubes as discussed below:

--spectrum
Generate a spectrum (measurement along the first two FITS dimensions) for each label when the input dataset is a 3D data cube. With this option, a separate table/spectrum will be generated for every label. If the output is a FITS file, each label’s spectrum will be written into an extension of that file with a standard name of SPECTRUM_NN (the label will be replaced with NN). If the output is a plain text file, each label’s spectrum will be written into a separate file with the suffix spec-NN.txt. See Section 7.4.5.4 [MakeCatalog output], page 324, for more on specifying MakeCatalog’s output file.

The spectra will contain one row for every slice (third FITS dimension) of the cube. Since the physical nature of the third dimension is different, two types of spectra (along with their errors) are measured: 1) Sum of values in each slice that only have the requested label. 2) Sum of values on the 2D projection of the whole label (the area of this projection can be requested with the --areaxy column above).
Labels can overlap when they are projected onto the first two FITS dimensions (the spatial domain). To help separate them, MakeCatalog does a third measurement on each slice: the area, sum of values and error of all pixels that belong to other labels but overlap with the 2D projection. This can be used to see how reliable the emission line measurement is (on the projected spectra) and also if multiple lines (labeled regions) belong to the same physical object.

\section*{--inbetweenints}
Output will contain one row for all integers between 1 and the largest label in the input (irrespective of their existence in the input image). By default, MakeCatalog’s output will only contain rows with integers that actually corresponded to at least one pixel in the input dataset.

For example if the input’s only labeled pixel values are 11 and 13, MakeCatalog’s default output will only have two rows. If you use this option, it will have 13 rows and all the columns corresponding to integer identifiers that didn’t correspond to any pixel will be 0 or NaN (depending on context).

\section*{7.4.5.4 MakeCatalog output}
After it has completed all the requested measurements (see Section 7.4.5.3 [MakeCatalog measurements], page 313), MakeCatalog will store its measurements in table(s). If an output filename is given (see --output in Section 4.1.2.1 [Input/Output options], page 109), the format of the table will be deduced from the name. When it isn’t given, the input name will be appended with a \_cat suffix (see Section 4.10 [Automatic output], page 142) and its format will be determined from the \--tableformat option, which is also discussed in Section 4.1.2.1 [Input/Output options], page 109. \--tableformat is also necessary when the requested output name is a FITS table (recall that FITS can accept ASCII and binary tables, see Section 4.1.2.1 [Input/Output options], page 109). By default (when --spectrum isn’t called) only a single catalog/table will be created for “objects”, however, if --clumpscat is called, a secondary catalog/table will also be created. For more on “objects” and “clumps”, see Section 7.3 [Segment], page 284. In short, if you only have one set of labeled images, you don’t have to worry about clumps (they are deactivated by default).

When --spectrum is called, it is not mandatory to specify any single-valued measurement columns. In this case, the output will only be the spectra of each labeled region. See the description of --spectrum in Section 7.4.5.3 [MakeCatalog measurements], page 313.

The full list of MakeCatalog’s output options are elaborated below.

-C
\section*{--clumpscat}
Do measurements on clumps and produce a second catalog (only devoted to clumps). When this option is given, MakeCatalog will also look for a secondary labeled dataset (identifying substructure) and produce a catalog from that. For more on the definition on “clumps”, see Section 7.3 [Segment], page 284.

When the output is a FITS file, the objects and clumps catalogs/tables will be stored as multiple extensions of one FITS file. You can use Section 5.4 [Table], page 171, to inspect the column meta-data and contents in this case. However, in plain text format (see Section 4.8.2 [Gnuastro text table format], page 137),
it is only possible to keep one table per file. Therefore, if the output is a text 
file, two output files will be created, ending in _o.txt (for objects) and _c.txt 
(for clumps).

--noclumpsort
Don't sort the clumps catalog based on object ID (only relevant with 
--clumpscat). This option will benefit the performance\(^{19}\) of MakeCatalog 
when it is run on multiple threads and the position of the rows in the clumps 
catalog is irrelevant (for example you just want the number-counts).

MakeCatalog does all its measurements on each object independently and in 
parallel. As a result, while it is writing the measurements on each object’s 
clumps, it doesn’t know how many clumps there were in previous objects. Each 
thread will just fetch the first available row and write the information of clumps 
in order) starting from that row. After all the measurements are done, by 
default (when this option isn’t called), MakeCatalog will reorder/permute the 
catalog to have both the object and clump ID in an ascending order.

If you would like to order the catalog later (when its a plain text file), you can 
rerun the following command to sort the rows by object ID (and clump ID within 
each object), assuming they are respectively the first and second columns:

\[
\$ \text{awk} \ '!/^#/\!' \text{out}_c\text{.txt} \mid \text{sort} \ -g \ -k1,1 \ -k2,2 
\]

--sfmagnsigma=FLT
Value to multiply with the median standard deviation (from a MEDSTD keyword 
in the Sky standard deviation image) for estimating the surface brightness limit. 
Note that the surface brightness limit is only reported when a standard deviation 
image is read, in other words a column using it is requested (for example 
--sn) or --forcereadstd is called.

This value is a per-pixel value, not per object/clump and is not found over an 
area or aperture, like the common 5\(\sigma\) values that are commonly reported as a 
measure of depth or the upper-limit measurements (see Section 7.4.2 [Quantifying 
measurement limits], page 298).

--sfmagarea=FLT
Area (in arcseconds squared) to convert the per-pixel estimation of 
--sfmagnsigma in the comments section of the output tables. Note that the 
surface brightness limit is only reported when a standard deviation image is 
read, in other words a column using it is requested (for example --sn) or 
--forcereadstd is called.

Note that this is just a unit conversion using the World Coordinate System 
(WCS) information in the input’s header. It does not actually do any mea-

\(^{19}\) The performance boost due to --noclumpsort can only be felt when there are a huge number of objects. 
Therefore, by default the output is sorted to avoid misunderstandings or bugs in the user’s scripts 
when the user forgets to sort the outputs.
7.5 Match

Data can come from different telescopes, filters, software and even different configurations for a single software. As a result, one of the primary things to do after generating catalogs from each of these sources (for example with Section 7.4 [MakeCatalog], page 295), is to find which sources in one catalog correspond to which in the other(s). In other words, to ‘match’ the two catalogs with each other.

Gnuastro’s Match program is in charge of such operations. The nearest objects in the two catalogs, within the given aperture, will be found and given as output. The aperture can be a circle or an ellipse with any orientation.

7.5.1 Invoking Match

When given two catalogs, Match finds the rows that are nearest to each other within an input aperture. The executable name is astmatch with the following general template

```
$ astmatch [OPTION ...] input-1 input-2
```

One line examples:

```
## 1D wavelength match (within 5 angstroms) of the two inputs.  
## The wavelengths are in the 5th and 10th columns respectively.
$ astmatch --aperture=5e-10 --ccol1=5 --ccol2=10 in1.fits in2.txt

## Match the two catalogs with a circular aperture of width 2.
## (Units same as given positional columns).
## (By default two columns are given for ‘--ccol1’ and ‘--ccol2’,
## The number of values to these determines the dimensions).
$ astmatch --aperture=2 input1.txt input2.fits

## Similar to before, but the output is created by merging various
## columns from the two inputs: columns 1, RA, DEC from the first
## input, followed by all columns starting with ‘MAG’ and the ‘BRG’
## column from second input and finally the 10th from first input.
$ astmatch --aperture=2 input1.txt input2.fits
  \|--outcols=a1,aRA,aDEC,b/^MAG/,bBRG,a10

## Match the two catalogs within an elliptical aperture of 1 and 2
## arcseconds along RA and Dec respectively.
$ astmatch --aperture=1/3600,2/3600 in1.fits in2.txt

## Match the RA and DEC columns of the first input with the RA_D
## and DEC_D columns of the second within a 0.5 arcseconds aperture.
$ astmatch --ccol1=RA,DEC --ccol2=RA_D,DEC_D --aperture=0.5/3600
  \ in1.fits in2.fits

## Match in 3D (RA, Dec and Wavelength).
$ astmatch --ccol1=2,3,4 --ccol2=2,3,4 -a0.5/3600,0.5/3600,5e-10
  \ in1.fits in2.txt
```
Chapter 7: Data analysis

Match will find the rows that are nearest to each other in two catalogs (given some coordinate columns). Therefore two catalogs are necessary for input. However, they don’t necessarily have to be files: 1) the first catalog can also come from the standard input (for example a pipe, see Section 4.1.3 [Standard input], page 118); 2) when only one point is needed, you can use the --coord option to avoid creating a file for the second catalog. When the inputs are files, they can be plain text tables or FITS tables, for more see Section 4.8 [Tables], page 135.

Match follows the same basic behavior of all Gnuastro programs as fully described in Chapter 4 [Common program behavior], page 105. If the first input is a FITS file, the common --hdu option (see Section 4.1.2.1 [Input/Output options], page 109) should be used to identify the extension. When the second input is FITS, the extension must be specified with --hdu2.

When --quiet is not called, Match will print the number of matches found in standard output (on the command-line). When matches are found, by default, the output file(s) will be the re-arranged input tables such that the rows match each other: both output tables will have the same number of rows which are matched with each other. If --outcols is called, the output is a single table with rows chosen from either of the two inputs in any order. If the --logasoutput option is called, the output will be a single table with the contents of the log file, see below. If no matches are found, the columns of the output table(s) will have zero rows (with proper meta-data).

If no output file name is given with the --output option, then automatic output Section 4.10 [Automatic output], page 142, will be used to determine the output name(s). Depending on --tableformat (see Section 4.1.2.1 [Input/Output options], page 109), the output will then be a (possibly multi-extension) FITS file or (possibly two) plain text file(s). When the output is a FITS file, the default re-arranged inputs will be two extensions of the output FITS file. With --outcols and --logasoutput, the FITS output will be a single table (in one extension).

When the --log option is called (see Section 4.1.2.3 [Operating mode options], page 114), and there was a match, Match will also create a file named astmatch.fits (or astmatch.txt, depending on --tableformat, see Section 4.1.2.1 [Input/Output options], page 109) in the directory it is run in. This log table will have three columns. The first and second columns show the matching row/record number (counting from 1) of the first and second input catalogs respectively. The third column is the distance between the two matched positions. The units of the distance are the same as the given coordinates (given the possible ellipticity, see description of --aperture below). When --logasoutput is called, no log file (with a fixed name) will be created. In this case, the output file (possibly given by the --output option) will have the contents of this log file.

--log isn't thread-safe: As described above, when --logasoutput is not called, the Log file has a fixed name for all calls to Match. Therefore if a separate log is requested in two simultaneous calls to Match in the same directory, Match will try to write to the same file. This will cause problems like unreasonable log file, undefined behavior, or a crash.
-H STR
--hdu2=STR
The extension/HDU of the second input if it is a FITS file. When it isn’t a FITS file, this option’s value is ignored. For the first input, the common option --hdu must be used.

--outcols=STR
Columns (from both inputs) to write into a single matched table output. The value to --outcols must be a comma-separated list of strings. The first character of each string specifies the input catalog: a for the first and b for the second. The rest of the characters of the string will be directly used to identify the proper column(s) in the respective table. See Section 4.8.3 [Selecting table columns], page 140, for how columns can be specified in Gnuastro.

For example the output of --outcols=a1,bRA,bDEC will have three columns: the first column of the first input, along with the RA and DEC columns of the second input.

If the string after a or b is _all, then all the columns of the respective input file will be written in the output. For example the command below will print all the input columns from the first catalog along with the 5th column from the second:

    $ astmatch a.fits b.fits --outcols=a_all,b5

_all can be used multiple times, possibly on both inputs. Tip: if an input’s column is called _all (an unlikely name!) and you don’t want all the columns from that table the output, use its column number to avoid confusion.

Another example is given in the one-line examples above. Compared to the default case (where two tables with all their columns) are saved separately, using this option is much faster: it will only read and re-arrange the necessary columns and it will write a single output table. Combined with regular expressions in large tables, this can be a very powerful and convenient way to merge various tables into one.

When --coord is given, no second catalog will be read. The second catalog will be created internally based on the values given to --coord. So column names aren’t defined and you can only request integer column numbers that are less than the number of coordinates given to --coord. For example if you want to find the row matching RA of 1.2345 and Dec of 6.7890, then you should use --coord=1.2345,6.7890. But when using --outcols, you can’t give bRA, or b25.

-l
--logasoutput
The output file will have the contents of the log file: indexes in the two catalogs that match with each other along with their distance. See description above. When this option is called, a log file called astmatch.txt will not be created. With this option, the default output behavior (two tables containing the re-arranged inputs) will be
--notmatched
Write the non-matching rows into the outputs, not the matched ones. Note
that with this option, the two output tables will not necessarily have the same
number of rows. Therefore, this option cannot be called with --outcols.
--outcols prints mixed columns from both inputs, so they must all have the
same number of elements and must correspond to each other.

-c INT/STR[,INT/STR]
--ccol1=INT/STR[,INT/STR]
The coordinate columns of the first input. The number of dimensions for the
match is determined by the number of comma-separated values given to this
option. The values can be the column number (counting from 1), exact col-
umn name or a regular expression. For more, see Section 4.8.3 [Selecting table
columns], page 140. See the one-line examples above for some usages of this
option.

-C INT/STR[,INT/STR]
--ccol2=INT/STR[,INT/STR]
The coordinate columns of the second input. See the example in --ccol1 for
more.

-d FLT[,FLT]
--coord=FLT[,FLT]
Manually specify the coordinates to match against the given catalog. With this
option, Match will not look for a second input file/table and will directly use
the coordinates given to this option.
When this option is called, the output changes in the following ways: 1) when
--outcols is specified, for the second input, it can only accept integer numbers
that are less than the number of values given to this option, see description
of that option for more. 2) By default (when --outcols isn’t used), only the
matching row of the first table will be output (a single file), not two separate
files (one for each table).
This option is good when you have a (large) catalog and only want to match a
single coordinate to it (for example to find the nearest catalog entry to your de-
sired point). With this option, you can write the coordinates on the command-
line and thus avoid the need to make a single-row file.

-a FLT[,FLT[,FLT]]
--aperture=FLT[,FLT[,FLT]]
Parameters of the aperture for matching. The values given to this option can
be fractions, for example when the position columns are in units of degrees,
1/3600 can be used to ask for one arcsecond. The interpretation of the values
depends on the requested dimensions (determined from --ccol1 and --ccol2)
and how many values are given to this option.
When multiple objects are found within the aperture, the match is defined as
the nearest one. In a multi-dimensional dataset, when the aperture is a general
ellipse or ellipsoid (and not a circle or sphere), the distance is calculated in the
elliptical space along the major axis. For the definition of this distance, see \( r_{el} \)
in Section 8.1.1.1 [Defining an ellipse and ellipsoid], page 332.
1D match The aperture/interval can only take one value: half of the interval around each point (maximum distance from each point).

2D match In a 2D match, the aperture can be a circle, an ellipse aligned in the axes or an ellipse with a rotated major axis. To simplify the usage, you can determine the shape based on the number of free parameters for each.

1 number For example --aperture=2. The aperture will be a circle of the given radius. The value will be in the same units as the columns in --ccol1 and --ccol2).

2 numbers For example --aperture=3,4e-10. The aperture will be an ellipse (if the two numbers are different) with the respective value along each dimension. The numbers are in units of the first and second axis. In the example above, the semi-axis value along the first axis will be 3 (in units of the first coordinate) and along the second axis will be $4 \times 10^{-10}$ (in units of the second coordinate). Such values can happen if you are comparing catalogs of a spectra for example. If more than one object exists in the aperture, the nearest will be found along the major axis as described in Section 8.1.1.1 [Defining an ellipse and ellipsoid], page 332.

3 numbers For example --aperture=2,0.6,30. The aperture will be an ellipse (if the second value is not 1). The first number is the semi-major axis, the second is the axis ratio and the third is the position angle (in degrees). If multiple matches are found within the ellipse, the distance (to find the nearest) is calculated along the major axis in the elliptical space, see Section 8.1.1.1 [Defining an ellipse and ellipsoid], page 332.

3D match The aperture (matching volume) can be a sphere, an ellipsoid aligned on the three axes or a general ellipsoid rotated in any direction. To simplify the usage, the shape can be determined based on the number of values given to this option.

1 number For example --aperture=3. The matching volume will be a sphere of the given radius. The value is in the same units as the input coordinates.

3 numbers For example --aperture=4,5,6e-10. The aperture will be a general ellipsoid with the respective extent along each dimension. The numbers must be in the same units as each axis. This is very similar to the two number case of 2D inputs. See there for more.

6 numbers For example --aperture=4,0.5,0.6,10,20,30. The numbers represent the full general ellipsoid definition...
(in any orientation). For the definition of a general ellipsoid, see Section 8.1.1.1 [Defining an ellipse and ellipsoid], page 332. The first number is the semi-major axis. The second and third are the two axis ratios. The last three are the three Euler angles in units of degrees in the ZXZ order as fully described in Section 8.1.1.1 [Defining an ellipse and ellipsoid], page 332.
8 Modeling and fitting

In order to fully understand observations after initial analysis on the image, it is very important to compare them with the existing models to be able to further understand both the models and the data. The tools in this chapter create model galaxies and will provide 2D fittings to be able to understand the detections.

8.1 MakeProfiles

MakeProfiles will create mock astronomical profiles from a catalog, either individually or together in one output image. In data analysis, making a mock image can act like a calibration tool, through which you can test how successfully your detection technique is able to detect a known set of objects. There are commonly two aspects to detecting: the detection of the fainter parts of bright objects (which in the case of galaxies fade into the noise very slowly) or the complete detection of an over-all faint object. Making mock galaxies is the most accurate (and idealistic) way these two aspects of a detection algorithm can be tested. You also need mock profiles in fitting known functional profiles with observations.

MakeProfiles was initially built for extra galactic studies, so currently the only astronomical objects it can produce are stars and galaxies. We welcome the simulation of any other astronomical object. The general outline of the steps that MakeProfiles takes are the following:

1. Build the full profile out to its truncation radius in a possibly over-sampled array.
2. Multiply all the elements by a fixed constant so its total magnitude equals the desired total magnitude.
3. If \texttt{--individual} is called, save the array for each profile to a FITS file.
4. If \texttt{--nomerged} is not called, add the overlapping pixels of all the created profiles to the output image and abort.

Using input values, MakeProfiles adds the World Coordinate System (WCS) headers of the FITS standard to all its outputs (except PSF images!). For a simple test on a set of mock galaxies in one image, there is no need for the third step or the WCS information.

However in complicated simulations like weak lensing simulations, where each galaxy undergoes various types of individual transformations based on their position, those transformations can be applied to the different individual images with other programs. After all the transformations are applied, using the WCS information in each individual profile image, they can be merged into one output image for convolution and adding noise.

8.1.1 Modeling basics

In the subsections below, first a review of some very basic information and concepts behind modeling a real astronomical image is given. You can skip this subsection if you are already sufficiently familiar with these concepts.

8.1.1.1 Defining an ellipse and ellipsoid

The PSF, see Section 8.1.1.2 [Point spread function], page 334, and galaxy radial profiles are generally defined on an ellipse. Therefore, in this section we’ll start defining an ellipse on a pixelated 2D surface. Labeling the major axis of an ellipse $a$, and its minor axis with
b, the axis ratio is defined as: \( q \equiv b/a \). The major axis of an ellipse can be aligned in any direction, therefore the angle of the major axis with respect to the horizontal axis of the image is defined to be the position angle of the ellipse and in this book, we show it with \( \theta \).

Our aim is to put a radial profile of any functional form \( f(r) \) over an ellipse. Hence we need to associate a radius/distance to every point in space. Let’s define the radial distance \( r_{el} \) as the distance on the major axis to the center of an ellipse which is located at \( i_c \) and \( j_c \) (in other words \( r_{el} \equiv a \)). We want to find \( r_{el} \) of a point located at \( (i, j) \) (in the image coordinate system) from the center of the ellipse with axis ratio \( q \) and position angle \( \theta \). First the coordinate system is rotated\(^1\) by \( \theta \) to get the new rotated coordinates of that point \((i_r, j_r)\):

\[
\begin{align*}
i_r(i, j) &= +(i_c - i) \cos \theta + (j_c - j) \sin \theta \\
j_r(i, j) &= -(i_c - i) \sin \theta + (j_c - j) \cos \theta
\end{align*}
\]

Recall that an ellipse is defined by \((i_r/a)^2 + (j_r/b)^2 = 1\) and that we defined \( r_{el} \equiv a \). Hence, multiplying all elements of the ellipse definition with \( r_{el}^2 \) we get the elliptical distance at this point point located: \( r_{el} = \sqrt{i_r^2 + (j_r/q)^2} \). To place the radial profiles explained below over an ellipse, \( f(r_{el}) \) is calculated based on the functional radial profile desired.

An ellipse in 3D, or an ellipsoid (https://en.wikipedia.org/wiki/Ellipsoid), can be defined following similar principles as before. Labeling the major (largest) axis length as \( a \), the second and third (in a right-handed coordinate system) axis lengths can be labeled as \( b \) and \( c \). Hence we have two axis ratios: \( q_1 \equiv b/a \) and \( q_2 \equiv c/a \). The orientation of the ellipsoid can be defined from the orientation of its major axis. There are many ways to define 3D orientation and order matters. So to be clear, here we use the ZXZ (or \( Z_1X_2Z_3 \)) proper Euler angles (https://en.wikipedia.org/wiki/Euler_angles) to define the 3D orientation. In short, when a point is rotated in this order, we first rotate it around the Z axis (third axis) by \( \alpha \), then about the (rotated) X axis by \( \beta \) and finally about the (rotated) Z axis by \( \gamma \).

Following the discussion in Section 6.4.2 [Merging multiple warpings], page 241, we can define the full rotation with the following matrix multiplication. However, here we are rotating the coordinates, not the point. Therefore, both the rotation angles and rotation order are reversed. We are also not using homogeneous coordinates (see Section 6.4.1 [Warping basics], page 239) since we aren’t concerned with translation in this context:

\[
\begin{bmatrix}
i_r \\
j_r \\
k_r
\end{bmatrix} = 
\begin{bmatrix}
cos \gamma & sin \gamma & 0 \\
-sin \gamma & cos \gamma & 0 \\
0 & 0 & 1
\end{bmatrix}
\begin{bmatrix}
1 & 0 & 0 \\
0 & cos \beta & sin \beta \\
0 & -sin \beta & cos \beta
\end{bmatrix}
\begin{bmatrix}
cos \alpha & sin \alpha & 0 \\
-sin \alpha & cos \alpha & 0 \\
0 & 0 & 1
\end{bmatrix}
\begin{bmatrix}
i_c - i \\
j_c - j \\
k_c - k
\end{bmatrix}
\]

Recall that an ellipsoid can be characterized with \((i_r/a)^2 + (j_r/b)^2 + (k_r/c)^2 = 1\), so similar to before \((r_{el} \equiv a)\), we can find the ellipsoidal radius at pixel \((i, j, k)\) as: \( r_{el} = \sqrt{i_r^2 + (j_r/q_1)^2 + (k_r/q_2)^2} \).

---

\(^1\) Do not confuse the signs of \( sin \) with the rotation matrix defined in Section 6.4.1 [Warping basics], page 239. In that equation, the point is rotated, here the coordinates are rotated and the point is fixed.
MakeProfiles builds the profile starting from the nearest element (pixel in an image) in the dataset to the profile center. The profile value is calculated for that central pixel using monte carlo integration, see Section 8.1.1.5 [Sampling from a function], page 336. The next pixel is the next nearest neighbor to the central pixel as defined by \( r_{el} \). This process goes on until the profile is fully built upto the truncation radius. This is done fairly efficiently using a breadth first parsing strategy\(^2\) which is implemented through an ordered linked list.

Using this approach, we build the profile by expanding the circumference. Not one more extra pixel has to be checked (the calculation of \( r_{el} \) from above is not cheap in CPU terms). Another consequence of this strategy is that extending MakeProfiles to three dimensions becomes very simple: only the neighbors of each pixel have to be changed. Everything else after that (when the pixel index and its radial profile have entered the linked list) is the same, no matter the number of dimensions we are dealing with.

### 8.1.1.2 Point spread function

Assume we have a ‘point’ source, or a source that is far smaller than the maximum resolution (a pixel). When we take an image of it, it will ‘spread’ over an area. To quantify that spread, we can define a ‘function’. This is how the point spread function or the PSF of an image is defined. This ‘spread’ can have various causes, for example in ground based astronomy, due to the atmosphere. In practice we can never surpass the ‘spread’ due to the diffraction of the lens aperture. Various other effects can also be quantified through a PSF. For example, the simple fact that we are sampling in a discrete space, namely the pixels, also produces a very small ‘spread’ in the image.

Convolution is the mathematical process by which we can apply a ‘spread’ to an image, or in other words blur the image, see Section 6.3.1.1 [Convolution process], page 217. The Brightness of an object should remain unchanged after convolution, see Section 8.1.3 [Brightness, Flux, Magnitude and Surface brightness], page 338. Therefore, it is important that the sum of all the pixels of the PSF be unity. The PSF image also has to have an odd number of pixels on its sides so one pixel can be defined as the center. In MakeProfiles, the PSF can be set by the two methods explained below.

**Parametric functions**

A known mathematical function is used to make the PSF. In this case, only the parameters to define the functions are necessary and MakeProfiles will make a PSF based on the given parameters for each function. In both cases, the center of the profile has to be exactly in the middle of the central pixel of the PSF (which is automatically done by MakeProfiles). When talking about the PSF, usually, the full width at half maximum or FWHM is used as a scale of the width of the PSF.

**Gaussian**

In the older papers, and to a lesser extent even today, some researchers use the 2D Gaussian function to approximate the PSF of ground based images. In its most general form, a Gaussian function can be written as:

\[
 f(r) = a \exp\left( -\frac{(x - \mu)^2}{2\sigma^2} \right) + d
\]

Since the center of the profile is pre-defined, \( \mu \) and \( d \) are constrained. \( a \) can also be found because the function has to be normalized. So the only important parameter for MakeProfiles is the \( \sigma \). In the Gaussian function we have this relation between the FWHM and \( \sigma \):

\[
\text{FWHM}_g = 2\sqrt{2\ln2} \sigma \approx 2.35482\sigma
\]

**Moffat** The Gaussian profile is much sharper than the images taken from stars on photographic plates or CCDs. Therefore in 1969, Moffat proposed this functional form for the image of stars:

\[
f(r) = a \left[ 1 + \left( \frac{r}{\alpha} \right)^2 \right]^{-\beta}
\]

Again, \( a \) is constrained by the normalization, therefore two parameters define the shape of the Moffat function: \( \alpha \) and \( \beta \). The radial parameter is \( \alpha \) which is related to the FWHM by

\[
\text{FWHM}_m = 2\alpha \sqrt{2^{1/\beta} - 1}
\]

Comparing with the PSF predicted from atmospheric turbulence theory with a Moffat function, Trujillo et al.\(^3\) claim that \( \beta \) should be 4.765. They also show how the Moffat PSF contains the Gaussian PSF as a limiting case when \( \beta \rightarrow \infty \).

An input FITS image

An input image file can also be specified to be used as a PSF. If the sum of its pixels are not equal to 1, the pixels will be multiplied by a fraction so the sum does become 1.

While the Gaussian is only dependent on the FWHM, the Moffat function is also dependent on \( \beta \). Comparing these two functions with a fixed FWHM gives the following results:

- Within the FWHM, the functions don’t have significant differences.
- For a fixed FWHM, as \( \beta \) increases, the Moffat function becomes sharper.
- The Gaussian function is much sharper than the Moffat functions, even when \( \beta \) is large.

---

8.1.1.3 Stars

In MakeProfiles, stars are generally considered to be a point source. This is usually the case for extra galactic studies, were nearby stars are also in the field. Since a star is only a point source, we assume that it only fills one pixel prior to convolution. In fact, exactly for this reason, in astronomical images the light profiles of stars are one of the best methods to understand the shape of the PSF and a very large fraction of scientific research is preformed by assuming the shapes of stars to be the PSF of the image.

8.1.1.4 Galaxies

Today, most practitioners agree that the flux of galaxies can be modeled with one or a few generalized de Vaucouleur’s (or Sérsic) profiles.

\[
I(r) = I_e \exp \left( -b_n \left( \frac{r}{r_e} \right)^{1/n} - 1 \right)
\]

Gérard de Vaucouleurs (1918-1995) was first to show in 1948 that this function resembles the galaxy light profiles, with the only difference that he held \( n \) fixed to a value of 4. 20 years later in 1968, J. L. Sérsic showed that \( n \) can have a variety of values and does not necessarily need to be 4. This profile depends on the effective radius \((r_e)\) which is defined as the radius which contains half of the profile brightness (see Section 8.1.4 [Profile magnitude], page 340). \( I_e \) is the flux at the effective radius. The Sérsic index \( n \) is used to define the concentration of the profile within \( r_e \) and \( b_n \) is a constant dependent on \( n \). MacArthur et al.\(^4\) show that for \( n > 0.35 \), \( b_n \) can be accurately approximated using this equation:

\[
b_n = 2n - \frac{1}{3} + \frac{4}{405n} + \frac{46}{25515n^2} + \frac{131}{1148175n^3} - \frac{2194697}{30690717750n^4}
\]

8.1.1.5 Sampling from a function

A pixel is the ultimate level of accuracy to gather data, we can’t get any more accurate in one image, this is known as sampling in signal processing. However, the mathematical profiles which describe our models have infinite accuracy. Over a large fraction of the area of astrophysically interesting profiles (for example galaxies or PSFs), the variation of the profile over the area of one pixel is not too significant. In such cases, the elliptical radius \((r_{el})\) of the center of the pixel can be assigned as the final value of the pixel, see Section 8.1.1.1 [Defining an ellipse and ellipsoid], page 332).

As you approach their center, some galaxies become very sharp (their value significantly changes over one pixel’s area). This sharpness increases with smaller effective radius and larger Sérsic values. Thus rendering the central value extremely inaccurate. The first method that comes to mind for solving this problem is integration. The functional form of the profile can be integrated over the pixel area in a 2D integration process. However, unfortunately numerical integration techniques also have their limitations and when such sharp profiles are needed they can become extremely inaccurate.

The most accurate method of sampling a continuous profile on a discrete space is by choosing a large number of random points within the boundaries of the pixel and taking their average value (or Monte Carlo integration). This is also, generally speaking, what happens in practice with the photons on the pixel. The number of random points can be set with \texttt{--numrandom}.

Unfortunately, repeating this Monte Carlo process would be extremely time and CPU consuming if it is to be applied to every pixel. In order to not lose too much accuracy, in MakeProfiles, the profile is built using both methods explained below. The building of the profile begins from its central pixel and continues (radially) outwards. Monte Carlo integration is first applied (which yields \(F_r\)), then the central pixel value (\(F_c\)) is calculated on the same pixel. If the fractional difference (\(|F_r - F_c|/F_r\)) is lower than a given tolerance level (specified with \texttt{--tolerance}) MakeProfiles will stop using Monte Carlo integration and only use the central pixel value.

The ordering of the pixels in this inside-out construction is based on \(r = \sqrt{(i_c - i)^2 + (j_c - j)^2}\), not \(r_{el}\), see Section 8.1.1.1 [Defining an ellipse and ellipsoid], page 332. When the axis ratios are large (near one) this is fine. But when they are small and the object is highly elliptical, it might seem more reasonable to follow \(r_{el}\) not \(r\). The problem is that the gradient is stronger in pixels with smaller \(r\) (and larger \(r_{el}\)) than those with smaller \(r_{el}\). In other words, the gradient is strongest along the minor axis. So if the next pixel is chosen based on \(r_{el}\), the tolerance level will be reached sooner and lots of pixels with large fractional differences will be missed.

Monte Carlo integration uses a random number of points. Thus, every time you run it, by default, you will get a different distribution of points to sample within the pixel. In the case of large profiles, this will result in a slight difference of the pixels which use Monte Carlo integration each time MakeProfiles is run. To have a deterministic result, you have to fix the random number generator properties which is used to build the random distribution. This can be done by setting the \texttt{GSL\_RNG\_TYPE} and \texttt{GSL\_RNG\_SEED} environment variables and calling MakeProfiles with the \texttt{--envseed} option. To learn more about the process of generating random numbers, see Section 8.2.1.4 [Generating random numbers], page 355.

The seed values are fixed for every profile: with \texttt{--envseed}, all the profiles have the same seed and without it, each will get a different seed using the system clock (which is accurate to within one microsecond). The same seed will be used to generate a random number for all the sub-pixel positions of all the profiles. So in the former, the sub-pixel points checked for all the pixels undergoing Monte Carlo integration in all profiles will be identical. In other words, the sub-pixel points in the first (closest to the center) pixel of all the profiles will be identical with each other. All the second pixels studied for all the profiles will also receive an identical (different from the first pixel) set of sub-pixel points and so on. As long as the number of random points used is large enough or the profiles are not identical, this should not cause any systematic bias.

### 8.1.1.6 Oversampling

The steps explained in Section 8.1.1.5 [Sampling from a function], page 336, do give an accurate representation of a profile prior to convolution. However, in an actual observation, the image is first convolved with or blurred by the atmospheric and instrument PSF in a continuous space and then it is sampled on the discrete pixels of the camera.
In order to more accurately simulate this process, the unconvolved image and the PSF are created on a finer pixel grid. In other words, the output image is a certain odd-integer multiple of the desired size, we can call this ‘oversampling’. The user can specify this multiple as a command-line option. The reason this has to be an odd number is that the PSF has to be centered on the center of its image. An image with an even number of pixels on each side does not have a central pixel.

The image can then be convolved with the PSF (which should also be oversampled on the same scale). Finally, image can be sub-sampled to get to the initial desired pixel size of the output image. After this, mock noise can be added as explained in the next section. This is because unlike the PSF, the noise occurs in each output pixel, not on a continuous space like all the prior steps.

### 8.1.2 If convolving afterwards

In case you want to convolve the image later with a given point spread function, make sure to use a larger image size. After convolution, the profiles become larger and a profile that is normally completely outside of the image might fall within it.

On one axis, if you want your final (convolved) image to be \( m \) pixels and your PSF is \( 2n + 1 \) pixels wide, then when calling MakeProfiles, set the axis size to \( m + 2n \), not \( m \). You also have to shift all the pixel positions of the profile centers on the that axis by \( n \) pixels to the positive.

After convolution, you can crop the outer \( n \) pixels with the section crop box specification of Crop: --section=n:*-n,n:*-n assuming your PSF is a square, see Section 6.1.2 [Crop section syntax], page 191. This will also remove all discrete Fourier transform artifacts (blurred sides) from the final image. To facilitate this shift, MakeProfiles has the options --xshift, --yshift and --prepforconv, see Section 8.1.5 [Invoking MakeProfiles], page 340.

### 8.1.3 Brightness, Flux, Magnitude and Surface brightness

Astronomical data pixels are usually in units of counts\(^5\) or electrons or either one divided by seconds. To convert from the counts to electrons, you will need to know the instrument gain. In any case, they can be directly converted to energy or energy/time using the basic hardware (telescope, camera and filter) information. We will continue the discussion assuming the pixels are in units of energy/time.

The **brightness** of an object is defined as its total detected energy per time. In the case of an imaged source, this is simply the sum of the pixels that are associated with that detection by our detection tool (for example Section 7.2 [NoiseChisel], page 269\(^6\)). The **flux** of an object is defined in units of energy/time/collection-area. For an astronomical target, the flux is therefore defined as its brightness divided by the area used to collect the light from the source: or the telescope aperture (for example in units of \( \text{cm}^2 \)). Knowing the flux \((f)\) and distance to the object \((r)\), we can define its **luminosity**: \( L = 4\pi r^2 f \).

Therefore, while flux and luminosity are intrinsic properties of the object, brightness depends on our detecting tools (hardware and software). In low-level observational astron-
omsky data analysis, we are usually more concerned with measuring the brightness, because it is the thing we directly measure from the image pixels and create in catalogs. On the other hand, luminosity is used in higher-level analysis (after image contents are measured as catalogs to deduce physical interpretations). It is just important avoid possible confusion between luminosity and brightness because both have the same units of energy per seconds.

Images of astronomical objects span over a very large range of brightness. With the Sun (as the brightest object) being roughly $2.5^{60} = 10^{24}$ times brighter than the fainter galaxies we can currently detect in the deepest images. Therefore discussing brightness directly will involve a large range of values which is inconvenient. So astronomers have chosen to use a logarithmic scale to talk about the brightness of astronomical objects.

But the logarithm can only be usable with a dimensionless value that is always positive. Fortunately brightness is always positive (atleast in theory\textsuperscript{7}). To remove the dimensions, we divide the brightness of the object ($B$) by a reference brightness ($B_r$). We then define a logarithmic scale as magnitude through the relation below. The $-2.5$ factor in the definition of magnitudes is a legacy of the our ancient colleagues and in particular Hipparchus of Nicaea (190-120 BC).

$$m - m_r = -2.5 \log_{10}\left(\frac{B}{B_r}\right)$$

$m$ is defined as the magnitude of the object and $m_r$ is the pre-defined magnitude of the reference brightness. One particularly easy condition is when the reference brightness is unity ($B_r = 1$). This brightness will thus summarize all the hardware-specific parameters discussed above (like the conversion of pixel values to physical units) into one number. That reference magnitude which is commonly known as the Zero point magnitude (because when $B = B_r = 1$, the right side of the magnitude definition above will be zero). Using the zero point magnitude ($Z$), we can write the magnitude relation above in a more simpler format:

$$m = -2.5 \log_{10}(B) + Z$$

Another important concept is the distribution of brightness over its area. For this, we define the surface brightness to be the magnitude of an object’s brightness divided by its solid angle over the celestial sphere (or coverage in the sky, commonly in units of arcsec\textsuperscript{2}). The solid angle is expressed in units of arcsec\textsuperscript{2} because astronomical targets are usually much smaller than one steradian. Recall that the steradian is the dimension-less SI unit of a solid angle and 1 steradian covers $1/4\pi$ (almost 8\%) of the full celestial sphere.

Surface brightness is therefore most commonly expressed in units of mag/arcsec\textsuperscript{2}. For example when the brightness is measured over an area of $A$ arcsec\textsuperscript{2}, then the surface brightness becomes:

$$S = -2.5 \log_{10}(B/A) + Z = -2.5 \log_{10}(B) + 2.5 \log_{10}(A) + Z$$

\textsuperscript{7}In practice, for very faint objects, if the background brightness is over-subtracted, we may end up with a negative brightness in a real object.
In other words, the surface brightness (in units of mag/arcsec$^2$) is related to the object’s magnitude ($m$) and area ($A$, in units of arcsec$^2$) through this equation:

$$S = m + 2.5 \log_{10}(A)$$

A common mistake is to follow the mag/arcsec$^2$ unit literally, and divide the object’s magnitude by its area. But this is wrong because magnitude is a logarithmic scale while area is linear. It is the brightness that should be divided by the solid angle because both have linear scales. The magnitude of that ratio is then defined to be the surface brightness.

### 8.1.4 Profile magnitude

To find the profile brightness or its magnitude, (see Section 8.1.3 [Brightness, Flux, Magnitude and Surface brightness], page 338), it is customary to use the 2D integration of the flux to infinity. However, in MakeProfiles we do not follow this idealistic approach and apply a more realistic method to find the total brightness or magnitude: the sum of all the pixels belonging to a profile within its predefined truncation radius. Note that if the truncation radius is not large enough, this can be significantly different from the total integrated light to infinity.

An integration to infinity is not a realistic condition because no galaxy extends indefinitely (important for high Sérsic index profiles), pixelation can also cause a significant difference between the actual total pixel sum value of the profile and that of integration to infinity, especially in small and high Sérsic index profiles. To be safe, you can specify a large enough truncation radius for such compact high Sérsic index profiles.

If oversampling is used then the brightness is calculated using the over-sampled image, see Section 8.1.1.6 [Oversampling], page 337, which is much more accurate. The profile is first built in an array completely bounding it with a normalization constant of unity (see Section 8.1.1.4 [Galaxies], page 336). Taking $B$ to be the desired brightness and $S$ to be the sum of the pixels in the created profile, every pixel is then multiplied by $B/S$ so the sum is exactly $B$.

If the --individual option is called, this same array is written to a FITS file. If not, only the overlapping pixels of this array and the output image are kept and added to the output array.

### 8.1.5 Invoking MakeProfiles

MakeProfiles will make any number of profiles specified in a catalog either individually or in one image. The executable name is astmkprof with the following general template

```bash
$ astmkprof [OPTION ...] [Catalog]
```

One line examples:

```bash
## Make an image with profiles in catalog.txt (with default size):
$ astmkprof catalog.txt

## Make the profiles in catalog.txt over image.fits:
$ astmkprof --background=image.fits catalog.txt
```
## Make a Moffat PSF with FWHM 3pix, beta=2.8, truncation=5

```bash
$ astmkprof --kernel=moffat,3,2.8,5 --oversample=1
```

## Make profiles in catalog, using RA and Dec in the given column:

```bash
$ astmkprof --ccol=RA_CENTER --ccol=DEC_CENTER --mode=wcs catalog.txt
```

## Make a 1500x1500 merged image (oversampled 500x500) image along
## with an individual image for all the profiles in catalog:

```bash
$ astmkprof --individual --oversample 3 --mergedsize=500,500 cat.txt
```

The parameters of the mock profiles can either be given through a catalog (which stores the parameters of many mock profiles, see Section 8.1.5.1 [MakeProfiles catalog], page 342), or the `--kernel` option (see Section 8.1.5.3 [MakeProfiles output dataset], page 348). The catalog can be in the FITS ASCII, FITS binary format, or plain text formats (see Section 4.8 [Tables], page 135). A plain text catalog can also be provided using the Standard input (see Section 4.1.3 [Standard input], page 118). The columns related to each parameter can be determined both by number, or by match/search criteria using the column names, units, or comments, with the options ending in `col`, see below.

Without any file given to the `--background` option, MakeProfiles will make a zero-valued image and build the profiles on that (its size and main WCS parameters can also be defined through the options described in Section 8.1.5.3 [MakeProfiles output dataset], page 348). Besides the main/merged image containing all the profiles in the catalog, it is also possible to build individual images for each profile (only enclosing one full profile to its truncation radius) with the `--individual` option.

If an image is given to the `--background` option, the pixels of that image are used as the background value for every pixel hence flux value of each profile pixel will be added to the pixel in that background value. You can disable this with the `--clearcanvas` option (which will initialize the background to zero-valued pixels and build profiles over that). With the `--background` option, the values to all options relating to the “canvas” (output size and WCS) will be ignored if specified, for example `--oversample`, `--mergedsize`, and `--prepforconv`.

The sections below discuss the options specific to MakeProfiles based on context: the input catalog settings which can have many rows for different profiles are discussed in Section 8.1.5.1 [MakeProfiles catalog], page 342, in Section 8.1.5.2 [MakeProfiles profile settings], page 345, we discuss how you can set general profile settings (that are the same for all the profiles in the catalog). Finally Section 8.1.5.3 [MakeProfiles output dataset], page 348, and Section 8.1.5.4 [MakeProfiles log file], page 352, discuss the outputs of MakeProfiles and how you can configure them. Besides these, MakeProfiles also supports all the common Gnuastro program options that are discussed in Section 4.1.2 [Common options], page 109, so please flip through them is well for a more comfortable usage.

When building 3D profiles, there are more degrees of freedom. Hence, more columns are necessary and all the values related to dimensions (for example size of dataset in each dimension and the WCS properties) must also have 3 values. To allow having an independent set of default values for creating 3D profiles, MakeProfiles also installs a `astmkprof-3d.conf` configuration file (see Section 4.2 [Configuration files], page 120). You can use this for default 3D profile values. For example, if you installed Gnuastro with the prefix `/usr/local` (the default location, see Section 3.3.1.2 [Installation directory], page 92), you can benefit
from this configuration file by running MakeProfiles like the example below. As with all
configuration files, if you want to customize a given option, call it before the configuration
file.

```bash
$ astmkprof --config=/usr/local/etc/astmkprof-3d.conf catalog.txt
```

To further simplify the process, you can define a shell alias in any startup file (for
example `~/.bashrc`, see Section 3.3.1.2 [Installation directory], page 92). Assuming that
you installed Gnuastro in `/usr/local`, you can add this line to the startup file (you may
put it all in one line, it is broken into two lines here for fitting within page limits).

```bash
alias astmkprof-3d="astmkprof --config=/usr/local/etc/astmkprof-3d.conf"
```

Using this alias, you can call MakeProfiles with the name `astmkprof-3d` (instead of
`astmkprof`). It will automatically load the 3D specific configuration file first, and then
parse any other arguments, options or configuration files. You can change the default
values in this 3D configuration file by calling them on the command-line as you do with `astmkprof`\(^8\).

Please see Section 2.1 [Sufi simulates a detection], page 17, for a very complete tutorial
explaining how one could use MakeProfiles in conjunction with other Gnuastro’s programs
to make a complete simulated image of a mock galaxy.

### 8.1.5.1 MakeProfiles catalog

The catalog containing information about each profile can be in the FITS ASCII, FITS
binary, or plain text formats (see Section 4.8 [Tables], page 135). The latter can also be
provided using standard input (see Section 4.1.3 [Standard input], page 118). Its columns
can be ordered in any desired manner. You can specify which columns belong to which
parameters using the set of options discussed below. For example through the `--rcol`
and `--tcol` options, you can specify the column that contains the radial parameter for each
profile and its truncation respectively. See Section 4.8.3 [Selecting table columns], page 140,
for a thorough discussion on the values to these options.

The value for the profile center in the catalog (the `--ccol` option) can be a floating point
number so the profile center can be on any sub-pixel position. Note that pixel positions in
the FITS standard start from 1 and an integer is the pixel center. So a 2D image actually
starts from the position (0.5, 0.5), which is the bottom-left corner of the first pixel. When a
`--background` image with WCS information is provided or you specify the WCS parameters
with the respective options, you may also use RA and Dec to identify the center of each
profile (see the `--mode` option below).

In MakeProfiles, profile centers do not have to be in (overlap with) the final image. Even
if only one pixel of the profile within the truncation radius overlaps with the final image
size, the profile is built and included in the final image image. Profiles that are completely
out of the image will not be created (unless you explicitly ask for it with the `--individual`
option). You can use the output log file (created with `--log` to see which profiles were
within the image, see Section 4.1.2 [Common options], page 109.

If PSF profiles (Moffat or Gaussian, see Section 8.1.1.2 [Point spread function], page 334)
are in the catalog and the profiles are to be built in one image (when `--individual` is not

---

\(^8\) Recall that for single-invocation options, the last command-line invocation takes precedence over all
previous invocations (including those in the 3D configuration file). See the description of `--config` in
Section 4.1.2.3 [Operating mode options], page 114.
used), it is assumed they are the PSF(s) you want to convolve your created image with. So by default, they will not be built in the output image but as separate files. The sum of pixels of these separate files will also be set to unity (1) so you are ready to convolve, see Section 6.3.1.1 [Convolution process], page 217. As a summary, the position and magnitude of PSF profile will be ignored. This behavior can be disabled with the \texttt{--psfinimg} option. If you want to create all the profiles separately (with \texttt{--individual}) and you want the sum of the PSF profile pixels to be unity, you have to set their magnitudes in the catalog to the zero point magnitude and be sure that the central positions of the profiles don't have any fractional part (the PSF center has to be in the center of the pixel).

The list of options directly related to the input catalog columns is shown below.

\begin{verbatim}
--ccol=STR/INT
Center coordinate column for each dimension. This option must be called two times to define the center coordinates in an image. For example \texttt{--ccol=RA} and \texttt{--ccol=DEC} (along with \texttt{--mode=wcs}) will inform MakeProfiles to look into the catalog columns named RA and DEC for the Right Ascension and Declination of the profile centers.

--fcol=INT/STR
The functional form of the profile with one of the values below depending on the desired profile. The column can contain either the numeric codes (for example ‘1’) or string characters (for example ‘sersic’). The numeric codes are easier to use in scripts which generate catalogs with hundreds or thousands of profiles. The string format can be easier when the catalog is to be written/checked by hand/eye before running MakeProfiles. It is much more readable and provides a level of documentation. All Gnuastro’s recognized table formats (see Section 4.8.1 [Recognized table formats], page 136) accept string type columns. To have string columns in a plain text table/catalog, see Section 4.8.2 [Gnuastro text table format], page 137.

\begin{itemize}
  \item Sérsic profile with ‘sersic’ or ‘1’.
  \item Moffat profile with ‘moffat’ or ‘2’.
  \item Gaussian profile with ‘gaussian’ or ‘3’.
  \item Point source with ‘point’ or ‘4’.
  \item Flat profile with ‘flat’ or ‘5’.
  \item Circumference profile with ‘circum’ or ‘6’. A fixed value will be used for all pixels less than or equal to the truncation radius ($r_t$) and greater than $r_t - w$ ($w$ is the value to the \texttt{--circumwidth}).
  \item Radial distance profile with ‘distance’ or ‘7’. At the lowest level, each pixel only has an elliptical radial distance given the profile’s shape and orientation (see Section 8.1.1.1 [Defining an ellipse and ellipsoid], page 332). When this profile is chosen, the pixel’s elliptical radial distance from the profile center is written as its value. For this profile, the value in the magnitude column (\texttt{--mcol}) will be ignored.
\end{itemize}
\end{verbatim}

You can use this for checks or as a first approximation to define your own higher-level radial function. In the latter case, just note that the
central values are going to be incorrect (see Section 8.1.1.5 [Sampling from a function], page 336).

`--rcol=STR/INT`  
The radius parameter of the profiles. Effective radius ($r_e$) if Sérsic, FWHM if Moffat or Gaussian.

`--ncol=STR/INT`  
The Sérsic index ($n$) or Moffat $\beta$.

`--pcol=STR/INT`  
The position angle (in degrees) of the profiles relative to the first FITS axis (horizontal when viewed in SAO ds9). When building a 3D profile, this is the first Euler angle: first rotation of the ellipsoid major axis from the first FITS axis (rotating about the third axis). See Section 8.1.1.1 [Defining an ellipse and ellipsoid], page 332.

`--p2col=STR/INT`  
Second Euler angle (in degrees) when building a 3D ellipsoid. This is the second rotation of the ellipsoid major axis (following `--pcol`) about the (rotated) X axis. See Section 8.1.1.1 [Defining an ellipse and ellipsoid], page 332. This column is ignored when building a 2D profile.

`--p3col=STR/INT`  
Third Euler angle (in degrees) when building a 3D ellipsoid. This is the third rotation of the ellipsoid major axis (following `--pcol` and `--p2col`) about the (rotated) Z axis. See Section 8.1.1.1 [Defining an ellipse and ellipsoid], page 332. This column is ignored when building a 2D profile.

`--qcol=STR/INT`  
The axis ratio of the profiles (minor axis divided by the major axis in a 2D ellipse). When building a 3D ellipse, this is the ratio of the major axis to the semi-axis length of the second dimension (in a right-handed coordinate system). See $q_1$ in Section 8.1.1.1 [Defining an ellipse and ellipsoid], page 332.

`--q2col=STR/INT`  
The ratio of the ellipsoid major axis to the third semi-axis length (in a right-handed coordinate system) of a 3D ellipsoid. See $q_1$ in Section 8.1.1.1 [Defining an ellipse and ellipsoid], page 332. This column is ignored when building a 2D profile.

`--mcol=STR/INT`  
The total pixelated magnitude of the profile within the truncation radius, see Section 8.1.4 [Profile magnitude], page 340.

`--tcol=STR/INT`  
The truncation radius of this profile. By default it is in units of the radial parameter of the profile (the value in the `--rcol` of the catalog). If `--tunitinp` is given, this value is interpreted in units of pixels (prior to oversampling) irrespective of the profile.
8.1.5.2 MakeProfiles profile settings

The profile parameters that differ between each created profile are specified through the columns in the input catalog and described in Section 8.1.5.1 [MakeProfiles catalog], page 342. Besides those there are general settings for some profiles that don’t differ between one profile and another, they are a property of the general process. For example how many random points to use in the monte-carlo integration, this value is fixed for all the profiles. The options described in this section are for configuring such properties.

--mode=STR

Interpret the center position columns (--ccol in Section 8.1.5.1 [MakeProfiles catalog], page 342) in image or WCS coordinates. This option thus accepts only two values: img and wcs. It is mandatory when a catalog is being used as input.

-r

--numrandom

The number of random points used in the central regions of the profile, see Section 8.1.1.5 [Sampling from a function], page 336.

-e

--envseed

Use the value to the GSL_RNG_SEED environment variable to generate the random Monte Carlo sampling distribution, see Section 8.1.1.5 [Sampling from a function], page 336, and Section 8.2.1.4 [Generating random numbers], page 355.

-t FLT

--tolerance=FLT

The tolerance to switch from Monte Carlo integration to the central pixel value, see Section 8.1.1.5 [Sampling from a function], page 336.

-p

--tunitinp

The truncation column of the catalog is in units of pixels. By default, the truncation column is considered to be in units of the radial parameters of the profile (--rcol). Read it as ‘t-unit-in-p’ for ‘truncation unit in pixels’.

-f

--mforflatpix

When making fixed value profiles (flat and circumference, see ‘--fcol’), don’t use the value in the column specified by ‘--mcol’ as the magnitude. Instead use it as the exact value that all the pixels of these profiles should have. This option is irrelevant for other types of profiles. This option is very useful for creating masks, or labeled regions in an image. Any integer, or floating point value can used in this column with this option, including NaN (or ‘nan’, or ‘NAN’, case is irrelevant), and infinities (inf, -inf, or +inf).

For example, with this option if you set the value in the magnitude column (--mcol) to NaN, you can create an elliptical or circular mask over an image (which can be given as the argument), see Section 6.1.3 [Blank pixels], page 191. Another useful application of this option is to create labeled elliptical or circular apertures in an image. To do this, set the value in the magnitude column
to the label you want for this profile. This labeled image can then be used in combination with NoiseChisel’s output (see Section 7.2.1.3 [NoiseChisel output], page 282) to do aperture photometry with MakeCatalog (see Section 7.4 [MakeCatalog], page 295).

Alternatively, if you want to mark regions of the image (for example with an elliptical circumference) and you don’t want to use NaN values (as explained above) for some technical reason, you can get the minimum or maximum value in the image\(^9\) using Arithmetic (see Section 6.2 [Arithmetic], page 199), then use that value in the magnitude column along with this option for all the profiles.

Please note that when using MakeProfiles on an already existing image, you have to set `--oversample=1`. Otherwise all the profiles will be scaled up based on the oversampling scale in your configuration files (see Section 4.2 [Configuration files], page 120) unless you have accounted for oversampling in your catalog.

`--mcolisbrightness`

The value given in the “magnitude column” (specified by `--mcol`, see Section 8.1.5.1 [MakeProfiles catalog], page 342) must be interpreted as brightness, not magnitude. The zero point magnitude (value to the `--zeropoint` option) is ignored and the given value must have the same units as the input dataset’s pixels.

Recall that the total profile magnitude or brightness that is specified with in the `--mcol` column of the input catalog is not an integration to infinity, but the actual sum of pixels in the profile (until the desired truncation radius). See Section 8.1.4 [Profile magnitude], page 340, for more on this point.

`--magatpeak`

The magnitude column in the catalog (see Section 8.1.5.1 [MakeProfiles catalog], page 342) will be used to find the brightness only for the peak profile pixel, not the full profile. Note that this is the flux of the profile’s peak pixel in the final output of MakeProfiles. So beware of the oversampling, see Section 8.1.1.6 [Oversampling], page 337.

This option can be useful if you want to check a mock profile’s total magnitude at various truncation radii. Without this option, no matter what the truncation radius is, the total magnitude will be the same as that given in the catalog. But with this option, the total magnitude will become brighter as you increase the truncation radius.

In sharper profiles, sometimes the accuracy of measuring the peak profile flux is more than the overall object brightness. In such cases, with this option, the final profile will be built such that its peak has the given magnitude, not the total profile.

---

\(^9\) The minimum will give a better result, because the maximum can be too high compared to most pixels in the image, making it harder to display.
CAUTION: If you want to use this option for comparing with observations, please note that MakeProfiles does not do convolution. Unless you have de-convolved your data, your images are convolved with the instrument and atmospheric PSF, see Section 8.1.1.2 [Point spread function], page 334. Particularly in sharper profiles, the flux in the peak pixel is strongly decreased after convolution. Also note that in such cases, besides de-convolution, you will have to set --oversample=1 otherwise after resampling your profile with Warp (see Section 6.4 [Warp], page 238), the peak flux will be different.

-X INT,INT
--shift=INT,INT
Shift all the profiles and enlarge the image along each dimension. To better understand this option, please see n in Section 8.1.2 [If convolving afterwards], page 338. This is useful when you want to convolve the image afterwards. If you are using an external PSF, be sure to oversample it to the same scale used for creating the mock images. If a background image is specified, any possible value to this option is ignored.

-c
--prepforconv
Shift all the profiles and enlarge the image based on half the width of the first Moffat or Gaussian profile in the catalog, considering any possible oversampling see Section 8.1.2 [If convolving afterwards], page 338. --prepforconv is only checked and possibly activated if --xshift and --yshift are both zero (after reading the command-line and configuration files). If a background image is specified, any possible value to this option is ignored.

-z FLT
--zeropoint=FLT
The zero point magnitude of the input. For more on the zero point magnitude, see Section 8.1.3 [Brightness, Flux, Magnitude and Surface brightness], page 338.

-w FLT
--circumwidth=FLT
The width of the circumference if the profile is to be an elliptical circumference or annulus. See the explanations for this type of profile in --fcol.

-R
--replace
Do not add the pixels of each profile over the background, or other profiles. But replace the values.

By default, when two profiles overlap, the final pixel value is the sum of all the profiles that overlap on that pixel. This is the expected situation when dealing with physical object profiles like galaxies or stars/PSF. However, when MakeProfiles is used to build integer labeled images (for example in Section 2.2.15 [Aperture photometry], page 51), this is not the expected situation: the sum of two labels will be a new label. With this option, the pixels are not added but the largest (maximum) value over that pixel is used. Because the maximum operator is independent of the order of values, the output is also thread-safe.
8.1.5.3 MakeProfiles output dataset

MakeProfiles takes an input catalog and uses basic properties that are defined there to build a dataset, for example a 2D image containing the profiles in the catalog. In Section 8.1.5.1 [MakeProfiles catalog], page 342, and Section 8.1.5.2 [MakeProfiles profile settings], page 345, the catalog and profile settings were discussed. The options of this section, allow you to configure the output dataset (or the canvas that will host the built profiles).

-k STR
   --background=STR
   A background image FITS file to build the profiles on. The extension that contains the image should be specified with the --backhdu option, see below. When a background image is specified, it will be used to derive all the information about the output image. Hence, the following options will be ignored: --mergesize, --oversample, --crpix, --crval (generally, all other WCS related parameters) and the output’s data type (see --type in Section 4.1.2.1 [Input/Output options], page 109).

The image will act like a canvas to build the profiles on: profile pixel values will be summed with the background image pixel values. With the --replace option you can disable this behavior and replace the profile pixels with the background pixels. If you want to use all the image information above, except for the pixel values (you want to have a blank canvas to build the profiles on, based on an input image), you can call --clearcanvas, to set all the input image’s pixels to zero before starting to build the profiles over it (this is done in memory after reading the input, so nothing will happen to your input file).

-B STR/INT
   --backhdu=STR/INT
   The header data unit (HDU) of the file given to --background.

-C
   --clearcanvas
   When an input image is specified (with the --background option, set all its pixels to 0.0 immediately after reading it into memory. Effectively, this will allow you to use all its properties (described under the --background option), without having to worry about the pixel values.

   --clearcanvas can come in handy in many situations, for example if you want to create a labeled image (segmentation map) for creating a catalog (see Section 7.4 [MakeCatalog], page 295). In other cases, you might have modeled the objects in an image and want to create them on the same frame, but without the original pixel values.

-E STR/INT,FLT[,FLT,[...]]
   --kernel=STR/INT,FLT[,FLT,[...]]
   Only build one kernel profile with the parameters given as the values to this option. The different values must be separated by a comma (,). The first value identifies the radial function of the profile, either through a string or through a number (see description of --fcol in Section 8.1.5.1 [MakeProfiles catalog], page 342). Each radial profile needs a different total number of parameters:
Sérsic and Moffat functions need 3 parameters: radial, Sérsic index or Moffat \( \beta \), and truncation radius. The Gaussian function needs two parameters: radial and truncation radius. The point function doesn’t need any parameters and flat and circumference profiles just need one parameter (truncation radius).

The PSF or kernel is a unique (and highly constrained) type of profile: the sum of its pixels must be one, its center must be the center of the central pixel (in an image with an odd number of pixels on each side), and commonly it is circular, so its axis ratio and position angle are one and zero respectively. Kernels are commonly necessary for various data analysis and data manipulation steps (for example see Section 6.3 [Convolve], page 216, and Section 7.2 [NoiseChisel], page 269. Because of this it is inconvenient to define a catalog with one row and many zero valued columns (for all the non-necessary parameters). Hence, with this option, it is possible to create a kernel with MakeProfiles without the need to create a catalog. Here are some examples:

```
--kernel=moffat,3,2.8,5
```

A Moffat kernel with FWHM of 3 pixels, \( \beta = 2.8 \) which is truncated at 5 times the FWHM.

```
--kernel=gaussian,2,3
```

A circular Gaussian kernel with FWHM of 2 pixels and truncated at 3 times the FWHM.

This option may also be used to create a 3D kernel. To do that, two small modifications are necessary: add a \(-3d\) (or \(-3D\)) to the profile name (for example moffat-3d) and add a number (axis-ratio along the third dimension) to the end of the parameters for all profiles except point. The main reason behind providing an axis ratio in the third dimension is that in 3D astronomical datasets, commonly the third dimension doesn’t have the same nature (units/sampling) as the first and second.

For example in IFU datacubes, the first and second dimensions are angular positions (like RA and Dec) but the third is in units of Angstroms for wavelength. Because of this different nature (which also affects the processing), it may be necessary for the kernel to have a different extent in that direction.

If the 3rd dimension axis ratio is equal to 1.0, then the kernel will be a spheroid. If its smaller than 1.0, the kernel will be button-shaped: extended less in the third dimension. However, when it is larger than 1.0, the kernel will be bullet-shaped: extended more in the third dimension. In the latter case, the radial parameter will correspond to the length along the 3rd dimension. For example, let’s have a look at the two examples above but in 3D:

```
--kernel=moffat-3d,3,2.8,5,0.5
```

An ellipsoid Moffat kernel with FWHM of 3 pixels, \( \beta = 2.8 \) which is truncated at 5 times the FWHM. The ellipsoid is circular in the first two dimensions, but in the third dimension its extent is half the first two.

```
--kernel=gaussian-3d,2,3,1
```

A spherical Gaussian kernel with FWHM of 2 pixels and truncated at 3 times the FWHM.
Of course, if a specific kernel is needed that doesn’t fit the constraints imposed by this option, you can always use a catalog to define any arbitrary kernel. Just call the `--individual` and `--nomerged` options to make sure that it is built as a separate file (individually) and no “merged” image of the input profiles is created.

```-x INT,INT
--mergedsize=INT,INT```

The number of pixels along each axis of the output, in FITS order. This is before over-sampling. For example if you call MakeProfiles with `--mergedsize=100,150 --oversample=5` (assuming no shift due for later convolution), then the final image size along the first axis will be 500 by 750 pixels. Fractions are acceptable as values for each dimension, however, they must reduce to an integer, so `--mergedsize=150/3,300/3` is acceptable but `--mergedsize=150/4,300/4` is not.

When viewing a FITS image in DS9, the first FITS dimension is in the horizontal direction and the second is vertical. As an example, the image created with the example above will have 500 pixels horizontally and 750 pixels vertically. If a background image is specified, this option is ignored.

```-s INT
--oversample=INT```

The scale to over-sample the profiles and final image. If not an odd number, will be added by one, see Section 8.1.1.6 [Oversampling], page 337. Note that this `--oversample` will remain active even if an input image is specified. If your input catalog is based on the background image, be sure to set `--oversample=1`.

```--psfinimg```

Build the possibly existing PSF profiles (Moffat or Gaussian) in the catalog into the final image. By default they are built separately so you can convolve your images with them, thus their magnitude and positions are ignored. With this option, they will be built in the final image like every other galaxy profile. To have a final PSF in your image, make a point profile where you want the PSF and after convolution it will be the PSF.

```-i
--individual```

If this option is called, each profile is created in a separate FITS file within the same directory as the output and the row number of the profile (starting from zero) in the name. The file for each row’s profile will be in the same directory as the final combined image of all the profiles and will have the final image’s name as a suffix. So for example if the final combined image is named `.out/fromcatalog.fits`, then the first profile that will be created with this option will be named `.out/0_fromcatalog.fits`.

Since each image only has one full profile out to the truncation radius the profile is centered and so, only the sub-pixel position of the profile center is important for the outputs of this option. The output will have an odd number of pixels. If there is no oversampling, the central pixel will contain the profile center. If the value to `--oversample` is larger than unity, then the profile center is on
any of the central --oversample'd pixels depending on the fractional value of
the profile center.
If the fractional value is larger than half, it is on the bottom half of the central
region. This is due to the FITS definition of a real number position: The center
of a pixel has fractional value 0.00 so each pixel contains these fractions: .5 –
.75 – .00 (pixel center) – .25 – .5.

-m
--nomerged
Don’t make a merged image. By default after making the profiles, they are
added to a final image with side lengths specified by --mergedsize if they
overlap with it.

The options below can be used to define the world coordinate system (WCS) properties
of the MakeProfiles outputs. The option names are deliberately chosen to be the same as the
FITS standard WCS keywords. See Section 8 of Pence et al [2010] (https://doi.org/10.1051/0004-6361/201015362) for a short introduction to WCS in the FITS standard\(^\text{10}\).

If you look into the headers of a FITS image with WCS for example you will see all these
names but in uppercase and with numbers to represent the dimensions, for example CRPIX1
and PC2_1. You can see the FITS headers with Gnuastro’s Section 5.1 [Fits], page 146,
program using a command like this: $ astfits -p image.fits.

If the values given to any of these options does not correspond to the number of dimen-
sions in the output dataset, then no WCS information will be added.

--crpix=FLT,FLT
The pixel coordinates of the WCS reference point. Fractions are acceptable for
the values of this option.

--crval=FLT,FLT
The WCS coordinates of the Reference point. Fractions are acceptable for the
values of this option.

--cdelt=FLT,FLT
The resolution (size of one data-unit or pixel in WCS units) of the
non-oversampled dataset. Fractions are acceptable for the values of this
option.

--pc=FLT,FLT,FLT,FLT
The PC matrix of the WCS rotation, see the FITS standard (link above) to
better understand the PC matrix.

--cunit=STR,STR
The units of each WCS axis, for example deg. Note that these values are part
of the FITS standard (link above). MakeProfiles won’t complain if you use
non-standard values, but later usage of them might cause trouble.

\(^{10}\) The world coordinate standard in FITS is a very beautiful and powerful concept to link/associate
datasets with the outside world (other datasets). The description in the FITS standard (link above)
only touches the tip of the ice-burg. To learn more please see Greisen and Calabretta [2002] (https://
doi.org/10.1051/0004-6361:20021326), Calabretta and Greisen [2002] (https://doi.org/10.1051/
0004-6361:20021327), Greisen et al. [2006] (https://doi.org/10.1051/0004-6361:20053818), and
Calabretta et al. (http://www.atnf.csiro.au/people/mcalabre/WCS/dcs_20040422.pdf)
--ctype=STR,STR

The type of each WCS axis, for example RA---TAN and DEC--TAN. Note that these values are part of the FITS standard (link above). MakeProfiles won’t complain if you use non-standard values, but later usage of them might cause trouble.

8.1.5.4 MakeProfiles log file

Besides the final merged dataset of all the profiles, or the individual datasets (see Section 8.1.5.3 [MakeProfiles output dataset], page 348), if the --log option is called MakeProfiles will also create a log file in the current directory (where you run MockProfiles). See Section 4.1.2 [Common options], page 109, for a full description of --log and other options that are shared between all Gnuastro programs. The values for each column are explained in the first few commented lines of the log file (starting with # character). Here is a more complete description.

- An ID (row number of profile in input catalog).
- The total magnitude of the profile in the output dataset. When the profile does not completely overlap with the output dataset, this will be different from your input magnitude.
- The number of pixels (in the oversampled image) which used Monte Carlo integration and not the central pixel value, see Section 8.1.1.5 [Sampling from a function], page 336.
- The fraction of flux in the Monte Carlo integrated pixels.
- If an individual image was created, this column will have a value of 1, otherwise it will have a value of 0.

8.2 MakeNoise

Real data are always buried in noise, therefore to finalize a simulation of real data (for example to test our observational algorithms) it is essential to add noise to the mock profiles created with MakeProfiles, see Section 8.1 [MakeProfiles], page 332. Below, the general principles and concepts to help understand how noise is quantified is discussed. MakeNoise options and argument are then discussed in Section 8.2.2 [Invoking MakeNoise], page 356.

8.2.1 Noise basics

Deep astronomical images, like those used in extragalactic studies, seriously suffer from noise in the data. Generally speaking, the sources of noise in an astronomical image are photon counting noise and Instrumental noise which are discussed in Section 8.2.1.1 [Photon counting noise], page 353, and Section 8.2.1.2 [Instrumental noise], page 354. This review finishes with Section 8.2.1.4 [Generating random numbers], page 355, which is a short introduction on how random numbers are generated. We will see that while software random number generators are not perfect, they allow us to obtain a reproducible series of random numbers through setting the random number generator function and seed value. Therefore in this section, we’ll also discuss how you can set these two parameters in Gnuastro’s programs (including MakeNoise).
8.2.1.1 Photon counting noise

With the very accurate electronics used in today’s detectors, photon counting noise\textsuperscript{11} is the most significant source of uncertainty in most datasets. To understand this noise (error in counting), we need to take a closer look at how a distribution produced by counting can be modeled as a parametric function.

Counting is an inherently discrete operation, which can only produce positive (including zero) integer outputs. For example we can’t count 3.2 or $-2$ of anything. We only count 0, 1, 2, 3 and so on. The distribution of values, as a result of counting efforts is formally known as the Poisson distribution (https://en.wikipedia.org/wiki/Poisson_distribution). It is associated to Siméon Denis Poisson, because he discussed it while working on the number of wrongful convictions in court cases in his 1837 book\textsuperscript{12}.

Let’s take $\lambda$ to represent the expected mean count of something. Furthermore, let’s take $k$ to represent the result of one particular counting attempt. The probability density function of getting $k$ counts (in each attempt, given the expected/mean count of $\lambda$) can be written as:

$$f(k) = \frac{\lambda^k}{k!} e^{-\lambda}, \quad k \in \{0, 1, 2, 3, \ldots\}$$

Because the Poisson distribution is only applicable to positive values (note the factorial operator, which only applies to non-negative integers), naturally it is very skewed when $\lambda$ is near zero. One qualitative way to understand this behavior is that there simply aren’t enough integers smaller than $\lambda$, than integers that are larger than it. Therefore to accommodate all possibilities/counts, it has to be strongly skewed when $\lambda$ is small.

As $\lambda$ becomes larger, the distribution becomes more and more symmetric. A very useful property of the Poisson distribution is that the mean value is also its variance. When $\lambda$ is very large, say $\lambda > 1000$, then the Normal (Gaussian) distribution (https://en.wikipedia.org/wiki/Normal_distribution), is an excellent approximation of the Poisson distribution with mean $\mu = \lambda$ and standard deviation $\sigma = \sqrt{\lambda}$. In other words, a Poisson distribution (with a sufficiently large $\lambda$) is simply a Gaussian that only has one free parameter ($\mu = \lambda$ and $\sigma = \sqrt{\lambda}$), instead of the two parameters (independent $\mu$ and $\sigma$) that it originally has.

In real situations, the photons/flux from our targets are added to a certain background flux (observationally, the Sky value). The Sky value is defined to be the average flux of a region in the dataset with no targets. Its physical origin can be the brightness of the atmosphere (for ground-based instruments), possible stray light within the imaging instrument, the average flux of undetected targets, etc. The Sky value is thus an ideal definition, because in real datasets, what lies deep in the noise (far lower than the detection limit) is never known\textsuperscript{13}. To account for all of these, the sky value is defined to be the

\textsuperscript{11} In practice, we are actually counting the electrons that are produced by each photon, not the actual photons.

\textsuperscript{12} [From Wikipedia] Poisson’s result was also derived in a previous study by Abraham de Moivre in 1711. Therefore some people suggest it should rightly be called the de Moivre distribution.

\textsuperscript{13} In a real image, a relatively large number of very faint objects can be fully buried in the noise and never detected. These undetected objects will bias the background measurement to slightly larger values.
average count/value of the undetected regions in the image. In a mock image/dataset, we
have the luxury of setting the background (Sky) value.

In each element of the dataset (pixel in an image), the flux is the sum of contributions
from various sources (after convolution by the PSF, see Section 8.1.1.2 [Point spread func-
tion], page 334). Let’s name the convolved sum of possibly overlapping objects, \( I_{nn} \). \( nn \)
representing ‘no noise’. For now, let’s assume the background (\( B \)) is constant and suffi-
ciently high for the Poisson distribution to be approximated by a Gaussian. Then the flux
after adding noise is a random value taken from a Gaussian distribution with the following
mean (\( \mu \)) and standard deviation (\( \sigma \)):

\[
\mu = B + I_{nn}, \quad \sigma = \sqrt{B + I_{nn}}
\]

Since this type of noise is inherent in the objects we study, it is usually measured on
the same scale as the astronomical objects, namely the magnitude system, see Section 8.1.3
[Brightness, Flux, Magnitude and Surface brightness], page 338. It is then internally con-
verted to the flux scale for further processing.

8.2.1.2 Instrumental noise
While taking images with a camera, a dark current is fed to the pixels, the variation of the
value of this dark current over the pixels, also adds to the final image noise. Another source
of noise is the readout noise that is produced by the electronics in the detector. Specifically,
the parts that attempt to digitize the voltage produced by the photo-electrons in the analog
to digital converter. With the current generation of instruments, this source of noise is not
as significant as the noise due to the background Sky discussed in Section 8.2.1.1 [Photon
counting noise], page 353.

Let \( C \) represent the combined standard deviation of all these instrumental sources of
noise. When only this source of noise is present, the noised pixel value would be a random
value chosen from a Gaussian distribution with

\[
\mu = I_{nn}, \quad \sigma = \sqrt{C^2 + I_{nn}}
\]

This type of noise is independent of the signal in the dataset, it is only determined by
the instrument. So the flux scale (and not magnitude scale) is most commonly used for this
type of noise. In practice, this value is usually reported in analog-to-digital units or ADUs,
not flux or electron counts. The gain value of the device can be used to convert between
these two, see Section 8.1.3 [Brightness, Flux, Magnitude and Surface brightness], page 338.

8.2.1.3 Final noised pixel value
Based on the discussions in Section 8.2.1.1 [Photon counting noise], page 353, and
Section 8.2.1.2 [Instrumental noise], page 354, depending on the values you specify for \( B \)

Our best approximation is thus to simply assume they are uniform, and consider their average effect.
See Figure 1 (a.1 and a.2) and Section 2.2 in Akhlaghi and Ichikawa [2015] (https://arxiv.org/abs/
1505.01664).
and $C$ from the above, the final noised value for each pixel is a random value chosen from a Gaussian distribution with

$$
\mu = B + I_{nn}, \quad \sigma = \sqrt{C^2 + B + I_{nn}}
$$

### 8.2.1.4 Generating random numbers

As discussed above, to generate noise we need to make random samples of a particular distribution. So it is important to understand some general concepts regarding the generation of random numbers. For a very complete and nice introduction we strongly advise reading Donald Knuth’s “The art of computer programming”, volume 2, chapter 3.\(^{14}\) Quoting from the GNU Scientific Library manual, “If you don’t own it, you should stop reading right now, run to the nearest bookstore, and buy it.”\(^{15}\)

Using only software, we can only produce what is called a psuedo-random sequence of numbers. A true random number generator is a hardware (let’s assume we have made sure it has no systematic biases), for example throwing dice or flipping coins (which have remained from the ancient times). More modern hardware methods use atmospheric noise, thermal noise or other types of external electromagnetic or quantum phenomena. All pseudo-random number generators (software) require a seed to be the basis of the generation. The advantage of having a seed is that if you specify the same seed for multiple runs, you will get an identical sequence of random numbers which allows you to reproduce the same final noised image.

The programs in GNU Astronomy Utilities (for example MakeNoise or MakeProfiles) use the GNU Scientific Library (GSL) to generate random numbers. GSL allows the user to set the random number generator through environment variables, see Section 3.3.1.2 [Installation directory], page 92, for an introduction to environment variables. In the chapter titled “Random Number Generation” they have fully explained the various random number generators that are available (there are a lot of them!). Through the two environment variables \texttt{GSL\_RNG\_TYPE} and \texttt{GSL\_RNG\_SEED} you can specify the generator and its seed respectively.

If you don’t specify a value for \texttt{GSL\_RNG\_TYPE}, GSL will use its default random number generator type. The default type is sufficient for most general applications. If no value is given for the \texttt{GSL\_RNG\_SEED} environment variable and you have asked Gnuastro to read the seed from the environment (through the \texttt{--envseed} option), then GSL will use the default value of each generator to give identical outputs. If you don’t explicitly tell Gnuastro programs to read the seed value from the environment variable, then they will use the system time (accurate to within a microsecond) to generate (apparently random) seeds. In this manner, every time you run the program, you will get a different random number distribution.

There are two ways you can specify values for these environment variables. You can call them on the same command-line for example:

```bash
$ GSL\_RNG\_TYPE="taus" GSL\_RNG\_SEED=345 astmknoise input.fits
```

In this manner the values will only be used for this particular execution of MakeNoise. Alternatively, you can define them for the full period of your terminal session or script.


\(^{15}\) For students, running to the library might be more affordable!
length, using the shell’s `export` command with the two separate commands below (for a script remove the $ signs):

```bash
$ export GSL_RNG_TYPE="taus"
$ export GSL_RNG_SEED=345
```

The subsequent programs which use GSL’s random number generators will henceforth use these values in this session of the terminal you are running or while executing this script. In case you want to set fixed values for these parameters every time you use the GSL random number generator, you can add these two lines to your `.bashrc` startup script\(^{16}\), see Section 3.3.1.2 [Installation directory], page 92.

**NOTE:** If the two environment variables `GSL_RNG_TYPE` and `GSL_RNG_SEED` are defined, GSL will report them by default, even if you don’t use the `--envseed` option. For example you can see the top few lines of the output of MakeProfiles:

```bash
$ export GSL_RNG_TYPE="taus"
$ export GSL_RNG_SEED=345
$ astmkprof -s1 --kernel=gaussian,2,5 --envseed
GSL_RNG_TYPE=taus
GSL_RNG_SEED=345
MakeProfiles A.B started on DDD MMM DD HH:MM:SS YYYY
- Building one gaussian kernel
- Random number generator (RNG) type: ranlxs1
- RNG seed for all profiles: 345
---- ./kernel.fits created.
MakeProfiles finished in 0.111271 seconds
```

The first two output lines (showing the names of the environment variables) are printed by GSL before MakeProfiles actually starts generating random numbers. The Gnuastro programs will report the values they use independently, you should check them for the final values used. For example if `--envseed` is not given, `GSL_RNG_SEED` will not be used and the last line shown above will not be printed. In the case of MakeProfiles, each profile will get its own seed value.

### 8.2.2 Invoking MakeNoise

MakeNoise will add noise to an existing image. The executable name is `astmknoise` with the following general template

```bash
$ astmknoise [OPTION ...] InputImage.fits
```

One line examples:

```bash
## Add noise with a standard deviation of 100 to image.
## (this is independent of the pixel value: not Poission noise)
$ astmknoise --sigma=100 image.fits
```

---

\(^{16}\) Don’t forget that if you are going to give your scripts (that use the GSL random number generator) to others you have to make sure you also tell them to set these environment variable separately. So for scripts, it is best to keep all such variable definitions within the script, even if they are within your `.bashrc`.\)
Add noise to input image assuming a background magnitude (with zero point magnitude of 0) and a certain instrumental noise:

```
$ astmknoise --background=-10 -z0 --instrumental=20 mockimage.fits
```

If actual processing is to be done, the input image is a mandatory argument. The full list of options common to all the programs in Gnuastro can be seen in Section 4.1.2 [Common options], page 109. The type (see Section 4.6 [Numeric data types], page 130) of the output can be specified with the --type option, see Section 4.1.2.1 [Input/Output options], page 109. The header of the output FITS file keeps all the parameters that were influential in making it. This is done for future reproducibility.

```
-b FLT
--background=FLT

The background value (per pixel) that will be added to each pixel value (internally) to estimate Poisson noise, see Section 8.2.1.1 [Photon counting noise], page 353. By default the units of this value are assumed to be in magnitudes, hence a --zeropoint is also necessary. But if the background is in units of brightness, you need add --bgisbrightness, see Section 8.1.3 [Brightness, Flux, Magnitude and Surface brightness], page 338.

Internally, the value given to this option will be converted to brightness (b, when --bgisbrightness is called, the value will be used directly). Assuming the pixel value is p, the random value for that pixel will be taken from a Gaussian distribution with mean of $p + b$ and standard deviation of $\sqrt{p + b}$. With this option, the noise will therefore be dependent on the pixel values: according to the Poisson noise model, as the pixel value becomes larger, its noise will also become larger. This is thus a realistic way to model noise, see Section 8.2.1.1 [Photon counting noise], page 353.
```

```
-B
--bgisbrightness

The value given to --background should be interpreted as brightness, not as a magnitude.
```

```
-z FLT
--zeropoint=FLT

The zero point magnitude used to convert the value of --background (in units of magnitude) to flux, see Section 8.1.3 [Brightness, Flux, Magnitude and Surface brightness], page 338.
```

```
-i FLT
--instrumental=FLT

The instrumental noise which is in units of flux, see Section 8.2.1.2 [Instrumental noise], page 354.
```

```
-s FLT
--sigma=FLT

The total noise sigma in the same units as the pixel values. With this option, the --background, --zeropoint and --instrumental will be ignored. With this option, the noise will be independent of the pixel values (which is not realistic, see Section 8.2.1.1 [Photon counting noise], page 353). Hence it is only useful
if you are working on low surface brightness regions where the change in pixel value (and thus real noise) is insignificant.

Generally, usage of this option is discouraged unless you understand the risks of not simulating real noise. This is because with this option, you will not get Poisson noise (the common noise model for astronomical imaging), where the noise varies based on pixel value. Use --background for adding Poission noise.

-e
--envseed
Use the GSL_RNG_SEED environment variable for the seed used in the random number generator, see Section 8.2.1.4 [Generating random numbers], page 355. With this option, the output image noise is always going to be identical (or reproducible).

-d
--doubletype
Save the output in the double precision floating point format that was used internally. This option will be most useful if the input images were of integer types.
9 High-level calculations

After the reduction of raw data (for example with the programs in Chapter 6 [Data manipulation], page 188) you will have reduced images/data ready for processing/analyzing (for example with the programs in Chapter 7 [Data analysis], page 248). But the processed/analyzed data (or catalogs) are still not enough to derive any scientific result. Even higher-level analysis is still needed to convert the observed magnitudes, sizes or volumes into physical quantities that we associate with each catalog entry or detected object which is the purpose of the tools in this section.

9.1 CosmicCalculator

To derive higher-level information regarding our sources in extra-galactic astronomy, cosmological calculations are necessary. In Gnuastro, CosmicCalculator is in charge of such calculations. Before discussing how CosmicCalculator is called and operates (in Section 9.1.3 [Invoking CosmicCalculator], page 364), it is important to provide a rough but mostly self-sufficient review of the basics and the equations used in the analysis. In Section 9.1.1 [Distance on a 2D curved space], page 359, the basic idea of understanding distances in a curved and expanding 2D universe (which we can visualize) are reviewed. Having solidified the concepts there, in Section 9.1.2 [Extending distance concepts to 3D], page 364, the formalism is extended to the 3D universe we are trying to study in our research.

The focus here is obtaining a physical insight into these equations (mainly for the use in real observational studies). There are many books thoroughly deriving and proving all the equations with all possible initial conditions and assumptions for any abstract universe, interested readers can study those books.

9.1.1 Distance on a 2D curved space

The observations to date (for example the Planck 2015 results), have not measured\(^1\) the presence of significant curvature in the universe. However to be generic (and allow its measurement if it does in fact exist), it is very important to create a framework that allows non-zero uniform curvature. However, this section is not intended to be a fully thorough and mathematically complete derivation of these concepts. There are many references available for such reviews that go deep into the abstract mathematical proofs. The emphasis here is on visualization of the concepts for a beginner.

As 3D beings, it is difficult for us to mentally create (visualize) a picture of the curvature of a 3D volume. Hence, here we will assume a 2D surface/space and discuss distances on that 2D surface when it is flat and when it is curved. Once the concepts have been created/visualized here, we will extend them, in Section 9.1.2 [Extending distance concepts to 3D], page 364, to a real 3D spatial slice of the Universe we live in and hope to study.

To be more understandable (actively discuss from an observer’s point of view) let’s assume there’s an imaginary 2D creature living on the 2D space (which might be curved in 3D). Here, we will be working with this creature in its efforts to analyze distances in its 2D universe. The start of the analysis might seem too mundane, but since it is difficult to

---

\(^1\) The observations are interpreted under the assumption of uniform curvature. For a relativistic alternative to dark energy (and maybe also some part of dark matter), non-uniform curvature may be even be more critical, but that is beyond the scope of this brief explanation.
imagine a 3D curved space, it is important to review all the very basic concepts thoroughly for an easy transition to a universe that is more difficult to visualize (a curved 3D space embedded in 4D).

To start, let’s assume a static (not expanding or shrinking), flat 2D surface similar to Figure 9.1 and that the 2D creature is observing its universe from point A. One of the most basic ways to parameterize this space is through the Cartesian coordinates \((x, y)\). In Figure 9.1, the basic axes of these two coordinates are plotted. An infinitesimal change in the direction of each axis is written as \(dx\) and \(dy\). For each point, the infinitesimal changes are parallel with the respective axes and are not shown for clarity. Another very useful way of parameterizing this space is through polar coordinates. For each point, we define a radius \((r)\) and angle \((\phi)\) from a fixed (but arbitrary) reference axis. In Figure 9.1 the infinitesimal changes for each polar coordinate are plotted for a random point and a dashed circle is shown for all points with the same radius.

![Figure 9.1: Two dimensional Cartesian and polar coordinates on a flat plane.](image)

Assuming an object is placed at a certain position, which can be parameterized as \((x, y)\), or \((r, \phi)\), a general infinitesimal change in its position will place it in the coordinates \((x + dx, y + dy)\) and \((r + dr, \phi + d\phi)\). The distance (on the flat 2D surface) that is covered by this infinitesimal change in the static universe \((ds_s)\), the subscript signifies the static nature of this universe) can be written as:

\[
ds_s = dx^2 + dy^2 = dr^2 + r^2 d\phi^2
\]

The main question is this: how can the 2D creature incorporate the (possible) curvature in its universe when it’s calculating distances? The universe that it lives in might equally be a curved surface like Figure 9.2. The answer to this question but for a 3D being (us) is the whole purpose to this discussion. Here, we want to give the 2D creature (and later, ourselves) the tools to measure distances if the space (that hosts the objects) is curved. Figure 9.2 assumes a spherical shell with radius \(R\) as the curved 2D plane for simplicity. The 2D plane is tangent to the spherical shell and only touches it at A. This idea will be generalized later. The first step in measuring the distance in a curved space is to imagine a third dimension along the \(z\) axis as shown in Figure 9.2. For simplicity, the \(z\) axis is assumed to pass through the center of the spherical shell. Our imaginary 2D creature cannot visualize the third dimension or a curved 2D surface within it, so the remainder of this discussion is purely abstract for it (similar to us having difficulty in visualizing a 3D curved space in 4D). But since we are 3D creatures, we have the advantage of visualizing the following steps. Fortunately the 2D creature is already familiar with our mathematical constructs, so it can follow our reasoning.
With the third axis added, a generic infinitesimal change over the full 3D space corresponds to the distance:

\[ ds^2 = dx^2 + dy^2 + dz^2 = dr^2 + r^2 d\phi^2 + dz^2. \]

Figure 9.2: 2D spherical shell (centered on O) and flat plane (light gray) tangent to it at point A.

It is very important to recognize that this change of distance is for any point in the 3D space, not just those changes that occur on the 2D spherical shell of Figure 9.2. Recall that our 2D friend can only do measurements on the 2D surfaces, not the full 3D space. So we have to constrain this general change to any change on the 2D spherical shell. To do that, let’s look at the arbitrary point \( P \) on the 2D spherical shell. Its image \( (P') \) on the flat plain is also displayed. From the dark gray triangle, we see that

\[
\sin \theta = \frac{r}{R}, \quad \cos \theta = \frac{R - z}{R}.
\]

These relations allow the 2D creature to find the value of \( z \) (an abstract dimension for it) as a function of \( r \) (distance on a flat 2D plane, which it can visualize) and thus eliminate \( z \). From \( \sin^2 \theta + \cos^2 \theta = 1 \), we get \( z^2 - 2Rz + r^2 = 0 \) and solving for \( z \), we find:

\[ z = R \left( 1 \pm \sqrt{1 - \frac{r^2}{R^2}} \right). \]
The ± can be understood from Figure 9.2: For each \( r \), there are two points on the sphere, one in the upper hemisphere and one in the lower hemisphere. An infinitesimal change in \( r \), will create the following infinitesimal change in \( z \):

\[
\frac{dz}{dr} = \mp \frac{r}{R} \left( \frac{1}{\sqrt{1-r^2/R^2}} \right) dr.
\]

Using the positive signed equation instead of \( dz \) in the \( ds^2 \) equation above, we get:

\[
ds^2_s = \frac{dr^2}{1-r^2/R^2} + r^2 d\phi^2.
\]

The derivation above was done for a spherical shell of radius \( R \) as a curved 2D surface. To generalize it to any surface, we can define \( K = 1/R^2 \) as the curvature parameter. Then the general infinitesimal change in a static universe can be written as:

\[
ds^2_s = \frac{dr^2}{1-Kr^2} + r^2 d\phi^2.
\]

Therefore, when \( K > 0 \) (and curvature is the same everywhere), we have a finite universe, where \( r \) cannot become larger than \( R \) as in Figure 9.2. When \( K = 0 \), we have a flat plane (Figure 9.1) and a negative \( K \) will correspond to an imaginary \( R \). The latter two cases may be infinite in area (which is not a simple concept, but mathematically can be modeled with \( r \) extending infinitely), or finite-area (like a cylinder is flat everywhere with \( ds^2_s = dx^2 + dy^2 \), but finite in one direction in size).

A very important issue that can be discussed now (while we are still in 2D and can actually visualize things) is that \( \vec{r} \) is tangent to the curved space at the observer’s position. In other words, it is on the gray flat surface of Figure 9.2, even when the universe if curved: \( \vec{r} = P' - A \). Therefore for the point \( P \) on a curved space, the raw coordinate \( r \) is the distance to \( P' \), not \( P \). The distance to the point \( P \) (at a specific coordinate \( r \) on the flat plane) over the curved surface (thick line in Figure 9.2) is called the proper distance and is displayed with \( l \). For the specific example of Figure 9.2, the proper distance can be calculated with: \( l = R\theta \) (\( \theta \) is in radians). Using the \( \sin \theta \) relation found above, we can find \( l \) as a function of \( r \):

\[
\theta = \sin^{-1} \left( \frac{r}{R} \right) \quad \rightarrow \quad l(r) = R\sin^{-1} \left( \frac{r}{R} \right)
\]

\( R \) is just an arbitrary constant and can be directly found from \( K \), so for cleaner equations, it is common practice to set \( R = 1 \), which gives: \( l(r) = \sin^{-1} r \). Also note that when \( R = 1 \), then \( l = \theta \). Generally, depending on the curvature, in a static universe the proper distance can be written as a function of the coordinate \( r \) as (from now on we are assuming \( R = 1 \)):

\[
l(r) = \sin^{-1}(r) \quad (K > 0), \quad l(r) = r \quad (K = 0), \quad l(r) = \sinh^{-1}(r) \quad (K < 0).
\]
With \( l \), the infinitesimal change of distance can be written in a more simpler and abstract form of

\[
    ds^2 = dl^2 + r^2 d\phi^2.
\]

Until now, we had assumed a static universe (not changing with time). But our observations so far appear to indicate that the universe is expanding (it isn’t static). Since there is no reason to expect the observed expansion is unique to our particular position of the universe, we expect the universe to be expanding at all points with the same rate at the same time. Therefore, to add a time dependence to our distance measurements, we can include a multiplicative scaling factor, which is a function of time: \( a(t) \). The functional form of \( a(t) \) comes from the cosmology, the physics we assume for it: general relativity, and the choice of whether the universe is uniform (‘homogeneous’) in density and curvature or inhomogeneous. In this section, the functional form of \( a(t) \) is irrelevant, so we can avoid these issues.

With this scaling factor, the proper distance will also depend on time. As the universe expands, the distance between two given points will shift to larger values. We thus define a distance measure, or coordinate, that is independent of time and thus doesn’t ‘move’. We call it the comoving distance and display with \( \chi \) such that: \( l(r,t) = \chi(r)a(t) \). We have therefore, shifted the \( r \) dependence of the proper distance we derived above for a static universe to the comoving distance:

\[
    \chi(r) = \begin{cases} 
    \sin^{-1}(r) & (K > 0), \\
    r & (K = 0), \\
    \sinh^{-1}(r) & (K < 0).
    \end{cases}
\]

Therefore, \( \chi(r) \) is the proper distance to an object at a specific reference time: \( t = t_r \) (the \( r \) subscript signifies “reference”) when \( a(t_r) = 1 \). At any arbitrary moment \( t \neq t_r \) before or after \( t_r \), the proper distance to the object can be scaled with \( a(t) \).

Measuring the change of distance in a time-dependent (expanding) universe only makes sense if we can add up space and time\(^2\). But we can only add bits of space and time together if we measure them in the same units: with a conversion constant (similar to how 1000 is used to convert a kilometer into meters). Experimentally, we find strong support for the hypothesis that this conversion constant is the speed of light (or gravitational waves\(^3\)) in a vacuum. This speed is postulated to be constant\(^4\) and is almost always written as \( c \). We can thus parameterize the change in distance on an expanding 2D surface as

\[
    ds^2 = c^2 dt^2 - a^2(t)ds^2_s = c^2 dt^2 - a^2(t)(d\chi^2 + r^2 d\phi^2).
\]

\(^2\) In other words, making our space-time consistent with Minkowski space-time geometry. In this geometry, different observers at a given point (event) in space-time split up space-time into ‘space’ and ‘time’ in different ways, just like people at the same spatial position can make different choices of splitting up a map into ‘left–right’ and ‘up–down’. This model is well supported by twentieth and twenty-first century observations.

\(^3\) The speed of gravitational waves was recently found to be very similar to that of light in vacuum, see arXiv:1710.05834 (https://arxiv.org/abs/1710.05834).

\(^4\) In natural units, speed is measured in units of the speed of light in vacuum.
9.1.2 Extending distance concepts to 3D

The concepts of Section 9.1.1 [Distance on a 2D curved space], page 359, are here extended to a 3D space that might be curved. We can start with the generic infinitesimal distance in a static 3D universe, but this time in spherical coordinates instead of polar coordinates. \( \theta \) is shown in Figure 9.2, but here we are 3D beings, positioned on \( O \) (the center of the sphere) and the point \( O \) is tangent to a 4D-sphere. In our 3D space, a generic infinitesimal displacement will correspond to the following distance in spherical coordinates:

\[
d s^2 = dx^2 + dy^2 + dz^2 = dr^2 + r^2 (d\theta^2 + \sin^2 \theta d\phi^2).
\]

Like the 2D creature before, we now have to assume an abstract dimension which we cannot visualize easily. Let’s call the fourth dimension \( w \), then the general change in coordinates in the full four dimensional space will be:

\[
d s^2 = dr^2 + r^2 (d\theta^2 + \sin^2 \theta d\phi^2) + dw^2.
\]

But we can only work on a 3D curved space, so following exactly the same steps and conventions as our 2D friend, we arrive at:

\[
d s^2 = \frac{dr^2}{1 - Kr^2} + r^2 (d\theta^2 + \sin^2 \theta d\phi^2).
\]

In a non-static universe (with a scale factor \( a(t) \)), the distance can be written as:

\[
d s^2 = c^2 dt^2 - a^2(t) [d\chi^2 + r^2 (d\theta^2 + \sin^2 \theta d\phi^2)].
\]

9.1.3 Invoking CosmicCalculator

CosmicCalculator will calculate cosmological variables based on the input parameters. The executable name is astcosmiccal with the following general template

$ astcosmiccal [OPTION...] ...$

One line examples:

## Print basic cosmological properties at redshift 2.5:
$ astcosmiccal -z2.5$

## Only print Comoving volume over 4pi stradian to z (Mpc^3):
$ astcosmiccal --redshift=0.8 --volume$

## Print redshift and age of universe when Lyman-alpha line is
## at 6000 angstrom (another way to specify redshift).
$ astcosmiccal --obsline=lyalpha,6000 --age$

## Print luminosity distance, angular diameter distance and age
## of universe in one row at redshift 0.4
$\text{astcosmiccal } -z0.4 \text{ -LA}$

Assume Lambda and matter density of 0.7 and 0.3 and print
## basic cosmological parameters for redshift 2.1:
$\text{astcosmiccal } -10.7 \text{ -m0.3 } -z2.1$

Print wavelength of all pre-defined spectral lines when
## Lyman-alpha is observed at 4000 Angstroms.
$\text{astcosmiccal } --\text{obsline}=\text{lyalpha,4000 } --\text{listlinesatz}$

The input parameters (for example current matter density, etc) can be given as
cmd-line options or in the configuration files, see Section 4.2 [Configuration files],
page 120. For a definition of the different parameters, please see the sections prior to this.
If no redshift is given, CosmicCalculator will just print its input parameters and abort.
For a full list of the input options, please see Section 9.1.3.1 [CosmicCalculator input
options], page 365.

Without any particular output requested (and only a given redshift), CosmicCalculator
will print all basic cosmological calculations (one per line) with some explanations before
each. This can be good when you want a general feeling of the conditions at a specific
redshift. Alternatively, if any specific calculation(s) are requested (its possible to call more
than one), only the requested value(s) will be calculated and printed with one character
space between them. In this case, no description or units will be printed. See Section 9.1.3.2
[CosmicCalculator basic cosmology calculations], page 368, for the full list of these options
along with some explanations how when/how they can be useful.

Another common operation in observational cosmology is dealing with spectral lines at
different redshifts. CosmicCalculator also has features to help in such situations, please see
Section 9.1.3.3 [CosmicCalculator spectral line calculations], page 370.

### 9.1.3.1 CosmicCalculator input options

The inputs to CosmicCalculator can be specified with the following options:

- $\text{-z FLT}$  
  $\text{--redshift=FLT}$

  The redshift of interest. There are two other ways that you can specify the
target redshift: 1) Spectral lines and their observed wavelengths, see $\text{--obsline}$.
  2) Velocity, see $\text{--velocity}$. Hence this option cannot be called with $\text{--obsline}$
or $\text{--velocity}$.

- $\text{-y FLT}$  
  $\text{--velocity=FLT}$

  Input velocity in km/s. The given value will be converted to redshift internally,
  and used in any subsequent calculation. This option is thus an alternative to
  $\text{--redshift}$ or $\text{--obsline}$, it cannot be used with them. The conversion will
  be done with the more general and accurate relativistic equation of
  \[1 + z = \sqrt{(c + v)/(c - v)},\]
  not the simplified \(z \approx v/c\).

- $\text{-H FLT}$  
  $\text{--H0=FLT}$

  Current expansion rate (in km sec\(^{-1}\) Mpc\(^{-1}\)).
-l FLT
   --olambda=FLT
   Cosmological constant density divided by the critical density in the current Universe ($\Omega_{\Lambda,0}$).

-m FLT
   --omatter=FLT
   Matter (including massive neutrinos) density divided by the critical density in the current Universe ($\Omega_{m,0}$).

-r FLT
   --oradiation=FLT
   Radiation density divided by the critical density in the current Universe ($\Omega_{r,0}$).

-0 STR/FLT,FLT
   --obslinestr/FLT,FLT
   Find the redshift to use in next steps based on the rest-frame and observed wavelengths of a line. This option is thus an alternative to --redshift or --velocity, it cannot be used with them. Wavelengths are assumed to be in Angstroms. The first argument identifies the line. It can be one of the standard names below, or any rest-frame wavelength in Angstroms. The second argument is the observed wavelength of that line. For example --obslinestr=lyalpha,6000 is the same as --obslinestr=1215.64,6000.

The pre-defined names are listed below, sorted from red (longer wavelength) to blue (shorter wavelength). You can get this list on the command-line with the --listlines:

   siired  [6731Å] SII doublet’s redder line.
   sii     [6724Å] SII doublet’s mean center at.
   siiblue [6717Å] SII doublet’s bluer line.
   niired  [6584Å] NII doublet’s redder line.
   nii     [6566Å] NII doublet’s mean center.
   halpha  [6562.8Å] H-\(\alpha\) line.
   niiblue [6548Å] NII doublet’s bluer line.
   oiiired-vis [5007Å] OIII doublet’s redder line in the visible.
   oiii-vis [4983Å] OIII doublet’s mean center in the visible.
   oiiiblue-vis [4959Å] OIII doublet’s bluer line in the visible.
   hbeta   [4861.36Å] H-\(\beta\) line.
   heii-vis [4686Å] HeII doublet’s redder line in the visible.
   hgamma  [4340.46Å] H-\(\gamma\) line.
   hdelta  [4101.74Å] H-\(\delta\) line.
hepsilon [3970.07Å] H-ε line.
neiii [3869Å] NEIII line.
oiired [3729Å] OII doublet’s redder line.
oii [3727.5Å] OII doublet’s mean center.
oiiblue [3726Å] OII doublet’s bluer line.
blimit [3646Å] Balmer limit.
mgiired [2803Å] MgII doublet’s redder line.
mgi [2799.5Å] MgII doublet’s mean center.
mgiiblue [2796Å] MgII doublet’s bluer line.
ciiired [1909Å] CIII doublet’s redder line.
ciii [1908Å] CIII doublet’s mean center.
ciiiblue [1907Å] CIII doublet’s bluer line.
si_iiired [1892Å] SiIII doublet’s redder line.
si_iii [1887.5Å] SiIII doublet’s mean center.
si_iiiblue [1883Å] SiIII doublet’s bluer line.
oiiired-uv [1666Å] OIII doublet’s redder line in the ultra-violet.
oiii-uv [1663.5Å] OIII doublet’s mean center in the ultra-violet.
oiiiblue-uv [1661Å] OIII doublet’s bluer line in the ultra-violet.
heii-uv [1640Å] HeII doublet’s bluer line in the ultra-violet.
civred [1551Å] CIV doublet’s redder line.
civ [1549Å] CIV doublet’s mean center.
civblue [1548Å] CIV doublet’s bluer line.
nv [1240Å] NV (four times ionized Sodium).
lyalpha [1215.67Å] Lyman-α line.
lybeta [1025.7Å] Lyman-β line.
lygamma [972.54Å] Lyman-γ line.
lydelta [949.74Å] Lyman-δ line.
lyepsilon [937.80Å] Lyman-ε line.
lylimit [912Å] Lyman limit.
9.1.3.2 CosmicCalculator basic cosmology calculations

By default, when no specific calculations are requested, CosmicCalculator will print a complete set of all its calculators (one line for each calculation, see Section 9.1.3 [Invoking CosmicCalculator], page 364). The full list of calculations can be useful when you don’t want any specific value, but just a general view. In other contexts (for example in a batch script or during a discussion), you know exactly what you want and don’t want to be distracted by all the extra information.

You can use any number of the options described below in any order. When any of these options are requested, CosmicCalculator’s output will just be a single line with a single space between the (possibly) multiple values. In the example below, only the tangential distance along one arcsecond (in kpc), absolute magnitude conversion, and age of the universe at redshift 2 are printed (recall that you can merge short options together, see Section 4.1.1.2 [Options], page 107).

```
$ astcosmiccal -z2 -sag
 8.585046 44.819248 3.289979
```

Here is one example of using this feature in scripts: by adding the following two lines in a script to keep/use the comoving volume with varying redshifts:

```
z=3.12
vol=$(astcosmiccal --redshift=$z --volume)
```

In a script, this operation might be necessary for a large number of objects (several of galaxies in a catalog for example). So the fact that all the other default calculations are ignored will also help you get to your result faster.

If you are indeed dealing with many (for example thousands) of redshifts, using CosmicCalculator is not the best/fastest solution. Because it has to go through all the configuration files and preparations for each invocation. To get the best efficiency (least overhead), we recommend using Gnuastro’s cosmology library (see Section 10.3.30 [Cosmology library (cosmology.h)], page 506). CosmicCalculator also calls the library functions defined there for its calculations, so you get the same result with no overhead. Gnuastro also has libraries for easily reading tables into a C program, see Section 10.3.10 [Table input output (table.h)], page 426. Afterwards, you can easily build and run your C program for the particular processing with Section 10.2 [BuildProgram], page 380.

If you just want to inspect the value of a variable visually, the description (which comes with units) might be more useful. In such cases, the following command might be better. The other calculations will also be done, but they are so fast that you will not notice on modern computers (the time it takes your eye to focus on the result is usually longer than the processing: a fraction of a second).

```
$ astcosmiccal --redshift=0.832 | grep volume
```

The full list of CosmicCalculator’s specific calculations is present below in two groups: basic cosmology calculations and those related to spectral lines. In case you have forgot the units, you can use the --help option which has the units along with a short description.

-e
--usedredshift

The redshift that was used in this run. In many cases this is the main input parameter to CosmicCalculator, but it is useful in others. For example
in combination with --obsline (where you give an observed and rest-frame wavelength and would like to know the redshift) or with --velocity (where you specify the velocity instead of redshift). Another example is when you run CosmicCalculator in a loop, while changing the redshift and you want to keep the redshift value with the resulting calculation.

-Y
--usedvelocity
The velocity (in km/s) that was used in this run. The conversion from redshift will be done with the more general and accurate relativistic equation of \(1 + z = \sqrt{(c + v)/(c - v)}\), not the simplified \(z \approx v/c\).

-G
--agenow
The current age of the universe (given the input parameters) in Ga (Giga annum, or billion years).

-C
--criticaldensitynow
The current critical density (given the input parameters) in grams per centimeter-cube \((g/cm^3)\).

-d
--properdistance
The proper distance (at current time) to object at the given redshift in Megaparsecs (Mpc). See Section 9.1.1 [Distance on a 2D curved space], page 359, for a description of the proper distance.

-A
--angulardimdist
The angular diameter distance to object at given redshift in Megaparsecs (Mpc).

-s
--arcsectandist
The tangential distance covered by 1 arcseconds at the given redshift in kiloparsecs (Kpc). This can be useful when trying to estimate the resolution or pixel scale of an instrument (usually in units of arcseconds) at a given redshift.

-L
--luminositydist
The luminosity distance to object at given redshift in Megaparsecs (Mpc).

-u
--distancemodulus
The distance modulus at given redshift.

-a
--absmagconv
The conversion factor (addition) to absolute magnitude. Note that this is practically the distance modulus added with \(-2.5 \log (1 + z)\) for the desired redshift based on the input parameters. Once the apparent magnitude and redshift of an object is known, this value may be added with the apparent magnitude to give the object’s absolute magnitude.
---
-g  
--age   Age of the universe at given redshift in Ga (Giga annum, or billion years).
-b  
--lookbacktime   
   The look-back time to given redshift in Ga (Giga annum, or billion years). The look-back time at a given redshift is defined as the current age of the universe (--agenow) subtracted by the age of the universe at the given redshift.
-c  
--criticaldensity   
   The critical density at given redshift in grams per centimeter-cube ($g/cm^3$).
-v  
--onlyvolume   
   The comoving volume in Megaparsecs cube (Mpc$^3$) until the desired redshift based on the input parameters.

9.1.3.3 CosmicCalculator spectral line calculations

At different redshifts, observed spectral lines are shifted compared to their rest frame wavelengths with this simple relation: $\lambda_{\text{obs}} = \lambda_{\text{rest}}(1 + z)$. Although this relation is very simple and can be done for one line in the head (or a simple calculator!), it slowly becomes tiring when dealing with a lot of lines or redshifts, or some precision is necessary. The options in this section are thus provided to greatly simplify usage of this simple equation, and also helping by storing a list of pre-defined spectral line wavelengths.

For example if you want to know the wavelength of the $H\alpha$ line (at 6562.8 Angstroms in rest frame), when $Ly\alpha$ is at 8000 Angstroms, you can call CosmicCalculator like the first example below. And if you want the wavelength of all pre-defined spectral lines at this redshift, you can use the second command.

```
$ astcosmiccal --obsline=lyalpha,8000 --lineatz=halpha
$ astcosmiccal --obsline=lyalpha,8000 --listlinesatz
```

Below you can see the printed/output calculations of CosmicCalculator that are related to spectral lines. Note that --obsline is an input parameter, so its discussed (with the full list of known lines) in Section 9.1.3.1 [CosmicCalculator input options], page 365.

--listlines

List the pre-defined rest frame spectral line wavelengths and their names on standard output, then abort CosmicCalculator. When this option is given, other operations on the command-line will be ignored. This is convenient when you forget the specific name of the spectral line used within Gnuastro, or when you forget the exact wavelength of a certain line.

These names can be used with the options that deal with spectral lines, for example --obsline and --lineatz (Section 9.1.3.2 [CosmicCalculator basic cosmology calculations], page 368).

The format of the output list is a two-column table, with Gnuastro’s text table format (see Section 4.8.2 [Gnuastro text table format], page 137). Therefore, if you are only looking for lines in a specific range, you can pipe the output into Gnuastro’s table program and use its --range option on the wavelength (first)
column. For example, if you only want to see the lines between 4000 and 6000 Angstroms, you can run this command:

```
$ astcosmiccal --listlines \n  | asttable --range=wavelength,4000,6000
```

And if you want to use the list later and have it as a table in a file, you can easily add the `--output` (or `-o`) option to the `asttable` command, and specify the filename, for example `--output=lines.fits` or `--output=lines.txt`.

**--listlinesatz**

Similar to `--listlines` (above), but the printed wavelength is not in the rest frame, but redshifted to the given redshift. Recall that the redshift can be specified by `--redshift` directly or by `--obsline`, see Section 9.1.3.1 [CosmicCalculator input options], page 365.

**-i STR/FLT**

**--lineatz=STR/FLT**

The wavelength of the specified line at the redshift given to CosmicCalculator. The line can be specified either by its name or directly as a number (its wavelength). To get the list of pre-defined names for the lines and their wavelength, you can use the `--listlines` option, see Section 9.1.3.1 [CosmicCalculator input options], page 365. In the former case (when a name is given), the returned number is in units of Angstroms. In the latter (when a number is given), the returned value is the same units of the input number (assuming its a wavelength).
10 Library

Each program in Gnuastro that was discussed in the prior chapters (or any program in general) is a collection of functions that is compiled into one executable file which can communicate directly with the outside world. The outside world in this context is the operating system. By communication, we mean that control is directly passed to a program from the operating system with a (possible) set of inputs and after it is finished, the program will pass control back to the operating system. For programs written in C and C++, the unique main function is in charge of this communication.

Similar to a program, a library is also a collection of functions that is compiled into one executable file. However, unlike programs, libraries don’t have a main function. Therefore they can’t communicate directly with the outside world. This gives you the chance to write your own main function and call library functions from within it. After compiling your program into a binary executable, you just have to link it to the library and you are ready to run (execute) your program. In this way, you can use Gnuastro at a much lower-level, and in combination with other libraries on your system, you can significantly boost your creativity.

This chapter starts with a basic introduction to libraries and how you can use them in Section 10.1 [Review of library fundamentals], page 372. The separate functions in the Gnuastro library are then introduced (classified by context) in Section 10.3 [Gnuastro library], page 384. If you end up routinely using a fixed set of library functions, with a well-defined input and output, it will be much more beneficial if you define a program for the job. Therefore, in its Section 3.2.2 [Version controlled source], page 85, Gnuastro comes with the Section 11.4.2 [The TEMPLATE program], page 525, to easily define your own programs(s).

10.1 Review of library fundamentals

Gnuastro’s libraries are written in the C programming language. In Section 11.1 [Why C programming language?], page 516, we have thoroughly discussed the reasons behind this choice. C was actually created to write Unix, thus understanding the way C works can greatly help in effectively using programs and libraries in all Unix-like operating systems. Therefore, in the following subsections some important aspects of C, as it relates to libraries (and thus programs that depend on them) on Unix are reviewed. First we will discuss header files in Section 10.1.1 [Headers], page 373, and then go onto Section 10.1.2 [Linking], page 376. This section finishes with Section 10.1.3 [Summary and example on libraries], page 379. If you are already familiar with these concepts, please skip this section and go directly to Section 10.3 [Gnuastro library], page 384.

In theory, a full operating system (or any software) can be written as one function. Such a software would not need any headers or linking (that are discussed in the subsections below). However, writing that single function and maintaining it (adding new features, fixing bugs, documentation, etc) would be a programmer or scientist’s worst nightmare! Furthermore, all the hard work that went into creating it cannot be reused in other software: every other programmer or scientist would have to re-invent the wheel. The ultimate purpose behind libraries (which come with headers and have to be linked) is to address this problem and increase modularity: “the degree to which a system’s components may be separated and
recombined” (from Wikipedia). The more modular the source code of a program or library, the easier maintaining it will be, and all the hard work that went into creating it can be reused for a wider range of problems.

10.1.1 Headers

C source code is read from top to bottom in the source file, therefore program components (for example variables, data structures and functions) should all be defined or declared closer to the top of the source file: before they are used. Defining something in C or C++ is jargon for providing its full details. Declaring it, on the other-hand, is jargon for only providing the minimum information needed for the compiler to pass it temporarily and fill in the detailed definition later.

For a function, the declaration only contains the inputs and their data-types along with the output’s type\(^1\). The definition adds to the declaration by including the exact details of what operations are done to the inputs to generate the output. As an example, take this simple summation function:

```c
double sum(double a, double b)
{
    return a + b;
}
```

What you see above is the definition of this function: it shows you (and the compiler) exactly what it does to the two double type inputs and that the output also has a double type. Note that a function’s internal operations are rarely so simple and short, it can be arbitrarily long and complicated. This unreasonably short and simple function was chosen here for ease of reading. The declaration for this function is:

```c
double sum(double a, double b);
```

You can think of a function’s declaration as a building’s address in the city, and the definition as the building’s complete blueprints. When the compiler confronts a call to a function during its processing, it doesn’t need to know anything about how the inputs are processed to generate the output. Just as the postman doesn’t need to know the inner structure of a building when delivering the mail. The declaration (address) is enough. Therefore by declaring the functions once at the start of the source files, we don’t have to worry about defining them after they are used.

Even for a simple real-world operation (not a simple summation like above!), you will soon need many functions (for example, some for reading/preparing the inputs, some for the processing, and some for preparing the output). Although it is technically possible, managing all the necessary functions in one file is not easy and is contrary to the modularity principle (see Section 10.1 [Review of library fundamentals], page 372), for example the functions for preparing the input can be usable in your other projects with a different processing. Therefore, as we will see later (in Section 10.1.2 [Linking], page 376), the functions don’t necessarily need to be defined in the source file where they are used. As long as their definitions are ultimately linked to the final executable, everything will be fine. For now, it is just important to remember that the functions that are called within

---

\(^1\) Recall that in C, functions only have one output.
one source file must be declared within the source file (declarations are mandatory), but not necessarily defined there.

In the spirit of modularity, it is common to define contextually similar functions in one source file. For example, in Gnuastro, functions that calculate the median, mean and other statistical functions are defined in `lib/statistics.c`, while functions that deal directly with FITS files are defined in `lib/fits.c`.

Keeping the definition of similar functions in a separate file greatly helps their management and modularity, but this fact alone doesn’t make things much easier for the caller’s source code: recall that while definitions are optional, declarations are mandatory. So if this was all, the caller would have to manually copy and paste (include) all the declarations from the various source files into the file they are working on now. To address this problem, programmers have adopted the header file convention: the header file of a source code contains all the declarations that a caller would need to be able to use any of its functions. For example, in Gnuastro, `lib/statistics.c` (file containing function definitions) comes with `lib/gnuastro/statistics.h` (only containing function declarations).

The discussion above was mainly focused on functions, however, there are many more programming constructs such as pre-processor macros and data structures. Like functions, they also need to be known to the compiler when it confronts a call to them. So the header file also contains their definitions or declarations when they are necessary for the functions.

Pre-processor macros (or macros for short) are replaced with their defined value by the pre-processor before compilation. Conventionally they are written only in capital letters to be easily recognized. It is just important to understand that the compiler doesn’t see the macros, it sees their fixed values. So when a header specifies macros you can do your programming without worrying about the actual values. The standard C types (for example `int`, or `float`) are very low-level and basic. We can collect multiple C types into a structure for a higher-level way to keep and pass-along data. See Section 10.3.6.1 [Generic data container (gal_data_t)], page 400, for some examples of macros and data structures.

The contents in the header need to be included into the caller’s source code with a special pre-processor command: `#include <path/to/header.h>`. As the name suggests, the pre-processor goes through the source code prior to the processor (or compiler). One of its jobs is to include, or merge, the contents of files that are mentioned with this directive in the source code. Therefore the compiler sees a single entity containing the contents of the main file and all the included files. This allows you to include many (sometimes thousands of) declarations into your code with only one line. Since the headers are also installed with the library into your system, you don’t even need to keep a copy of them for each separate program, making things even more convenient.

Try opening some of the `.c` files in Gnuastro’s `lib/` directory with a text editor to check out the include directives at the start of the file (after the copyright notice). Let’s take `lib/fits.c` as an example. You will notice that Gnuastro’s header files (like `gnuastro/fits.h`) are indeed within this directory (the `fits.h` file is in the `gnuastro/` directory). You will notice that files like `stdio.h`, or `string.h` are not in this directory (or anywhere within Gnuastro).
On most systems the basic C header files (like stdio.h and string.h mentioned above) are located in /usr/include/. Your compiler is configured to automatically search that directory (and possibly others), so you don’t have to explicitly mention these directories. Go ahead, look into the /usr/include directory and find stdio.h for example. When the necessary header files are not in those specific libraries, the pre-processor can also search in places other than the current directory. You can specify those directories with this pre-processor option³:

```
-I DIR  "Add the directory DIR to the list of directories to be searched for header files. Directories named by '-I' are searched before the standard system include directories. If the directory DIR is a standard system include directory, the option is ignored to ensure that the default search order for system directories and the special treatment of system headers are not defeated...” (quoted from the GNU Compiler Collection manual). Note that the space between I and the directory is optional and commonly not used.
```

If the pre-processor can’t find the included files, it will abort with an error. In fact a common error when building programs that depend on a library is that the compiler doesn’t not know where a library’s header is (see Section 3.3.5 [Known issues], page 102). So you have to manually tell the compiler where to look for the library’s headers with the -I option. For a small software with one or two source files, this can be done manually (see Section 10.1.3 [Summary and example on libraries], page 379). However, to enhance modularity, Gnuastro (and most other bin/libraries) contain many source files, so the compiler is invoked many times⁴. This makes manual addition or modification of this option practically impossible.

To solve this problem, in the GNU build system, there are conventional environment variables for the various kinds of compiler options (or flags). These environment variables are used in every call to the compiler (they can be empty). The environment variable used for the C Pre-Processor (or CPP) is CPPFLAGS. By giving CPPFLAGS a value once, you can be sure that each call to the compiler will be affected. See Section 3.3.5 [Known issues], page 102, for an example of how to set this variable at configure time.

As described in Section 3.3.1.2 [Installation directory], page 92, you can select the top installation directory of a software using the GNU build system, when you ./configure it. All the separate components will be put in their separate sub-directory under that, for example the programs, compiled libraries and library headers will go into $prefix/bin (replace $prefix with a directory), $prefix/lib, and $prefix/include respectively. For enhanced modularity, libraries that contain diverse collections of functions (like GSL, WC-SLIB, and Gnuastro), put their header files in a sub-directory unique to themselves. For example all Gnuastro’s header files are installed in $prefix/include/gnuastro. In your source code, you need to keep the library’s sub-directory when including the headers from such libraries, for example #include <gnuastro/fits.h>⁵. Not all libraries need to follow

---

² The include/ directory name is taken from the pre-processor’s #include directive, which is also the motivation behind the '-I' in the -I option to the pre-processor.
³ Try running Gnuastro’s make and find the directories given to the compiler with the -I option.
⁴ Nearly every command you see being executed after running make is one call to the compiler.
⁵ the top $prefix/include directory is usually known to the compiler
this convention, for example CFITSIO only has one header (fitsio.h) which is directly installed in \$prefix/include.

## 10.1.2 Linking

To enhance modularity, similar functions are defined in one source file (with a .c suffix, see Section 10.1.1 [Headers], page 373, for more). After running `make`, each human-readable, .c file is translated (or compiled) into a computer-readable “object” file (ending with .o). Note that object files are also created when building programs, they aren’t particular to libraries. Try opening Gnuastro’s lib/ and bin/progname/ directories after running `make` to see these object files\(^6\). Afterwards, the object files are *linked* together to create an executable program or a library.

The object files contain the full definition of the functions in the respective .c file along with a list of any other function (or generally “symbol”) that is referenced there. To get a list of those functions you can use the `nm` program which is part of GNU Binutils. For example from the top Gnuastro directory, run:

```
$ nm bin/arithmetic/arithmetic.o
```

This will print a list of all the functions (more generally, ‘symbols’) that were called within `bin/arithmetic/arithmetic.c` along with some further information (for example a T in the second column shows that this function is actually defined here, U says that it is undefined here). Try opening the .c file to check some of these functions for your self. Run `info nm` for more information.

To recap, the *compiler* created the separate object files mentioned above for each .c file. The *linker* will then combine all the symbols of the various object files (and libraries) into one program or library. In the case of Arithmetic (a program) the contents of the object files in `bin/arithmetic/` are copied (and re-ordered) into one final executable file which we can run from the operating system.

There are two ways to *link* all the necessary symbols: static and dynamic/shared. When the symbols (computer-readable function definitions in most cases) are copied into the output, it is called *static* linking. When the symbols are kept in their original file and only a reference to them is kept in the executable, it is called *dynamic*, or *shared* linking.

Let’s have a closer look at the executable to understand this better: we’ll assume you have built Gnuastro without any customization and installed Gnuastro into the default /usr/local/ directory (see Section 3.3.1.2 [Installation directory], page 92). If you tried the `nm` command on one of Arithmetic’s object files above, then with the command below you can confirm that all the functions that were defined in the object file above (had a T in the second column) are also defined in the astarithmetic executable:

```
$ nm /usr/local/bin/astarithmetic
```

These symbols/function have been statically linked (copied) in the final executable. But you will notice that there are still many undefined symbols in the executable (those with a U in the second column). One class of such functions are Gnuastro’s own library functions that start with ‘gal_’:

```
$ nm /usr/local/bin/astarithmetic | grep gal_
```

\(^6\) Gnuastro uses GNU Libtool for portable library creation. Libtool will also make a .lo file for each .c file when building libraries (.lo files are human-readable).
These undefined symbols (functions) are present in another file and will be linked to the Arithmetic program every time you run it. Therefore they are known as dynamically linked libraries. As we saw above, static linking is done when the executable is being built. However, when a program is dynamically linked to a library, at build-time, the library’s symbols are only checked with the available libraries: they are not actually copied into the program’s executable. Every time you run the program, the (dynamic) linker will be activated and will try to link the program to the installed library before the program starts.

If you want all the libraries to be statically linked to the executables, you have to tell Libtool (which Gnuastro uses for the linking) to disable shared libraries at configure time:

```bash
$ configure --disable-shared
```

Try configuring Gnuastro with the command above, then build and install it (as described in Section 1.1 [Quick start], page 1). Afterwards, check the gal symbols in the installed Arithmetic executable like before. You will see that they are actually copied this time (have a T in the second column). If the second column doesn’t convince you, look at the executable file size with the following command:

```bash
$ ls -lh /usr/local/bin/astarithmetic
```

It should be around 4.2 Megabytes with this static linking. If you configure and build Gnuastro again with shared libraries enabled (which is the default), you will notice that it is roughly 100 Kilobytes!

This huge difference would have been very significant in the old days, but with the roughly Terabyte storage drives commonly in use today, it is negligible. Fortunately, output file size is not the only benefit of dynamic linking: since it links to the libraries at run-time (rather than build-time), you don’t have to re-build a higher-level program or library when an update comes for one of the lower-level libraries it depends on. You just install the new low-level library and it will automatically be used/linked next time in the programs that use it. To be fair, this also creates a few complications:

- Reproducibility: Even though your high-level tool has the same version as before, with the updated library, you might not get the same results.
- Broken links: if some functions have been changed or removed in the updated library, then the linker will abort with an error at run-time. Therefore you need to re-build your higher-level program or library.

To see a list of all the shared libraries that are needed for a program or a shared library to run, you can use GNU C library’s `ldd` program, for example:

```bash
$ ldd /usr/local/bin/astarithmetic
```

Library file names (in their installation directory) start with a `lib` and their ending (suffix) shows if they are static (`.a`) or dynamic (`.so`), as described below. The name of

---

7 Do not confuse dynamically linked libraries with dynamically loaded libraries. The former (that is discussed here) are only loaded once at the program startup. However, the latter can be loaded anytime during the program’s execution, they are also known as plugins.

8 Libtool is very common and is commonly used. Therefore, you can use this option to configure on most programs using the GNU build system if you want static linking.

9 Both of these can be avoided by joining the mailing lists of the lower-level libraries and checking the changes in newer versions before installing them. Updates that result in such behaviors are generally heavily emphasized in the release notes.

10 If your operating system is not using the GNU C library, you might need another tool.
the library is in the middle of these two, for example `libgsl.a` or `libgnuastro.a` (GSL and Gnuastro's static libraries), and `libgsl.so.23.0.0` or `libgnuastro.so.4.0.0` (GSL and Gnuastro's shared library, the numbers may be different).

- A static library is known as an archive file and has the `.a` suffix. A static library is not an executable file.
- A shared library ends with the `.so.X.Y.Z` suffix and is executable. The three numbers in the suffix, describe the version of the shared library. Shared library versions are defined to allow multiple versions of a shared library simultaneously on a system and to help detect possible updates in the library and programs that depend on it by the linker.

It is very important to mention that this version number is different from the software version number (see Section 1.5 [Version numbering], page 7), so do not confuse the two. See the “Library interface versions” chapter of GNU Libtool for more.

For each shared library, we also have two symbolic links ending with `.so.X` and `.so`. They are automatically set by the installer, but you can change them (point them to another version of the library) when you have multiple versions of a library on your system.

Libraries that are built with GNU Libtool (including Gnuastro and its dependencies), build both static and dynamic libraries by default and install them in `prefix/lib/` directory (for more on `prefix`, see Section 3.3.1.2 [Installation directory], page 92). In this way, programs depending on the libraries can link with them however they prefer. See the contents of `/usr/local/lib` with the command below to see both the static and shared libraries available there, along with their executable nature and the symbolic links:

```
$ ls -l /usr/local/lib/
```

To link with a library, the linker needs to know where to find the library. At compilation time, these locations can be passed to the linker with two separate options (see Section 10.1.3 [Summary and example on libraries], page 379, for an example) as described below. You can see these options and their usage in practice while building Gnuastro (after running `make`):

```
-L DIR  Will tell the linker to look into DIR for the libraries. For example 
-L/usr/local/lib, or -L/home/yourname/.local/lib. You can make 
multiple calls to this option, so the linker looks into several directories at 
compilation time. Note that the space between L and the directory is optional 
and commonly ignored (written as -LDIR).

-lLIBRARY Specify the unique library identifier/name (not containing directory or 
shared/dynamic nature) to be linked with the executable. As discussed above, 
library file names have fixed parts which must not be given to this option. 
So -lgsl will guide the linker to either look for libgsl.a or libgsl.so (depending on the type of linking it is suppose to do). You can link many 
libraries by repeated calls to this option.

**Very important:** The place of this option on the compiler’s command matters. 
This is often a source of confusion for beginners, so let’s assume you have asked 
the linker to link with library A using this option. As soon as the linker confronts
this option, it looks into the list of the undefined symbols it has found until that point and does a search in library A for any of those symbols. If any pending undefined symbol is found in library A, it is used. After the search in undefined symbols is complete, the contents of library A are completely discarded from the linker’s memory. Therefore, if a later object file or library uses an unlinked symbol in library A, the linker will abort after it has finished its search in all the input libraries or object files.

As an example, Gnuastro’s gal_fits_img_read function depends on the fits_read_pix function of CFITSIO (specified with -lcfitsio, which in turn depends on the cURL library, called with -lcurl). So the proper way to link something that uses this function is -lgnuastro -lcfitsio -lcurl. If instead, you give: -lcfitsio -lgnuastro the linker will complain and abort. To avoid such linking complexities when using Gnuastro’s library, we recommend using Section 10.2 [BuildProgram], page 380.

If you have compiled and linked your program with a dynamic library, then the dynamic linker also needs to know the location of the libraries after building the program: every time the program is run afterwards. Therefore, it may happen that you don’t get any errors when compiling/linking a program, but are unable to run your program because of a failure to find a library. This happens because the dynamic linker hasn’t found the dynamic library at run time.

To find the dynamic libraries at run-time, the linker looks into the paths, or directories, in the LD_LIBRARY_PATH environment variable. For a discussion on environment variables, especially search paths like LD_LIBRARY_PATH, and how you can add new directories to them, see Section 3.3.1.2 [Installation directory], page 92.

10.1.3 Summary and example on libraries

After the mostly abstract discussions of Section 10.1.1 [Headers], page 373, and Section 10.1.2 [Linking], page 376, we’ll give a small tutorial here. But before that, let’s recall the general steps of how your source code is prepared, compiled and linked to the libraries it depends on so you can run it:

1. The pre-processor includes the header (.h) files into the function definition (.c) files, expands pre-processor macros. Generally the pre-processor prepares the human-readable source for compilation (reviewed in Section 10.1.1 [Headers], page 373).

2. The compiler will translate (compile) the human-readable contents of each source (merged .c and the .h files, or generally the output of the pre-processor) into the computer-readable code of .o files.

3. The linker will link the called function definitions from various compiled files to create one unified object. When the unified product has a main function, this function is the product’s only entry point, enabling the operating system or user to directly interact with it, so the product is a program. When the product doesn’t have a main function, the linker’s product is a library and its exported functions can be linked to other executables (it has many entry points).

The GNU Compiler Collection (or GCC for short) will do all three steps. So as a first example, from Gnuastro’s source, go to tests/lib/. This directory contains the library
tests, you can use these as some simple tutorials. For this demonstration, we will compile and run the `arraymanip.c`. This small program will call Gnuastro library for some simple operations on an array (open it and have a look). To compile this program, run this command inside the directory containing it.

$$\texttt{gcc arraymanip.c -lgnuastro -lm -o arraymanip}$$

The two `-lgnuastro` and `-lm` options (in this order) tell GCC to first link with the Gnuastro library and then with C’s math library. The `-o` option is used to specify the name of the output executable, without it the output file name will be `a.out` (on most OSs), independent of your input file name(s).

If your top Gnuastro installation directory (let’s call it `$prefix$, see Section 3.3.1.2 [Installation directory], page 92) is not recognized by GCC, you will get pre-processor errors for unknown header files. Once you fix it, you will get linker errors for undefined functions. To fix both, you should run GCC as follows: additionally telling it which directories it can find Gnuastro’s headers and compiled library (see Section 10.1.1 [Headers], page 373, and Section 10.1.2 [Linking], page 376):

$$\texttt{gcc -I$prefix/include -L$prefix/lib arraymanip.c -lgnuastro -lm -o arraymanip}$$

This single command has done all the pre-processor, compilation and linker operations. Therefore no intermediate files (object files in particular) were created, only a single output executable was created. You are now ready to run the program with:

$$\texttt{./arraymanip}$$

The Gnuastro functions called by this program only needed to be linked with the C math library. But if your program needs WCS coordinate transformations, needs to read a FITS file, needs special math operations (which include its linear algebra operations), or you want it to run on multiple CPU threads, you also need to add these libraries in the call to GCC: `-lgnuastro -lwcs -lcfitsio -l gsl -lgslcblas -pthread -lm`. In Section 10.3 [Gnuastro library], page 384, where each function is documented, it is mentioned which libraries (if any) must also be linked when you call a function. If you feel all these linkings can be confusing, please consider Gnuastro’s Section 10.2 [BuildProgram], page 380, program.

### 10.2 BuildProgram

The number and order of libraries that are necessary for linking a program with Gnuastro library might be too confusing when you need to compile a small program for one particular job (with one source file). BuildProgram will use the information gathered during configuring Gnuastro and link with all the appropriate libraries on your system. This will allow you to easily compile, link and run programs that use Gnuastro’s library with one simple command and not worry about which libraries to link to, or the linking order.

BuildProgram uses GNU Libtool to find the necessary libraries to link against (GNU Libtool is the same program that builds all of Gnuastro’s libraries and programs when you run `make`). So in the future, if Gnuastro’s prerequisite libraries change or other libraries are added, you don’t have to worry, you can just run BuildProgram and internal linking will be done correctly.
**BuildProgram requires GNU Libtool:** BuildProgram depends on GNU Libtool, other implementations don’t have some necessary features. If GNU Libtool isn’t available at Gnuastro’s configure time, you will get a notice at the end of the configuration step and BuildProgram will not be built or installed. Please see Section 3.1.2 [Optional dependencies], page 77, for more information.

### 10.2.1 Invoking BuildProgram

BuildProgram will compile and link a C source program with Gnuastro’s library and all its dependencies, greatly facilitating the compilation and running of small programs that use Gnuastro’s library. The executable name is `astbuildprog` with the following general template:

```
$ astbuildprog [OPTION...] C_SOURCE_FILE
```

One line examples:

```bash
## Compile, link and run ‘myprogram.c’:
$ astbuildprog myprogram.c

## Similar to previous, but with optimization and compiler warnings:
$ astbuildprog -Wall -O2 myprogram.c

## Compile and link ‘myprogram.c’, then run it with ‘image.fits’
## as its argument:
$ astbuildprog myprogram.c image.fits

## Also look in other directories for headers and linking:
$ astbuildprog -Lother -Iother/dir myprogram.c

## Just build (compile and link) ‘myprogram.c’, don’t run it:
$ astbuildprog --onlybuild myprogram.c
```

If BuildProgram is to run, it needs a C programming language source file as input. By default it will compile and link the given source into a final executable program and run it. The built executable name can be set with the optional `--output` option. When no output name is set, BuildProgram will use Gnuastro’s Section 4.10 [Automatic output], page 142, system to remove the suffix of the input source file (usually `.c`) and use the resulting name as the built program name.

For the full list of options that BuildProgram shares with other Gnuastro programs, see Section 4.1.2 [Common options], page 109. You may also use Gnuastro’s Section 4.2 [Configuration files], page 120, to specify other libraries/headers to use for special directories and not have to type them in every time.

The C compiler can be chosen with the `--cc` option, or environment variables, please see the description of `--cc` for more. The two common `LDFlags` and `CPPFlags` environment variables are also checked and used in the build by default. Note that they are placed after the values to the corresponding options `--includedir` and `--linkdir`. Therefore BuildProgram’s own options take precedence. Using environment variables can be disabled with the `--noenv` option. Just note that BuildProgram also keeps the important flags in these environment variables in its configuration file. Therefore, in many cases, even though you may needed them to build Gnuastro, you won’t need them in BuildProgram.
The first argument is considered to be the C source file that must be compiled and linked. Any other arguments (non-option tokens on the command-line) will be passed onto the program when BuildProgram wants to run it. Recall that by default BuildProgram will run the program after building it. This behavior can be disabled with the `--onlybuild` option.

When the `--quiet` option (see Section 4.1.2.3 [Operating mode options], page 114) is not called, BuildPrograms will print the compilation and running commands. Once your program grows and you break it up into multiple files (which are much more easily managed with Make), you can use the linking flags of the non-quiet output in your `Makefile`.

`-c STR`  
`--cc=STR`  
C compiler to use for the compilation, if not given environment variables will be used as described in the next paragraph. If the compiler is in your system’s search path, you can simply give its name, for example `--cc=gcc`. If its not in your system’s search path, you can give its full path, for example `--cc=/path/to/your/custom/cc`.  
If this option has no value after parsing the command-line and all configuration files (see Section 4.2.2 [Configuration file precedence], page 121), then BuildProgram will look into the following environment variables in the given order `CC` and `GCC`. If they are also not defined, BuildProgram will ultimately default to the `gcc` command which is present in many systems (sometimes as a link to other compilers).

`-I STR`  
`--includedir=STR`  
Directory to search for files that you `#include` in your C program. Note that headers relating to Gnuastro and its dependencies don’t need this option. This is only necessary if you want to use other headers. It may be called multiple times and order matters. This directory will be searched before those of Gnuastro’s build and also the system search directories. See Section 10.1.1 [Headers], page 373, for a thorough introduction.

From the GNU C Pre-Processor manual: “Add the directory `STR` to the list of directories to be searched for header files. Directories named by `-I` are searched before the standard system include directories. If the directory `STR` is a standard system include directory, the option is ignored to ensure that the default search order for system directories and the special treatment of system headers are not defeated”.

`-L STR`  
`--linkdir=STR`  
Directory to search for compiled libraries to link the program with. Note that all the directories that Gnuastro was built with will already be used by BuildProgram (GNU Libtool). This option is only necessary if your libraries are in other directories. Multiple calls to this option are possible and order matters. This directory will be searched before those of Gnuastro’s build and also the system search directories. See Section 10.1.2 [Linking], page 376, for a thorough introduction.
-l STR
--linklib=STR
Library to link with your program. Note that all the libraries that Gnuastro was built with will already be linked by BuildProgram (GNU Libtool). This option is only necessary if you want to link with other directories. Multiple calls to this option are possible and order matters. This library will be linked before Gnuastro’s library or its dependencies. See Section 10.1.2 [Linking], page 376, for a thorough introduction.

-O INT/STR
--optimize=INT/STR
Compiler optimization level: 0 (for no optimization, good debugging), 1, 2, 3 (for the highest level of optimizations). From the GNU Compiler Collection (GCC) manual: “Without any optimization option, the compiler’s goal is to reduce the cost of compilation and to make debugging produce the expected results. Statements are independent: if you stop the program with a break point between statements, you can then assign a new value to any variable or change the program counter to any other statement in the function and get exactly the results you expect from the source code. Turning on optimization flags makes the compiler attempt to improve the performance and/or code size at the expense of compilation time and possibly the ability to debug the program.” Please see your compiler’s manual for the full list of acceptable values to this option.

-g
--debug
Emit extra information in the compiled binary for use by a debugger. When calling this option, it is best to explicitly disable optimization with -O0. To combine both options you can run -gO0 (see Section 4.1.1.2 [Options], page 107, for how short options can be merged into one).

-W STR
--warning=STR
Print compiler warnings on command-line during compilation. “Warnings are diagnostic messages that report constructions that are not inherently erroneous but that are risky or suggest there may have been an error.” (from the GCC manual). It is always recommended to compile your programs with warnings enabled.

All compiler warning options that start with w are usable by this option in BuildProgram also, see your compiler’s manual for the full list. Some of the most common values to this option are: pedantic (Warnings related to standard C) and all (all issues the compiler confronts).

-t
--tag=STR
The language configuration information. Libtool can build objects and libraries in many languages. In many cases, it can identify the language automatically, but when it doesn’t you can use this option to explicitly notify Libtool of the language. The acceptable values are: CC for C, CXX for C++, GCJ for Java, F77
for Fortran 77, FC for Fortran, GO for Go and RC for Windows Resource. Note that the Gnuastro library is not yet fully compatible with all these languages.

-b
--onlybuild
Only build the program, don’t run it. By default, the built program is immediately run afterwards.

-d
--deletecompiled
Delete the compiled binary file after running it. This option is only relevant when the compiled program is run after being built. In other words, it is only relevant when --onlybuild is not called. It can be useful when you are busy testing a program or just want a fast result and the actual binary/compiled file is not of later use.

-a STR
--la=STR
Use the given .la file (Libtool control file) instead of the one that was produced from Gnuastro’s configuration results. The Libtool control file keeps all the necessary information for building and linking a program with a library built by Libtool. The default prefix/lib/libgnuastro.la keeps all the information necessary to build a program using the Gnuastro library gathered during configure time (see Section 3.3.1.2 [Installation directory], page 92, for prefix). This option is useful when you prefer to use another Libtool control file.

-e
--noenv
Don’t use environment variables in the build, just use the values given to the options. As described above, environment variables like CC, GCC, LDFLAGS, CPPFLAGS will be read by default and used in the build if they have been defined.

10.3 Gnuastro library

Gnuastro library’s programming constructs (function declarations, macros, data structures, or global variables) are classified by context into multiple header files (see Section 10.1.1 [Headers], page 373)\textsuperscript{11}. In this section, the functions in each header will be discussed under a separate sub-section, which includes the name of the header. Assuming a function declaration is in\texttt{headername.h}, you can include its declaration in your source code with:

```c
#include <gnuastro/headername.h>
```

The names of all constructs in \texttt{headername.h} are prefixed with \texttt{gal_headername} (or GAL\_HEADNAME for macros). The \texttt{gal} prefix stands for GNU Astronomy Library.

Gnuastro library functions are compiled into a single file which can be linked on the command-line with the \texttt{-lgnuastro} option. See Section 10.1.2 [Linking], page 376, and Section 10.1.3 [Summary and example on libraries], page 379, for an introduction on linking and some fully working examples of the libraries.

Gnuastro’s library is a high-level library which depends on lower level libraries for some operations (see Section 3.1 [Dependencies], page 74). Therefore if at least one of Gnuastro’s

\textsuperscript{11}Within Gnuastro’s source, all installed .h files in \texttt{lib/gnuastro/} are accompanied by a .c file in \texttt{/lib/}.
functions in your program use functions from the dependencies, you will also need to link those dependencies after linking with Gnuastro. See Section 10.2 [BuildProgram], page 380, for a convenient way to deal with the dependencies. BuildProgram will take care of the libraries to link with your program (which uses the Gnuastro library), and can even run the built program afterwards. Therefore it allows you to conveniently focus on your exciting science/research when using Gnuastro's libraries.

**Libraries are still under heavy development:** Gnuastro was initially created to be a collection of command-line programs. However, as the programs and their shared functions grew, internal (not installed) libraries were added. Since the 0.2 release, the libraries are install-able. Hence the libraries are currently under heavy development and will significantly evolve between releases and will become more mature and stable in due time. It will stabilize with the removal of this notice. Check the NEWS file for interface changes. If you use the Info version of this manual (see Section 4.3.4 [Info], page 125), you don’t have to worry: the documentation will correspond to your installed version.

### 10.3.1 Configuration information (config.h)

The `gnuastro/config.h` header contains information about the full Gnuastro installation on your system. Gnuastro developers should note that this is the only header that is not available within Gnuastro, it is only available to a Gnuastro library user after installation. Within Gnuastro, `config.h` (which is included in every Gnuastro `.c` file, see Section 11.3 [Coding conventions], page 519) has more than enough information about the overall Gnuastro installation.

**GAL_CONFIG_VERSION** [Macro]

This macro can be used as a string literal\(^\text{12}\) containing the version of Gnuastro that is being used. See Section 1.5 [Version numbering], page 7, for the version formats. For example:

```c
printf("Gnuastro version: \%s\n", GAL_CONFIG_VERSION);
```

or

```c
char *gnuastro_version=GAL_CONFIG_VERSION;
```

**GAL_CONFIG_HAVE_LIBGIT2** [Macro]

Libgit2 is an optional dependency of Gnuastro (see Section 3.1.2 [Optional dependencies], page 77). When it is installed and detected at configure time, this macro will have a value of 1 (one). Otherwise, it will have a value of 0 (zero). Gnuastro also comes with some wrappers to make it easier to use libgit2 (see Section 10.3.27 [Git wrappers (git.h)], page 502).

**GAL_CONFIG_HAVE_FITS_IS_REENTRANT** [Macro]

This macro will have a value of 1 when the CFITSIO of the host system has the `fits_is_reentrant` function (available from CFITSIO version 3.30). This function is used to see if CFITSIO was configured to read a FITS file simultaneously on different threads.

GAL_CONFIG_HAVE_WCSLIB_VERSION [Macro]
WCSLIB is the reference library for world coordinate system transformation (see Section 3.1.1.3 [WCSLIB], page 76, and Section 10.3.13 [World Coordinate System (wcs.h)], page 449). However, only more recent versions of WCSLIB also provide its version number. If the WCSLIB that is installed on the system provides its version (through the possibly existing wcslib_version function), this macro will have a value of one, otherwise it will have a value of zero.

GAL_CONFIG_HAVE_WCSLIB_DIS_H [Macro]
This macro has a value of 1 if the host’s WCSLIB has the wcslib/dis.h header for distortion-related operations.

GAL_CONFIG_HAVE_WCSLIB_MJDREF [Macro]
This macro has a value of 1 if the host’s WCSLIB reads and stores the MJDREF FITS header keyword as part of its core wcsptrm structure.

GAL_CONFIG_HAVE_WCSLIB_OBSFIX [Macro]
This macro has a value of 1 if the host’s WCSLIB supports the OBSFIX feature (used by wcsfix function to parse the input WCS for known errors).

GAL_CONFIG_HAVE_PTHREAD_BARRIER [Macro]
The POSIX threads standard define barriers as an optional requirement. Therefore, some operating systems choose to not include it. As one of the ./configure step checks, Gnuastro we check if your system has this POSIX thread barriers. If so, this macro will have a value of 1, otherwise it will have a value of 0. see Section 10.3.2.1 [Implementation of pthread_barrier], page 387, for more.

GAL_CONFIG_SIZEOF_LONG
GAL_CONFIG_SIZEOF_SIZE_T [Macro]
The size of (number of bytes in) the system’s long and size_t types. Their values are commonly either 4 or 8 for 32-bit and 64-bit systems. You can also get this value with the expression ‘sizeof size_t’ for example without having to include this header.

10.3.2 Multithreaded programming (threads.h)
In recent years, newer CPUs don’t have significantly higher frequencies any more. However, CPUs are being manufactured with more cores, enabling more than one operation (thread) at each instant. This can be very useful to speed up many aspects of processing and in particular image processing.

Most of the programs in Gnuastro utilize multi-threaded programming for the CPU intensive processing steps. This can potentially lead to a significant decrease in the running time of a program, see Section 4.5.1 [A note on threads], page 128. In terms of reading the code, you don’t need to know anything about multi-threaded programming. You can simply follow the case where only one thread is to be used. In these cases, threads are not used and can be completely ignored.

When the C language was defined (the K&R’s book was written), using threads was not common, so C’s threading capabilities aren’t introduced there. Gnuastro uses POSIX threads for multi-threaded programming, defined in the pthread.h system wide header. There are various resources for learning to use POSIX threads. An excellent tutorial
Chapter 10: Library

(https://computing.llnl.gov/tutorials/pthreads/) is provided by the Lawrence Livermore National Laboratory, with abundant figures to better understand the concepts, it is a very good start. The book ‘Advanced programming in the Unix environment’\(^{13}\), by Richard Stevens and Stephen Rago, Addison-Wesley, 2013 (Third edition) also has two chapters explaining the POSIX thread constructs which can be very helpful.

An alternative to POSIX threads was OpenMP, but POSIX threads are low level, allowing much more control, while being easier to understand, see Section 11.1 [Why C programming language?], page 516. All the situations where threads are used in Gnuastro currently are completely independent with no need of coordination between the threads. Such problems are known as “embarrassingly parallel” problems. They are some of the simplest problems to solve with threads and are also the ones that benefit most from them, see the LLNL introduction\(^{14}\).

One very useful POSIX thread concept is `pthread_barrier`. Unfortunately, it is only an optional feature in the POSIX standard, so some operating systems don’t include it. Therefore in Section 10.3.2.1 [Implementation of `pthread_barrier`], page 387, we introduce our own implementation. This is a rather technical section only necessary for more technical readers and you can safely ignore it. Following that, we describe the helper functions in this header that can greatly simplify writing a multi-threaded program, see Section 10.3.2.2 [Gnuastro’s thread related functions], page 388, for more.

### 10.3.2.1 Implementation of `pthread_barrier`

One optional feature of the POSIX Threads standard is the `pthread_barrier` concept. It is a very useful high-level construct that allows for independent threads to “wait” behind a “barrier” for the rest after they finish. Barriers can thus greatly simplify the code in a multi-threaded program, so they are heavily used in Gnuastro. However, since its an optional feature in the POSIX standard, some operating systems don’t include it. So to make Gnuastro portable, we have written our own implementation of those `pthread_barrier` functions.

At `./configure` time, Gnuastro will check if `pthread_barrier` constructs are available on your system or not. If `pthread_barrier` is not available, our internal implementation will be compiled into the Gnuastro library and the definitions and declarations below will be usable in your code with `#include <gnuastro/threads.h>`.

```c

**Compile_time**

`#include <gnuastro/threads.h>`

*Threads related functions*

### `pthread_barrierattr_t`

Type to specify the attributes of a POSIX threads barrier.

### `pthread_barrier_t`

Structure defining the POSIX threads barrier.

### `int` [Function]

**`pthread_barrier_init`**

`pthread_barrier_init (pthread_barrier_t *b, pthread_barrierattr_t *attr, unsigned int limit)`

Initialize the barrier `b`, with the attributes `attr` and total limit (a number of) threads that must wait behind it. This function must be called before spinning off threads.

---

\(^{13}\) Don’t let the title scare you! The two chapters on Multi-threaded programming are very self-sufficient and don’t need any more knowledge than K&R.

\(^{14}\) https://computing.llnl.gov/tutorials/parallel_comp/
int [Function]

pthread_barrier_wait (pthread_barrier_t *b)
This function is called within each thread, just before it is ready to return. Once a thread’s function hits this, it will “wait” until all the other functions are also finished.

int [Function]

pthread_barrier_destroy (pthread_barrier_t *b)
Destroy all the information in the barrier structure. This should be called by the function that spun-off the threads after all the threads have finished.

Destroy a barrier before re-using it: It is very important to destroy the barrier before (possibly) reusing it. This destroy function not only destroys the internal structures, it also waits (in 1 microsecond intervals, so you will not notice!) until all the threads don’t need the barrier structure any more. If you immediately start spinning off new threads with a not-destroyed barrier, then the internal structure of the remaining threads will get mixed with the new ones and you will get very strange and apparently random errors that are extremely hard to debug.

10.3.2.2 Gnuastro’s thread related functions
The POSIX Threads functions offered in the C library are very low-level and offer a great range of control over the properties of the threads. So if you are interested in customizing your tools for complicated thread applications, it is strongly encouraged to get a nice familiarity with them. Some resources were introduced in Section 10.3.2 [Multithreaded programming (threads.h)], page 386.

However, in many cases used in astronomical data analysis, you don’t need communication between threads and each target operation can be done independently. Since such operations are very common, Gnuastro provides the tools below to facilitate the creation and management of jobs without any particular knowledge of POSIX Threads for such operations. The most interesting high-level functions of this section are the gal_threads_number and gal_threads_spin_off that identify the number of threads on the system and spin-off threads. You can see a demonstration of using these functions in Section 10.4.3 [Library demo - multi-threaded operation], page 509.

gal_threads_params
[C struct]
Structure keeping the parameters of each thread. When each thread is created, a pointer to this structure is passed to it. The params element can be the pointer to a structure defined by the user which contains all the necessary parameters to pass onto the worker function. The rest of the elements within this structure are set internally by gal_threads_spin_off and are relevant to the worker function.

struct gal_threads_params
{
  size_t id; /* Id of this thread. */
  void *params; /* User-identified pointer. */
  size_t *indices; /* Target indices given to this thread. */
  pthread_barrier_t *b; /* Barrier for all threads. */
};
size_t gal_threads_number ()

Return the number of threads that the operating system has available for your program. This number is usually fixed for a single machine and doesn’t change. So this function is useful when you want to run your program on different machines (with different CPUs).

void gal_threads_spin_off (void *(*worker)(void *), void *caller_params, size_t numactions, size_t numthreads)

Distribute numactions jobs between numthreads threads and spin-off each thread by calling the worker function. The caller_params pointer will also be passed to worker as part of the gal_threads_params structure. For a fully working example of this function, please see Section 10.4.3 [Library demo - multi-threaded operation], page 509.

void gal_threads_attr_barrier_init (pthread_attr_t *attr, pthread_barrier_t *b, size_t limit)

This is a low-level function in case you don’t want to use gal_threads_spin_off. It will initialize the general thread attribute attr and the barrier b with limit threads to wait behind the barrier. For maximum efficiency, the threads initialized with this function will be detached. Therefore no communication is possible between these threads and in particular pthread_join won’t work on these threads. You have to use the barrier constructs to wait for all threads to finish.

void gal_threads_dist_in_threads (size_t numactions, size_t numthreads, size_t **outthrds, size_t *outthrdcols)

This is a low-level function in case you don’t want to use gal_threads_spin_off. Identify the “index” es (starting from 0) of the actions to be done on each thread in the outthrds array. outthrds is treated as a 2D array with numthreads rows and outthrdcols columns. The indexes in each row, identify the actions that should be done by one thread. Please see the explanation below to understand the purpose of this operation.

Let’s assume you have A actions (where there is only one function and the input values differ for each action) and T threads available to the system with A > T (common values for these two would be A > 1000 and T < 10). Spinning off a thread is not a cheap job and requires a significant number of CPU cycles. Therefore, creating A threads is not the best way to address such a problem. The most efficient way to manage the actions is such that only T threads are created, and each thread works on a list of actions identified for it in series (one after the other). This way your CPU will get all the actions done with minimal overhead.

The purpose of this function is to do what we explained above: each row in the outthrds array contains the indexes of actions which must be done by one thread. outthrds contains outthrdcols columns. In using outthrds, you don’t have to know the number of columns. The GAL_BLANK_SIZE_T macro has a role very similar to a string’s \0: every row finishes with this macro, so can easily stop parsing
the indexes in the row when you confront it. Please see the example program in
\texttt{tests/lib/multithread.c} for a demonstration.

\subsection*{10.3.3 Library data types (\texttt{type.h})}

Data in astronomy can have many types, numeric (numbers) and strings (names, identifiers). The former can also be divided into integers and floats, see Section 4.6 [Numeric data types], page 130, for a thorough discussion of the different numeric data types and which one is useful for different contexts.

To deal with the very large diversity of types that are available (and used in different contexts), in Gnuastro each type is identified with global integer variable with a fixed name, this variable is then passed onto functions that can work on any type or is stored in Gnuastro’s Section 10.3.6.1 [Generic data container (\texttt{gal_data_t})], page 400, as one piece of meta-data.

The actual values within these integer constants is irrelevant and you should never rely on them. When you need to check, explicitly use the named variable in the table below. If you want to check with more than one type, you can use C’s \texttt{switch} statement.

Since Gnuastro heavily deals with file input-output, the types it defines are fixed width types, these types are portable to all systems and are defined in the standard C header \texttt{stdint.h}. You don’t need to include this header, it is included by any Gnuastro header that deals with the different types. However, the most commonly used types in a C (or C++) program (for example \texttt{int} or \texttt{long}) are not defined by their exact width (storage size), but by their minimum storage. So for example on some systems, \texttt{int} may be 2 bytes (16-bits, the minimum required by the standard) and on others it may be 4 bytes (32-bits, common in modern systems).

With every type, a unique “blank” value (or place holder showing the absence of data) can be defined. Please see Section 10.3.5 [Library blank values (\texttt{blank.h})], page 396, for constants that Gnuastro recognizes as a blank value for each type. See Section 4.6 [Numeric data types], page 130, for more explanation on the limits and particular aspects of each type.

\begin{description}
\item[\texttt{GAL_TYPE_INVALID}] [Global integer]
This is just a place holder to specifically mark that no type has been set.
\item[\texttt{GAL_TYPE_BIT}] [Global integer]
Identifier for a bit-stream. Currently no program in Gnuastro works directly on bits, but features will be added in the future.
\item[\texttt{GAL_TYPE_UINT8}] [Global integer]
Identifier for an unsigned, 8-bit integer type: \texttt{uint8_t} (from \texttt{stdint.h}), or an \texttt{unsigned char} in most modern systems.
\item[\texttt{GAL_TYPE_INT8}] [Global integer]
Identifier for a signed, 8-bit integer type: \texttt{int8_t} (from \texttt{stdint.h}), or a \texttt{signed char} in most modern systems.
\item[\texttt{GAL_TYPE_UINT16}] [Global integer]
Identifier for an unsigned, 16-bit integer type: \texttt{uint16_t} (from \texttt{stdint.h}), or an \texttt{unsigned short} in most modern systems.
\end{description}
GAL_TYPE_INT16  
Identifier for a signed, 16-bit integer type: int16_t (from stdint.h), or a short in most modern systems.

GAL_TYPE_UINT32  
Identifier for an unsigned, 32-bit integer type: uint32_t (from stdint.h), or an unsigned int in most modern systems.

GAL_TYPE_INT32  
Identifier for a signed, 32-bit integer type: int32_t (from stdint.h), or an int in most modern systems.

GAL_TYPE_UINT64  
Identifier for an unsigned, 64-bit integer type: uint64_t (from stdint.h), or an unsigned long in most modern 64-bit systems.

GAL_TYPE_INT64  
Identifier for a signed, 64-bit integer type: int64_t (from stdint.h), or an long in most modern 64-bit systems.

GAL_TYPE_INT  
Identifier for a int type. This is just an alias to int16, or int32 types, depending on the system.

GAL_TYPE_UINT  
Identifier for a unsigned int type. This is just an alias to uint16, or uint32 types, depending on the system.

GAL_TYPE_ULONG  
Identifier for a unsigned long type. This is just an alias to uint32, or uint64 types for 32-bit, or 64-bit systems respectively.

GAL_TYPE_LONG  
Identifier for a long type. This is just an alias to int32, or int64 types for 32-bit, or 64-bit systems respectively.

GAL_TYPE_SIZE_T  
Identifier for a size_t type. This is just an alias to uint32, or uint64 types for 32-bit, or 64-bit systems respectively.

GAL_TYPE_FLOAT32  
Identifier for a 32-bit single precision floating point type or float in C.

GAL_TYPE_FLOAT64  
Identifier for a 64-bit double precision floating point type or double in C.

GAL_TYPE_COMPLEX32  
Identifier for a complex number composed of two float types. Note that the complex type is not yet fully implemented in all Gnuastro’s programs.
Chapter 10: Library

GAL_TYPE_COMPLEX64 [Global integer]
Identifier for a complex number composed of two double types. Note that the complex type is not yet fully implemented in all Gnuastro’s programs.

GAL_TYPE_STRING [Global integer]
Identifier for a string of characters (char *).

GAL_TYPE_STRLL [Global integer]
Identifier for a linked list of string of characters (gal_list_str_t, see Section 10.3.8.1 [List of strings], page 413).

The functions below are defined to make working with the integer constants above easier. In the functions below, the constants above can be used for the type input argument.

size_t [Function]
gal_type_sizeof (uint8_t type)
Return the number of bytes occupied by type. Internally, this function uses C’s sizeof operator to measure the size of each type.

char * [Function]
gal_type_name (uint8_t type, int long_name)
Return a string literal that contains the name of type. It can return both short and long formats of the type names (for example f32 and float32). If long_name is non-zero, the long format will be returned, otherwise the short name will be returned. The output string is statically allocated, so it should not be freed. This function is the inverse of the gal_type_from_name function. For the full list of names/strings that this function will return, see Section 4.6 [Numeric data types], page 130.

uint8_t [Function]
gal_type_from_name (char *str)
Return the Gnuastro integer constant that corresponds to the string str. This function is the inverse of the gal_type_name function and accepts both the short and long formats of each type. For the full list of names/strings that this function will return, see Section 4.6 [Numeric data types], page 130.

void [Function]
gal_type_min (uint8_t type, void *in)
Put the minimum possible value of type in the space pointed to by in. Since the value can have any type, this function doesn’t return anything, it assumes the space for the given type is available to in and writes the value there. Here is one example

```c
int32_t min;
gal_type_min(GAL_TYPE_INT32, &min);
```

Note: Do not use the minimum value for a blank value of a general (initially unknown) type, please use the constants/functions provided in Section 10.3.5 [Library blank values (blank.h)], page 396, for the definition and usage of blank values.

void [Function]
gal_type_max (uint8_t type, void *in)
Put the maximum possible value of type in the space pointed to by in. Since the value can have any type, this function doesn’t return anything, it assumes the space for the given type is available to in and writes the value there. Here is one example
uint16_t max;
gal_type_max(GAL_TYPE_INT16, &max);

Note: Do not use the maximum value for a blank value of a general (initially unknown) type, please use the constants/functions provided in Section 10.3.5 [Library blank values (blank.h)], page 396, for the definition and usage of blank values.

int

[Function]
gal_type_is_int (uint8_t type)
Return 1 if the type is an integer (any width and any sign).

int

[Function]
gal_type_is_list (uint8_t type)
Return 1 if the type is a linked list and zero otherwise.

int

[Function]
gal_type_out (int first_type, int second_type)
Return the larger of the two given types which can be used for the type of the output of an operation involving the two input types.

char *

[Function]
gal_type_bit_string (void *in, size_t size)
Return the bit-string in the size bytes that in points to. The string is dynamically allocated and must be freed afterwards. You can use it to inspect the bits within one region of memory. Here is one short example:

```c
int32_t a=2017;
char *bitstr=gal_type_bit_string(&a, 4);
printf("%d: %s (%X)\n", a, bitstr, a);
free(bitstr);
```

which will produce:

```
2017: 11100001000001110000000000000000 (7E1)
```

As the example above shows, the bit-string is not the most efficient way to inspect bits. If you are familiar with hexadecimal notation, it is much more compact, see https://en.wikipedia.org/wiki/Hexadecimal. You can use printf’s %x or %X to print integers in hexadecimal format.

char *

[Function]
gal_type_to_string (void *ptr, uint8_t type, int quote_if_str_has_space);
Read the contents of the memory that ptr points to (assuming it has type type and print it into an allocated string which is returned.

If the memory is a string of characters and quote_if_str_has_space is non-zero, the output string will have double-quotes around it if it contains space characters. Also, note that in this case, ptr must be a pointer to an array of characters (or char **), as in the example below (which will put "sample string" into out):

```c
char *out, *string="sample string"
out = gal_type_to_string(&string, GAL_TYPE_STRING, 1);
```
Chapter 10: Library

int gal_type_from_string (void **out, char *string, uint8_t type)
Read a string as a given data type and put a pointer to it in *out. When *out!=NULL,
then it is assumed to be already allocated and the value will be simply put there. If
*out==NULL, then space will be allocated for the given type and the string will be
read into that type.

Note that when we are dealing with a string type, *out should be interpreted as char
** (one element in an array of pointers to different strings). In other words, out
should be char ***.

This function can be used to fill in arrays of numbers from strings (in an already
allocated data structure), or add nodes to a linked list (if the type is a list type). For
an array, you have to pass the pointer to the i\textsuperscript{th} element where you want the value
to be stored, for example &array[i]).

If the string was successfully parsed to the requested type, this function will return a
0 (zero), otherwise it will return 1 (one). This output format will help you check the
status of the conversion in a code like the example below:

```c
if( gal_type_from_string(&out, string, GAL_TYPE_FLOAT32) )
{
    fprintf(stderr, "%s couldn’t be read as float32.\n", string);
    exit(EXIT_FAILURE);
}
```

void * gal_type_string_to_number (char *string, uint8_t *type)
Read string into smallest type that can host the number, the allocated space for
the number will be returned and the type of the number will be put into the memory
that type points to. If string couldn’t be read as a number, this function will return
NULL.

This function calls the C library’s `strtod` function to read string as a double-
precision floating point number. When successful, it will check the value to put
it in the smallest numerical data type that can handle it. However, if string is suc-
cessfully parsed as a number and there is . in string, it will force the number into
floating point types. For example "5" is read as an integer, while "5." or "5.0", or
"5.00" will be read as a floating point (single-precision).

For the ranges acceptable by each type see Section 4.6 [Numeric data types], page 130.
For integers, the range is clear, but for floating point types, this function will count
the number of significant digits and determine if the given string is single or double
precision as described in that section.

10.3.4 Pointers (pointer.h)

Pointers play an important role in the C programming language. As the name suggests,
they point to a byte in memory (like an address in a city). The C programming language
gives you complete freedom in how to use the byte (and the bytes that follow it). Pointers
are thus a very powerful feature of C. However, as the saying goes: “With great power
comes great responsibility”, so they must be approached with care. The functions in this
header are not very complex, they are just wrappers over some basic pointer functionality regarding pointer arithmetic and allocation (in memory or HDD/SSD).

```c
void * gal_pointer_increment (void *pointer, size_t increment, uint8_t type)
    // Return a pointer to an element that is increment elements ahead of pointer, assuming each element has type of type. For the type codes, see Section 10.3.3 [Library data types (type.h)], page 390.
    // When working with the array elements of gal_data_t, we are actually dealing with void * pointers. However, pointer arithmetic doesn’t apply to void *, because the system doesn’t know how many bytes there are in each element to increment the pointer respectively. This function will use the given type to calculate where the incremented element is located in memory.
```

```c
size_t gal_pointer_num_between (void *earlier, void *later, uint8_t type)
    // Return the number of elements (in the given type) between earlier and later. For the type codes, see Section 10.3.3 [Library data types (type.h)], page 390.
```

```c
void * gal_pointer_allocate (uint8_t type, size_t size, int clear, const char *funcname, const char *varname)
    // Allocate an array of type type with size elements in RAM (for the type codes, see Section 10.3.3 [Library data types (type.h)], page 390). If clear!=0, then the allocated space is set to zero (cleared). This is effectively just a wrapper around C’s malloc or calloc functions but takes Gnuastro’s integer type codes and will also abort with a clear error if there the allocation was not successful.
    // When space cannot be allocated, this function will abort the program with a message containing the reason for the failure. funcname (name of the function calling this function) and varname (name of variable that needs this space) will be used in this error message if they are not NULL. In most modern compilers, you can use the generic __func__ variable for funcname. In this way, you don’t have to manually copy and paste the function name or worry about it changing later (__func__ was standardized in C99).
```

```c
void * gal_pointerAllocateMmap (size_t size, uint8_t type, int clear, char **mmapname)
    // Allocate the necessary space to keep size elements of type type in HDD/SSD (a file, not in RAM). for the type codes, see Section 10.3.3 [Library data types (type.h)], page 390. If clear!=0, then the allocated space will also be cleared. The allocation is done using C’s mmap function. The name of the file containing the allocated space is an allocated string that will be put in *mmapname.
    // Note that the kernel doesn’t allow an infinite number of memory mappings to files. So it is not recommended to use this function with every allocation. The best case scenario to use this function is for large arrays that are very large and can fill up the RAM. Keep the smaller arrays in RAM, which is faster and can have a (theoretically) unlimited number of allocations.
```
When you are done with the dataset and don’t need it anymore, don’t use `free` (the dataset isn’t in RAM). Just delete the file (and the allocated space for the filename) with the commands below:

```c
remove(mmapname);
free(mmapname);
```

### 10.3.5 Library blank values (`blank.h`)

When the position of an element in a dataset is important (for example a pixel in an image), a place-holder is necessary for the element if we don’t have a value to fill it with (for example the CCD cannot read those pixels). We cannot simply shift all the other pixels to fill in the one we have no value for. In other cases, it often occurs that the field of sky that you are studying is not a clean rectangle to nicely fit into the boundaries of an image. You need a way to separate the pixels outside your scientific field from those inside it. Blank values act as these place holders in a dataset. They have no usable value but they have a position.

Every type needs a corresponding blank value (see Section 4.6 [Numeric data types], page 130, and Section 10.3.3 [Library data types (`type.h`)], page 390). Floating point types have a unique value identified by IEEE known as Not-a-Number (or NaN) which is a unique value that is recognized by the compiler. However, integer and string types don’t have any standard value. For integers, in Gnuastro we take an extremum of the given type: for signed types (that allow negatives), the minimum possible value is used as blank and for unsigned types (that only accept positives), the maximum possible value is used. To be generic and easy to read/write we define a macro for these blank values and strongly encourage you only use these, and never make any assumption on the value of a type’s blank value.

The IEEE NaN blank value type is defined to fail on any comparison, so if you are dealing with floating point types, you cannot use equality (a NaN will not be equal to a NaN). If you know your dataset if floating point, you can use the `isnan` function in C’s `math.h` header. For a description of numeric data types see Section 4.6 [Numeric data types], page 130. For the constants identifying integers, please see Section 10.3.3 [Library data types (`type.h`)], page 390.

**GAL_BLANK_UINT8**

Blank value for an unsigned, 8-bit integer.

**GAL_BLANK_INT8**

Blank value for a signed, 8-bit integer.

**GAL_BLANK_UINT16**

Blank value for an unsigned, 16-bit integer.

**GAL_BLANK_INT16**

Blank value for a signed, 16-bit integer.

**GAL_BLANK_UINT32**

Blank value for an unsigned, 32-bit integer.

**GAL_BLANK_INT32**

Blank value for a signed, 32-bit integer.
Chapter 10: Library

GAL_BLANK_UINT64  
Blank value for an unsigned, 64-bit integer.

GAL_BLANK_INT64   
Blank value for a signed, 64-bit integer.

GAL_BLANK_INT     
Blank value for int type (int16_t or int32_t depending on the system.

GAL_BLANK_UINT    
Blank value for int type (int16_t or int32_t depending on the system.

GAL_BLANK_LONG    
Blank value for long type (int32_t or int64_t in 32-bit or 64-bit systems).

GAL_BLANK_ULONG   
Blank value for unsigned long type (uint32_t or uint64_t in 32-bit or 64-bit systems).

GAL_BLANK_SIZE_T  
Blank value for size_t type (uint32_t or uint64_t in 32-bit or 64-bit systems).

GAL_BLANK_FLOAT32 
Blank value for a single precision, 32-bit floating point type (IEEE NaN value).

GAL_BLANK_FLOAT64 
Blank value for a double precision, 64-bit floating point type (IEEE NaN value).

GAL_BLANK_STRING  
Blank value for string types (this is itself a string, it isn’t the NULL pointer).

The functions below can be used to work with blank pixels.

void             
gal_blank_write (void *pointer, uint8_t type)  
Write the blank value for the given type into the space that pointer points to. This can be used when the space is already allocated (for example one element in an array or a statically allocated variable).

void *           
gal_blank_alloc_write (uint8_t type)  
Allocate the space required to keep the blank for the given data type type, write the blank value into it and return the pointer to it.

void             
gal_blank_initialize (gal_data_t *input)  
Initialize all the elements in the input dataset to the blank value that corresponds to its type. If input is a tile over a larger dataset, only the region that the tile covers will be set to blank.
void gal_blank_initialize_array (void *array, size_t size, uint8_t type)
Initialize all the elements in the array to the blank value that corresponds to its type (identified with type), assuming the array has size elements.

char * gal_blank_as_string (uint8_t type, int width)
Write the blank value for the given data type type into a string and return it. The space for the string is dynamically allocated so it must be freed after you are done with it. If width!=0, then the final string will be padded with white space characters to have the requested width if it is smaller.

int gal_blank_is (void *pointer, uint8_t type)
Return 1 if the contents of pointer (assuming a type of type) is blank. Otherwise, return 0. Note that this function only works on one element of the given type. So if pointer is an array, only its first element will be checked. Therefore for strings, the type of pointer is assumed to be char *. To check if an array/dataset has blank elements or to find which elements in an array are blank, you can use gal_blank_present or gal_blank_flag respectively (described below).

int gal_blank_present (gal_data_t *input, int updateflag)
Return 1 if the dataset has a blank value and zero if it doesn’t. Before checking the dataset, this function will look at input’s flags. If the GAL_DATA_FLAG_BLANK_CH bit of input->flag is on, this function will not do any check and will just use the information in the flags. This can greatly speed up processing when a dataset needs to be checked multiple times.
When the dataset’s flags were not used and updateflags is non-zero, this function will set the flags appropriately to avoid having to re-check the dataset in future calls. When updateflags==0, this function has no side-effects on the dataset: it will not toggle the flags.
If you want to re-check a dataset with the blank-value-check flag already set (for example if you have made changes to it), then explicitly set the GAL_DATA_FLAG_BLANK_CH bit to zero before calling this function. When there are no other flags, you can just set the flags to zero (input->flag=0), otherwise you can use this expression:
input->flag &= ~GAL_DATA_FLAG_BLANK_CH;

size_t gal_blank_number (gal_data_t *input, int updateflag)
Return the number of blank elements in input. If updateflag!=0, then the dataset blank keyword flags will be updated. See the description of gal_blank_present (above) for more on these flags. If input==NULL, then this function will return GAL_BLANK_SIZE_T.

gal_data_t * gal_blank_flag (gal_data_t *input)
Create a dataset of the same size as the input, but with an uint8_t type that has a value of 1 for data that are blank and 0 for those that aren’t.
void gal_blank_flag_apply (gal_data_t *input, gal_data_t *flag)
Set all non-zero and non-blank elements of flag to blank in input. flag has to have
an unsigned 8-bit type and be the same size as input.

void gal_blank_flag_remove (gal_data_t *input, gal_data_t *flag)
Remove all elements within input that are flagged, convert it to a 1D dataset and ad-
just the size properly (the number of non-flagged elements). In practice this function
doesn’t realloc the input array (see gal_blank_remove_realloc for shrinking/re-
allocating also), it just shifts the blank elements to the end and adjusts the size ele-
ments of the gal_data_t, see Section 10.3.6.1 [Generic data container (gal_data_t)],
page 400.
Note that elements that are blank, but not flagged will not be removed. This function
will only remove flagged elements.
If all the elements were flagged, then input->size will be zero. This is thus a good
parameter to check after calling this function to see if there actually were any non-
flagged elements in the input or not and take the appropriate measure. This check is
highly recommended because it will avoid strange bugs in later steps.

void gal_blank_remove (gal_data_t *input)
Remove blank elements from a dataset, convert it to a 1D dataset, adjust the size
properly (the number of non-blank elements), and toggle the blank-value-related bit-
flags. In practice this function doesn’t realloc the input array (see gal_blank_re-
move_realloc for shrinking/re-allocating also), it just shifts the blank elements to
the end and adjusts the size elements of the gal_data_t, see Section 10.3.6.1 [Generic
data container (gal_data_t)], page 400.
If all the elements were blank, then input->size will be zero. This is thus a good
parameter to check after calling this function to see if there actually were any non-
blank elements in the input or not and take the appropriate measure. This check is
highly recommended because it will avoid strange bugs in later steps.

void gal_blank_remove_realloc (gal_data_t *input)
Similar to gal_blank_remove, but also shrinks/re-allocates the dataset’s allocated
memory.

gal_data_t *
gal_blank_remove_rows (gal_data_t *columns, gal_list_sizet_t *column_indices)
Remove any row that has at least one blank value in any of the input columns. The
input columns is a list of gal_data_ts (see Section 10.3.8.9 [List of gal_data_t],
page 423). After this function, all the elements in columns will still have the same
size as each other, but if any of the searched columns has blank elements, all their
sizes will decrease together.
If column_indices==NULL, then all the columns (nodes in the list) will be checked
for blank elements, and any row that has atleast one blank element will be removed.
When `column_indexs!=NULL`, only the columns whose index (counting from zero) is in `column_indexs` will be used to check for blank values (see Section 10.3.8.3 [List of `size_t`], page 415. In any case (no matter which columns are checked for blanks), the selected rows from all columns will be removed.

### 10.3.6 Data container (data.h)

Astronomical datasets have various dimensions, for example 1D spectra or table columns, 2D images, or 3D Integral field data cubes. Datasets can also have various numeric data types, depending on the operation/purpose, for example processed images are commonly stored in floating point format, but their mask images are integers (allowing bit-wise flags to identify certain classes of pixels to keep or mask, see Section 4.6 [Numeric data types], page 130). Certain other information about a dataset are also commonly necessary, for example the units of the dataset, the name of the dataset and some comments. To deal with any generic dataset, Gnuastro defines the `gal_data_t` as input or output.

#### 10.3.6.1 Generic data container (gal_data_t)

To be able to deal with any dataset (various dimensions, numeric data types, units and higher-level structures), Gnuastro defines the `gal_data_t` type which is the input/output container of choice for many of Gnuastro library’s functions. It is defined in `gnuastro/data.h`. If you will be using (`# include`ing) those libraries, you don’t need to include this header explicitly, it is already included by any library header that uses `gal_data_t`.

```c
typedef struct gal_data_t
{
    void *restrict array; /* Basic array information. */
    uint8_t type;
    size_t ndim;
    size_t *dsize;
    size_t size;
    int quietmmap;
    char *mmapname;
    size_t minmapsize;

    int nwcs; /* WCS information. */
    struct wcsprm *wcs;

    uint8_t flag; /* Content description. */
    int status;
    char *name;
    char *unit;
    char *comment;
} gal_data_t;
```

The main container for datasets in Gnuastro. It can host data of any dimensions, with any numeric data type. It is actually a structure, but `typedef`’d as a new type to avoid having to write the `struct` before any declaration. The actual structure is shown below which is followed by a description of each element.
int disp_fmt; /* For text printing. */
int disp_width;
int disp_precision;

struct gal_data_t *next; /* For higher-level datasets. */
struct gal_data_t *block;
}
gal_data_t;

The list below contains a description for each gal_data_t element.

**void *restrict array**

This is the pointer to the main array of the dataset containing the raw data (values). All the other elements in this data-structure are actually meta-data enabling us to use/understand the series of values in this array. It must allow data of any type (see Section 4.6 [Numeric data types], page 130), so it is defined as a void * pointer. A void * array is not directly usable in C, so you have to cast it to proper type before using it, please see Section 10.4.1 [Library demo - reading a FITS image], page 507, for a demonstration.

The restrict keyword was formally introduced in C99 and is used to tell the compiler that at any moment only this pointer will modify what it points to (a pixel in an image for example)\(^\text{15}\). This extra piece of information can greatly help in compiler optimizations and thus the running time of the program. But older compilers might not have this capability, so at ./configure time, Gnuastro checks this feature and if the user’s compiler doesn’t support restrict, it will be removed from this definition.

**uint8_t type**

A fixed code (integer) used to identify the type of data in array (see Section 4.6 [Numeric data types], page 130). For the list of acceptable values to this variable, please see Section 10.3.3 [Library data types (type.h)], page 390.

**size_t ndim**

The dataset’s number of dimensions.

**size_t *dsize**

The size of the dataset along each dimension. This is an array (with ndim elements), of positive integers in row-major order\(^\text{16}\) (based on C). When a data file is read into memory with Gnuastro’s libraries, this array is dynamically allocated based on the number of dimensions that the dataset has.

It is important to remember that C’s row-major ordering is the opposite of the FITS standard which is in column-major order: in the FITS standard the fastest dimension’s size is specified by NAXIS1, and slower dimensions follow. The FITS standard was defined mainly based on the FORTRAN language which is the opposite of C’s approach to multi-dimensional arrays (and also starts counting from 1 not 0). Hence if a FITS image has NAXIS1==20 and NAXIS2==50, the dsize array must be filled with dsize[0]==50 and dsize[1]==20.

\(^{15}\) Also see https://en.wikipedia.org/wiki/Restrict.

\(^{16}\) Also see https://en.wikipedia.org/wiki/Row_-and_column-major_order.
The fastest dimension is the one that is contiguous in memory: to increment by one along that dimension, just go to the next element in the array. As we go to slower dimensions, the number of memory cells we have to skip for an increment along that dimension becomes larger.

**size_t size**

The total number of elements in the dataset. This is actually a multiplication of all the values in the `dsize` array, so it is not an independent parameter. However, low-level operations with the dataset (irrespective of its dimensions) commonly need this number, so this element is designed to avoid calculating it every time.

**int quietmmap**

When this value is zero, and the dataset must not be allocated in RAM (see `mmapname` and `minmapsize`), a warning will be printed to inform the user when the file is created and when it is deleted. The warning includes the filename, the size in bytes, and the fact that they can toggle this behavior through `--minmapsize` option in Gnuastro’s programs.

**char *mmapname**

Name of file hosting the `mmap`’d contents of `array`. If the value of this variable is `NULL`, then the contents of `array` are actually stored in RAM, not in a file on the HDD/SSD. See the description of `minmapsize` below for more.

If a file is used, it will be kept in the hidden `.gnuastro_mmap` directory. Its name is randomly selected to allow multiple arrays at the same time, see description of `--minmapsize` in Section 4.1.2.2 [Processing options], page 112. When `gal_data_free` is called the randomly named file will be deleted.

**size_t minmapsize**

The minimum size of an array (in bytes) to store the contents of `array` as a file (on the non-volatile HDD/SSD), not in RAM. This can be very useful for large datasets which can be very memory intensive and the user’s RAM might not be sufficient to keep/process it. A random filename is assigned to the array which is available in the `mmapname` element of `gal_data_t` (above), see there for more. `minmapsize` is stored in each `gal_data_t`, so it can be passed on to subsequent/derived datasets.

See the description of the `--minmapsize` option in Section 4.1.2.2 [Processing options], page 112, for more on using this value.

**nwcs**

The number of WCS coordinate representations (for WCSLIB).

**struct wcsprm *wcs**

The main WCSLIB structure keeping all the relevant information necessary for WCSLIB to do its processing and convert data-set positions into real-world positions. When it is given a `NULL` value, all possible WCS calculations/measurements will be ignored.

**uint8_t flag**

Bit-wise flags to describe general properties of the dataset. The number of bytes available in this flag is stored in the `GAL_DATA_FLAG_SIZE` macro. Note
that you should use bit-wise operators\textsuperscript{17} to check these flags. The currently recognized bits are stored in these macros:

\textbf{GAL\_DATA\_FLAG\_BLANK\_CH}

Marking that the dataset has been checked for blank values or not. When a dataset doesn’t have any blank values, the \texttt{GAL\_DATA\_FLAG\_HASBLANK} bit will be zero. But upon initialization, all bits also get a value of zero. Therefore, a checker needs this flag to see if the value in \texttt{GAL\_DATA\_FLAG\_HASBLANK} is reliable (dataset has actually been parsed for a blank value) or not.

Also, if it is necessary to re-check the presence of flags, you just have to set this flag to zero and call \texttt{gal\_blank\_present} for example to parse the dataset and check for blank values. Note that for improved efficiency, when this flag is set, \texttt{gal\_blank\_present} will not actually parse the dataset, it will just use \texttt{GAL\_DATA\_FLAG\_HASBLANK}.

\textbf{GAL\_DATA\_FLAG\_HASBLANK}

This bit has a value of 1 when the given dataset has blank values. If this bit is 0 and \texttt{GAL\_DATA\_FLAG\_BLANK\_CH} is 1, then the dataset has been checked and it didn’t have any blank values, so there is no more need for further checks.

\textbf{GAL\_DATA\_FLAG\_SORT\_CH}

Marking that the dataset is already checked for being sorted or not and thus that the possible 0 values in \texttt{GAL\_DATA\_FLAG\_SORTED\_I} and \texttt{GAL\_DATA\_FLAG\_SORTED\_D} are meaningful. The logic behind this is similar to that in \texttt{GAL\_DATA\_FLAG\_BLANK\_CH}.

\textbf{GAL\_DATA\_FLAG\_SORTED\_I}

This bit has a value of 1 when the given dataset is sorted in an increasing manner. If this bit is 0 and \texttt{GAL\_DATA\_FLAG\_SORT\_CH} is 1, then the dataset has been checked and wasn’t sorted (increasing), so there is no more need for further checks.

\textbf{GAL\_DATA\_FLAG\_SORTED\_D}

This bit has a value of 1 when the given dataset is sorted in a decreasing manner. If this bit is 0 and \texttt{GAL\_DATA\_FLAG\_SORT\_CH} is 1, then the dataset has been checked and wasn’t sorted (decreasing), so there is no more need for further checks.

The macro \texttt{GAL\_DATA\_FLAG\_MAXFLAG} contains the largest internally used bit-position. Higher-level flags can be defined with the bit-wise shift operators using this macro to define internal flags for libraries/programs that depend on Gnuastro without causing any possible conflict with the internal flags discussed above or having to check the values manually on every release.

\textsuperscript{17} See \url{https://en.wikipedia.org/wiki/Bitwise_operations_in_C}. 


int status
A context-specific status values for this data-structure. This integer will not be set by Gnuastro’s libraries. You can use it to keep some additional information about the dataset (with integer constants) depending on your applications.

char *name
The name of the dataset. If the dataset is a multi-dimensional array and read/written as a FITS image, this will be the value in the EXTNAME FITS keyword. If the dataset is a one-dimensional table column, this will be the column name. If it is set to NULL (by default), it will be ignored.

char *unit
The units of the dataset (for example BUNIT in the standard FITS keywords) that will be read from or written to files/tables along with the dataset. If it is set to NULL (by default), it will be ignored.

char *comment
Any further explanation about the dataset which will be written to any output file if present.

disp_fmt Format to use for printing each element of the dataset to a plain text file, the acceptable values to this element are defined in Section 10.3.10 [Table input output (table.h)], page 426. Based on C’s printf standards.

disp_width Width of printing each element of the dataset to a plain text file, the acceptable values to this element are defined in Section 10.3.10 [Table input output (table.h)], page 426. Based on C’s printf standards.

disp_precision Precision of printing each element of the dataset to a plain text file, the acceptable values to this element are defined in Section 10.3.10 [Table input output (table.h)], page 426. Based on C’s printf standards.

gal_data_t *next
Through this pointer, you can link a gal_data_t with other datasets related datasets, for example the different columns in a dataset each have one gal_data_t associate with them and they are linked to each other using this element. There are several functions described below to facilitate using gal_data_t as a linked list. See Section 10.3.8 [Linked lists (list.h)], page 411, for more on these wonderful high-level constructs.

gal_data_t *block
Pointer to the start of the complete allocated block of memory. When this pointer is not NULL, the dataset is not treated as a contiguous patch of memory. Rather, it is seen as covering only a portion of the larger patch of memory that block points to. See Section 10.3.15 [Tessellation library (tile.h)], page 460, for a more thorough explanation and functions to help work with tiles that are created from this pointer.
10.3.6.2 Dataset allocation

Gnuastro’s main data container was defined in Section 10.3.6.1 [Generic data container (gal_data_t)], page 400. The functions listed in this section describe the most basic operations on gal_data_t: those related to allocation and freeing. These functions are declared in gnuastro/data.h which is also visible from the function names (see Section 10.3 [Gnuastro library], page 384).

```c
[Function]
gal_data_t *
gal_data_alloc (void *array, uint8_t type, size_t ndim, size_t *dsize, struct wcsprm *wcs, int clear, size_t minmapsize, int quietmmap, char *name, char *unit, char *comment)
```

Dynamically allocate a gal_data_t and initialize it with all the given values. See the description of gal_data_initialize and Section 10.3.6.1 [Generic data container (gal_data_t)], page 400, for more information. This function will often be the most frequently used because it allocates the gal_data_t hosting all the values and initializes it. Once you are done with the dataset, be sure to clean up all the allocated spaces with gal_data_free.

```c
[Function]
void
gal_data_initialize (gal_data_t *data, void *array, uint8_t type, size_t ndim, size_t *dsize, struct wcsprm *wcs, int clear, size_t minmapsize, int quietmmap, char *name, char *unit, char *comment)
```

Initialize the given data structure (data) with all the given values. Note that the raw input gal_data_t must already have been allocated before calling this function. For a description of each variable see Section 10.3.6.1 [Generic data container (gal_data_t)], page 400. It will set the values and do the necessary allocations. If they aren’t NULL, all input arrays (dsize, wcs, name, unit, comment) are separately copied (allocated) by this function for usage in data, so you can safely use one value to initialize many datasets or use statically allocated variables in this function call. Once you are done with the dataset, you can free all the allocated spaces with gal_data_free_contents.

If array is not NULL, it will be directly copied into data->array (based on the total number of elements calculated from dsize) and no new space will be allocated for the array of this dataset, this has many low-level advantages and can be used to work on regions of a dataset instead of the whole allocated array (see the description under block in Section 10.3.6.1 [Generic data container (gal_data_t)], page 400, for one example). If the given pointer is not the start of an allocated block of memory or it is used in multiple datasets, be sure to set it to NULL (with data->array=NULL) before cleaning up with gal_data_free_contents.

ndim may be zero. In this case no allocation will occur, data->array and data->dsize will be set to NULL and data->size will be zero. However (when necessary) dsize must not have any zero values (a dimension of length zero is not defined).
void gal_data_free_contents (gal_data_t *data)
    Free all the non-NULL pointers in gal_data_t except for next and block. If data is actually a tile (data->block!=NULL, see Section 10.3.15 [Tessellation library (tile.h)], page 460), then data->array is not freed. For a complete description of gal_data_t and its contents, see Section 10.3.6.1 [Generic data container (gal_data_t)], page 400.

void gal_data_free (gal_data_t *data)
    Free all the non-NULL pointers in gal_data_t, then free the actual data structure.

10.3.6.3 Arrays of datasets

Gnuastro’s generic data container (gal_data_t) is a very versatile structure that can be used in many higher-level contexts. One such higher-level construct is an array of gal_data_t structures to simplify the allocation (and later cleaning) of several gal_data_ts that are related.

For example, each column in a table is usually represented by one gal_data_t (so it has its own name, data type, units, etc). A table (with many columns) can be seen as an array of gal_data_ts (when the number of columns is known a-priori). The functions below are defined to create a cleared array of data structures and to free them when none are necessary any more. These functions are declared in gnuastro/data.h which is also visible from the function names (see Section 10.3 [Gnuastro library], page 384).

gal_data_t * gal_data_array_calloc (size_t size)
    Allocate an array of gal_data_t with size elements. This function will also initialize all the values (NULL for pointers and 0 for other types). You can use gal_data_initialize to fill each element of the array afterwards. The following code snippet is one example of doing this.

    size_t i;
    gal_data_t *dataarr;
    dataarr=gal_data_array_calloc(10);
    for(i=0;i<10;++i) gal_data_initialize(&dataarr[i], ...);
    ... gal_data_array_free(dataarr, 10, 1);

void gal_data_array_free (gal_data_t *dataarr, size_t num, int free_array)
    Free all the num elements within dataarr and the actual allocated array. If free_array is not zero, then the array element of all the datasets will also be freed, see Section 10.3.6.1 [Generic data container (gal_data_t)], page 400.

gal_data_t ** gal_data_array_ptr_calloc (size_t size)
    Allocate an array of pointers to Gnuastro’s generic data structure and initialize all pointers to NULL. This is useful when you want to allocate individual datasets later (for example with gal_data_alloc).
void gal_data_array_ptr_free (gal_data_t **dataptr, size_t size, int free_array);

Free all the individual datasets within the elements of dataptr, then free dataptr itself (the array of pointers that was probably allocated with gal_data_array_ptrcalloc).

### 10.3.6.4 Copying datasets

The functions in this section describe Gnuastro’s facilities to copy a given dataset into another. The new dataset can have a different type (including a string), it can be already allocated (in which case only the values will be written into it). In all these cases, if the input dataset is a tile or a list, only the data within the given tile, or the given node in a list, are copied. If the input is a list, the next pointer will also be copied to the output, see Section 10.3.8.9 [List of gal_data_t], page 423.

In many of the functions here, it is possible to copy the dataset to a new numeric data type (see Section 4.6 [Numeric data types], page 130. In such cases, Gnuastro’s library is going to use the native conversion by C. So if you are converting to a smaller type, it is up to you to make sure that the values fit into the output type.

**gal_data_t** *gal_data_copy (gal_data_t *in)**

Return a new dataset that is a copy of in, all of in’s meta-data will also copied into the output, except for block. If the dataset is a tile/list, only the given tile/node will be copied, the next pointer will also be copied however.

**gal_data_t** *gal_data_copy_to_new_type (gal_data_t *in, uint8_t newtype)**

Return a copy of the dataset in, converted to newtype, see Section 10.3.3 [Library data types (type.h)], page 390, for Gnuastro library’s type identifiers. The returned dataset will have all meta-data except their type and block equal to the input’s metadata. If the dataset is a tile/list, only the given tile/node will be copied, the next pointer will also be copied however.

**gal_data_t** *gal_data_copy_to_new_type_free (gal_data_t *in, uint8_t newtype)**

Return a copy of the dataset in that is converted to newtype and free the input dataset. See Section 10.3.3 [Library data types (type.h)], page 390, for Gnuastro library’s type identifiers. The returned dataset will have all meta-data, except their type, equal to the input’s metadata (including next). Note that if the input is a tile within a larger block, it will not be freed. This function is similar to gal_data_copy_to_new_type, except that it will free the input dataset.

void gal_data_copy_to_allocated (gal_data_t *in, gal_data_t *out)**

Copy the contents of the array in into the already allocated array in out. The types of the input and output may be different, type conversion will be done internally. When in->size != out->size this function will behave as follows:
out->size < in->size
This function won’t re-allocate the necessary space, it will abort with an
error, so please check before calling this function.

out->size > in->size
This function will write the values in out->size and out->dsize from
the same values of in. So if you want to use a pre-allocated space/dataset
multiple times with varying input sizes, be sure to reset out->size before
every call to this function.

gal_data_t *
gal_data_copy_string_to_number (char *string)
Read string into the smallest type that can store the value (see Section 4.6 [Numeric
data types], page 130). This function is just a wrapper for the gal_type_string_to_number,
but will put the value into a single-element dataset.

10.3.7 Dimensions (dimension.h)
An array is a contiguous region of memory. Hence, at the lowest level, every element of
an array just has one single-valued position: the number of elements that lie between it
and the first element in the array. This is also known as the index of the element within
the array. A dataset’s number of dimensions is high-level abstraction (meta-data) that we
project onto that contiguous patch of memory. When the array is interpreted as a one-
dimensional dataset, this index is also the coordinate of the element. But once we associate
the patch of memory with a higher dimension, there must also be one coordinate for each
dimension.

The functions and macros in this section provide you with the tools to convert an index
into a coordinate and vice-versa along with several other issues for example issues with the
neighbors of an element in a multi-dimensional context.

size_t

gal_dimension_total_size (size_t ndim, size_t *dsize)
Return the total number of elements for a dataset with ndim dimensions that has
dsize elements along each dimension.

int

gal_dimension_is_different (gal_data_t *first, gal_data_t *second)
Return 1 (one) if the two datasets don’t have the same size along all dimensions. This
function will also return 1 when the number of dimensions of the two datasets are
different.

size_t *
gal_dimension_increment (size_t ndim, size_t *dsize)
Return an allocated array that has the number of elements necessary to increment an
index along every dimension. For example along the fastest dimension (last element
in the dsize and returned arrays), the value is 1 (one).
size_t gal_dimension_num_neighbors (size_t ndim)
The maximum number of neighbors (any connectivity) that a data element can have in ndim dimensions. Effectively, this function just returns $3^n - 1$ (where $n$ is the number of dimensions).

GAL_DIMENSION_FLT_TO_INT (FLT)
Calculate the integer pixel position that the floating point FLT number belongs to. In the FITS format (and thus in Gnuastro), the center of each pixel is allocated on an integer (not it edge), so the pixel which hosts a floating point number cannot simply be found with internal type conversion.

void gal_dimension_add_coords (size_t *c1, size_t *c2, size_t *out, size_t ndim)
For every dimension, add the coordinates in c1 with c2 and put the result into out. In other words, for dimension i run out[i]=c1[i]+c2[i];. Hence out may be equal to any one of c1 or c2.

size_t gal_dimension_coord_to_index (size_t ndim, size_t *dsize, size_t *coord)
Return the index (counting from zero) from the coordinates in coord (counting from zero) assuming the dataset has ndim elements and the size of the dataset along each dimension is in the dsize array.

void gal_dimension_index_to_coord (size_t index, size_t ndim, size_t *dsize, size_t *coord)
Fill in the coord array with the coordinates that correspond to index assuming the dataset has ndim elements and the size of the dataset along each dimension is in the dsize array. Note that both index and each value in coord are assumed to start from 0 (zero). Also that the space which coord points to must already be allocated before calling this function.

size_t gal_dimension_dist_manhattan (size_t *a, size_t *b, size_t ndim)
Return the manhattan distance (see Wikipedia (https://en.wikipedia.org/wiki/Taxicab_geometry)) between the two coordinates a and b (each an array of ndim elements).

float gal_dimension_dist_radial (size_t *a, size_t *b, size_t ndim)
Return the radial distance between the two coordinates a and b (each an array of ndim elements).

gal_data_t * gal_dimensionCollapse_sum (gal_data_t *in, size_t c_dim, gal_data_t *weight)
Collapse the input dataset (in) along the given dimension (c_dim, in C definition: starting from zero, from the slowest dimension), by summing all elements in that direction. If weight!=NULL, it must be a single-dimensional array, with the same size
as the dimension to be collapsed. The respective weight will be multiplied to each element during the collapse.

For generality, the returned dataset will have a `GAL_TYPE_FLOAT64` type. See Section 10.3.6.4 [Copying datasets], page 407, for converting the returned dataset to a desired type. Also, for more on the application of this function, see the Arithmetic program’s `collapse-sum` operator (which uses this function) in Section 6.2.2 [Arithmetic operators], page 200.

```c
[Function]
gal_data_t *
gal_dimension_collapse_mean (gal_data_t *in, size_t c_dim, gal_data_t *weight)
  Similar to `gal_dimension_collapse_sum` (above), but the collapse will be done by calculating the mean along the requested dimension, not summing over it.
```

```c
[Function]
gal_data_t *
gal_dimension_collapse_number (gal_data_t *in, size_t c_dim)
  Collapse the input dataset (`in`) along the given dimension (`c_dim`, in C definition: starting from zero, from the slowest dimension), by counting how many non-blank elements there are along that dimension.

  For generality, the returned dataset will have a `GAL_TYPE_INT32` type. See Section 10.3.6.4 [Copying datasets], page 407, for converting the returned dataset to a desired type. Also, for more on the application of this function, see the Arithmetic program’s `collapse-number` operator (which uses this function) in Section 6.2.2 [Arithmetic operators], page 200.
```

```c
[Function]
gal_data_t *
gal_dimension_collapse_minmax (gal_data_t *in, size_t c_dim, int max1_min0)
  Collapse the input dataset (`in`) along the given dimension (`c_dim`, in C definition: starting from zero, from the slowest dimension), by using the largest/smallest non-blank value along that dimension. If `max1_min0` is non-zero, then the collapsed dataset will have the maximum value along the given dimension and if it is zero, the minimum.
```

```c
[Function]
gal_data_t *
gal_dimension_remove_extra (size_t ndim, size_t *dsize, struct wcsprm *wcs)
  Remove extra dimensions (those that only have a length of 1) from the basic size information of a dataset. `ndim` is the number of dimensions and `dsize` is an array with `ndim` elements containing the size along each dimension in the C dimension order. When `wcs!=NULL`, the respective dimension will also be removed from the WCS.

  This function will return the new number of dimensions and the `dsize` elements will contain the length along each new dimension.
```

```c
GAL_DIMENSION_NEIGHBOR_OP (index, ndim, dsize, connectivity, dinc, operation)
  Parse the neighbors of the element located at `index` and do the requested operation on them. This is defined as a macro to allow easy definition of any operation on the neighbors of a given element without having to use loops within your source code (the loops are implemented by this macro). For an example of using this function,
please see Section 10.4.2 [Library demo - inspecting neighbors], page 509. The input arguments to this function-like macro are described below:

**index**  Distance of this element from the first element in the array on a contiguous patch of memory (starting from 0), see the discussion above.

**ndim**  The number of dimensions associated with the contiguous patch of memory.

**dsize**  The full array size along each dimension. This must be an array and is assumed to have the same number elements as **ndim**. See the discussion under the same element in Section 10.3.6.1 [Generic data container (**gal_data_t**)], page 400.

**connectivity**  Most distant neighbors to consider. Depending on the number of dimensions, different neighbors may be defined for each element. This function-like macro distinguish between these different neighbors with this argument. It has a value between 1 (one) and **ndim**. For example in a 2D dataset, 4-connected neighbors have a connectivity of 1 and 8-connected neighbors have a connectivity of 2. Note that this is inclusive, so in this example, a connectivity of 2 will also include connectivity 1 neighbors.

**dinc**  An array keeping the length necessary to increment along each dimension. You can make this array with the following function. Just don’t forget to free the array after you are done with it:

```
size_t *dinc=gal_dimension_increment(ndim, dsize);
```

**operation**  Any C operation that you would like to do on the neighbor. This macro will provide you a **nind** variable that can be used as the index of the neighbor that is currently being studied. It is defined as ‘**size_t ndim;**’. Note that **operation** will be repeated the number of times there is a neighbor for this element.

This macro works fully within its own {} block and except for the **nind** variable that shows the neighbor’s index, all the variables within this macro’s block start with **gdn_**.

### 10.3.8 Linked lists (**list.h**)

An array is a contiguous region of memory that is very efficient and easy to use for recording and later accessing any random element as fast as any other. This makes array the primary data container when you have many elements (for example an image which has millions of pixels). One major problem with an array is that the number of elements that go into it must be known in advance and adding or removing an element will require a re-set of all the other elements. For example if you want to remove the 3rd element in a 1000 element array, all 997 subsequent elements have to pulled back by one position, the reverse will happen if you need to add an element.

In many contexts such situations never come up, for example you don’t want to shift all the pixels in an image by one or two pixels from some random position in the image:
their positions have scientific value. But in other contexts you will find your self frequently adding/removing an a-priori unknown number of elements. Linked lists (or lists for short) are the data-container of choice in such situations. As in a chain, each node in a list is an independent C structure, keeping its own data along with pointer(s) to its immediate neighbor(s). Below, you can see one single linked list node structure along with an ASCII art schematic of how we can use the next pointer to add any number of elements to the list that we want. By convention, a list is terminated when next is the NULL pointer.

```c
struct list_float /* --------- --------- */
{ /* | Value | | Value | */
  float  value; /* | --- | | --- | */
  struct list_float *next; /* | next-|--> | next-|--> NULL */
} /* --------- --------- */
```

The schematic shows another great advantage of linked lists: it is very easy to add or remove/pop a node anywhere in the list. If you want to modify the first node, you just have to change one pointer. If it is in the middle, you just have to change two. You initially define a variable of this type with a NULL pointer as shown below:

```c
struct list_float *mylist=NULL;
```

To add or remove/pop a node from the list you can use functions provided for the respective type in the sections below.

When you add an element to the list, it is conventionally added to the “top” of the list: the general list pointer will point to the newly created node, which will point to the previously created node and so on. So when you “pop” from the top of the list, you are actually retrieving the last value you put in and changing the list pointer to the next youngest node. This is thus known as a “last-in-first-out” list. This is the most efficient type of linked list (easier to implement and faster to process). Alternatively, you can add each newly created node at the end of the list. If you do that, you will get a “first-in-first-out” list. But that will force you to go through the whole list for each new element that is created (this will slow down the processing)\(^\text{18}\).

The node example above creates the simplest kind of a list. We can define each node with two pointers to both the next and previous neighbors, this is called a “Doubly linked list”. In general, lists are very powerful and simple constructs that can be very useful. But going into more detail would be out of the scope of this short introduction in this book. Wikipedia (https://en.wikipedia.org/wiki/Linked_list) has a nice and more thorough discussion of the various types of lists. To appreciate/use the beauty and elegance of these powerful constructs even further, see Chapter 2 (Information Structures, in volume 1) of Donald Knuth’s “The art of computer programming”.

In this section we will review the functions and structures that are available in Gnuastro for working on lists. They differ by the type of data that each node can keep. For each linked-list node structure, we will first introduce the structure, then the functions for working on the structure. All these structures and functions are defined and declared in gnuastro/list.h.

\(^{18}\) A better way to get a first-in-first-out is to first keep the data as last-in-first-out until they are all read. Afterwards, reverse the list by popping each node and immediately add it to the new list. This practically reverses the last-in-first-out list to a first-in-first-out one. All the list types discussed in this chapter have a function with a .reverse suffix for this job.
10.3.8.1 List of strings

Probably one of the most common lists you will be using are lists of strings. They are the best tools when you are reading the user’s inputs, or when adding comments to the output files. Below you can see Gnuastro’s string list type and several functions to help in adding, removing/popping, reversing and freeing the list.

```c
typedef struct gal_list_str_t {
    char *v;
    struct gal_list_str_t *next;
} gal_list_str_t;
```

```c
void gal_list_str_add (gal_list_str_t **list, char *value, int allocate)
Add a new node to the list of strings (list) and update it. The new node will contain the string value. If allocate is not zero, space will be allocated specifically for the string of the new node and the contents of value will be copied into it. This can be useful when your string may be changed later in the program, but you want your list to remain. Here is one short/simple example of initializing and adding elements to a string list:

```c
gal_list_str_t *strlist=NULL;
gal_list_str_add(&strlist, "bottom of list.");
gal_list_str_add(&strlist, "second last element of list.");
```
```
char * gal_list_str_pop (gal_list_str_t **list)
Pop the top element of list, change list to point to the next node in the list, and return the string that was in the popped node. If *list==NULL, then this function will also return a NULL pointer.
```
```
size_t gal_list_str_number (gal_list_str_t *list)
Return the number of nodes in list.
```
```
size_t gal_list_str_last (gal_list_str_t *list)
Return a pointer to the last node in list.
```
```
void gal_list_str_print (gal_list_str_t *list)
Print the strings within each node of *list on the standard output in the same order that they are stored. Each string is printed on one line. This function is mainly good for checking/debugging your program. For program outputs, its best to make your own implementation with a better, more user-friendly, format. For example the following code snippet.

```c
size_t i;
```
gal_list_str_t *tmp;
for(tmp=list; tmp!=NULL; tmp=tmp->next)
    printf("String %zu: %s\n", i, tmp->v);

void gal_list_str_reverse (gal_list_str_t **list)
    Reverse the order of the list such that the top node in the list before calling this
    function becomes the bottom node after it.

void gal_list_str_free (gal_list_str_t *list, int freevalue)
    Free every node in list. If freevalue is not zero, also free the string within the
    nodes.

10.3.8.2 List of int32_t

Signed integers are the best types when you are dealing with a positive or negative integers. The are generally useful in many contexts, for example when you want to keep the order of a series of states (each state stored as a given number in an enum for example). On many modern systems, int32_t is just an alias for int, so you can use them interchangeably. To make sure, check the size of int on your system:

gal_list_i32_t
    A single node in a list containing a 32-bit signed integer (see Section 4.6 [Numeric
data types], page 130).

typedef struct gal_list_i32_t
{
    int32_t v;
    struct gal_list_i32_t *next;
} gal_list_i32_t;

void gal_list_i32_add (gal_list_i32_t **list, int32_t value)
    Add a new node (containing value) to the top of the list of int32_ts (uint32_t is
equal to int on many modern systems), and update list. Here is one short example
of initializing and adding elements to a string list:
    gal_list_i32_t *i32list=NULL;
    gal_list_i32_add(&i32list, 52);
    gal_list_i32_add(&i32list, -4);

int32_t gal_list_i32_pop (gal_list_i32_t **list)
    Pop the top element of list and return the value. This function will also change
    list to point to the next node in the list. If *list==NULL, then this function will
    also return GAL_BLANK_INT32 (see Section 10.3.5 [Library blank values (blank.h)],
    page 396).

size_t gal_list_i32_number (gal_list_i32_t *list)
    Return the number of nodes in list.
size_t

gal_list_i32_last (gal_list_i32_t *list)
    Return a pointer to the last node in list.

void

gal_list_i32_print (gal_list_i32_t *list)
    Print the integers within each node of *list on the standard output in the same
    order that they are stored. Each integer is printed on one line. This function is
    mainly good for checking/debugging your program. For program outputs, its best to
    make your own implementation with a better, more user-friendly format. For example
    the following code snippet. You can also modify it to print all values in one line, etc,
    depending on the context of your program.

    size_t i;
    gal_list_i32_t *tmp;
    for(tmp=list; tmp!=NULL; tmp=tmp->next)
        printf("String %zu: %s\n", i, tmp->v);

void

gal_list_i32_reverse (gal_list_i32_t **list)
    Reverse the order of the list such that the top node in the list before calling this
    function becomes the bottom node after it.

int32_t *

gal_list_i32_to_array (gal_list_i32_t *list, int reverse, size_t *num)
    Dynamically allocate an array and fill it with the values in list. The function will
    return a pointer to the allocated array and put the number of elements in the array
    into the num pointer. If reverse has a non-zero value, the array will be filled in the
    opposite order of elements in list. This function can be useful after you have finished
    reading an initially unknown number of values and want to put them in an array for
    easy random access.

void

gal_list_i32_free (gal_list_i32_t *list)
    Free every node in list.

10.3.8.3 List of size_t

The size_t type is a unique type in C: as the name suggests it is defined to store sizes,
or more accurately, the distances between memory locations. Hence it is always positive
(an unsigned type) and it is directly related to the address-able spaces on the host system:
on 32-bit and 64-bit systems it is an alias for uint32_t and uint64_t, respectively (see
Section 4.6 [Numeric data types], page 130).

size_t is the default compiler type to index an array (recall that an array index in
C is just a pointer increment of a given size). Since it is unsigned, its a great type for
counting (where negative is not defined), you are always sure it will never exceed the
system’s (virtual) memory and since its name has the word “size” inside it, it provides
a good level of documentation19. In Gnuastro, we do all counting and array indexing with

19 So you know that a variable of this type is not used to store some generic state for example.
this type, so this list is very handy. As discussed above, size_t maps to different types on
different machines, so a portable way to print them with printf is to use C99’s %zu format.

gal_list_sizet_t                 [Type (C struct)]
   A single node in a list containing a size_t value (which maps to uint32_t or uint64_t
   on 32-bit and 64-bit systems), see Section 4.6 [Numeric data types], page 130.

   typedef struct gal_list_sizet_t
   {
      size_t v;
      struct gal_list_sizet_t *next;
   } gal_list_sizet_t;

void                                    [Function]
gal_list_sizet_add (gal_list_sizet_t **list, size_t value)
   Add a new node (containing value) to the top of the list of size_ts and update
   list. Here is one short example of initializing and adding elements to a string list:

      gal_list_sizet_t *slist=NULL;
      gal_list_sizet_add(&slist, 45493);
      gal_list_sizet_add(&slist, 930484);

size_t                                  [Function]
gal_list_sizet_pop (gal_list_sizet_t **list)
   Pop the top element of list and return the value. This function will also change
   list to point to the next node in the list. If *list==NULL, then this function will
   also return GAL_BLANK_SIZE_T (see Section 10.3.5 [Library blank values (blank.h)],
   page 396).

size_t                                  [Function]
gal_list_sizet_number (gal_list_sizet_t *list)
   Return the number of nodes in list.

size_t                                  [Function]
gal_list_sizet_last (gal_list_sizet_t *list)
   Return a pointer to the last node in list.

void                                    [Function]
gal_list_sizet_print (gal_list_sizet_t *list)
   Print the values within each node of *list on the standard output in the same order
   that they are stored. Each integer is printed on one line. This function is mainly
good for checking/debugging your program. For program outputs, its best to make
your own implementation with a better, more user-friendly format. For example, the
following code snippet. You can also modify it to print all values in one line, etc,
depending on the context of your program.

      size_t i;
      gal_list_sizet_t *tmp;
      for(tmp=list; tmp!=NULL; tmp=tmp->next)
         printf("String %zu: %zu
", i, tmp->v);
Chapter 10: Library

void  

gal_list_sizet_reverse (gal_list_sizet_t **list)
    Reverse the order of the list such that the top node in the list before calling this
    function becomes the bottom node after it.

size_t *

gal_list_sizet_to_array (gal_list_sizet_t *list, int reverse, size_t *num)
    Dynamically allocate an array and fill it with the values in list. The function will
    return a pointer to the allocated array and put the number of elements in the array
    into the num pointer. If reverse has a non-zero value, the array will be filled in the
    inverse of the order of elements in list. This function can be useful after you have
    finished reading an initially unknown number of values and want to put them in an
    array for easy random access.

void  

gal_list_sizet_free (gal_list_sizet_t *list)
    Free every node in list.

10.3.8.4 List of float

Single precision floating point numbers can accurately store real number until 7.2 deci-
imals and only consume 4 bytes (32-bits) of memory, see Section 4.6 [Numeric data types],
page 130. Since astronomical data rarely reach that level of precision, single precision float-
ing points are the type of choice to keep and read data. However, when processing the data,
it is best to use double precision floating points (since errors propagate).

gal_list_f32_t  
A single node in a list containing a 32-bit single precision float value: see Section 4.6
[Numeric data types], page 130.

    typedef struct gal_list_f32_t
    {
        float v;
        struct gal_list_f32_t *next;
    } gal_list_f32_t;

void  

gal_list_f32_add (gal_list_f32_t **list, float value)
    Add a new node (containing value) to the top of the list of floats and update
    list. Here is one short example of initializing and adding elements to a string list:
    gal_list_f32_t *flist=NULL;
    gal_list_f32_add(&flist, 3.89);
    gal_list_f32_add(&flist, 1.23e-20);

float  

gal_list_f32_pop (gal_list_f32_t **list)
    Pop the top element of list and return the value. This function will also change
    list to point to the next node in the list. If *list==NULL, then this function will
    return GAL_BLANK_FLOAT32 (NaN, see Section 10.3.5 [Library blank values (blank.h)],
page 396).
size_t [Function]
gal_list_f32_number (gal_list_f32_t *list)
    Return the number of nodes in list.

size_t [Function]
gal_list_f32_last (gal_list_f32_t *list)
    Return a pointer to the last node in list.

void [Function]
gal_list_f32_print (gal_list_f32_t *list)
    Print the values within each node of *list on the standard output in the same order
    that they are stored. Each floating point number is printed on one line. This function
    is mainly good for checking/debugging your program. For program outputs, its best
    to make your own implementation with a better, more user-friendly format. For
    example, in the following code snippet. You can also modify it to print all values in
    one line, etc, depending on the context of your program.

        size_t i;
        gal_list_f32_t *tmp;
        for(tmp=list; tmp!=NULL; tmp=tmp->next)
            printf("Node %zu: %f\n", i, tmp->v);

void [Function]
gal_list_f32_reverse (gal_list_f32_t **list)
    Reverse the order of the list such that the top node in the list before calling this
    function becomes the bottom node after it.

float * [Function]
gal_list_f32_to_array (gal_list_f32_t *list, int reverse, size_t *num)
    Dynamically allocate an array and fill it with the values in list. The function will
    return a pointer to the allocated array and put the number of elements in the array
    into the num pointer. If reverse has a non-zero value, the array will be filled in the
    inverse of the order of elements in list. This function can be useful after you have
    finished reading an initially unknown number of values and want to put them in an
    array for easy random access.

void [Function]
gal_list_f32_free (gal_list_f32_t *list)
    Free every node in list.

10.3.8.5 List of double

Double precision floating point numbers can accurately store real number until 15.9 decimals
and consume 8 bytes (64-bits) of memory, see Section 4.6 [Numeric data types], page 130.
This level of precision makes them very good for serious processing in the middle of a
program's execution: in many cases, the propagation of errors will still be insignificant
compared to actual observational errors in a data set. But since they consume 8 bytes and
more CPU processing power, they are often not the best choice for storing and transferring
of data.
gal_list_f64_t

A single node in a list containing a 64-bit double precision double value: see Section 4.6 [Numeric data types], page 130.

typedef struct gal_list_f64_t
{
    double v;
    struct gal_list_f64_t *next;
} gal_list_f64_t;

void gal_list_f64_add (gal_list_f64_t **list, double value)

Add a new node (containing value) to the top of the list of doubles and update list. Here is one short example of initializing and adding elements to a string list:

gal_list_f64_t *dlist=NULL;
gal_list_f64_add(&dlist, 3.8129395763193);
gal_list_f64_add(&dlist, 1.239378923931e-20);

double gal_list_f64_pop (gal_list_f64_t **list)

Pop the top element of list and return the value. This function will also change list to point to the next node in the list. If *list==NULL, then this function will return GAL_BLANK_FLOAT64 (NaN, see Section 10.3.5 [Library blank values (blank.h)], page 396).

size_t gal_list_f64_number (gal_list_f64_t *list)

Return the number of nodes in list.

size_t gal_list_f64_last (gal_list_f64_t *list)

Return a pointer to the last node in list.

void gal_list_f64_print (gal_list_f64_t *list)

Print the values within each node of *list on the standard output in the same order that they are stored. Each floating point number is printed on one line. This function is mainly good for checking/debugging your program. For program outputs, its best to make your own implementation with a better, more user-friendly format. For example, in the following code snippet. You can also modify it to print all values in one line, etc, depending on the context of your program.

    size_t i;
gal_list_f64_t *tmp;
    for(tmp=list; tmp!=NULL; tmp=tmp->next)
        printf("Node %zu: %f\n", i, tmp->v);

void gal_list_f64_reverse (gal_list_f64_t **list)

Reverse the order of the list such that the top node in the list before calling this function becomes the bottom node after it.
double *

gal_list_f64_to_array (gal_list_f64_t *list, int reverse, size_t *num)

Dynamically allocate an array and fill it with the values in list. The function will return a pointer to the allocated array and put the number of elements in the array into the num pointer. If reverse has a non-zero value, the array will be filled in the inverse of the order of elements in list. This function can be useful after you have finished reading an initially unknown number of values and want to put them in an array for easy random access.

void

gal_list_f64_free (gal_list_f64_t *list)

Free every node in list.

10.3.8.6 List of void *

In C, void * is the most generic pointer. Usually pointers are associated with the type of content they point to. For example int * means a pointer to an integer. This ancillary information about the contents of the memory location is very useful for the compiler, catching bad errors and also documentation (it helps the reader see what the address in memory actually contains). However, void * is just a raw address (pointer), it contains no information on the contents it points to.

These properties make the void * very useful when you want to treat the contents of an address in different ways. You can use the void * list defined in this section and its function on any kind of data: for example you can use it to keep a list of custom data structures that you have built for your own separate program. Each node in the list can keep anything and this gives you great versatility. But in using void *, please beware that “with great power comes great responsibility”.

gal_list_void_t

A single node in a list containing a void * pointer.

typedef struct gal_list_void_t
{
    void *v;
    struct gal_list_void_t *next;
} gal_list_void_t;

void

gal_list_void_add (gal_list_void_t **list, void *value)

Add a new node (containing value) to the top of the list of void *s and update list. Here is one short example of initializing and adding elements to a string list:

gal_list_void_t *vlist=NULL;
gal_list_f64_add(&vlist, some_pointer);
gal_list_f64_add(&vlist, another_pointer);

void *

gal_list_void_pop (gal_list_void_t **list)

Pop the top element of list and return the value. This function will also change list to point to the next node in the list. If *list==NULL, then this function will return NULL.
Chapter 10: Library

size_t

gal_list_void_number (gal_list_void_t *list)
Return the number of nodes in list.

size_t

gal_list_void_last (gal_list_void_t *list)
Return a pointer to the last node in list.

void

gal_list_void_reverse (gal_list_void_t **list)
Reverse the order of the list such that the top node in the list before calling this
function becomes the bottom node after it.

void

gal_list_void_free (gal_list_void_t *list)
Free every node in list.

10.3.8.7 Ordered list of size_t

Positions/sizes in a dataset are conventionally in the size_t type (see Section 10.3.8.3 [List
of size_t], page 415) and it sometimes occurs that you want to parse and read the values
in a specific order. For example you want to start from one pixel and add pixels to the list
based on their distance to that pixel. So that ever time you pop an element from the list,
you know it is the nearest that has not yet been studied. The gal_list_osizet_t type
and its functions in this section are designed to facilitate such operations.

gal_list_osizet_t
[Type (C struct)]

Each node in this singly-linked list contains a size_t value and a floating point value.
The floating point value is used as a reference to add new nodes in a sorted manner.
At any moment, the first popped node in this list will have the smallest tosort value,
and subsequent nodes will have larger to values.

typedef struct gal_list_osizet_t
{
    size_t v;        /* The actual value. */
    float  s;        /* The parameter to sort by. */
    struct gal_list_osizet_t *next;
} gal_list_osizet_t;

void

gal_list_osizet_add (gal_list_osizet_t **list, size_t value, float tosort)
Allocate space for a new node in list, and store value and tosort into it. The new
node will not necessarily be at the “top” of the list. If *list!=NULL, then the tosort
values of existing nodes is inspected and the given node is placed in the list such
that the top element (which is popped with gal_list_osizet_pop) has the smallest
tosort value.

size_t

gal_list_osizet_pop (gal_list_osizet_t **list, float *sortvalue)
Pop a node from the top of list, return the node’s value and put its sort value in
the space that sortvalue points to. This function will also free the allocated space
for the popped node and after this function, list will point to the next node (which has a larger tosort element).

```c
void gal_list_osizet_to_sizet_free (gal_list_osizet_t *in, gal_list_sizet_t **out)
```

Convert the ordered list of size_t's into an ordinary size_t linked list. This can be useful when all the elements have been added and you just need to pop-out elements and don’t care about the sorting values any more. After the conversion is done, this function will free the input list. Note that the out list doesn’t have to be empty. If it already contains some nodes, the new nodes will be added on top of them.

### 10.3.8.8 Doubly linked ordered list of size_t

An ordered list of indexes is required in many contexts, one example was discussed at the beginning of Section 10.3.8.7 [Ordered list of size_t], page 421. But the list that was introduced there only has one point of entry: you can always only parse the list from smallest to largest. In this section, the doubly-linked `gal_list_dosizet_t` node is defined which will allow us to parse the values in ascending or descending order.

```c
gal_list_dosizet_t
```

Doubly-linked, ordered size_t list node structure. Each node in this Doubly-linked list contains a size_t value and a floating point value. The floating point value is used as a reference to add new nodes in a sorted manner. In the functions here, this linked list can be pointed to by two pointers (largest and smallest) with the following format:

```
largest pointer
| NULL <-- (v0,s0) <-- (v1,s1) <-- ... (vn,sn) --> NULL
| smallest pointer
```

At any moment, the two pointers will point to the nodes containing the “largest” and “smallest” values and the rest of the nodes will be sorted. This is useful when an unknown number of nodes are being added continuously and during the operations it is important to have the nodes in a sorted format.

```c
typedef struct gal_list_dosizet_t {
    size_t v;           /* The actual value. */
    float s;            /* The parameter to sort by. */
    struct gal_list_dosizet_t *prev;
    struct gal_list_dosizet_t *next;
} gal_list_dosizet_t;
```

```c
void gal_list_dosizet_add (gal_list_dosizet_t **largest, gal_list_dosizet_t *smallest, size_t value, float tosort)
```

Allocate space for a new node in list, and store value and tosort into it. If the list is empty, both largest and smallest must be NULL.
size_t

gal_list_dosizet_pop_smallest (gal_list_dosizet_t **largest,
        gal_list_dosizet_t **smallest, float tosort)

Pop the value with the smallest reference from the doubly linked list and store the
reference into the space pointed to by tosort. Note that even though only the smallest
pointer will be popped, when there was only one node in the list, the largest pointer
also has to change, so we need both.

void

gal_list_dosizet_print (gal_list_dosizet_t *largest, gal_list_dosizet_t
        *smallest)

Print the largest and smallest values sequentially until the list is parsed.

void

gal_list_dosizet_to_sizet (gal_list_dosizet_t *in, gal_list_sizet_t **out)

Convert the doubly linked, ordered size_t list into a singly-linked list of size_t.

void

gal_list_dosizet_free (gal_list_dosizet_t *largest)

Free the doubly linked, ordered sized_t list.

10.3.8.9 List of gal_data_t

Gnuastro’s generic data container has a next element which enables it to be used as a
singly-linked list (see Section 10.3.6.1 [Generic data container (gal_data_t)], page 400).
The ability to connect the different data containers offers great advantages. For example
each column in a table in an independent dataset: with its own name, units, numeric data
type (see Section 4.6 [Numeric data types], page 130). Another application is in Tessellating
an input dataset into separate tiles or only studying particular regions, or tiles, of a larger
dataset (see Section 4.9 [Tessellation], page 141, and Section 10.3.15 [Tessellation library
(tile.h)], page 460). Each independent tile over the dataset can be connected to the others
as a linked list and thus any number of tiles can be represented with one variable.

void

gal_list_data_add (gal_data_t **list, gal_data_t *newnode)

Add an already allocated dataset (newnode) to top of list. Note that if
newnode->next!=NULL (newnode is itself a list), then list will be added to its end.

In this example multiple images are linked together as a list:

```c
int quietmmap=1;
size_t minmapsiz=-1;
gal_data_t *tmp, *list=NULL;
tmp = gal.fits_img_read("file1.fits", "1", minmapsiz, quietmmap);
gal_list_data_add( &list, tmp );
tmp = gal.fits_img_read("file2.fits", "1", minmapsiz, quietmmap);
gal_list_data_add( &list, tmp );
```
Chapter 10: Library

void [Function]
gal_list_data_add_alloc (gal_data_t **list, void *array, uint8_t type, size_t ndim, size_t *dsizes, struct wcsprm *wcs, int clear, size_t minmapsize, int quietmmap, char *name, char *unit, char *comment)
Allocate a new dataset (with gal_data_alloc in Section 10.3.6.2 [Dataset allocation], page 405) and put it as the first element of list. Note that if this is the first node to be added to the list, list must be NULL.

gal_data_t * [Function]
gal_list_data_pop (gal_data_t **list)
Pop the top node from list and return it.

void [Function]
gal_list_data_reverse (gal_data_t **list)
Reverse the order of the list such that the top node in the list before calling this function becomes the bottom node after it.

gal_data_t ** [Function]
gal_list_data_to_array_ptr (gal_data_t *list, size_t *num)
Allocate and return an array of gal_data_t * pointers with the same number of elements as the nodes in list. The pointers will be put in the same order that the list is parsed. Hence the N-th element in the array will point to the same dataset that the N-th node in the list points to.

size_t [Function]
gal_list_data_number (gal_data_t *list)
Return the number of nodes in list.

size_t [Function]
gal_list_data_last (gal_data_t *list)
Return a pointer to the last node in list.

void [Function]
gal_list_data_free (gal_data_t *list)
Free all the datasets in list along with all the allocated spaces in each.

10.3.9 Array input output

Getting arrays (commonly images or cubes) from a file into your program or writing them after the processing into an output file are some of the most common operations. The functions in this section are designed for such operations with the known file types. The functions here are thus just wrappers around functions of lower-level file type functions of this library, for example Section 10.3.11 [FITS files (fits.h)], page 430, or Section 10.3.12.2 [TIFF files (tiff.h)], page 445. If the file type of the input/output file is already known, you can use the functions in those sections respectively.

int [Function]
gal_array_name_recognized (char *filename)
Return 1 if the given file name corresponds to one of the recognized file types for reading arrays.
int gal_array_name_recognized_multiext (char *filename)

Return 1 if the given file name corresponds to one of the recognized file types for reading arrays which may contain multiple extensions (for example FITS or TIFF) formats.

gal_data_t gal_array_read (char *filename, char *extension, gal_list_str_t *lines, size_t minmapsize, int quietmmap)

Read the array within the given extension (extension) of filename, or the lines list (see below). If the array is larger than minmapsize bytes, then it won't be read into RAM, but a file on the HDD/SSD (no difference for the programmer). Messages about the memory-mapped file can be disabled with quietmmap.

extension will be ignored for files that don’t support them (for example JPEG or text). For FITS files, extension can be a number or a string (name of the extension), but for TIFF files, it has to be number. In both cases, counting starts from zero.

For multi-channel formats (like RGB images in JPEG or TIFF), this function will return a Section 10.3.8.9 [List of gal_data_t], page 423: one data structure per channel. Thus if you just want a single array (and want to check if the user hasn’t given a multi-channel input), you can check the next pointer of the returned gal_data_t.

lines is a list of strings with each node representing one line (including the new-line character), see Section 10.3.8.1 [List of strings], page 413. It will mostly be the output of gal_txt_stdin_read, which is used to read the program’s input as separate lines from the standard input (see Section 10.3.12.1 [Text files (txt.h)], page 442). Note that filename and lines are mutually exclusive and one of them must be NULL.

void gal_array_read_to_type (char *filename, char *extension, gal_list_str_t *lines, uint8_t type, size_t minmapsize, int quietmmap)

Similar to gal_array_read, but the output data structure(s) will have a numeric data type of type, see Section 4.6 [Numeric data types], page 130.

void gal_array_read_one_ch (char *filename, char *extension, gal_list_str_t *lines, size_t minmapsize, int quietmmap)

Read the dataset within filename (extension/hdu/dir extension) and make sure it is only a single channel. This is just a simple wrapper around gal_array_read that checks if there was more than one dataset and aborts with an informative error if there is more than one channel in the dataset.

Formats like JPEG or TIFF support multiple channels per input, but it may happen that your program only works on a single dataset. This function can be a convenient way to make sure that the data that comes into your program is only one channel.
void gal_array_read_one_ch_to_type (char *filename, char *extension,
    gal_list_str_t *lines, uint8_t type, size_t minmapsize, int quietmmap)

Similar to gal_array_read_one_ch, but the output data structure will have a numeric
data type of type, see Section 4.6 [Numeric data types], page 130.

10.3.10 Table input output (table.h)

Tables are a collection of one dimensional datasets that are packed together into one file. They are the single most common format to store high-level (processed) information, hence they play a very important role in Gnuastro. For a more thorough introduction, please see Section 5.4 [Table], page 171. Gnuastro’s Table program, and all the other programs that can read from and write into tables, use the functions of this section for reading and writing their input/output tables. For a simple demonstration of using the constructs introduced here, see Section 10.4.4 [Library demo - reading and writing table columns], page 512.

Currently only plain text (see Section 4.8.2 [Gnuastro text table format], page 137) and FITS (ASCII and binary) tables are supported by Gnuastro. However, the low-level table infra-structure is written such that accommodating other formats is also possible and in future releases more formats will hopefully be supported. Please don’t hesitate to suggest your favorite format so it can be implemented when possible.

GAL_TABLE_DEF_WIDTH_STR [Macro]
GAL_TABLE_DEF_WIDTH_INT [Macro]
GAL_TABLE_DEF_WIDTH_LINT [Macro]
GAL_TABLE_DEF_WIDTH_FLT [Macro]
GAL_TABLE_DEF_WIDTH_DBL [Macro]
GAL_TABLE_DEF_precision_INT [Macro]
GAL_TABLE_DEF_precision_FLT [Macro]
GAL_TABLE_DEF_precision_DBL [Macro]

The default width and precision for generic types to use in writing numeric types into a text file (plain text and FITS ASCII tables). When the dataset doesn’t have any pre-set width and precision (see disp_width and disp_precision in Section 10.3.6.1 [Generic data container (gal_data_t)], page 400) these will be directly used in C’s printf command to write the number as a string.

GAL_TABLE_DISPLAY_FMT_STRING [Macro]
GAL_TABLE_DISPLAY_FMT_DECIMAL [Macro]
GAL_TABLE_DISPLAY_FMT_UDECIMAL [Macro]
GAL_TABLE_DISPLAY_FMT_OCTAL [Macro]
GAL_TABLE_DISPLAY_FMT_HEX [Macro]
GAL_TABLE_DISPLAY_FMT_FLOAT [Macro]
GAL_TABLE_DISPLAY_FMT_EXP [Macro]
GAL_TABLE_DISPLAY_FMT_GENERAL [Macro]

The display format used in C’s printf to display data of different types. The _STRING and _DECIMAL are unique for printing strings and signed integers, they are mainly here for completeness. However, unsigned integers and floating points can be displayed in multiple formats:
Chapter 10: Library

Unsigned integer

For unsigned integers, it is possible to choose from _UDECIMAL (unsigned decimal), _OCTAL (octal notation, for example 125 in decimal will be displayed as 175), and _HEX (hexadecimal notation, for example 125 in decimal will be displayed as 7D).

Floating point

For floating point, it is possible to display the number in _FLOAT (floating point, for example 1500.345), _EXP (exponential, for example 1.500345e+03), or _GENERAL which is the best of the two for the given number.

GAL_TABLE_FORMAT_INVALID
GAL_TABLE_FORMAT_TXT
GAL_TABLE_FORMAT_AFITS
GAL_TABLE_FORMAT_BFITS

All the current acceptable table formats to Gnuastro. The AFITS and BFITS represent FITS ASCII tables and FITS Binary tables. You can use these anywhere you see the tableformat variable.

GAL_TABLE_SEARCH_INVALID
GAL_TABLE_SEARCH_NAME
GAL_TABLE_SEARCH_UNIT
GAL_TABLE_SEARCH_COMMENT

When the desired column is not a number, these values determine if the string to match, or regular expression to search, be in the name, units or comments of the column meta data. These values should be used for the searchin variables of the functions.

gal_data_t *
gal_table_info (char *filename, char *hdu, gal_list_str_t *lines, size_t *numcols, size_t *numrows, int *tableformat)

Store the information of each column of a table into an array of data structures with numcols datasets (one data structure for each column). The number of rows is stored in numrows. The format of the table (e.g., ASCII text file, or FITS binary or ASCII table) will be put in tableformat (macros defined above). If the filename is not a FITS file, then hdu will not be used (can be NULL).

The input must be either a file (specified by filename) or a list of strings (lines). lines is a list of strings with each node representing one line (including the new-line character), see Section 10.3.8.1 [List of strings], page 413. It will mostly be the output of gal_txt_stdin_read, which is used to read the program’s input as separate lines from the standard input (see Section 10.3.12.1 [Text files (txt.h)], page 442). Note that filename and lines are mutually exclusive and one of them must be NULL.

In the output datasets, only the meta-data strings (column name, units and comments), will be allocated and set. This function is just for column information (metadata), not column contents.
void gal_table_print_info (gal_data_t *allcols, size_t numcols, size_t numrows)
This program will print the column information for all the columns (output of gal_table_info). The output is in the same format as this command with Gnuastro Table program (see Section 5.4 [Table], page 171):

$ asttable --info table.fits

gal_data_t *
gal_table_read (char *filename, char *hdu, gal_list_str_t *lines, gal_list_str_t *cols, int searchin, int ignorecase, size_t minmapsize, int quietmmap, size_t *colmatch)
Read the specified columns in a file (named filename), or list of strings (lines) into a linked list of data structures. If the file is FITS, then hdu will also be used, otherwise, hdu is ignored.

lines is a list of strings with each node representing one line (including the new-line character), see Section 10.3.8.1 [List of strings], page 413. It will mostly be the output of gal_txt_stdin_read, which is used to read the program’s input as separate lines from the standard input (see Section 10.3.12.1 [Text files (txt.h)], page 442). Note that filename and lines are mutually exclusive and one of them must be NULL.

The information to search for columns should be specified by the cols list of strings (see Section 10.3.8.1 [List of strings], page 413). The string in each node of the list may be a number, an exact match to a column name, or a regular expression (in GNU AWK format) enclosed in / /. The searchin value must be one of the macros defined above. If cols is NULL, then this function will read the full table.

The output is an individually allocated list of datasets (see Section 10.3.8.9 [List of gal_data_t], page 423) with the same order of the cols list. Note that one column node in the cols list might give multiple columns (for example from regular expressions), in this case, the order of output columns that correspond to that one input, are in order of the table (which column was read first). So the first requested column is the first popped data structure and so on.

if colmatch!=NULL, it is assumed to be an array that has at least the same number of elements as nodes in the cols list. The number of columns that matched each input column will be stored in each element.

gal_list_sizet_t *
gal_table_list_of_indexs (gal_list_str_t *cols, gal_data_t *allcols, size_t numcols, int searchin, int ignorecase, char *filename, char *hdu, size_t *colmatch)
Returns a list of indexes (starting from 0) of the input columns that match the names/numbers given to cols. This is a low-level operation which is called by gal_table_read (described above), see there for more on each argument’s description.
allcols is the returned array of gal_table_info.
void gal_table_comments_add_intro (gal_list_str_t **comments, char *program_string, time_t *rawtime)

Add some basic information to the list of comments. This basic information includes the following information:

- If the program is run in a Git version controlled directory, Git’s description is printed (see description under COMMIT in Section 4.11 [Output FITS files], page 143).
- The calendar time that is stored in rawtime (time_t is C’s calendar time format defined in time.h). You can calculate the time in this format with the following expressions:
  
  ```
  time_t rawtime;
  time(&rawtime);
  ```
- The name of your program in program_string. If it is NULL, this line is ignored.

void gal_table_write (gal_data_t *cols, struct gal.fits_list_key_t **keywords, gal_list_str_t *comments, int tableformat, char *filename, char *extname, uint8_t colinfoinstdout)

Write cols (a list of datasets, see Section 10.3.8.9 [List of gal_data_t], page 423) into a table stored in filename. The format of the table can be determined with tableformat that accepts the macros defined above. When filename==NULL, the column information will be printed on the standard output (command-line).

If comments!=NULL, the list of comments (see Section 10.3.8.1 [List of strings], page 413) will also be printed into the output table. When the output table is a plain text file, every node of comments will be printed after a # (so it can be considered as a comment) and in FITS table they will follow a COMMENT keyword.

If a file named filename already exists, the operation depends on the type of output. When filename is a FITS file, the table will be added as a new extension after all existing extensions. If filename is a plain text file, this function will abort with an error.

If filename is a FITS file, the table extension will have the name extname.

When colinfoinstdout!=0 and filename==NULL (columns are printed in the standard output), the dataset metadata will also printed in the standard output. When printing to the standard output, the column information can be piped into another program for further processing and thus the meta-data (lines starting with a #) must be ignored. In such cases, you only print the column values by passing 0 to colinfoinstdout.

void gal_table_write_log (gal_data_t *logll, char *program_string, time_t *rawtime, gal_list_str_t *comments, char *filename, int quiet)

Write the logll list of datasets into a table in filename (see Section 10.3.8.9 [List of gal_data_t], page 423). This function is just a wrapper around gal_table_comments_add_intro and gal_table_write (see above). If quiet is non-zero, this function will print a message saying that the filename has been created.
10.3.11 FITS files (fits.h)

The FITS format is the most common format to store data (images and tables) in astronomy. The CFITSIO library already provides a very good low-level collection of functions for manipulating FITS data. The low-level nature of CFITSIO is defined for versatility and portability. As a result, even a simple and basic operation, like reading an image or table column into memory, will require a special sequence of CFITSIO function calls which can be inconvenient and buggy to manage in separate locations. To ease this process, Gnuastro's library provides wrappers for CFITSIO functions. With these, it much easier to read, write, or modify FITS file data, header keywords and extensions. Hence, if you feel these functions don’t exactly do what you want, we strongly recommend reading the CFITSIO manual to use its great features directly (afterwards, send us your wrappers so we can include it here for others to benefit also).

All the functions and macros introduced in this section are declared in gnuastro/fits.h. When you include this header, you are also including CFITSIO’s fitsio.h header. So you don’t need to explicitly include fitsio.h anymore and can freely use any of its macros or functions in your code along with those discussed here.

10.3.11.1 FITS Macros, errors and filenames

Some general constructs provided by Gnuastro’s FITS handling functions are discussed here. In particular there are several useful functions about FITS file names.

```
GAL_FITS_MAX_NDIM  [Macro]
  The maximum number of dimensions a dataset can have in FITS format, according to the FITS standard this is 999.

void  [Function]
gal_fits_io_error (int status, char *message)
  If status is non-zero, this function will print the CFITSIO error message corresponding to status, print message (optional) in the next line and abort the program. If message==NULL, it will print a default string after the CFITSIO error.

int  [Function]
gal_fits_name_is_fits (char *name)
  If the name is an acceptable CFITSIO FITS filename return 1 (one), otherwise return 0 (zero). The currently acceptable FITS suffixes are .fits, .fit, .fits.gz, .fits.Z, .imh, .fits.fz. IMH is the IRAF format which is acceptable to CFITSIO.

int  [Function]
gal_fits_suffix_is_fits (char *suffix)
  Similar to gal_fits_name_is_fits, but only for the suffix. The suffix doesn’t have to start with ‘.’: this function will return 1 (one) for both fits and .fits.

char *  [Function]
gal_fits_name_save_as_string (char *filename, char *hdu)
  If the name is a FITS name, then put a (hdu: ...) after it and return the string. If it isn’t a FITS file, just print the name, if filename==NULL, then return the string stdin. Note that the output string’s space is allocated.
```
This function is useful when you want to report a random file to the user which may be FITS or not (for a FITS file, simply the filename is not enough, the HDU is also necessary).

### 10.3.11.2 CFITSIO and Gnuastro types

Both Gnuastro and CFITSIO have special identifiers for each type that they accept. Gnuastro’s type identifiers are fully described in Section 10.3.3 [Library data types (type.h)], page 390, and are usable for all kinds of datasets (images, table columns, etc) as part of Gnuastro’s Section 10.3.6.1 [Generic data container (gal_data_t)], page 400. However, following the FITS standard, CFITSIO has different identifiers for images and tables. Following CFITSIO’s own convention, we will use bitpix for image type identifiers and datatype for its internal identifiers (and mainly used in tables). The functions introduced in this section can be used to convert between CFITSIO and Gnuastro’s type identifiers.

One important issue to consider is that CFITSIO’s types are not fixed width (for example long may be 32-bits or 64-bits on different systems). However, Gnuastro’s types are defined by their width. These functions will use information on the host system to do the proper conversion. To have a portable (usable on different systems) code, is thus recommended to use these functions and not to assume a fixed correspondence between CFITSIO and Gnuastro’s types.

```c
uint8_t
gal_fits_bitpix_to_type (int bitpix)

int
gal_fits_type_to_bitpix (uint8_t type)

char
gal_fits_type_to_bin_tform (uint8_t type)

int
gal_fits_type_to_datatype (uint8_t type)

uint8_t
gal_fits_datatype_to_type (int datatype, int is_table_column)
```

Return the Gnuastro type identifier that corresponds to CFITSIO’s bitpix on this system.

Return the CFITSIO bitpix value that corresponds to Gnuastro’s type.

Return the FITS standard binary table TFORM character that corresponds to Gnuastro’s type.

Return the CFITSIO datatype that corresponds to Gnuastro’s type on this machine.

Return Gnuastro’s type identifier that corresponds to the CFITSIO datatype. Note that when dealing with CFITSIO’s TLONG, the fixed width type differs between tables and images. So if the corresponding dataset is a table column, put a non-zero value into is_table_column.

### 10.3.11.3 FITS HDUs

A FITS file can contain multiple HDUs/extensions. The functions in this section can be used to get basic information about the extensions or open them. Note that fitsfile is defined in CFITSIO’s fitsio.h which is automatically included by Gnuastro’s gnuastro/fits.h.
fitsfile *

gal_fits_open_to_write (char *filename)
If filename exists, open it and return the fitsfile pointer that corresponds to it. If
filename doesn’t exist, the file will be created which contains a blank first extension
and the pointer to its next extension will be returned.

size_t

gal_fits_hdu_num (char *filename)
Return the number of HDUs/extensions in filename.

int

gal_fits_hdu_format (char *filename, char *hdu)
Return the format of the HDU as one of CFITSIO’s recognized macros: IMAGE_HDU,
ASCII_TBL, or BINARY_TBL.

fitsfile *

gal_fits_hdu_open (char *filename, char *hdu, int iomode)
Open the HDU/extension hdu from filename and return a pointer to CFITSIO’s
fitsfile. iomode determines how the FITS file will be opened using CFITSIO’s
macros: READONLY or READWRITE.

The string in hdu will be appended to filename in square brackets so CFITSIO only
opens this extension. You can use any formatting for the hdu that is acceptable to
CFITSIO. See the description under --hdu in Section 4.1.2.1 [Input/Output options],
page 109, for more.

fitsfile *

gal_fits_hdu_open_format (char *filename, char *hdu, int img0_tab1)
Open (in read-only format) the hdu HDU/extension of filename as an image or table.
When img0_tab1 is 0(zero) but the HDU is a table, this function will abort with an
error. It will also abort with an error when img0_tab1 is 1(one), but the HDU is an
image.

A FITS HDU may contain both tables or images. When your program needs one of
these formats, you can call this function so if the user provided the wrong HDU/file,
it will abort and inform the user that the file/HDU is has the wrong format.

10.3.11.4 FITS header keywords

Each FITS extension/HDU contains a raw dataset which can either be a table or an image
along with some header keywords. The keywords can be used to store meta-data about
the actual dataset. The functions in this section describe Gnuastro’s high-level functions
for reading and writing FITS keywords. Similar to all Gnuastro’s FITS-related functions,
these functions are all wrappers for CFITSIO’s low-level functions.

The necessary meta-data (header keywords) for a particular dataset are commonly nu-
merous, it is much more efficient to list them in one variable and call the reading/writing
functions once. Hence the functions in this section use linked lists, a thorough intro-
duction to them is given in Section 10.3.8 [Linked lists (list.h)], page 411. To reading FITS
keywords, these functions use a list of Gnuastro’s generic dataset format that is discussed
in Section 10.3.8.9 [List of gal_data_t], page 423. To write FITS keywords we define the
gal_fits_list_key_t node that is defined below.
gal_fits_list_key_t  
Structure for writing FITS keywords. This structure is used for one keyword and you don’t need to set all elements. With the next element, you can link it to another keyword thus creating a linked list to add any number of keywords easily and at any step during your program (see Section 10.3.8 [Linked lists (list.h)], page 411, for an introduction on lists). See the functions below for adding elements to the list.

typedef struct gal_fits_list_key_t
{
    int kfree; /* ==1, free name. */
    int vfree; /* ==1, free value. */
    int cfree; /* ==1, free comment. */
    uint8_t type; /* Keyword value type. */
    char *keyname; /* Keyword Name. */
    void *value; /* Keyword value. */
    char *comment; /* Keyword comment. */
    char *unit; /* Keyword unit. */
    struct gal_fits_list_key_t *next; /* Next keyword. */
} gal_fits_list_key_t;

void * gal_fits_key_img_blank (uint8_t type)  
Returns a pointer to an allocated space containing the value to the FITS BLANK header keyword, when the input array has a type of type. This is useful when you want to write the BLANK keyword using CFITSIO’s fits_write_key function.

According to the FITS standard: “If the BSCALE and BZERO keywords do not have the default values of 1.0 and 0.0, respectively, then the value of the BLANK keyword must equal the actual value in the FITS data array that is used to represent an undefined pixel and not the corresponding physical value”. Therefore a special BLANK value is needed for datasets containing signed 8-bit, unsigned 16-bit, unsigned 32-bit, and unsigned 64-bit integers (types that are defined with BSCALE and BZERO in the FITS standard).

Not usable when reading a dataset: As quoted from the FITS standard above, the value returned by this function can only be generically used for the writing of the BLANK keyword header. It must not be used as the blank pointer when when reading a FITS array using CFITSIO. When reading an array with CFITSIO, you can use gal_blank_alloc_write to generate the necessary pointer.

void gal_fits_key_clean_str_value (char *string)  
Remove the single quotes and possible extra spaces around the keyword values that CFITSIO returns when reading a string keyword. CFITSIO doesn’t remove the two single quotes around the string value of a keyword. Hence the strings it reads are like: ‘value ’, or ‘some_very_long_value’. To use the value during your processing, it is commonly necessary to remove the single quotes (and possible extra spaces). This function will do this within the allocated space of the string.
char *

gal_fits_key_date_to_struct_tm (char *fitsdate, struct tm *tp)

Parse fitsdate as a FITS date format string (most generally: YYYY-MM-DDThh:mm:ss.ddd...) into the C library’s broken-down time structure, or struct tm (declared in time.h) and return a pointer to a newly allocated array for the sub-second part of the format (.ddd...). Therefore it needs to be freed afterwards (if it isn’t NULL) When there is no sub-second portion, this pointer will be NULL.

This is a relatively low-level function, an easier function to use is gal_fits_key_date_to_seconds which will return the sub-seconds as double precision floating point.

Note that the FITS date format mentioned above is the most complete representation. The following two formats are also acceptable: YYYY-MM-DDThh:mm:ss and YYYY-MM-DD. This option can also interpret the older FITS date format where only two characters are given to the year and the date format is reversed (DD/MM/YYThh:mm:ss.ddd...). In this case (following the GNU C Library), this option will make the following assumption: values 68 to 99 correspond to the years 1969 to 1999, and values 0 to 68 as the years 2000 to 2068.

size_t

gal_fits_key_date_to_seconds (char *fitsdate, char **subsecstr, double *subsec)

Return the Unix epoch time (number of seconds that have passed since 00:00:00 Thursday, January 1st, 1970) corresponding to the FITS date format string fitsdate (see description of gal_fits_key_date_to_struct_tm above). This function will return GAL_BLANK_SIZE_T if the broken-down time couldn’t be converted to seconds.

The Unix epoch time is in units of seconds, but the FITS date format allows sub-second accuracy. The last two arguments are for the (optional) sub-second portion. If fitsdate contains sub-second accuracy, then the starting of the sub-second part’s string is stored in subsecstr (allocated separately), and subsec will be the corresponding numerical value (between 0 and 1, in double precision floating point). So to avoid leaking memory, when subsecstr!=NULL, it must be freed.

This is a very useful function for operations on the FITS date values, for example sorting FITS files by their dates, or finding the time difference between two FITS files. The advantage of working with the Unix epoch time is that you don’t have to worry about calendar details (for example the number of days in different months, or leap years, etc).

void

gal_fits_key_read_from_ptr (fitsfile *fptr, gal_data_t *keysll, int readcomment, int readunit)

Read the list of keyword values from a FITS pointer. The input should be a linked list of Gnuastro’s generic data container (gal_data_t). Before calling this function, you just have to set the name and desired type values of each node in the list to the keyword you want it to keep the value of. The given name value will be directly passed to CFITSIO to read the desired keyword name. This function will allocate space to keep the value. If readcomment and readunit are non-zero, this function will also try to read the possible comments and units of the keyword.
Here is one example of using this function:

```c
/* Allocate an array of datasets. */
gal_data_t *keysll=gal_data_array_calloc(N);

/* Make the array usable as a list too (by setting ‘next’). */
for(i=0;i<N-1;++i) keysll[i].next=keysll[i+1];

/* Fill the datasets with a ‘name’ and a ‘type’. */
keysll[0].name="NAME1"; keysll[0].type=GAL_TYPE_INT32;
keysll[1].name="NAME2"; keysll[1].type=GAL_TYPE_STRING;
...
...

/* Call this function. */
gal_fits_key_read_from_ptr(fptr, keysll, 0, 0);

/* Use the values as you like... */

/* Free all the allocated spaces. Note that ‘name’ wasn’t allocated in this example, so we should explicitly set it to NULL before calling ‘gal_data_array_free’. */
for(i=0;i<N;++i) keysll[i].name=NULL;
gal_data_array_free(keysll, N, 1);
```

If the `array` pointer of each keyword’s dataset is not NULL, then it is assumed that the space to keep the value has already been allocated. If it is NULL, space will be allocated for the value by this function.

Strings need special consideration: the reason is that generally, `gal_data_t` needs to also allow for array of strings (as it supports arrays of integers for example). Hence when reading a string value, two allocations may be done by this function (one if `array!=NULL`).

Therefore, when using the values of strings after this function, `keysll[i].array` must be interpreted as `char **`: one allocation for the pointer, one for the actual characters. If you use something like the example, above you don’t have to worry about the freeing, `gal_data_array_free` will free both allocations. So to read a string, one easy way would be the following:

```c
char *str, **strarray;
strarr = keysll[i].array;
str    = strarray[0];
```

If CFITSIO is unable to read a keyword for any reason the `status` element of the respective `gal_data_t` will be non-zero. If it is zero, then the keyword was found and successfully read. Otherwise, it is a CFITSIO status value. You can use CFITSIO’s error reporting tools or `gal_fits_io_error` (see Section 10.3.11.1 [FITS Macros, errors and filenames], page 430) for reporting the reason of the failure. A tip: when the keyword doesn’t exist, CFITSIO’s status value will be `KEY_NO_EXIST`. 
CFITSIO will start searching for the keywords from the last place in the header that it searched for a keyword. So it is much more efficient if the order that you ask for keywords is based on the order they are stored in the header.

```c
void gal_fits_key_read (char *filename, char *hdru, gal_data_t *keysll, int readcomment, int readunit)
```

Same as `gal_fits_read_keywords_fptr` (see above), but accepts the filename and HDU as input instead of an already opened CFITSIO `fitsfile` pointer.

```c
void gal_fits_key_list_add (galfitslist_key_t **list, uint8_t type, char *keyname, int kfree, void *value, int vfree, char *comment, int cfree, char *unit, int ufree)
```

Add a keyword to the top of list of header keywords that need to be written into a FITS file. In the end, the keywords will have to be freed, so it is important to know before hand if they were allocated or not (hence the presence of the arguments ending in `free`). If the space for the respective element is not allocated, set these arguments to 0 (zero).

You can call this function multiple times on a single list add several keys that will be written in one call to `gal_fits_key_write` or `gal_fits_key_write_in_ptr`. However, the resulting list will be a last-in-first-out list (for more on lists, see Section 10.3.8 [Linked lists (list.h)], page 411). Hence, the written keys will have the inverse order of your calls to this function. To avoid this problem, you can either use `gal_fits_key_list_add_end` instead (which will add each key to the end of the list, not to the top like this function). Alternatively, you can use `gal_fits_key_list_reverse` after adding all the keys with this function.

**Important note for strings**: the value should be the pointer to the string its-self (`char *`), not a pointer to a pointer (`char **`).

```c
void gal_fits_key_list_add_end (galfitslist_key_t **list, uint8_t type, char *keyname, int kfree, void *value, int vfree, char *comment, int cfree, char *unit, int ufree)
```

Similar to `gal_fits_key_list_add`, but add the given keyword to the end of the list, see the description of `gal_fits_key_list_add` for more. Use this function if you want the keywords to be written in the same order that you add nodes to the list of keywords.

```c
void gal_fits_key_list_title_add (galfitslist_key_t **list, char *title, int tfree)
```

Add a special “title” keyword (with the `title` string) to the top of the keywords list.

```c
void gal_fits_key_list_title_add_end (galfitslist_key_t **list, char *title, int tfree)
```

Add a special “title” keyword (with the `title` string) to the end/bottom of the keywords list.
void gal_fits_key_list_reverse (gal_fits_list_key_t **list)
    Reverse the input list of keywords.

void gal_fits_key_write_title_in_ptr (char *title, fitsfile *fptr)
    Add two lines of “title” keywords to the given CFITSIO fptr pointer. The first line will be blank and the second will have the string in title roughly in the middle of the line (a fixed distance from the start of the keyword line). A title in the list of keywords helps in classifying the keywords into groups and inspecting them by eye. If title==NULL, this function won’t do anything.

void gal_fits_key_write_filename (char *keynamebase, char *filename, gal_fits_list_key_t **list, int top1end0)
    Put filename into the gal_fits_list_key_t list (possibly broken up into multiple keywords) to later write into a HDU header. The keynamebase string will be appended with a _N (N>0) and used as the keyword name. If top1end0!=0, then the keywords containing the filename will be added to the top of the list.

    The FITS standard sets a maximum length for the value of a keyword. This creates problems with file names (which include directories). Because file names/addresses can become very long. Therefore, when filename is longer than the maximum length of a FITS keyword value, this function will break it into several keywords (breaking up the string on directory separators).

void gal_fits_key_write_wcsstr (fitsfile *fptr, char *wcsstr, int nkeyrec)
    Write the WCS header string (produced with WCSLIB’s wcshdo function) into the CFITSIO fitsfile pointer. nkeyrec is the number of FITS header keywords in wcsstr. This function will put a few blank keyword lines along with a comment WCS information before writing each keyword record.

void gal_fits_key_write (gal_fits_list_key_t **keylist, char *title, char *filename, char *hdu)
    Write the list of keywords in keylist into the hdu extension of the file called filename (the file must already exist) and free the list.

    The list nodes are meant to be dynamically allocated (because they will be freed after being written). We thus recommend using the gal_fits_key_list_add or gal_fits_key_list_add_end to create and fill the list. Below is one fully working example of using this function to write a keyword into an existing FITS file.

    #include <stdio.h>
    #include <stdlib.h>
    #include <gnuastro/fits.h>

    int main()
    {

    ...
char *filename="test.fits";
gal_fits_list_key_t *keylist=NULL;

char *unit="unit";
float value=123.456;
char *keyname="MYKEY";
char *comment="A good description of the key";
gal_fits_key_list_add_end(&keylist, GAL_TYPE_FLOAT32, keyname, 0, &value, 0, comment, 0, unit, 0);
gal_fits_key_write(&keylist, "Matching metadata", filename, "1");
return EXIT_SUCCESS;
}

void    [Function]
gal_fits_key_write_in_ptr (gal_fits_list_key_t **keylist, fitsfile *fpotr)    
    Write the list of keywords in keylist into the given CFITSIO fitsfile pointer and free keylist. For more on the input keylist, see the description and example for gal_fits_key_write, above.

def void    [Function]
gal_fits_key_write_version (gal_fits_list_key_t **keylist, char *title, char *filename, char *hdu)    
    Write the (optional, when keylist!=NULL) given list of keywords under the optional FITS keyword title, then print all the important version and date information. This is basically, just a wrapper over gal_fits_key_write_version_in_ptr.

def void    [Function]
gal_fits_key_write_version_in_ptr (gal_fits_list_key_t **keylist, char *title, fitsfile *fpotr)    
    Write or update (all the) keyword(s) in headers into the FITS pointer, but also the date, name of your program (program_name), along with the versions of CFITSIO, WCSLIB (when available), GSL, Gnuastro, and (the possible) commit information into the header as described in Section 4.11 [Output FITS files], page 143.

Since the data processing depends on the versions of the libraries you have used, it is strongly recommended to include this information in every FITS output. gal_fits_img_write and gal_fits_tab_write will automatically use this function.

def void    [Function]
gal_fits_key_write_config (gal_fits_list_key_t **keylist, char *title, char *extname, char *filename, char *hdu)    
    Write the given keyword list (keylist) into the hdu extension of filename, ending it with version information. This function will write extname as the name of the extension (value to the standard EXTNAME FITS keyword). The list of keywords will then be printed under a title called title.

This function is used by many Gnuastro programs and is primarily intended for writing configuration settings of a program into the zero-th extension of their FITS outputs (which is empty when the FITS file is created by Gnuastro’s program and this library).
10.3.11.5 FITS arrays (images)

Images (or multi-dimensional arrays in general) are one of the common data formats that is stored in FITS files. Only one image may be stored in each FITS HDU/extension. The functions described here can be used to get the information of, read, or write images in FITS files.

**void**

```c
void gal_fits_img_info (fitsfile *fptr, int *type, size_t *ndim, size_t **dsize, char **name, char **unit)
```

Read the type (see Section 10.3.3 [Library data types (type.h)], page 390), number of dimensions, and size along each dimension of the CFITSIO fitsfile into the type, ndim, and dsize pointers respectively. If name and unit are not NULL (point to a char *), then if the image has a name and units, the respective string will be put in these pointers.

**size_t**

```c
size_t * gal_fits_img_info_dim (char *filename, char *hdu, size_t *ndim)
```

Put the number of dimensions in the hdu extension of filename in the space that ndim points to and return the size of the dataset along each dimension as an allocated array with *ndim elements.

**gal_data_t**

```c
gal_data_t * gal_fits_img_read (char *filename, char *hdu, size_t minmapsize, int quietmmap)
```

Read the contents of the hdu extension/HDU of filename into a Gnuastro generic data container (see Section 10.3.6.1 [Generic data container (gal_data_t)], page 400) and return it. If the necessary space is larger than minmapsize, then don’t keep the data in RAM, but in a file on the HDD/SSD. For more on minmapsize and quietmmap see the description under the same name in Section 10.3.6.1 [Generic data container (gal_data_t)], page 400.

Note that this function only reads the main data within the requested FITS extension, the WCS will not be read into the returned dataset. To read the WCS, you can use gal_wcs_read function as shown below. Afterwards, the gal_data_free function will free both the dataset and any WCS structure (if there are any).

```c
data=gal_fits_img_read(filename, hdu, -1, 1);
data->wcs=gal_wcs_read(filename, hdu, 0, 0, &data->wcs->nwcs);
```

```c
gal_data_t * gal_fits_img_read_to_type (char *inputname, char *inhdu, uint8_t type, size_t minmapsize, int quietmmap)
```

Read the contents of the hdu extension/HDU of filename into a Gnuastro generic data container (see Section 10.3.6.1 [Generic data container (gal_data_t)], page 400) of type type and return it.

This is just a wrapper around gal_fits_img_read (to read the image/array of any type) and gal_data_copy_to_new_type_free (to convert it to type and free the initially read dataset). See the description there for more.
gal_data_t * [Function]
gal_fits_img_read_kernel (char *filename, char *hdu, size_t minmapsize, int quietmmap)

Read the hdu of filename as a convolution kernel. A convolution kernel must have
an odd size along all dimensions, it must not have blank (NaN in floating point
types) values and must be flipped around the center to make the proper convolution
(see Section 6.3.1.1 [Convolution process], page 217). If there are blank values, this
function will change the blank values to 0.0. If the input image doesn’t have the other
two requirements, this function will abort with an error describing the condition to
the user. The finally returned dataset will have a float32 type.

fitsfile * [Function]
gal_fits_img_write_to_ptr (gal_data_t *input, char *filename)

Write the input dataset into a FITS file named filename and return the correspond-
ing CFITSIO fitsfile pointer. This function won’t close fitsfile, so you can still add
other extensions to it after this function or make other modifications.

void [Function]
gal_fits_img_write (gal_data_t *data, char *filename, gal_fits_list_key_t *
headers, char *program_string)

Write the input dataset into the FITS file named filename. Also add the headers
keywords to the newly created HDU/extension it along with your program’s name
(program_string).

void [Function]
gal_fits_img_write_to_type (gal_data_t *data, char *filename,
gal_fits_list_key_t *headers, char *program_string, int type)

Convert the input dataset into type, then write it into the FITS file named filename. Also add the headers
keywords to the newly created HDU/extension along with your program’s name (program_string). After the FITS file is written, this function will
free the copied dataset (with type type) from memory.

This is just a wrapper for the gal_data_copy_to_new_type and gal_fits_img_write functions.

void [Function]
gal_fits_img_write_corr_wcs_str (gal_data_t *data, char *filename, char *
wcsstr, int nkeyrec, double *crpix, gal_fits_list_key_t *headers, char *
program_string)

Write the input dataset into filename using the wcsstr while correcting the CRPIX
values.

This function is mainly useful when you want to make FITS files in parallel (from one
main WCS structure, with just differing CRPIX). This can happen in the following
cases for example:

• When a large number of FITS images (with WCS) need to be created in parallel,
it can be much more efficient to write the header’s WCS keywords once at first,
write them in the FITS file, then just correct the CRPIX values.

• WCSLIB’s header writing function is not thread safe. So when writing FITS
images in parallel, we can’t write the header keywords in each thread.
10.3.11.6 FITS tables

Tables are one of the common formats of data that is stored in FITS files. Only one table may be stored in each FITS HDU/extension, but each table column must be viewed as a different dataset (with its own name, units and numeric data type for example). The only constraint of the column datasets in a table is that they must be one-dimensional and have the same number of elements as the other columns. The functions described here can be used to get the information of, read, or write columns into FITS tables.

```c
void gal_fits_tab_size (fitsfile *fitsptr, size_t *nrows, size_t *ncols)
    Read the number of rows and columns in the table within CFITSIO's fitsptr.

int gal_fits_tab_format (fitsfile *fitsptr)
    Return the format of the FITS table contained in CFITSIO's fitsptr. Recall that FITS tables can be in binary or ASCII formats. This function will return GAL_TABLE_FORMAT_AFITS or GAL_TABLE_FORMAT_BFITS (defined in Section 10.3.10 [Table input output (table.h)], page 426). If the fitsptr is not a table, this function will abort the program with an error message informing the user of the problem.

gal_data_t *
    Store the information of each column in hdu of filename into an array of data structures with numcols elements (one data structure for each column) see Section 10.3.6.3 [Arrays of datasets], page 406. The total number of rows in the table is also put into the memory that nrows points to. The format of the table (e.g., FITS binary or ASCII table) will be put in tableformat (macros defined in Section 10.3.10 [Table input output (table.h)], page 426).

This function is just for column information. Therefore it only stores meta-data like column name, units and comments. No actual data (contents of the columns for example the array or dsize elements) will be allocated by this function. This is a low-level function particular to reading tables in FITS format. To be generic, it is recommended to use gal_table_info which will allow getting information from a variety of table formats based on the filename (see Section 10.3.10 [Table input output (table.h)], page 426).

gal_data_t *
    Read the columns given in the list indexll from a FITS table (in filename and HDU/extension hdu) into the returned linked list of data structures, see Section 10.3.8.3 [List of size_t], page 415, and Section 10.3.8.9 [List of gal_data_t], page 423. If the necessary space for each column is larger than minmapszie, don't keep it in the RAM, but in a file in the HDD/SSD. For more on minmapszie and quietmmap, see the description under the same name in Section 10.3.6.1 [Generic data container (gal_data_t)], page 400.
```
Each column will have `numrows` rows and `colinfo` contains any further information about the columns (returned by `gal_fits_tab_info`, described above). Note that this is a low-level function, so the output data linked list is the inverse of the input indexes linked list. It is recommended to use `gal_table_read` for generic reading of tables, see Section 10.3.10 [Table input output (table.h)], page 426.

```c
void

\texttt{gal\_fits\_tab\_write(gal\_data\_t *cols, gal\_list\_str\_t *comments, int tableformat, char *filename, char *extname)}

Write the list of datasets in `cols` (see Section 10.3.8.9 [List of \texttt{gal\_data\_t}], page 423) as separate columns in a FITS table in `filename`. If `filename` already exists then this function will write the table as a new extension called `extname`, after all existing ones. The format of the table (ASCII or binary) may be specified with the `tableformat` (see Section 10.3.10 [Table input output (table.h)], page 426). If `comments!=NULL`, each node of the list of strings will be written as a \texttt{COMMENT} keywords in the output FITS file (see Section 10.3.8.1 [List of strings], page 413).

This is a low-level function for tables. It is recommended to use `gal_table_write` for generic writing of tables in a variety of formats, see Section 10.3.10 [Table input output (table.h)], page 426.

10.3.12 File input output

The most commonly used file format in astronomical data analysis is the FITS format (see Section 5.1 [Fits], page 146, for an introduction), therefore Gnuastro’s library provides a large and separate collection of functions to read/write data from/to them (see Section 10.3.11 [FITS files (fits.h)], page 430). However, FITS is not well recognized outside the astronomical community and cannot be imported into documents or slides. Therefore, in this section, we discuss the other different file formats that Gnuastro’s library recognizes.

10.3.12.1 Text files (txt.h)

The most universal and portable format for data storage are plain text files. They can be viewed and edited on any text editor or even on the command-line. This section are describes some functions that help in reading from and writing to plain text files.

Lines are one of the most basic building blocks (delimiters) of a text file. Some operating systems like Microsoft Windows, terminate their ASCII text lines with a carriage return character and a new-line character (two characters, also known as CRLF line terminators). While Unix-like operating systems just use a single new-line character. The functions below that read an ASCII text file are able to identify lines with both kinds of line terminators.

Gnuastro defines a simple format for metadata of table columns in a plain text file that is discussed in Section 4.8.2 [Gnuastro text table format], page 137. The functions to get information from, read from and write to plain text files also follow those conventions.

\begin{verbatim}
GAL_TXT_LINESTAT_INVALID [Macro]
GAL_TXT_LINESTAT_BLANK [Macro]
GAL_TXT_LINESTAT_COMMENT [Macro]
\end{verbatim}
Chapter 10: Library 443

GAL.TXT.LINESTAT.DATAROW
[Macro]
Status codes for lines in a plain text file that are returned by gal_txt_line_stat. Lines which have a # character as their first non-white character are considered to be comments. Lines with nothing but white space characters are considered blank. The remaining lines are considered as containing data.

int
[Function]
gal_txt_line_stat (char *line)
Check the contents of line and see if it is a blank, comment, or data line. The returned values are the macros that start with GAL.TXT.LINESTAT.

cchar *
[Function]
gal_txt_trim_space (char *str)
Trim the white space characters before and after the given string. The operation is done within the allocated space of the string, so if you need the string untouched, please pass an allocated copy of the string to this function. The returned pointer is within the input string. If the input pointer is NULL, or the string only has white-space characters, the returned pointer will be NULL.

gal_data_t *
[Function]
gal_txt_table_info (char *filename, gal_list_str_t *lines, size_t *numcols, size_t *numrows)
Store the information of each column in a text file filename, or list of strings (lines) into an array of data structures with numcols elements (one data structure for each column) see Section 10.3.6.3 [Arrays of datasets], page 406. The total number of rows in the table is also put into the memory that numrows points to.
lines is a list of strings with each node representing one line (including the new-line character), see Section 10.3.8.1 [List of strings], page 413. It will mostly be the output of gal_txt_stdin_read, which is used to read the program’s input as separate lines from the standard input (see below). Note that filename and lines are mutually exclusive and one of them must be NULL.
This function is just for column information. Therefore it only stores meta-data like column name, units and comments. No actual data (contents of the columns for example the array or dsize elements) will be allocated by this function. This is a low-level function particular to reading tables in plain text format. To be generic, it is recommended to use gal_table_info which will allow getting information from a variety of table formats based on the filename (see Section 10.3.10 [Table input output (table.h)], page 426).

gal_data_t *
[Function]
gal_txt_table_read (char *filename, gal_list_str_t *lines, size_t numrows, gal_data_t *colinfo, gal_list_sizet_t *indexll, size_t minmapsize, int quietmmap)
Read the columns given in the list indexll from a plain text file (filename) or list of strings (lines), into a linked list of data structures (see Section 10.3.8.3 [List of size_t], page 415, and Section 10.3.8.9 [List of gal_data_t], page 423). If the necessary space for each column is larger than minmapsize, don’t keep it in the RAM, but in a file on the HDD/SSD. For more one minmapsize and quietmmap,
see the description under the same name in Section 10.3.6.1 [Generic data container (gal_data_t)], page 400.

lines is a list of strings with each node representing one line (including the new-line character), see Section 10.3.8.1 [List of strings], page 413. It will mostly be the output of gal_txt_stdin_read, which is used to read the program’s input as separate lines from the standard input (see below). Note that filename and lines are mutually exclusive and one of them must be NULL.

Note that this is a low-level function, so the output data list is the inverse of the input indexes linked list. It is recommended to use gal_table_read for generic reading of tables in any format, see Section 10.3.10 [Table input output (table.h)], page 426.

**gal_data_t **
**gal_txt_image_read (char *filename, gal_list_str_t **lines, size_t minmapsize, int quietmmap) **
Read the 2D plain text dataset in file (filename) or list of strings (lines) into a dataset and return the dataset. If the necessary space for the image is larger than minmapsize, don’t keep it in the RAM, but in a file on the HDD/SSD. For more on minmapsize and quietmmap, see the description under the same name in Section 10.3.6.1 [Generic data container (gal_data_t)], page 400.

lines is a list of strings with each node representing one line (including the new-line character), see Section 10.3.8.1 [List of strings], page 413. It will mostly be the output of gal_txt_stdin_read, which is used to read the program’s input as separate lines from the standard input (see below). Note that filename and lines are mutually exclusive and one of them must be NULL.

**gal_list_str_t **
**gal_txt_stdin_read (long timeout_microsec) **
Read the complete standard input and return a list of strings with each line (including the new-line character) as one node of that list. If the standard input is already filled (for example connected to another program’s output with a pipe), then this function will parse the whole stream.

If Standard input is not pre-configured and the first line is typed/written in the terminal before timeout_microsec micro-seconds, it will continue parsing until reaches an end-of-file character (CTRL-D after a new-line on the keyboard) with no time limit. If nothing is entered before timeout_microsec micro-seconds, it will return NULL.

All the functions that can read plain text tables will accept a filename as well as a list of strings (intended to be the output of this function for using Standard input). The reason for keeping the standard input is that once something is read from the standard input, it is hard to put it back. We often need to read a text file several times: once to count how many columns it has and which ones are requested, and another time to read the desired columns. So it easier to keep it all in allocated memory and pass it on from the start for each round.
void gal_txt_write (gal_data_t *cols, struct gal_fits_list_key_t **keylist, gal_list_str_t *comment, char *filename, uint8_t colinfoinstdout)

Write cols in a plain text file filename. cols may have one or two dimensions which determines the output:

1D cols is treated as a column and a list of datasets (see Section 10.3.8.9 [List of gal_data_t], page 423): every node in the list is written as one column in a table.

2D cols is a two dimensional array, it cannot be treated as a list (only one 2D array can currently be written to a text file). So if cols->next!=NULL the next nodes in the list are ignored and will not be written.

This is a low-level function for tables. It is recommended to use gal_table_write for generic writing of tables in a variety of formats, see Section 10.3.10 [Table input output (table.h)], page 426.

It is possible to add two types of metadata to the printed table: comments and keywords. Each string in the list given to comments will be printed into the file as a separate line, starting with #. Keywords have a more specific and computer-parsable format and are passed through keylist. Each keyword is also printed in one line, but with the format below. Because of the various components in a keyword, it is thus necessary to use the gal_fits_list_key_t data structure. For more, see Section 10.3.11.4 [FITS header keywords], page 432.

# [key] NAME: VALUE / [UNIT] KEYWORD COMMENT.

If filename already exists this function will abort with an error and will not write over the existing file. Before calling this function make sure if the file exists or not. If comments!=NULL, a # will be put at the start of each node of the list of strings and will be written in the file before the column meta-data in filename (see Section 10.3.8.1 [List of strings], page 413).

When filename==NULL, the column information will be printed on the standard output (command-line). When colinfoinstdout!=0 and filename==NULL (columns are printed in the standard output), the dataset metadata will also printed in the standard output. When printing to the standard output, the column information can be piped into another program for further processing and thus the meta-data (lines starting with a #) must be ignored. In such cases, you only print the column values by passing 0 to colinfoinstdout.

10.3.12.2 TIFF files (tiff.h)

Outside of astronomy, the TIFF standard is arguably the most commonly used format to store high-precision data/images. Unlike FITS however, the TIFF standard only supports images (not tables), but like FITS, it has support for all standard data types (see Section 4.6 [Numeric data types], page 130) which is the primary reason other fields use it.

Another similarity of the TIFF and FITS standards is that TIFF supports multiple images in one file. The TIFF standard calls each one of these images (and their accompanying meta-data) a 'directory' (roughly equivalent to the FITS extensions). Unlike FITS however, the directories can only be identified by their number (counting from zero), recall that in FITS you can also use the extension name to identify it.
The functions described here allow easy reading (and later writing) of TIFF files within Gnuastro or for users of Gnuastro's libraries. Currently only reading is supported, but if you are interested, please get in touch with us.

**Function**

```c
int gal_tiff_name_is_tiff (char *name)
```

Return 1 if `name` has a TIFF suffix. This can be used to make sure that a given input file is TIFF. See `gal_tiff_suffix_is_tiff` for a list of recognized suffixes.

**Function**

```c
int gal_tiff_suffix_is_tiff (char *name)
```

Return 1 if suffix is a recognized TIFF suffix. The recognized suffixes are `tif`, `tiff`, `TIFF` and `TIFF`.

**Function**

```c
size_t gal_tiff_dir_string_read (char *string)
```

Return the number within `string` as a `size_t` number to identify a TIFF directory. Note that the directories start counting from zero.

**Function**

```c
gal_data_t * gal_tiff_read (char *filename, size_t dir, size_t minmapsize, int quietmmap)
```

Read the `dir` directory within the TIFF file `filename` and return the contents of that TIFF directory as `gal_data_t`. If the directory's image contains multiple channels, the output will be a list (see Section 10.3.8.9 [List of `gal_data_t`], page 423).

### 10.3.12.3 JPEG files (jpeg.h)

The JPEG file format is one of the most common formats for storing and transferring images, recognized by almost all image rendering and processing programs. In particular, because of its lossy compression algorithm, JPEG files can have low volumes, making it used heavily on the internet. For more on this file format, and a comparison with others, please see Section 5.3.1 [Recognized file formats], page 162.

For scientific purposes, the lossy compression and very limited dynamic range (8-bit integers) make JPEG very unattractive for storing of valuable data. However, because of its commonality, it will inevitably be needed in some situations. The functions here can be used to read and write JPEG images into Gnuastro’s Section 10.3.6.1 [Generic data container (`gal_data_t`)], page 400. If the JPEG file has more than one color channel, each channel is treated as a separate node in a list of datasets (see Section 10.3.8.9 [List of `gal_data_t`], page 423).

**Function**

```c
int gal_jpeg_name_is_jpeg (char *name)
```

Return 1 if `name` has a JPEG suffix. This can be used to make sure that a given input file is JPEG. See `gal_jpeg_suffix_is_jpeg` for a list of recognized suffixes.

**Function**

```c
int gal_jpeg_suffix_is_jpeg (char *name)
```

Return 1 if suffix is a recognized JPEG suffix. The recognized suffixes are `jpg`, `.JPG`, `.jpeg`, `.JPEG`, `.jpe`, `.jif`, `.jfif` and `.jfi`.
gal_data_t * [Function]
gal_jpeg_read (char *filename, size_t minmapsize, int quietmmap)
   Read the JPEG file filename and return the contents as gal_data_t. If the directory’s image contains multiple colors/channels, the output will be a list with one node per color/channel (see Section 10.3.8.9 [List of gal_data_t], page 423).

void [Function]
gal_jpeg_write (gal_data_t *in, char *filename, uint8_t quality, float widthincm)
   Write the given dataset (in) into filename (a JPEG file). If in is a list, then each node in the list will be a color channel, therefore there can only be 1, 3 or 4 nodes in the list. If the number of nodes is different, then this function will abort the program with a message describing the cause. The lossy JPEG compression level can be set through quality which is a value between 0 and 100 (inclusive, 100 being the best quality). The display width of the JPEG file in units of centimeters (to suggest to viewers/users, only a meta-data) can be set through widthincm.

10.3.12.4 EPS files (eps.h)
The Encapsulated PostScript (EPS) format is commonly used to store images (or individual/single-page parts of a document) in the PostScript documents. For a more complete introduction, please see Section 5.3.1 [Recognized file formats], page 162. To provide high quality graphics, the Postscript language is a vectorized format, therefore pixels (elements of a “rasterized” format) aren’t defined in their context.

To display rasterized images, PostScript does allow arrays of pixels. However, since the over-all EPS file may contain many vectorized elements (for example borders, text, or other lines over the text) and interpreting them is not trivial or necessary within Gnuastro’s scope, Gnuastro only provides some functions to write a dataset (in the gal_data_t format, see Section 10.3.6.1 [Generic data container (gal_data_t)], page 400) into EPS.

int [Function]
gal_eps_name_is_eps (char *name)
   Return 1 if name has an EPS suffix. This can be used to make sure that a given input file is EPS. See gal_eps_suffix_is_eps for a list of recognized suffixes.

int [Function]
gal_eps_suffix_is_eps (char *name)
   Return 1 if suffix is a recognized EPS suffix. The recognized suffixes are .eps, .EPS, .epsf, .epsi.

void [Function]
gal_eps_to_pt (float widthincm, size_t *dsize, size_t *w_h_in_pt)
   Given a specific width in centimeters (widthincm and the number of the dataset’s pixels in each dimension (dsize) calculate the size of the output in PostScript points. The output values are written in the w_h_in_pt array (which has to be allocated before calling this function). The first element in w_h_in_pt is the width and the second is the height of the image.
void gal_eps_write (gal_data_t *in, char *filename, float widthincm, uint32_t borderwidth, int hex, int dontoptimize, int forpdf)

Write the in dataset into an EPS file called filename. in has to be an unsigned 8-bit character type (GAL_TYPE_UINT8, see Section 4.6 [Numeric data types], page 130). The desired width of the image in human/non-pixel units (to help the display) can be set with the widthincm argument. If borderwidth is non-zero, it is interpreted as the width (in points) of a solid black border around the image. A border can be helpful when importing the EPS file into a document.

EPS files are plain-text (can be opened/edited in a text editor), therefore there are different encodings to store the data (pixel values) within them. Gnuastro supports the Hexadecimal and ASCII85 encoding. ASCII85 is more efficient (producing small file sizes), so it is the default encoding. To use Hexadecimal encoding, set hex to a non-zero value. Currently If you don't directly want to import the EPS file into a PostScript document but want to later compile it into a PDF file, set the forpdf argument to 1.

By default, when the dataset only has two values, this function will use the PostScript optimization that allows setting the pixel values per bit, not byte (Section 5.3.1 [Recognized file formats], page 162). This can greatly help reduce the file size. However, when dontoptimize!=0, this optimization is disabled: even though there are only two values (is binary), the difference between them does not correspond to the full contrast of black and white.

10.3.12.5 PDF files (pdf.h)

The portable document format (PDF) has arguably become the most common format used for distribution of documents. In practice, a PDF file is just a compiled PostScript file. For a more complete introduction, please see Section 5.3.1 [Recognized file formats], page 162. To provide high quality graphics, the PDF is a vectorized format, therefore pixels (elements of a “rasterized” format) aren’t defined in their context. As a result, similar to Section 10.3.12.4 [EPS files (eps.h)], page 447, Gnuastro only writes datasets to a PDF file, not vice-versa.

int gal_pdf_name_is_pdf (char *name)

Return 1 if name has an PDF suffix. This can be used to make sure that a given input file is PDF. See gal_pdf_suffix_is_pdf for a list of recognized suffixes.

int gal_pdf_suffix_is_pdf (char *name)

Return 1 if suffix is a recognized PDF suffix. The recognized suffixes are .pdf and .PDF.

void gal_pdf_write (gal_data_t *in, char *filename, float widthincm, uint32_t borderwidth, int dontoptimize)

Write the in dataset into an EPS file called filename. in has to be an unsigned 8-bit character type (GAL_TYPE_UINT8, see Section 4.6 [Numeric data types], page 130). The desired width of the image in human/non-pixel units (to help the display) can
be set with the `widthincm` argument. If `borderwidth` is non-zero, it is interpreted as
the width (in points) of a solid black border around the image. A border can helpful
when importing the PDF file into a document.

This function is just a wrapper for the `gal_eps_write` function in Section 10.3.12.4
[EPS files (`eps.h`)], page 447. After making the EPS file, Ghostscript (with a version
of 9.10 or above, see Section 3.1.2 [Optional dependencies], page 77) will be used to
compile the EPS file to a PDF file. Therefore if GhostScript doesn’t exist, doesn’t
have the proper version, or fails for any other reason, the EPS file will remain. It can
be used to find the cause, or use another converter or PostScript compiler.

By default, when the dataset only has two values, this function will use the PostScript
optimization that allows setting the pixel values per bit, not byte (Section 5.3.1 [Rec-
ognized file formats], page 162). This can greatly help reduce the file size. However,
when `dontoptimize!=0`, this optimization is disabled: even though there are only
two values (is binary), the difference between them does not correspond to the full
contrast of black and white.

### 10.3.13 World Coordinate System (`wcs.h`)

The FITS standard defines the world coordinate system (WCS) as a mechanism to associate
physical values to positions within a dataset. For example, it can be used to convert pixel
coordinates in an image to celestial coordinates like the right ascension and declination.
The functions in this section are mainly just wrappers over CFITSIO, WCSLIB and GSL
library functions to help in common applications.

Gnuastro identifiers of the various WCS distortion conventions, for more, see Cal-
abretta et al. (2004, preprint)\(^\text{20}\). Among these, SIP is a prior distortion, the rest
other are sequent distortions. TPD is a superset of all these, hence it has both prior
and sequent distortion coefficients. More information is given in the documentation
of `dis.h`, from the WCSLIB manual\(^\text{21}\).

#### GAL_WCS_FLTERROR

Limit of rounding for floating point errors.

<table>
<thead>
<tr>
<th>Function</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>gal_wcs_read_fitsptr</code></td>
</tr>
</tbody>
</table>

\(\text{\textbf{Not thread-safe}}\) Return the WCSLIB `wcsprm` structure that is read from the CFIT-
SIO `fptr` pointer to an opened FITS file. Also put the number of coordinate rep-
resentations found into the space that `nwcs` points to. To read the WCS structure


directly from a filename, see `gal_wcs_read` below. After processing has finished, you can free the returned structure with WCSLIB's `wcsfree` keyword:

```c
status = wcsfree(&nwcs,&wcs);
```

If you don’t want to search the full FITS header for WCS-related FITS keywords (for example due to conflicting keywords), but only a specific range of the header keywords you can use the `hstartwcs` and `hendwcs` arguments to specify the keyword number range (counting from zero). If `hendwcs` is larger than `hstartwcs`, then only keywords in the given range will be checked. Hence, to ignore this feature (and search the full FITS header), give both these arguments the same value.

If the WCS information couldn’t be read from the FITS file, this function will return a `NULL` pointer and put a zero in `nwcs`. A WCSLIB error message will also be printed in `stderr` if there was an error.

This function is just a wrapper over WCSLIB’s `wcspih` function which is not thread-safe. Therefore, be sure to not call this function simultaneously (over multiple threads).

```c
struct wcsprm *
gal_wcs_read (char *filename, char *hdu, size_t hstartwcs, size_t hendwcs, int *nwcs)
```

[Not thread-safe] Return the WCSLIB structure that is read from the HDU/extension `hdu` of the file `filename`. Also put the number of coordinate representations found into the space that `nwcs` points to. Please see `gal_wcs_read_fitsptr` for more.

```c
char *
gal_wcs_dimension_name (struct wcsprm *wcs, size_t dimension)
```

Return an allocated string array (that should be freed later) containing the first part of the `CTYPEi` FITS keyword (which contains the dimension name in the FITS standard). For example if `CTYPE1` is `RA---TAN`, the string that function returns will be `RA`. Recall that the second component of `CTYPEi` contains the type of projection.

```c
void
gal_wcs_write (struct wcsprm *wcs, char *filename, char *extname, 
gal.fits_list_key_t *headers, char *program_string)
```

Write the given WCS structure into the second extension of an empty FITS header. The first/primary extension will be empty like the default format of all Gnuastro outputs. When `extname`!=`NULL` it will be used as the FITS extension name. Any set of extra headers can also be written through the `headers` list and if `program_string`!=`NULL` it will be used in a commented keyword title just above the written version information.

```c
void
gal_wcs_write_in_fitsptr(fitsfile *fptr, struct wcsprm *wcs)
```

Convert the input `wcs` structure (keeping the WCS programmatically) into FITS keywords and write them into the given FITS file pointer. This is a relatively low-level function which assumes the FITS file has already been opened with CFITSIO. If you just want to write the WCS into an empty file, you can use `gal_wcs_write` (which internally calls this function after creating the FITS file and later closes it safely).
struct wcsprm *
gal_wcs_copy (struct wcsprm *wcs)
    Return a fully allocated (independent) copy of wcs.

void
gal_wcs_remove_dimension (struct wcsprm *wcs, size_t fitsdim)
    Remove the given FITS dimension from the given wcs structure.

void
gal_wcs_on_tile (gal_data_t *tile)
    Create a WCSLIB wcsprm structure for tile using WCS parameters of the tile’s allocated block dataset, see Section 10.3.15 [Tessellation library (tile.h)], page 460, for the definition of tiles. If tile already has a WCS structure, this function won’t do anything.

    In many cases, tiles are created for internal/low-level processing. Hence for performance reasons, when creating the tiles they don’t have any WCS structure. When needed, this function can be used to add a WCS structure to each tile tile by copying the WCS structure of its block and correcting the reference point’s coordinates within the tile.

double *
gal_wcs_warp_matrix (struct wcsprm *wcs)
    Return the Warping matrix of the given WCS structure as an array of double precision floating points. This will be the final matrix, irrespective of the type of storage in the WCS structure. Recall that the FITS standard has several methods to store the matrix. The output is an allocated square matrix with each side equal to the number of dimensions.

void
gal_wcs_clean_small_errors (struct wcsprm *wcs)
    Errors can make small differences between the pixel-scale elements (CDELT) and can also lead to extremely small values in the PC matrix. With this function, such errors will be “cleaned” as follows: 1) if the maximum difference between the CDELT elements is smaller than the reference error, it will be set to the mean value. When the FITS keyword CRDER (optional) is defined it will be used as a reference, if not the default value is GAL_WCS_FLTERROR. 2) If any of the PC elements differ from 0, 1 or -1 by less than GAL_WCS_FLTERROR, they will be rounded to the respective value.

void
gal_wcs_decompose_pc_cdel (struct wcsprm *wcs)
    Decompose the PCI_j and CDELTj elements of wcs. According to the FITS standard, in the PCI_j WCS formalism, the rotation matrix elements \( m_{ij} \) are encoded in the PCI_j keywords and the scale factors are encoded in the CDELTj keywords. There is also another formalism (the CDi_j formalism) which merges the two into one matrix. However, WCSLIB’s internal operations are apparently done in the PCI_j formalism. So its outputs are also all in that format by default. When the input is a CDi_j, WCSLIB will still read the matrix directly into the PCI_j matrix and the CDELTj values are set to 1 (one). This function is designed to correct such issues: after it is
finished, the CDELTi values in wcs will correspond to the pixel scale, and the PCI_\text{j} will correction show the rotation.

**Function**

```c
int gal_wcs_distortion_from_string (char *distortion)
```

Convert the given string (assumed to be a FITS-standard, string-based distortion identifier) to a Gnuastro's integer-based distortion identifier (one of the GAL_WCS_DISTORTION_* macros defined above). The sting-based distortion identifiers have three characters and are all in capital letters.

**Function**

```c
int gal_wcs_distortion_to_string (int distortion)
```

Convert the given Gnuastro integer-based distortion identifier (one of the GAL_WCS_DISTORTION_* macros defined above) to the string-based distortion identifier) of the FITS standard. The sting-based distortion identifiers have three characters and are all in capital letters.

**Function**

```c
int gal_wcs_distortion_identify (struct wcsprm *wcs)
```

Returns the Gnuastro identifier for the distortion of the input WCS structure. The returned value is one of the GAL_WCS_DISTORTION_* macros defined above. When the input pointer to a structure is NULL, or it doesn’t contain a distortion, the returned value will be GAL_WCS_DISTORTION_INVALID.

**Function**

```c
struct wcsprm * gal_wcs_distortion_convert(struct wcsprm *inwcs, int outdisptype, size_t *fitsize)
```

Return a newly allocated WCS structure, where the distortion is implemented in a different standard, identified by the identifier outdisptype. The Gnuastro WCS distortion identifiers are defined in the GAL_WCS_DISTORTION_* macros mentioned above.

The available conversions in this function will grow. Currently it only supports converting TPV to SIP and vice versa, following the recipe of Shupe et al. (2012)\(^2\). Please get in touch with us if you need other types of conversions.

For some conversions, direct analytical conversions don’t exist. It is thus necessary to model and fit the two types. In such cases, it is also necessary to specify the fitsize array that is the size of the array along each C-ordered dimension, so you can simply pass the dsize element of your gal_data_t dataset, see Section 10.3.6.1 [Generic data container (gal_data_t)], page 400. Currently this is only necessary when converting TPV to SIP. For other conversions you may simply pass a NULL pointer.

For example, if you want to convert the TPV coefficients of your input image.fits to SIP coefficients, you can use the following functions (which are also available as a command-line operation in Section 5.1 [Fits], page 146).

```c
int nwcs;

gal_data_t *data=gal_fits_img_read("image.fits", "1", -1, 1);
```

inwcs=gal_wcs_read("image.fits", "1", 0, &nwcs);
data->wcs=gal_wcs_distortion_convert(inwcs, GAL_WCS_DISTORTION_TPV, NULL);
wcsfree(inwcs);
gal_fits_img_write(data, "tpv.fits", NULL, NULL);

double

gal_wcs_angular_distance_deg (double r1, double d1, double r2, double d2)
Return the angular distance (in degrees) between a point located at (r1, d1) to (r2, d2). All input coordinates are in degrees. The distance (along a great circle) on a sphere between two points is calculated with the equation below.

$$\cos(d) = \sin(d_1) \sin(d_2) + \cos(d_1) \cos(d_2) \cos(r_1 - r_2)$$

However, since the pixel scales are usually very small numbers, this function won’t use that direct formula. It will be use the Haversine formula (https://en.wikipedia.org/wiki/Haversine_formula) which is better considering floating point errors:

$$\frac{\sin^2(d)}{2} = \sin^2 \left( \frac{d_1 - d_2}{2} \right) + \cos(d_1) \cos(d_2) \sin^2 \left( \frac{r_1 - r_2}{2} \right)$$

double *

gal_wcs_pixel_scale (struct wcsprm *wcs)
Return the pixel scale for each dimension of wcs in degrees. The output is an allocated array of double precision floating point type with one element for each dimension. If its not successful, this function will return NULL.

double

gal_wcs_pixel_area_arcsec2 (struct wcsprm *wcs)
Return the pixel area of wcs in arcsecond squared. If the input WCS structure is not two dimensional and the units (CUNIT keywords) are not deg (for degrees), then this function will return NaN.

int

gal_wcs_coverage (char *filename, char *hdu, size_t *ondim, double **ocenter, double ***owidth, double ***omin, double ***omax)
Find the sky coverage of the image HDU (hdu) within filename. The the number of dimensions is written into ndim, and space for the various output arrays is internally allocated and filled with the respective values.

gal_data_t *

gal_wcs_world_to_img (gal_data_t *coords, struct wcsprm *wcs, int inplace)
Convert the linked list of world coordinates in coords to a linked list of image coordinates given the input WCS structure. coords must be a linked list of data structures of float64 (‘double’) type, see Section 10.3.8 [Linked lists (list.h)], page 411, and Section 10.3.8.9 [List of gal_data_t], page 423. The top (first popped/read) node
of the linked list must be the first WCS coordinate (RA in an image usually) etc. Similarly, the top node of the output will be the first image coordinate (in the FITS standard).

If inplace is zero, then the output will be a newly allocated list and the input list will be untouched. However, if inplace is non-zero, the output values will be written into the input’s already allocated array and the returned pointer will be the same pointer to coords (in other words, you can ignore the returned value). Note that in the latter case, only the values will be changed, things like units or name (if present) will be untouched.

```c
[Function]
gal_data_t *
gal_wcs_img_to_world (gal_data_t *coords, struct wcsprm *wcs, int inplace)
```

Convert the linked list of image coordinates in coords to a linked list of world coordinates given the input WCS structure. See the description of `gal_wcs_world_to_img` for more details.

### 10.3.14 Arithmetic on datasets (arithmetic.h)

When the dataset’s type and other information are already known, any programming language (including C) provides some very good tools for various operations (including arithmetic operations like addition) on the dataset with a simple loop. However, as an author of a program, making assumptions about the type of data, its dimensions and other basic characteristics will come with a large processing burden.

For example if you always read your data as double precision floating points for a simple operation like addition with an integer constant, you will be wasting a lot of CPU and memory when the input dataset is `int32` type for example (see Section 4.6 [Numeric data types], page 130). This overhead may be small for small images, but as you scale your process up and work with hundred/thousands of files that can be very large, this overhead will take a significant portion of the processing power. The functions and macros in this section are designed precisely for this purpose: to allow you to do any of the defined operations on any dataset with no overhead (in the native type of the dataset).

Gnuastro’s Arithmetic program uses the functions and macros of this section, so please also have a look at the Section 6.2 [Arithmetic], page 199, program and in particular Section 6.2.2 [Arithmetic operators], page 200, for a better description of the operators discussed here.

The main function of this library is `gal_arithmetic` that is described below. It can take an arbitrary number of arguments as operands (depending on the operator, similar to printf). Its first two arguments are integers specifying the flags and operator. So first we will review the constants for the recognized flags and operators and discuss them, then introduce the actual function.

```c
GAL_ARITHMETIC_INPLACE [Macro]
GAL_ARITHMETIC_FREE [Macro]
GAL_ARITHMETIC_NUMOK [Macro]
GAL_ARITHMETIC_FLAGS_ALL [Macro]
```

Bit-wise flags to pass onto `gal_arithmetic` (see below). To pass multiple flags, use the bitwise-or operator, for example `GAL_ARITHMETIC_INPLACE | GAL_ARITHMETIC_
FREE. **GAL_ARITHMETIC_FLAGS_ALL** is a combination of all flags to shorten your code if you want all flags activated. Each flag is described below:

**GAL_ARITHMETIC_INPLACE**

Do the operation in-place (in the input dataset, thus modifying it) to improve CPU and memory usage. If this flag is used, after **gal_arithmetic** finishes, the input dataset will be modified. It is thus useful if you have no more need for the input after the operation.

**GAL_ARITHMETIC_FREE**

Free (all the) input dataset(s) after the operation is done. Hence the inputs are no longer usable after **gal_arithmetic**.

**GAL_ARITHMETIC_NUMOK**

It is acceptable to use a number and an array together. For example if you want to add all the pixels in an image with a single number you can pass this flag to avoid having to allocate a constant array the size of the image (with all the pixels having the same number).

**GAL_ARITHMETIC_OP_PLUS**  [Macro]

**GAL_ARITHMETIC_OP_MINUS**  [Macro]

**GAL_ARITHMETIC_OP_MULTIPLY**  [Macro]

**GAL_ARITHMETIC_OP_DIVIDE**  [Macro]

**GAL_ARITHMETIC_OP_LT**  [Macro]

**GAL_ARITHMETIC_OP_LE**  [Macro]

**GAL_ARITHMETIC_OP_GT**  [Macro]

**GAL_ARITHMETIC_OP_GE**  [Macro]

**GAL_ARITHMETIC_OP_EQ**  [Macro]

**GAL_ARITHMETIC_OP_NE**  [Macro]

**GAL_ARITHMETIC_OP_AND**  [Macro]

**GAL_ARITHMETIC_OP_OR**  [Macro]

Binary operators (requiring two operands) that accept datasets of any recognized type (see Section 4.6 [Numeric data types], page 130). When **gal_arithmetic** is called with any of these operators, it expects two datasets as arguments. For a full description of these operators with the same name, see Section 6.2.2 [Arithmetic operators], page 200. The first dataset/operand will be put on the left of the operator and the second will be put on the right. The output type of the first four is determined from the input types (largest type of the inputs). The rest (which are all conditional operators) will output a binary **uint8_t** (or **unsigned char**) dataset with values of either 0 (zero) or 1 (one).

**GAL_ARITHMETIC_OP_NOT**  [Macro]

The logical NOT operator. When **gal_arithmetic** is called with this operator, it only expects one operand (dataset), since this is a unary operator. The output is **uint8_t** (or **unsigned char**) dataset of the same size as the input. Any non-zero element in the input will be 0 (zero) in the output and any 0 (zero) will have a value of 1 (one).
**GAL_ARITHMETIC_OP_ISBLANK**  
A unary operator with output that is 1 for any element in the input that is blank, and 0 for any non-blank element. When *gal_arithmetic* is called with this operator, it will only expect one input dataset. The output dataset will have *uint8_t* (or *unsigned char*) type.

*gal_arithmetic* with this operator is just a wrapper for the *gal_blank_flag* function of Section 10.3.5 [Library blank values (*blank.h*), page 396, and this operator is just included for completeness in arithmetic operations. So in your program, it might be easier to just call *gal_blank_flag*.

**GAL_ARITHMETIC_OP_WHERE**  
The three-operand *where* operator thoroughly discussed in Section 6.2.2 [Arithmetic operators], page 200. When *gal_arithmetic* is called with this operator, it will only expect three input datasets: the first (which is the same as the returned dataset) is the array that will be modified. The second is the condition dataset (that must have a *uint8_t* or *unsigned char*) type, and the third is the value to be used if condition is non-zero.

As a result, note that the order of operands when calling *gal_arithmetic* with **GAL_ARITHMETIC_OP_WHERE** is the opposite of running Gnuastro’s Arithmetic program with the *where* operator (see Section 6.2 [Arithmetic], page 199). This is because the latter uses the reverse-Polish notation which isn’t necessary when calling a function (see Section 6.2.1 [Reverse polish notation], page 199).

**GAL_ARITHMETIC_OP_SQRT**  
**GAL_ARITHMETIC_OP_LOG**  
**GAL_ARITHMETIC_OP_LOG10**  
Unary operator functions for calculating the square root (\(\sqrt{i}\)), \(ln(i)\) and \(log(i)\) mathematical operators on each element of the input dataset. The returned dataset will have a floating point type, but its precision is determined from the input: if the input is a 64-bit floating point, the output will also be 64-bit. Otherwise, the returned dataset will be 32-bit floating point. See Section 4.6 [Numeric data types], page 130, for the respective precision.

If you want your output to be 64-bit floating point but your input is a different type, you can convert the input to a floating point type with *gal_data_copy_to_new_type* or *gal_data_copy_to_new_type_free* (see Section 10.3.6.4 [Copying datasets], page 407).

**GAL_ARITHMETIC_OP_RA_TO_DEGREE**  
**GAL_ARITHMETIC_OP_DEC_TO_DEGREE**  
**GAL_ARITHMETIC_OP_DEGREE_TO_RA**  
**GAL_ARITHMETIC_OP_DEGREE_TO_DEC**  
Unary operators to convert between degrees (as a single floating point number) to the sexagesimal Right Ascension and Declination format (as strings, respectively in the format of \(h_m_s\) and \(d_m_s\)). The first two operators expect a string operand (in the sexagesimal formats mentioned above, but also in the \(_:\_:_\_) and will return a double-precision floating point operand. The latter two are the opposite.
 Unary operand statistical operators that will return a single value for datasets of any size. These are just wrappers around similar functions in Section 10.3.22 [Statistical operations (statistics.h)], page 482, and are included in gal_arithmetic only for completeness (to use easily in Section 6.2 [Arithmetic], page 199). In your programs, it will probably be easier if you use those gal_statistics functions directly.

 Unary operand absolute-value operator.

 Multi-operand statistical operations. When gal_arithmetic is called with any of these operators, it will expect only a single operand that will be interpreted as a list of datasets (see Section 10.3.8.9 [List of gal_data_t], page 423). These operators can work on multiple threads using the numthreads argument. See the discussion under the min operator in Section 6.2.2 [Arithmetic operators], page 200.

 The output will be a single dataset with each of its elements replaced by the respective statistical operation on the whole list. The type of the output is determined from the operator (irrespective of the input type): for GAL_ARITHMETIC_OP_MIN and GAL_ARITHMETIC_OP_MAX, it will be the same type as the input, for GAL_ARITHMETIC_OP_NUMBER, the output will be GAL_TYPE_UINT32 and for the rest, it will be GAL_TYPE_FLOAT32.

 Similar to the operands above (including GAL_ARITHMETIC_MIN), except that when gal_arithmetic is called with these operators, it requires two arguments. The first is the list of datasets like before, and the second is the 1-element dataset with the quantile value. The output type is the same as the inputs.

 Similar to the operands above (including GAL_ARITHMETIC_MIN), except that when gal_arithmetic is called with these operators, it requires two arguments. The first is the list of datasets like before, and the second is the 2-element list of $\sigma$-clipping
parameters. The first element in the parameters list is the multiple of sigma and the second is the termination criteria (see Section 7.1.3 [Sigma clipping], page 251). The output type of \texttt{GAL\_ARITHMETIC\_OP\_SIGCLIP\_NUMBER} will be \texttt{GAL\_TYPE\_UINT32} and for the rest it will be \texttt{GAL\_TYPE\_FLOAT32}.

\texttt{GAL\_ARITHMETIC\_OP\_SIZE} \quad \text{[Macro]}\newline
Size operator that will return a single value for datasets of any kind. When \texttt{gal\_arithmetic} is called with this operator, it requires two arguments. The first is the dataset, and the second is a single integer value. The output type is a single integer.

\texttt{GAL\_ARITHMETIC\_OP\_POW} \quad \text{[Macro]}\newline
Binary operator to-power operator. When \texttt{gal\_arithmetic} is called with any of these operators, it will expect two operands: raising the first by the second (returning a floating point, inputs can be integers).

\texttt{GAL\_ARITHMETIC\_OP\_BITAND} \quad \text{[Macro]}\newline
\texttt{GAL\_ARITHMETIC\_OP\_BITOR} \quad \text{[Macro]}\newline
\texttt{GAL\_ARITHMETIC\_OP\_BITXOR} \quad \text{[Macro]}\newline
\texttt{GAL\_ARITHMETIC\_OP\_BITLSH} \quad \text{[Macro]}\newline
\texttt{GAL\_ARITHMETIC\_OP\_BITRSH} \quad \text{[Macro]}\newline
\texttt{GAL\_ARITHMETIC\_OP\_MODULO} \quad \text{[Macro]}\newline
Binary integer-only operand operators. These operators are only defined on integer data types. When \texttt{gal\_arithmetic} is called with any of these operators, it will expect two operands: the first is put on the left of the operator and the second on the right. The ones starting with \texttt{BIT} are the respective bit-wise operators in C and \texttt{MODULO} is the modulo/remainder operator. For a discussion on these operators, please see Section 6.2.2 [Arithmetic operators], page 200.

The output type is determined from the input types and C's internal conversions: it is strongly recommended that both inputs have the same type (any integer type), otherwise the bit-wise behavior will be determined by your compiler.

\texttt{GAL\_ARITHMETIC\_OP\_BITNOT} \quad \text{[Macro]}\newline
The unary bit-wise NOT operator. When \texttt{gal\_arithmetic} is called with any of these operators, it will expect one operand of an integer type and perform the bitwise-NOT operation on it. The output will have the same type as the input.

\texttt{GAL\_ARITHMETIC\_OP\_TO\_UINT8} \quad \text{[Macro]}\newline
\texttt{GAL\_ARITHMETIC\_OP\_TO\_INT8} \quad \text{[Macro]}\newline
\texttt{GAL\_ARITHMETIC\_OP\_TO\_UINT16} \quad \text{[Macro]}\newline
\texttt{GAL\_ARITHMETIC\_OP\_TO\_INT16} \quad \text{[Macro]}\newline
\texttt{GAL\_ARITHMETIC\_OP\_TO\_UINT32} \quad \text{[Macro]}\newline
\texttt{GAL\_ARITHMETIC\_OP\_TO\_INT32} \quad \text{[Macro]}\newline
\texttt{GAL\_ARITHMETIC\_OP\_TO\_UINT64} \quad \text{[Macro]}\newline
\texttt{GAL\_ARITHMETIC\_OP\_TO\_INT64} \quad \text{[Macro]}\newline
\texttt{GAL\_ARITHMETIC\_OP\_TO\_FLOAT32} \quad \text{[Macro]}\newline
\texttt{GAL\_ARITHMETIC\_OP\_TO\_FLOAT64} \quad \text{[Macro]}\newline
Unary type-conversion operators. When \texttt{gal\_arithmetic} is called with any of these operators, it will expect one operand and convert it to the requested
type. Note that with these operators, `gal_arithmetic` is just a wrapper over the `gal_data_copy_to_new_type` or `gal_data_copy_to_new_type_free` that are discussed in Copying datasets. It accepts these operators only for completeness and easy usage in Section 6.2 [Arithmetic], page 199. So in your programs, it might be preferable to directly use those functions.

`GAL_ARITHMETIC_OP_MAKENEW`

Create a new, zero-valued dataset with an unsigned 8-bit data type. The length along each dimension of the dataset should be given as a single list of `gal_data_t`s. The number of dimensions is derived from the number of nodes in the list and the length along each dimension is the single-valued element within that list. Just note that the list should be in the reverse of the desired dimensions.

`gal_data_t *`  
`gal_arithmetic (int operator, size_t numthreads, int flags, ...)`

Do the arithmetic operation of `operator` on the given operands (the third argument and any further argument). If the operator can work on multiple threads, the number of threads can be specified with `numthreads`. When the operator is single-threaded, `numthreads` will be ignored. Special conditions can also be specified with the `flag` operator (a bit-flag with bits described above, for example `GAL_ARITHMETIC_INPLACE` or `GAL_ARITHMETIC_FREE`). The acceptable values for `operator` are also defined in the macros above.

`gal_arithmetic` is a multi-argument function (like C’s `printf`). In other words, the number of necessary arguments is not fixed and depends on the value to `operator`. Here are a few examples showing this variability:

```c
out_1=gal_arithmetic(GAL_ARITHMETIC_OP_LOG, 1, 0, in_1);
out_2=gal_arithmetic(GAL_ARITHMETIC_OP_PLUS, 1, 0, in_1, in_2);
out_3=gal_arithmetic(GAL_ARITHMETIC_OP_WHERE, 1, 0, in_1, in_2, in_3);
```

The number of necessary operands for each operator (and thus the number of necessary arguments to `gal_arithmetic`) are described above under each operator.

`int`

`gal_arithmetic_set_operator (char *string, size_t *num_operands)`

Return the operator macro/code that corresponds to `string`. The number of operands that it needs are written into the space that `*num_operands` points to. If the string couldn’t be interpreted as an operator, this function will return `GAL_ARITHMETIC_OP_INVALID`.

This function will check `string` with the fixed human-readable names (using `strcmp`) for the operators and return the two numbers. Note that `string` must only contain the single operator name and nothing else (not even any extra white space).

`char *`

`gal_arithmetic_operator_string (int operator)`

Return the human-readable standard string that corresponds to the given operator. For example when the input is `GAL_ARITHMETIC_OP_PLUS` or `GAL_ARITHMETIC_OP_MEAN`, the strings `+` or `mean` will be returned.
10.3.15 Tessellation library (tile.h)

In many contexts, it is desirable to slice the dataset into subsets or tiles (overlapping or not). In such a way that you can work on each tile independently. One method would be to copy that region to a separate allocated space, but in many contexts this isn’t necessary and in fact can be a big burden on CPU/Memory usage. The block pointer in Gnuastro’s Section 10.3.6.1 [Generic data container (gal_data_t)], page 400, is defined for such situations: where allocation is not necessary. You just want to read the data or write to it independently (or in coordination with) other regions of the dataset. Added with parallel processing, this can greatly improve the time/memory consumption.

See the figure below for example: assume the larger dataset is a contiguous block of memory that you are interpreting as a 2D array. But you only want to work on the smaller tile region.

```
+-----------------------------|
|                             |
| tile                        |
| ____________________________|
| |                           |
| |_                          |
| |*|                          |
+-----------------------------|
```

To use gal_data_t’s block concept, you allocate a gal_data_t *tile which is initialized with the pointer to the first element in the sub-array (as its array argument). Note that this is not necessarily the first element in the larger array. You can set the size of the tile along with the initialization as you please. Recall that, when given a non-NULL pointer as array, gal_data_initialize (and thus gal_data_alloc) do not allocate any space and just uses the given pointer for the new array element of the gal_data_t. So your tile data structure will not be pointing to a separately allocated space.

After the allocation is done, you just point tile->block to the larger dataset which hosts the full block of memory. Where relevant, Gnuastro’s library functions will check the block pointer of their input dataset to see how to deal with dimensions and increments so they can always remain within the tile. The tools introduced in this section are designed to help in defining and working with tiles that are created in this manner.

Since the block structure is defined as a pointer, arbitrary levels of tessellation/grid-ing are possible (tile->block may itself be a tile in an even larger allocated space). Therefore, just like a linked-list (see Section 10.3.8 [Linked lists (list.h)], page 411), it is important to have the block pointer of the largest (allocated) dataset set to NULL. Normally, you won’t have to worry about this, because gal_data_initialize (and thus gal_data_alloc) will set the block element to NULL by default, just remember not to change it. You can then only change the block element for the tiles you define over the allocated space.
Below, we will first review constructs for Section 10.3.15.1 [Independent tiles], page 461, and then define the current approach to fully tessellating a dataset (or covering every pixel/data-element with a non-overlapping tile grid in Section 10.3.15.2 [Tile grid], page 466. This approach to dealing with parts of a larger block was inspired from a similarly named concept in the GNU Scientific Library (GSL), see its “Vectors and Matrices” chapter for their implementation.

### 10.3.15.1 Independent tiles

The most general application of tiles is to treat each independently, for example they may overlap, or they may not cover the full image. This section provides functions to help in checking/inspecting such tiles. In Section 10.3.15.2 [Tile grid], page 466, we will discuss functions that define/work-with a tile grid (where the tiles don’t overlap and fully cover the input dataset). Therefore, the functions in this section are general and can be used for the tiles produced by that section also.

```c
void gal_tile_start_coord (gal_data_t *tile, size_t *start_coord)
Calculate the starting coordinates of a tile in its allocated block of memory and
write them in the memory that start_coord points to (which must have tile->ndim
elements).

void gal_tile_start_end_coord (gal_data_t *tile, size_t *start_end, int rel_block)
Put the starting and ending (end point is not inclusive) coordinates of tile into
the start_end array. It is assumed that a space of 2*tile->ndim has been already
allocated (static or dynamic) for start_end before this function is called.

rel_block (or relative-to-block) is only relevant when tile has an intermediate tile
between it and the allocated space (like a channel, see gal_tile_full_two_layers).
If it doesn’t (tile->block points the allocated dataset), then the value to rel_block
is irrelevant.

When tile->block is its self a larger block and rel_block is set to 0, then the
starting and ending positions will be based on the position within tile->block, not
the allocated space.

void * gal_tile_start_end_ind_inclusive (gal_data_t *tile, gal_data_t *work, size_t
*start_end_inc)
Put the indexs of the first/start and last/end pixels (inclusive) in a tile into the
start_end array (that must have two elements). NOTE: this function stores the
index of each point, not its coordinates. It will then return the pointer to the start of
the tile in the work data structure (which doesn’t have to be equal to tile->block.

The outputs of this function are defined to make it easy to parse over an n-dimensional
tile. For example, this function is one of the most important parts of the internal pro-
cessing of in GAL_TILE_PARSE_OPERATE function-like macro that is described below.
gal_data_t *
gal_tile_series_from_minmax (gal_data_t *block, size_t *minmax, size_t number)

Construct a list of tile(s) given coordinates of the minimum and maximum of each tile.
The minimum and maximums are assumed to be inclusive and in C order (slowest
dimension first). The returned pointer is an allocated gal_data_t array that can
later be freed with gal_data_array_free (see Section 10.3.6.3 [Arrays of datasets],
page 406). Internally, each element of the output array points to the next element,
so the output may also be treated as a list of datasets (see Section 10.3.8.9 [List of
gal_data_t], page 423) and passed onto the other functions described in this section.

The array keeping the minimum and maximum coordinates for each tile must have
the following format. So in total minmax must have 2*ndim*number elements.

| min0_d0 | min0_d1 | max0_d0 | max0_d1 | ... |
|         | ...     |         |         |     |
|         | minN_d0 | minN_d1 | maxN_d0 | maxN_d1 |

gal_data_t *
gal_tile_block (gal_data_t *tile)

Return the dataset that contains tile's allocated block of memory. If tile is immedi-
ately defined as part of the allocated block, then this is equivalent to tile->block.
However, it is possible to have multiple layers of tiles (where tile->block is itself a
tile). So this function is the most generic way to get to the actual allocated dataset.

size_t

gal_tile_block_increment (gal_data_t *block, size_t *tsize, size_t num_increment, size_t *coord)

Return the increment necessary to start at the next contiguous patch memory associ-
ated with a tile. block is the allocated block of memory and tsize is the size of the
tile along every dimension. If coord is NULL, it is ignored. Otherwise, it will contain
the coordinate of the start of the next contiguous patch of memory.

This function is intended to be used in a loop and num_increment is the main variable
to this function. For the first time you call this function, it should be 1. In subsequent
calls (while you are parsing a tile), it should be increased by one.

gal_data_t *
gal_tile_block_write_const_value (gal_data_t *tilevalues, gal_data_t *tilesll, int withblank, int initialize)

Write a constant value for each tile over the area it covers in an allocated dataset
that is the size of tile's allocated block of memory (found through gal_tile_block
described above). The arguments to this function are:

tilevalues

This must be an array that has the same number of elements as the nodes in in tilesll and in the same order that 'tilesll' elements are parsed (from
top to bottom, see Section 10.3.8 [Linked lists (list.h)], page 411). As a result the array's number of dimensions is irrelevant, it will be parsed
contiguously.
tilesll The list of input tiles (see Section 10.3.8.9 [List of gal_data_t], page 423). Internally, it might be stored as an array (for example the output of `gal_tile_series_from_minmax` described above), but this function doesn’t care, it will parse the next elements to go to the next tile. This function will not pop-from or free the tilesll, it will only parse it from start to end.

withblank

If the block containing the tiles has blank elements, those blank elements will be blank in the output of this function also, hence the array will be initialized with blank values when this option is called (see below).

initialize

Initialize the allocated space with blank values before writing in the constant values. This can be useful when the tiles don’t cover the full allocated block.

gal_data_t * [Function]
gal_tile_block_check_tiles (gal_data_t *tilesll)

Make a copy of the memory block and fill it with the index of each tile in tilesll (counting from 0). The non-filled areas will have blank values. The output dataset will have a type of GAL_TYPE_INT32 (see Section 10.3.3 [Library data types (type.h)], page 390).

This function can be used when you want to check the coverage of each tile over the allocated block of memory. It is just a wrapper over the `gal_tile_block_write_const_value` (with `withblank` set to zero).

void * [Function]
gal_tile_block_relative_to_other (gal_data_t *tile, gal_data_t *other)

Return the pointer corresponding to the start of the region covered by `tile` over the `other` dataset. See the examples in GAL_TILE_PARSE_OPERATE for some example applications of this function.

void [Function]
gal_tile_block_blank_flag (gal_data_t *tilell, size_t numthreads)

Check if each tile in the list has blank values and update its flag to mark this check and its result (see Section 10.3.6.1 [Generic data container (gal_data_t)], page 400). The operation will be done on `numthreads` threads.

GAL_TILE_PARSE_OPERATE (IN, OTHER, PARSE_OTHER, CHECK_BLANK, OP) [Function-like macro]

Parse IN (which can be a tile or a fully allocated block of memory) and do the OP operation on it. OP can be any combination of C expressions. If OTHER!=NULL, OTHER will be interpreted as a dataset and this macro will allow access to its element(s) and it can optionally be parsed while parsing over IN.

If OTHER is a fully allocated block of memory (not a tile), then the same region that is covered by IN within its own block will be parsed (the same starting pixel with the same number of pixels in each dimension). Hence, in this case, the blocks of OTHER and IN must have the same size. When OTHER is a tile it must have the same size as IN.
and parsing will start from its starting element/pixel. Also, the respective allocated blocks of OTHER and IN (if different) may have different sizes. Using OTHER (along with PARSE_OTHER), this function-like macro will thus enable you to parse and define your own operation on two fixed size regions in one or two blocks of memory. In the latter case, they may have different numeric data types, see Section 4.6 [Numeric data types], page 130).

The input arguments to this macro are explained below, the expected type of each argument are also written following the argument name:

IN (gal_data_t)
Input dataset, this can be a tile or an allocated block of memory.

OTHER (gal_data_t)
Dataset (gal_data_t) to parse along with IN. It can be NULL. In that case, o (see description of OP below) will be NULL and should not be used.
If PARSE_OTHER is zero, only its first element will be used and the size of this dataset is irrelevant.
When OTHER is a block of memory, it has to have the same size as the allocated block of IN. When its a tile, it has to have the same size as IN.

PARSE_OTHER (int)
Parse the other dataset along with the input. When this is non-zero and OTHER!=NULL, then the o pointer will be incremented to cover the OTHER tile at the same rate as i, see description of OP for i and o.

CHECK_BLANK (int)
If it is non-zero, then the input will be checked for blank values and OP will only be called when we are not on a blank element.

OP
Operator: this can be any number of C expressions. This macro is going to define a itype *i variable which will increment over each element of the input array/tile. itype will be replaced with the C type that corresponds to the type of INPUT. As an example, if INPUT's type is GAL_DATA_UINT16 or GAL_DATA_FLOAT32, i will be defined as uint16 or float respectively.
This function-like macro will also define an otype *o which you can use to access an element of the OTHER dataset (if OTHER!=NULL). o will correspond to the type of OTHER (similar to itype and INPUT discussed above).
If PARSE_OTHER is non-zero, then o will also be incremented to the same index element but in the other array. You can use these along with any other variable you define before this macro to process the input and/or the other.

All variables within this function-like macro begin with tpo_, except for the three variables listed below. Therefore, as long as you don’t start the names of your variables with this prefix everything will be fine. Note that i (and possibly o) will be incremented once by this function-like macro, so don’t increment them within OP.

i
Pointer to the element of INPUT that is being parsed with the proper type.
o Pointer to the element of OTHER that is being parsed with the proper type. o can only be used if OTHER!=NULL and it will be parsed/incremented if PARSE_OTHER is non-zero.

b Blank value in the type of INPUT.

You can use a given tile (tile on a dataset that it was not initialized with but has the same size, let’s call it new) with the following steps:

```c
void *tarray;
gal_data_t *tblock;

/* ‘tile->block’ must be corrected AFTER ‘tile->array’. */
tarray = tile->array;
tblock = tile->block;
tile->array = gal_tile_block_relative_to_other(tile, new);
tile->block = new;

/* Parse and operate over this region of the ‘new’ dataset. */
GAL_TILE.Parse_OPERATE(tile, NULL, 0, 0, {
    YOUR_PROCESSING;
});

/* Reset ‘tile->block’ and ‘tile->array’. */
tile->array=tarray;
tile->block=tblock;
```

You can work on the same region of another block in one run of this function-like macro. To do that, you can make a fake tile and pass that as the OTHER argument. Below is a demonstration, tile is the actual tile that you start with and new is the other block of allocated memory.

```c
size_t zero=0;
gal_data_t *faketile;

/* Allocate the fake tile, these can be done outside a loop */
* (over many tiles). */
faketile=gal_data_alloc(NULL, new->type, 1, &zero,
    NULL, 0, -1, 1, NULL, NULL, NULL);
free(faketile->array); /* To keep things clean. */
free(faketile->dsize); /* To keep things clean. */
faketile->block = new;
faketile->ndim = new->ndim;

/* These can be done in a loop (over many tiles). */
faketile->size = tile->size;
faketile->dsize = tile->dsize;
faketile->array = gal_tile_block_relative_to_other(tile, new);

/* Do your processing.... in a loop (over many tiles). */
```
GAL_TILE_PARSE_OPERATE(tile, faketile, 1, 1, {
    YOUR_PROCESSING_EXPRESSIONS;
});

/ * Clean up (outside the loop). */
faketile->array=NULL;
faketile->dszsize=NULL;
gal_data_free(faketile);

10.3.15.2 Tile grid

One very useful application of tiles is to completely cover an input dataset with tiles. Such
that you know every pixel/data-element of the input image is covered by only one tile. The
constructs in this section allow easy definition of such a tile structure. They will create lists
of tiles that are also usable by the general tools discussed in Section 10.3.15.1 [Independent
tiles], page 461.

As discussed in Section 4.9 [Tessellation], page 141, (mainly raw) astronomical images
will mostly require two layers of tessellation, one for amplifier channels which all have the
same size and another (smaller tile-size) tessellation over each channel. Hence, in this section
we define a general structure to keep the main parameters of this two-layer tessellation and
help in benefiting from it.

gal_tile_two_layer_params

[Type (C struct)]
The general structure to keep all the necessary parameters for a two-layer tessellation.

struct gal_tile_two_layer_params
{
    /* Inputs */
    size_t *tilesize; /**<-----------------------------*/
    size_t *numchannels; /* These parameters have to be */
    float remainderfrac; /* filled manually before */
    uint8_t workoverch; /* calling the functions in */
    uint8_t checktiles; /* this section. */
    uint8_t oneelempertile; /**<-----------------------------*/

    /* Internal parameters. */
    size_t ndim;
    size_t tottiles;
    size_t tottilesinch;
    size_t totchannels;
    size_t *channelsize;
    size_t *numtiles;
    size_t *numtilesinch;
    char *tilecheckname;
    size_t *permutation;
    size_t *firsttsize;

    /* Tile and channel arrays (which are also lists). */
gal_data_t *tiles;
gal_data_t *channels;
};

size_t *  

gal_tile_full (gal_data_t *input, size_t *regular, float remainderfrac,
   gal_data_t **out, size_t multiple, size_t **firsttsize)

Cover the full dataset with (mostly) identical tiles and return the number of tiles created along each dimension. The regular tile size (along each dimension) is determined from the regular array. If input's size is not an exact multiple of regular for each dimension, then the tiles touching the edges in that dimension will have a different size to fully cover every element of the input (depending on remainderfrac).

The output is an array with the same dimensions as input which contains the number of tiles along each dimension. See Section 4.9 [Tessellation], page 141, for a description of its application in Gnuastro’s programs and remainderfrac, just note that this function defines only one layer of tiles.

This is a low-level function (independent of the gal_tile_two_layer_params structure defined above). If you want a two-layer tessellation, directly call gal_tile_full_two_layers that is described below. The input arguments to this function are:

input The main dataset (allocated block) which you want to create a tessellation over (only used for its sizes). So input may be a tile also.

regular The the size of the regular tiles along each of the input’s dimensions. So it must have the same number of elements as the dimensions of input (or input->ndim).

remainderfrac The significant fraction of the remainder space to see if it should be split into two and put on both sides of a dimension or not. This is thus only relevant input length along a dimension isn’t an exact multiple of the regular tile size along that dimension. See Section 4.9 [Tessellation], page 141, for a more thorough discussion.

out Pointer to the array of data structures that will keep all the tiles (see Section 10.3.6.3 [Arrays of datasets], page 406). If *out==NULL, then the necessary space to keep all the tiles will be allocated. If not, then all the tile information will be filled from the dataset that *out points to, see multiple for more.

multiple When *out==NULL (and thus will be allocated by this function), allocate space for multiple times the number of tiles needed. This can be very useful when you have several more identically sized inputs, and you want all their tiles to be allocated (and thus indexed) together, even though they have different block datasets (that then link to one allocated space).

See the definition of channels in Section 4.9 [Tessellation], page 141, and gal_tile_full_two_layers below.

firsttsize The size of the first tile along every dimension. This is only different from the regular tile size when regular is not an exact multiple of input’s
length along every dimension. This array is allocated internally by this function.

```c
void [Function]
gal_tile_full_sanity_check (char *filename, char *hdu, gal_data_t *input,
                         struct gal_tile_two_layer_params *tl)
Make sure that the input parameters (in tl, short for two-layer) correspond to the input dataset. filename and hdu are only required for error messages. Also, allocate and fill the tl->channelsize array.
```

```c
void [Function]
gal_tile_full_two_layers (gal_data_t *input, struct gal_tile_two_layer_params *
                         tl)
Create the two layered tessellation in tl. The general set of steps you need to take to define the two-layered tessellation over an image can be seen in the example code below.

gal_data_t *input;
struct gal_tile_two_layer_params tl;
char *filename="input.fits", *hdu="1";

/* Set all the inputs shown in the structure definition. */
...

/* Read the input dataset. */
input=gal_fits_img_read(filename, hdu, -1, 1);

/* Do a sanity check and preparations. */
gal_tile_full_sanity_check(filename, hdu, input, &tl);

/* Build the two-layer tessellation*/
gal_tile_full_two_layers(input, &tl);
/* ‘tl.tiles’ and ‘tl.channels’ are now a lists of tiles.*/
```

```c
void [Function]
gal_tile_full_permutation (struct gal_tile_two_layer_params *tl)
Make a permutation to allow the conversion of tile location in memory to its location in the full input dataset and put it in tl->permutation. If a permutation has already been defined for the tessellation, this function will not do anything. If permutation won’t be necessary (there is only one channel or one dimension), then this function will not do anything (tl->permutation must have been initialized to NULL).

When there is only one channel OR one dimension, the tiles are allocated in memory in the same order that they represent the input data. However, to make channel-independent processing possible in a generic way, the tiles of each channel are allocated contiguously. So, when there is more than one channel AND more than one dimension, the index of the tile does not correspond to its position in the grid covering the input dataset.
```
The example below may help clarify: assume you have a 6x6 tessellation with two channels in the horizontal and one in the vertical. On the left you can see how the tile IDs correspond to the input dataset. NOTE how ‘03’ is on the second row, not on the first after ‘02’. On the right, you can see how the tiles are stored in memory (and shown if you simply write the array into a FITS file for example).

<table>
<thead>
<tr>
<th>Corresponding to input</th>
<th>In memory</th>
</tr>
</thead>
<tbody>
<tr>
<td>15 16 17 33 34 35</td>
<td>30 31 32 33 34 35</td>
</tr>
<tr>
<td>12 13 14 30 31 32</td>
<td>24 25 26 27 28 29</td>
</tr>
<tr>
<td>09 10 11 27 28 29</td>
<td>18 19 20 21 22 23</td>
</tr>
<tr>
<td>06 07 08 24 25 26</td>
<td>&lt;--</td>
</tr>
<tr>
<td>03 04 05 21 22 23</td>
<td>06 07 08 09 10 11</td>
</tr>
<tr>
<td>00 01 02 18 19 20</td>
<td>00 01 02 03 04 05</td>
</tr>
</tbody>
</table>

As a result, if your values are stored in same order as the tiles, and you want them in over-all memory (for example to save as a FITS file), you need to permute the values:

```c
gal_permutation_apply(values, tl->permutation);
```

If you have values over-all and you want them in tile-order, you can apply the inverse permutation:

```c
gal_permutation_apply_inverse(values, tl->permutation);
```

Recall that this is the definition of permutation in this context:

- permute: \( IN\_ALL[ i ] = IN\_MEMORY[ \text{perm}[i] ] \)
- inverse: \( IN\_ALL[ \text{perm}[i] ] = IN\_MEMORY[ i ] \)

```c
void [Function]
gal_tile_full_values_write (gal_data_t *tilevalues, struct
gal_tile_two_layer_params *tl, int withblank, char *filename,
galfits_list_key_t *keys, char *program_string)
```

Write one value for each tile into a file. It is important to note that the values in `tilevalues` must be ordered in the same manner as the tiles, so `tilevalues->array[i]` is the value that should be given to `tl->tiles[i]`. The `tl->permutation` array must have been initialized before calling this function with `gal_tile_full_permutation`.

If `withblank` is non-zero, then block structure of the tiles will be checked and all blank pixels in the block will be blank in the final output file also.

```c
gal_data_t *
gal_tile_full_values_smooth (gal_data_t *tilevalues, struct
gal_tile_two_layer_params *tl, size_t width, size_t numthreads)
```

Smooth the given values with a flat kernel of the given width. This cannot be done manually because if `tl->workoverch==0`, tiles in different channels must not be mixed/smoothed. Also the tiles are contiguous within the channel, not within the image, see the description under `gal_tile_full_permutation`.

```c
void [Function]
gal_permutation_apply(values, tl->permutation);
```
size_t  

`gal_tile_full_id_from_coord (struct gal_tile_two_layer_params *tl, size_t *coord)`

Return the ID of the tile that corresponds to the coordinates `coord`. Having this ID, you can use the `tl->tiles` array to get to the proper tile or read/write a value into an array that has one value per tile.

void  

`gal_tile_full_free_contents (struct gal_tile_two_layer_params *tl)`

Free all the allocated arrays within `tl`.

10.3.16 Bounding box (box.h)

Functions related to reporting the bounding box of certain inputs are declared in `gnuastro/box.h`. All coordinates in this header are in the FITS format (first axis is the horizontal and the second axis is vertical).

void  

`gal_box_bound_ellipse_extent (double a, double b, double theta_deg, double *extent)`

Return the maximum extent along each dimension of the given ellipse from the center of the ellipse. Therefore this is half the extent of the box in each dimension. `a` is the ellipse semi-major axis, `b` is the semi-minor axis, `theta_deg` is the position angle in degrees. The extent in each dimension is in floating point format and stored in `extent` which must already be allocated before this function.

void  

`gal_box_bound_ellipse (double a, double b, double theta_deg, long *width)`

Any ellipse can be enclosed into a rectangular box. This function will write the height and width of that box where `width` points to. It assumes the center of the ellipse is located within the central pixel of the box. `a` is the ellipse semi-major axis length, `b` is the semi-minor axis, `theta_deg` is the position angle in degrees. The `width` array will contain the output size in long integer type. `width[0]`, and `width[1]` are the number of pixels along the first and second FITS axis. Since the ellipse center is assumed to be in the center of the box, all the values in `width` will be an odd integer.

void  

`gal_box_bound_ellipsoid_extent (double *semiaxes, double *euler_deg, double *extent)`

Return the maximum extent along each dimension of the given ellipsoid from its center. Therefore this is half the extent of the box in each dimension. The semi-axis lengths of the ellipsoid must be present in the 3 element `semiaxis` array. The `euler_deg` array contains the three ellipsoid Euler angles in degrees. For a description of the Euler angles, see description of `gal_box_bound_ellipsoid` below. The extent in each dimension is in floating point format and stored in `extent` which must already be allocated before this function.
void [Function]
gal_box_bound_ellipsoid (double *semiaxes, double *euler_deg, long *width)

Any ellipsoid can be enclosed into a rectangular volume/box. The purpose of this function is to give the integer size/width of that box. The semi-axes lengths of the ellipse must be in the semiaxes array (with three elements). The major axis length must be the first element of semiaxes. The only other condition is that the next two semi-axes must both be smaller than the first. The orientation of the major axis is defined through three proper Euler angles (ZXZ order in degrees) that are given in the euler_deg array. The width array will contain the output size in long integer type (in FITS axis order). Since the ellipsoid center is assumed to be in the center of the box, all the values in width will be an odd integer.

The proper Euler angles can be defined in many ways (which axes to rotate about). For a full description of the Euler angles, please see Wikipedia (https://en.wikipedia.org/wiki/Euler_angles). Here we adopt the ZXZ (or $Z_1X_2Z_3$) proper Euler angles were the first rotation is done around the Z axis, the second one about the (rotated) X axis and the third about the (rotated) Z axis.

void [Function]
gal_box_border_from_center (double center, size_t ndim, long *width, long *fpixel, long *lpixel)

Given the center coordinates in center and the width (along each dimension) of a box, return the coordinates of the first (fpixel) and last (lpixel) pixels. All arrays must have ndim elements (one for each dimension).

int [Function]
gal_box_overlap (long *naxes, long *fpixel_i, long *lpixel_i, long *fpixel_o, long *lpixel_o, size_t ndim)

An ndim-dimensional dataset of size naxes (along each dimension, in FITS order) and a box with first and last (inclusive) coordinate of fpixel_i and lpixel_i is given. This box doesn’t necessarily have to lie within the dataset, it can be outside of it, or only partially overlap. This function will change the values of fpixel_i and lpixel_i to exactly cover the overlap in the input dataset’s coordinates.

This function will return 1 if there is an overlap and 0 if there isn’t. When there is an overlap, the coordinates of the first and last pixels of the overlap will be put in fpixel_o and lpixel_o.

10.3.17 Polygons (polygon.h)

Polygons are commonly necessary in image processing. For example in Crop they are used for cutting out non-rectangular regions of an image (see Section 6.1 [Crop], page 188), and in Warp, for mapping different pixel grids over each other (see Section 6.4 [Warp], page 238).

Polygons come in two classes: convex and concave (or generally, non-convex!), see below for a demonstration. Convex polygons are those where all inner angles are less than 180 degrees. By contrast, a convex polygon is one where an inner angle may be more than 180 degrees.

**Concave Polygon**

**Convex Polygon**
In all the functions here the vertices (and points) are defined as an array. So a polygon with 4 vertices will be identified with an array of 8 elements with the first two elements keeping the 2D coordinates of the first vertex and so on.

**GAL_POLYGON_MAX_CORNERS**

The largest number of vertices a polygon can have in this library.

**GAL_POLYGON_ROUND_ERR**

We have to consider floating point round-off errors when dealing with polygons. For example we will take $A$ as the maximum of $A$ and $B$ when $A>B-GAL_POLYGON_ROUND_ERR$.

**void gal_polygon_vertices_sort_convex (double *in, size_t n, size_t *ordinds)**

We have a simple polygon (that can result from projection, so its edges don’t collide or it doesn’t have holes) and we want to order its corners in an anticlockwise fashion. This is necessary for clipping it and finding its area later. The input vertices can have practically any order.

The input (**in**) is an array containing the coordinates (two values) of each vertex. **n** is the number of corners. So **in** should have $2*n$ elements. The output (**ordinds**) is an array with **n** elements specifying the indexes in order. This array must have been allocated before calling this function. The indexes are output for more generic usage, for example in a homographic transform (necessary in warping an image, see Section 6.4.1 [Warping basics], page 239), the necessary order of vertices is the same for all the pixels. In other words, only the positions of the vertices change, not the way they need to be ordered. Therefore, this function would only be necessary once.

As a summary, the input is unchanged, only **n** values will be put in the **ordinds** array. Such that calling the input coordinates in the following fashion will give an anti-clockwise order when there are 4 vertices:

1st vertex: in[ordinds[0]*2], in[ordinds[0]*2+1]
2nd vertex: in[ordinds[1]*2], in[ordinds[1]*2+1]
3rd vertex: in[ordinds[2]*2], in[ordinds[2]*2+1]
4th vertex: in[ordinds[3]*2], in[ordinds[3]*2+1]

The implementation of this is very similar to the Graham scan in finding the Convex Hull. However, in projection we will never have a concave polygon (the left condition below, where this algorithm will get to E before D), we will always have a convex polygon (right case) or E won’t exist! This is because we are always going to be calculating the area of the overlap between a quadrilateral and the pixel grid or the quadrilateral itself.

The **GAL_POLYGON_MAX_CORNERS** macro is defined so there will be no need to allocate these temporary arrays separately. Since we are dealing with pixels, the polygon can’t really have too many vertices.
Chapter 10: Library

**int**  
**gal_polygon_is_convex** (*double *v*, *size_t n*)  
Returns 1 if the polygon is convex with vertices defined by v and 0 if it is a concave polygon. Note that the vertices of the polygon should be sorted in an anti-clockwise manner.

**double**  
**gal_polygon_area** (*double *v*, *size_t n*)  
Find the area of a polygon with vertices defined in v. v points to an array of doubles which keep the positions of the vertices such that v[0] and v[1] are the positions of the first vertex to be considered.

**int**  
**gal_polygon_is_inside** (*double *v*, *double *p*, *size_t n*)  
Returns 0 if point p in inside a polygon, either convex or concave. The vertices of the polygon are defined by v and 0 otherwise, they have to be ordered in an anti-clockwise manner. This function uses the winding number algorithm ([https://en.wikipedia.org/wiki/Point_in_polygon#Winding_number_algorithm](https://en.wikipedia.org/wiki/Point_in_polygon#Winding_number_algorithm)), to check the points. Note that this is a generic function (working on both concave and convex polygons, so if you know before-hand that your polygon is convex, it is much more efficient to use **gal_polygon_is_inside_convex**.

**int**  
**gal_polygon_is_inside_convex** (*double *v*, *double *p*, *size_t n*)  
Return 1 if the point p is within the polygon whose vertices are defined by v. The polygon is assumed to be convex, for a more generic function that deals with concave and convex polygons, see **gal_polygon_is_inside**. Note that the vertices of the polygon have to be sorted in an anti-clock-wise manner.

**int**  
**gal_polygon_ppropin** (*double *v*, *double *p*, *size_t n*)  
Similar to **gal_polygon_is_inside_convex**, except that if the point p is on one of the edges of a polygon, this will return 0.

**int**  
**gal_polygon_is_counterclockwise** (*double *v*, *size_t n*)  
Returns 1 if the sorted polygon has a counter-clockwise orientation and 0 otherwise. This function uses the concept of “winding”, which defines the relative order in which the vertices of a polygon are listed to determine the orientation of vertices. For complex polygons (where edges, or sides, intersect), the most significant orientation is returned. In a complex polygon, when the alternative windings are equal (for example an 8-shape) it will return 1 (as if it was counter-clockwise). Note that the polygon vertices have to be sorted before calling this function.

**int**  
**gal_polygon_to_counterclockwise** (*double *v*, *size_t n*)  
Arrange the vertices of the sorted polygon in place, to be in a counter-clockwise direction. If the input polygon already has a counter-clockwise direction it won’t touch the input. The return value is 1 on successful execution. This function is just a
wrapper over `gal_polygon_is_counterclockwise`, and will reverse the order of the vertices when necessary necessary.

```c
void gal_polygon_clip (double *s, size_t n, double *c, size_t m, double *o, size_t *numcrn)
```

Clip (find the overlap of) two polygons. This function uses the Sutherland-Hodgman (https://en.wikipedia.org/wiki/Sutherland%E2%80%93Hodgman_algorithm) polygon clipping algorithm. Note that the vertices of both polygons have to be sorted in an anti-clock-wise manner.

```c
void gal_polygon_vertices_sort (double *vertices, size_t n, size_t *ordinds)
```

Sort the indexs of the un-ordered `vertices` array to a counter-clockwise polygon in the already allocated space of `ordinds`. It is assumed that there are `n` vertices, and thus that `vertices` contains `2*n` elements where the two coordinates of the first vertice occupy the first two elements of the array and so on.

The polygon can be both concave and convex (see the start of this section). However, note that for concave polygons there is no unique sort from an un-ordered set of vertices. So after this function you may want to use `gal_polygon_is_convex` and print a warning to check the output if the polygon was concave.

Note that the contents of the `vertices` array are left untouched by this function. If you want to write the ordered vertice coordinates in another array with the same size, you can use a loop like this:

```c
for(i=0;i<n;++i)
{
    ordered[i*2 ] = vertices[ ordinds[i]*2  ];
    ordered[i*2+1] = vertices[ ordinds[i]*2 + 1];
}
```

In this algorithm, we find the rightmost and leftmost points (based on their x-coordinate) and use the diagonal vector between those points to group the points in arrays based on their position with respect to this vector. For anticlockwise sorting, all the points below the vector are sorted by their ascending x-coordinates and points above the vector are sorted in decreasing order using `qsort`. Finally, both these arrays are merged together to get the final sorted array of points, from which the points are indexed into the `ordinds` using linear search.

### 10.3.18 Qsort functions (qsort.h)

When sorting a dataset is necessary, the C programming language provides the `qsort` (Quick sort) function. `qsort` is a generic function which allows you to sort any kind of data structure (not just a single array of numbers). To define “greater” and “smaller” (for sorting), `qsort` needs another function, even for simple numerical types. The functions introduced in this section are to passed onto `qsort`.

Note that larger and smaller operators are not defined on NaN elements. Therefore, if the input array is a floating point type, and contains NaN values, the relevant functions of this section are going to put the NaN elements at the end of the list (after the sorted non-NaN elements), irrespective of the requested sorting order (increasing or decreasing).
The first class of functions below (with TYPE in their names) can be used for sorting a simple numeric array. Just replace TYPE with the dataset’s numeric datatype. The second set of functions can be used to sort indexes (leave the actual numbers untouched). To use the second set of functions, a global variable or structure are also necessary as described below.

**gal_qsort_index_single**  
[Global variable]  
Pointer to an array (for example float * or int *) to use as a reference in gal_qsort_index_single_TYPE_d or gal_qsort_index_single_TYPE_i, see the explanation of these functions for more. Note that if more than one array is to be sorted in a multi-threaded operation, these functions will not work as expected. However, when all the threads just sort the indexes based on a single array, this global variable can safely be used in a multi-threaded scenario.

**gal_qsort_index_multi**  
[Type (C struct)]  
Structure to get the sorted indexes of multiple datasets on multiple threads with gal_qsort_index_multi_d or gal_qsort_index_multi_i. Note that the values array will not be changed by these functions, it is only read. Therefore all the values elements in the (to be sorted) array of gal_qsort_index_multi must point to the same place.

```c
struct gal_qsort_index_multi
{
    float *values; /* Array of values (same in all). */
    size_t index; /* Index of each element to be sorted. */
};
```

**int gal_qsort_TYPE_d (const void *a, const void *b)**  
When passed to qsort, this function will sort a TYPE array in decreasing order (first element will be the largest). Please replace TYPE (in the function name) with one of the Section 4.6 [Numeric data types], page 130, for example gal_qsort_int32_d, or gal_qsort_float64_d.

**int gal_qsort_TYPE_i (const void *a, const void *b)**  
When passed to qsort, this function will sort a TYPE array in increasing order (first element will be the smallest). Please replace TYPE (in the function name) with one of the Section 4.6 [Numeric data types], page 130, for example gal_qsort_int32_i, or gal_qsort_float64_i.

**int gal_qsort_index_single_TYPE_d (const void *a, const void *b)**  
When passed to qsort, this function will sort a size_t array based on decreasing values in the gal_qsort_index_single. The global gal_qsort_index_single pointer has a void * pointer which will be cast to the proper type based on this function: for example gal_qsort_index_single_uint16_d will cast the array to an unsigned 16-bit integer type. The array that gal_qsort_index_single points to will not be changed, it is only read. For example, see this demo program:

```c
#include <stdio.h>
```
Chapter 10: Library

```c
#include <stdlib.h> /* qsort is defined in stdlib.h. */
#include <gnuastro/qsort.h>

int main (void)
{
    size_t s[4]={0, 1, 2, 3};
    float f[4]={1.3,0.2,1.8,0.1};
    gal_qsort_index_single=f;
    qsort(s, 4, sizeof(size_t), gal_qsort_index_single_float_d);
    printf("%zu, %zu, %zu, %zu\n", s[0], s[1], s[2], s[3]);
    return EXIT_SUCCESS;
}
```

The output will be: 2, 0, 1, 3.

```c
int gal_qsort_index_single_TYPE_i (const void *a, const void *b)
    Similar to gal_qsort_index_single_TYPE_d, but will sort the indexes such that the
values of gal_qsort_index_single can be parsed in increasing order.
```

```c
int gal_qsort_index_multi_d (const void *a, const void *b)
    When passed to qsort with an array of gal_qsort_index_multi, this function will
sort the array based on the values of the given indexes. The sorting will be ordered
according to the values pointer of gal_qsort_index_multi. Note that values must
point to the same place in all the structures of the gal_qsort_index_multi array.
This function is only useful when the indexes of multiple arrays on multiple threads
are to be sorted. If your program is single threaded, or all the indexes belong to a
single array (sorting different sub-sets of indexes in a single array on multiple threads),
it is recommended to use gal_qsort_index_single_d.
```

```c
int gal_qsort_index_multi_i (const void *a, const void *b)
    Similar to gal_qsort_index_multi_d, but the result will be sorted in increasing
order (first element will have the smallest value).
```

10.3.19 K-d tree (kdtree.h)

K-d tree is a space-partitioning binary search tree for organizing points in a k-dimensional
space. They are a very useful data structure for multidimensional searches like range
searches and nearest neighbor searches. For a more formal and complete introduction see

Each non-leaf node in a k-d tree divides the space into two parts, known as half-spaces.
To select the top/root node for partitioning, we find the median of the points and make a
hyperplane normal to the first dimension. The points to the left of this space are represented
by the left subtree of that node and points to the right of the space are represented by the
right subtree. This is then repeated for all the points in the input, thus associating a “left”
and “right” branch for each input point.
Gnuastro uses the standard algorithms of the k-d tree with one small difference that makes it much more memory and CPU optimized. The set of input points that define the tree nodes are given as a list of Gnuastro’s data container type, see Section 10.3.8.9 [List of gal_data_t], page 423. Each gal_data_t in the list represents the point’s coordinate in one dimension, and the first element in the list is the first dimension. Hence the number of data values in each gal_data_t (which must be equal in all of them) represents the number of points. This is the same format that Gnuastro’s Table reading/writing functions read/write columns in tables, see Section 10.3.10 [Table input output (table.h)], page 426.

The output k-d tree is a list of two gal_data_ts, representing the input’s row-number (or index, counting from 0) of the left and right subtrees of each row. Each gal_data_t thus has the same number of rows (or points) as the input, but only containing integers with a type of uint32_t (unsigned 32-bit integer). If a node has no left, or right subtree, then GAL_BLANK_UINT32 will be used. Below you can see the simple tree for 2D points from Wikipedia. The input point coordinates are represented as two input gal_data_ts (X and Y, where X->next=Y and Y->next=NULL). If you had three dimensional points, you could define an extra gal_data_t such that Y->next=Z and Z->next=NULL. The output is always a list of two gal_data_ts, where the first one contains the index of the left sub-tree in the input, and the second one, the index of the right subtree. The index of the root node (2 in the case below) is also returned as a single number.

<table>
<thead>
<tr>
<th>INDEX (as guide)</th>
<th>INPUT</th>
<th>OUTPUT</th>
<th>K-D Tree (visualized)</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>5</td>
<td>1</td>
<td>(7,2)</td>
</tr>
<tr>
<td>1</td>
<td>2</td>
<td>BLANK</td>
<td>\</td>
</tr>
<tr>
<td>2</td>
<td>7</td>
<td>0</td>
<td>3</td>
</tr>
<tr>
<td>3</td>
<td>9</td>
<td>5</td>
<td>BLANK</td>
</tr>
<tr>
<td>4</td>
<td>4</td>
<td>BLANK</td>
<td>(2,3)</td>
</tr>
<tr>
<td>5</td>
<td>8</td>
<td>BLANK</td>
<td>(8,1)</td>
</tr>
</tbody>
</table>

This format is therefore scalable to any number of dimensions: the number of dimensions are determined from the number of nodes in the input list of gal_data_ts (for example, using gal_list_data_number). In Gnuastro’s k-d tree implementation, there are thus no special structures to keep every tree node (which would take extra memory and would need to be moved around as the tree is being created). Everything is done internally on the index of each point in the input dataset: the only thing that is flipped/sorted during tree creation is the index to the input row for any number of dimensions. As a result, Gnuastro’s k-d tree implementation is very memory and CPU efficient and its two output columns can directly be written into a standard table (without having to define any special binary format).

```c
#include <stdio.h>

gal_data_t *
gal_kdtree_create (gal_data_t *coords_raw, size_t *root)

Create a k-d tree in a bottom-up manner (from leaves to the root). This function returns two gal_data_ts connected as a list, see description above. The first dataset contains the indexes of left and right nodes of the subtrees for each input node. The index of the root node is written into the memory that root points to. coords_raw is the list of the input points (one gal_data_t per dimension, see above).

#include <stdio.h>
```
#include <gnuastro/table.h>
#include <gnuastro/kdtree.h>

int
main (void)
{
size_t root;
gal_data_t *input, *kdtree;
char kdtreefile[]="kd-tree.txt"; /* Inputs and outputs can */
char inputfile[]="coordinates.txt"; /* also be FITS tables. */

/* Read the input table. Note: this assumes the table only */
* contains your input point coordinates (one column for each
* dimension). If it contains more columns with other properties
* for each point, you can specify which columns to read by
* name or number, see the documentation of 'gal_table_read'. */
input=gal_table_read(inputfile, "1", NULL, NULL,
GAL_TABLE_SEARCH_NAME, 0, -1, 0, NULL);

/* Construct a k-d tree. The index of root is stored in 'root' */
kdtree=gal_kdtree_create(coords_raw, &root);

/* Write output to a file. */
gal_table_write(kdtree, NULL, GAL_TABLE_FORMAT_BFITS,
        kdtreefile, "kdtree", 0);

/* Report k-d tree root. */
printf("Root row of '%s': %zu\n", kdtreefile, root);

/* Clean up and return. */
gal_list_data_free(input);
gal_list_data_free(kdtree);
return EXIT_SUCCESS;
}

size_t
[Function]
gal_kdtree_nearest_neighbour (gal_data_t *coords_raw, gal_data_t *kdtree,
size_t root, double *point, double *least_dist)
Returns the index of the nearest input point to the query point (point, assumed to
be an array with same number of elements as gal_data_ts in coords_raw). The
distance between the query point and its nearest neighbor is stored in the space that
least_dist points to. This search is efficient due to the constantly checking for the
presence of possible best points in other branches. If it isn’t possible for the other
branch to have a better nearest neighbor, that branch is not searched.
For example the function below reads the input, and the k-d tree file created in the
example of gal_kdtree_create (so you won’t have to re-create the k-d tree every
time) and finds the input point that is closest to a given query point.
#include <stdio.h>
#include <gnuastro/table.h>
#include <gnuastro/kdtree.h>

int
main (void)
{
size_t root=KDTREE_ROOT;
gal_data_t *input, *kdtree;
char kdtreefile[]="kd-tree.txt"; /* Inputs and outputs can */
char inputfile[]="coordinates.txt"; /* also be FITS tables. */

double point[2]={9,8}; /* assuming a 2-d tree. */
size_t nearest_index;

/* Read the input coordinates, see comments in example of
 * 'gal_kdtree_create' for more. */
input=gal_table_read(inputfile, "1", NULL, NULL,
GAL_TABLE_SEARCH_NAME, 0, -1, 0, NULL);

/* Read the k-d tree (created before). */
kdtree=gal_table_read(kdtreefile, "1", NULL, NULL,
GAL_TABLE_SEARCH_NAME, 0, -1, 0, NULL);

/* Find the nearest neighbour of the point. */
nearest_index=gal_kdtree_nearest_neighbour(input, kdtree, root,
point);

/* Clean up and return. */
gal_list_data_free(input);
gal_list_data_free(kdtree);
return EXIT_SUCCESS;
}

10.3.20 Permutations (permutation.h)

Permutation is the technical name for re-ordering of values. The need for permutations occurs a lot during (mainly low-level) processing. To do permutation, you must provide two inputs: an array of values (that you want to re-order in place) and a permutation array which contains the new index of each element (let’s call it perm). The diagram below shows the input array before and after the re-ordering.

\[
\text{permute: } \text{AFTER}[ i ] = \text{BEFORE}[ \text{perm}[i] ] \quad i = 0 \ldots N-1
\]
\[
\text{inverse: } \text{AFTER}[ \text{perm}[i] ] = \text{BEFORE}[ i ] \quad i = 0 \ldots N-1
\]

The functions here are a re-implementation of the GNU Scientific Library’s \texttt{gsl_permute} function. The reason we didn’t use that function was that it uses system-specific types (like \texttt{long} and \texttt{int}) which can have different widths on different systems, hence are not easily convertible to Gnuastro’s fixed width types (see Section 4.6 \textit{[Numeric data types]}, page 130).
There is also a separate function for each type, heavily using macros to allow a base function to work on all the types. Thus it is hard to read/understand. Hence, Gnuastro contains a re-write of their steps in a new type-agnostic method which is a single function that can work on any type.

As described in GSL’s source code and manual, this implementation comes from Donald Knuth’s Art of computer programming book, in the “Sorting and Searching” chapter of Volume 3 (3rd ed). Exercise 10 of Section 5.2 defines the problem and in the answers, Knuth describes the solution. So if you are interested, please have a look there for more.

We are in contact with the GSL developers and in the future we will submit these implementations to GSL. If they are finally incorporated there, we will delete this section in future versions.

```c
void gal_permutation_check (size_t *permutation, size_t size)
    Print how permutation will re-order an array that has size elements for each element in one one line.

void gal_permutation_apply (gal_data_t *input, size_t *permutation)
    Apply permutation on the input dataset (can have any type), see above for the definition of permutation.

void gal_permutation_apply_inverse (gal_data_t *input, size_t *permutation)
    Apply the inverse of permutation on the input dataset (can have any type), see above for the definition of permutation.
```

### 10.3.21 Matching (match.h)

Matching is often necessary when the measurements have been done using different instruments, different software or different configurations of the same software. The functions in this part of Gnuastro’s library will be growing to allow matching of images and finding a match between different catalogs (register them). Currently it only provides the The high-level measurements are stored in tables with positions (commonly in RA and Dec with units of degrees).

```c
void gal_match_coordinates (gal_data_t *coord1, gal_data_t *coord2, double *aperture, int sorted_by_first, int inplace, size_t minmapsize, int quietmmap, size_t *nummatched)
    Return the permutations that when applied, the first nummatched rows of both inputs match with each other (are the nearest within the given aperture). The two inputs (coord1 and coord2) must be Section 10.3.8.9 [List of gal_data_t], page 423. Each gal_data_t node in the list should be a single dimensional dataset (column in a table). The dimensions of the coordinates is determined by the number of gal_data_t nodes in the two input lists (which must be equal). Note that the number of rows
```

---

23 Gnuastro’s Task 14497 ([http://savannah.gnu.org/task/?14497](http://savannah.gnu.org/task/?14497)). If this task is still “postponed” when you are reading this and you are interested to help, your help would be very welcome. Both Gnuastro and GSL developers are very busy, hence both would appreciate your help.
(or the number of elements in each `gal_data_t`) in the columns of `coord1` and `coord2` can be different.

The matching aperture is defined by the `aperture` array. If several points of one catalog lie within this aperture of a point in the other, the nearest is defined as the match. In a 2D situation (where the input lists have two nodes), for the most generic case, it must have three elements: the major axis length, axis ratio and position angle (see Section 8.1.1.1 [Defining an ellipse and ellipsoid], page 332). If `aperture[1]==1`, the aperture will be a circle of radius `aperture[0]` and the third value won’t be used. When the aperture is an ellipse, distances between the points are also calculated in the respective elliptical distances (`rel` in Section 8.1.1.1 [Defining an ellipse and ellipsoid], page 332).

To speed up the search, this function will sort the input coordinates by their first column (first axis). If both are already sorted by their first column, you can avoid the sorting step by giving a non-zero value to `sorted_by_first`.

When sorting is necessary and `inplace` is non-zero, the actual input columns will be sorted. Otherwise, an internal copy of the inputs will be made, used (sorted) and later freed before returning. Therefore, when `inplace==0`, inputs will remain untouched, but this function will take more time and memory.

If internal allocation is necessary and the space is larger than `minmapsize`, the space will be not allocated in the RAM, but in a file, see description of `--minmapsize` and `--quietmmap` in Section 4.1.2.2 [Processing options], page 112.

The number of matches will be put in the space pointed by `nummatched`. If there wasn’t any match, this function will return `NULL`. If match(s) were found, a list with three `gal_data_t` nodes will be returned. The top two nodes in the list are the permutations that must be applied to the first and second inputs respectively. After applying the permutations, the top `nummatched` elements will match with each other. The third node is the distances between the respective match. Note that the three nodes of the list are all one-dimensional (a column) and can have different lengths.

```
Output permutations ignore internal sorting: the output permutations will correspond to the initial inputs. Therefore, even when `inplace!=0` (and this function re-arranges the inputs), the output permutation will correspond to original (possibly non-sorted) inputs.

The reason for this is that you rarely want the actual positional columns after the match. Usually, you also have other columns (measurements, for example magnitudes) for higher-level processing after the match (that correspond to the input order before sorting). Once you have the permutations, they can be applied to those other columns (see Section 10.3.20 [Permutations (`permutation.h`)], page 479) and the higher-level processing can continue.
```

When you read the coordinates from a table using `gal_table_read` (see Section 10.3.10 [Table input output (`table.h`)], page 426), and only ask for the coordinate columns, the inputs to this function are the returned `gal_data_t *` from two different tables.
10.3.22 Statistical operations (statistics.h)

After reading a dataset into memory from a file or fully simulating it with another process, the most common processes that will be done on it are statistical operations to let you quantify different aspects of the data. The functions in this section describe Gnuastro’s current set of tools for this job. All these functions can work on any numeric data type natively (see Section 4.6 [Numeric data types], page 130) and can also work on tiles over a dataset. Hence the inputs and outputs are in Gnuastro’s Section 10.3.6.1 [Generic data container (gal_data_t)], page 400.

**GAL_STATISTICS_SIG_CLIP_MAX_CONVERGE**  
[Macro]  
The maximum number of clips, when $\sigma$-clipping should be done by convergence. If the clipping does not converge before making this many clips, all $\sigma$-clipping outputs will be NaN.

**GAL_STATISTICS_MODE_GOOD_SYM**  
[Macro]  
The minimum acceptable symmetricity of the mode calculation. If the symmetricity of the derived mode is less than this value, all the returned values by `gal_statistics_mode` will have a value of NaN.

**GAL_STATISTICS_BINS_INVALID, GAL_STATISTICS_BINS_REGULAR, GAL_STATISTICS_BINS_IRREGULAR**  
[Macro]  
Macros used to identify if the regularity of the bins when defining bins.

**gal_data_t * gal_data_number (gal_data_t *input)**  
[Function]  
Return a single-element dataset with type `size_t` which contains the number of non-blank elements in `input`.

**gal_data_t * gal_data_minimum (gal_data_t *input)**  
[Function]  
Return a single-element dataset containing the minimum non-blank value in `input`. The numerical datatype of the output is the same as `input`.

**gal_data_t * gal_data_maximum (gal_data_t *input)**  
[Function]  
Return a single-element dataset containing the maximum non-blank value in `input`. The numerical datatype of the output is the same as `input`.

**gal_data_t * gal_data_sum (gal_data_t *input)**  
[Function]  
Return a single-element (double or float64) dataset containing the sum of the non-blank values in `input`.

**gal_data_t * gal_data_mean (gal_data_t *input)**  
[Function]  
Return a single-element (double or float64) dataset containing the mean of the non-blank values in `input`.
Chapter 10: Library

```
gal_data_t *
gal_statistics_std (gal_data_t *input)
Return a single-element (double or float64) dataset containing the standard deviation of the non-blank values in input.

gal_data_t *
gal_statistics_mean_std (gal_data_t *input)
Return a two-element (double or float64) dataset containing the mean and standard deviation of the non-blank values in input. The first element of the returned dataset is the mean and the second is the standard deviation.
This function will calculate both values in one pass over the dataset. Hence when both the mean and standard deviation of a dataset are necessary, this function is much more efficient than calling gal_statistics_mean and gal_statistics_std separately.

gal_data_t *
gal_statistics_median (gal_data_t *input, int inplace)
Return a single-element dataset containing the median of the non-blank values in input. The numerical datatype of the output is the same as input.
Calculating the median involves sorting the dataset and removing blank values, for better performance (and less memory usage), you can give a non-zero value to the inplace argument. In this case, the sorting and removal of blank elements will be done directly on the input dataset. However, after this function the original dataset may have changed (if it wasn’t sorted or had blank values).

size_t
gal_statistics_quantile_index (size_t size, double quantile)
Return the index of the element that has a quantile of quantile assuming the dataset has size elements.

gal_data_t *
gal_statistics_quantile (gal_data_t *input, double quantile, int inplace)
Return a single-element dataset containing the value with in a quantile quantile of the non-blank values in input. The numerical datatype of the output is the same as input. See gal_statistics_median for a description of inplace.

size_t
gal_statistics_quantile_function_index (gal_data_t *input, gal_data_t *value, int inplace)
Return the index of the quantile function (inverse quantile) of input at value. In other words, this function will return the index of the nearest element (of a sorted and non-blank) input to value. If the value is outside the range of the input, then this function will return GAL_BLANK_SIZE_T.

gal_data_t *
gal_statistics_quantile_function (gal_data_t *input, gal_data_t *value, int inplace)
Return a single-element (double or float64) dataset containing the quantile function of the non-blank values in input at value. In other words, this function will return
the quantile of `value` in `input`. If the value is smaller than the input’s smallest element, the returned value will be zero. If the value is larger than the input’s largest element, then the returned value is 1. See `gal_statistics_median` for a description of `inplace`.

### `gal_data_t * gal_statistics_unique (gal_data_t *input, int inplace)`

Return a 1D dataset with the same numeric data type as the input, but only containing its unique elements and without any (possible) blank/NaN elements. Note that the input’s number of dimensions is irrelevant for this function. If `inplace` is not zero, then the unique values will over-write the allocated space of the input, otherwise a new space will be allocated and the input will not be touched.

### `gal_data_t * gal_statistics_mode (gal_data_t *input, float mirrordist, int inplace)`

Return a four-element (double or float64) dataset that contains the mode of the input distribution. This function implements the non-parametric algorithm to find the mode that is described in Appendix C of Akhlaghi and Ichikawa [2015] (https://arxiv.org/abs/1505.01664).

In short it compares the actual distribution and its “mirror distribution” to find the mode. In order to be efficient, you can determine how far the comparison goes away from the mirror through the `mirrordist` parameter (think of it as a multiple of sigma/error). See `gal_statistics_median` for a description of `inplace`.

The output array has the following elements (in the given order, note that counting in C starts from 0).

- array[0]: mode
- array[1]: mode quantile.
- array[2]: symmetricity.
- array[3]: value at the end of symmetricity.

### `gal_data_t * gal_statistics_mode_mirror_plots (gal_data_t *input, gal_data_t *value, size_t numbins, int inplace, double *mirror_val)`

Make a mirrored histogram and cumulative frequency plot (with `numbins`) with the mirror distribution of the `input` having a value in `value`. If all the input elements are blank, or the mirror value is outside the range of the input, this function will return a NULL pointer.

The output is a list of data structures (see Section 10.3.8.9 [List of `gal_data_t`], page 423): the first is the bins with one bin at the mirror point, the second is the histogram with a maximum of one and the third is the cumulative frequency plot (with a maximum of one).

### `int gal_statistics_is_sorted (gal_data_t *input, int updateflags)`

Return 0 if the input is not sorted, if it is sorted, this function will return 1 and 2 if it is increasing or decreasing, respectively. This function will abort with an error if `input` has zero elements and will return 1 (sorted, increasing) when there is only one
element. This function will only look into the dataset if the GAL_DATA_FLAG_SORT_CH bit of input->flag is 0, see Section 10.3.6.1 [Generic data container (gal_data_t)], page 400.

When the flags don’t indicate a previous check and updateflags is non-zero, this function will set the flags appropriately to avoid having to re-check the dataset in future calls (this can be very useful when repeated checks are necessary). When updateflags==0, this function has no side-effects on the dataset: it will not toggle the flags.

If you want to re-check a dataset with the blank-value-check flag already set (for example if you have made changes to it), then explicitly set the GAL_DATA_FLAG_SORT_CH bit to zero before calling this function. When there are no other flags, you can simply set the flags to zero (with input->flag=0), otherwise you can use this expression:

input->flag &= ~GAL_DATA_FLAG_SORT_CH;

void gal_statistics_sort_increasing (gal_data_t *input) 
Sort the input dataset (in place) in an increasing order and toggle the sort-related bit flags accordingly.

void gal_statistics_sort_decreasing (gal_data_t *input) 
Sort the input dataset (in place) in a decreasing order and toggle the sort-related bit flags accordingly.

gal_data_t * gal_statistics_no_blank_sorted (gal_data_t *input, int inplace) 
Remove all the blanks and sort the input dataset. If inplace is non-zero this will happen on the input dataset (in the allocated space of the input dataset). However, if inplace is zero, this function will allocate a new copy of the dataset and work on that. Therefore if inplace==0, the input dataset will be modified.

This function uses the bit flags of the input, so if you have modified the dataset, set input->flag=0 before calling this function. Also note that inplace is only for the dataset elements. Therefore even when inplace==0, if the input is already sorted and has no blank values, then the flags will be updated to show this.

If all the elements were blank, then the returned dataset’s size will be zero. This is thus a good parameter to check after calling this function to see if there actually were any non-blank elements in the input or not and take the appropriate measure. This can help avoid strange bugs in later steps. The flags of a zero-sized returned dataset will indicate that it has no blanks and is sorted in an increasing order. Even if having blank values or being sorted is not defined on a zero-element dataset, it is up to the caller to choose what they will do with a zero-element dataset. The flags have to be set after this function any way.
gal_data_t *
gal_statistics_regular_bins (gal_data_t *input, gal_data_t *inrange, size_t numbins, double onebinstart)
Generate an array of regularly spaced elements as a 1D array (column) of type double
(i.e., float64, it has to be double to account for small differences on the bin edges).
The input arguments are described below

input         The dataset you want to apply the bins to. This is only necessary if
              the range argument is not complete, see below. If inrange has all
              the necessary information, you can pass a NULL pointer for this.

inrange       This dataset keeps the desired range along each dimension of the input
data structure, it has to be in float (i.e., float32) type.
              • If you want the full range of the dataset (in any dimensions, then
                just set inrange to NULL and the range will be specified from the
                minimum and maximum value of the dataset (input cannot be NULL
                in this case).
              • If there is one element for each dimension in range, then it is viewed
                as a quantile (Q), and the range will be: ‘Q to 1-Q’.
              • If there are two elements for each dimension in range, then they are
                assumed to be your desired minimum and maximum values. When
                either of the two are NaN, the minimum and maximum will be cal-
                culated for it.

numbins       The number of bins: must be larger than 0.

onebinstart   A desired value for onebinstart. Note that with this option, the bins
              won’t start and end exactly on the given range values, it will be slightly
              shifted to accommodate this request.

gal_data_t *
gal_statistics_histogram (gal_data_t *input, gal_data_t *bins, int normalize, int maxone)
Make a histogram of all the elements in the given dataset with bin values that are
defined in the inbins structure (see gal_statistics_regular_bins, they currently
have to be equally spaced). inbins is not mandatory, if you pass a NULL pointer, the
bins structure will be built within this function based on the numbins input. As a
result, when you have already defined the bins, numbins is not used.

Let’s write the center of the i-th element of the bin array as \( b_i \), and the fixed half-
bin width as \( h \). Then element \( j \) of the input array \( (in_j) \) will be counted in \( b_i \) if
\( (b_i - h) \leq in_j < (b_i + h) \). However, if \( in_j \) is somewhere in the last bin, the condition
changes to \( (b_i - h) \leq in_j \leq (b_i + h) \).

gal_data_t *
gal_statistics_cfp (gal_data_t *input, gal_data_t *bins, int normalize)
Make a cumulative frequency plot (CFP) of all the elements in input with bin values
that are defined in the bins structure (see gal_statistics_regular_bins).
The CFP is built from the histogram: in each bin, the value is the sum of all previous bins in the histogram. Thus, if you have already calculated the histogram before calling this function, you can pass it onto this function as the data structure in bins->next (see List of gal_data_t). If bin->next=NULL, then it is assumed to be the histogram. If it is NULL, then the histogram will be calculated internally and freed after the job is finished.

When a histogram is given and it is normalized, the CFP will also be normalized (even if the normalized flag is not set here): note that a normalized CFP’s maximum value is 1.

**[Function]**

```c
gal_data_t * gal_statistics_sigma_clip (gal_data_t *input, float multip, float param, int inplace, int quiet)
```

Apply σ-clipping on a given dataset and return a dataset that contains the results. For a description of σ-clipping see Section 7.1.3 [Sigma clipping], page 251. multip is the multiple of the standard deviation (or σ, that is used to define outliers in each round of clipping).

The role of param is determined based on its value. If param is larger than 1 (one), it must be an integer and will be interpreted as the number clips to do. If it is less than 1 (one), it is interpreted as the tolerance level to stop the iteration.

The returned dataset (let’s call it out) contains a four-element array with type GAL_TYPE_FLOAT32. The final number of clips is stored in the out->status.

```c
float *array=out->array;
array[0]: Number of points used.
array[1]: Median.
array[2]: Mean.
array[3]: Standard deviation.
```

If the σ-clipping doesn’t converge or all input elements are blank, then this function will return NaN values for all the elements above.

**[Function]**

```c
gal_data_t * gal_statistics_outlier_bydistance (int pos1_neg0, gal_data_t *input, size_t window_size, float sigma, float sigclip_multip, float sigclip_param, int inplace, int quiet)
```

Find the first positive outlier (if pos1_neg0!=0) in the input distribution. When pos1_neg0==0, the same algorithm goes to the start of the dataset. The returned dataset contains a single element: the first positive outlier. It is one of the dataset’s elements, in the same type as the input. If the process fails for any reason (for example no outlier was found), a NULL pointer will be returned.

All (possibly existing) blank elements are first removed from the input dataset, then it is sorted. A sliding window of window_size elements is parsed over the dataset. Starting from the window_size-th element of the dataset, in the direction of increasing values. This window is used as a reference. The first element where the distance to the previous (sorted) element is sigma units away from the distribution of distances in its window is considered an outlier and returned by this function.
Formally, if we assume there are $N$ non-blank elements. They are first sorted. Searching for the outlier starts on element $W$. Let’s take $v_i$ to be the $i$-th element of the sorted input (with no blank values) and $m$ and $\sigma$ as the $\sigma$-clipped median and standard deviation from the distances of the previous $W$ elements (not including $v_i$). If the value given to sigma is displayed with $s$, the $i$-th element is considered as an outlier when the condition below is true.

$$\frac{(v_i - v_{i-1}) - m}{\sigma} > s$$

The `sigclip_multip` and `sigclip_param` arguments specify the properties of the $\sigma$-clipping (see Section 7.1.3 [Sigma clipping], page 251, for more). You see that by this definition, the outlier cannot be any of the lower half elements. The advantage of this algorithm compared to $\sigma$-clipping is that it only looks backwards (in the sorted array) and parses it in one direction.

If `inplace!=0`, the removing of blank elements and sorting will be done within the input dataset’s allocated space. Otherwise, this function will internally allocate (and later free) the necessary space to keep the intermediate space that this process requires.

If `quiet!=0`, this function will report the parameters every time it moves the window as a separate line with several columns. The first column is the value, the second (in square brackets) is the sorted index, the third is the distance of this element from the previous one. The Fourth and fifth (in parenthesis) are the median and standard deviation of the $\sigma$-clipped distribution within the window and the last column is the difference between the third and fourth, divided by the fifth.

```c
{\textit{Function}}
\begin{verbatim}
gal_data_t * gal_statistics_outlier_flat_cfp (gal_data_t *input, size_t numprev, float sigclip_multip, float sigclip_param, float thresh, size_t numcontig, int inplace, int quiet, size_t *index)
    Return the first element in the given dataset where the cumulative frequency plot first becomes significantly flat for a sufficient number of elements. The returned dataset only has one element (with the same type as the input). If index!=NULL, the index (counting from zero, after sorting the dataset and removing any blanks) is written in the space that index points to. If no sufficiently flat portion is found, the returned pointer will be NULL.

    The flatness on the cumulative frequency plot is defined like this (see Section 7.1.1 [Histogram and Cumulative Frequency Plot], page 248): on the sorted dataset, for every point ($a_i$), we calculate $d_i = a_{i+2} - a_{i-2}$. This done on the first $N$ elements (value of numprev). After element $a_{N+2}$, we start estimating the flatness as follows: for every element we use the $N$, $d_i$ measurements before it as the reference. Let’s call this set $D_i$ for element $i$. The $\sigma$-clipped median ($m$) and standard deviation ($s$) of $D_i$ are then calculated. The $\sigma$-clipping can be configured with the two `sigclip_param` and `sigclip_multip` arguments.

    Taking $t$ as the significance threshold (value to `thresh`), a point is considered flat when $a_i > m + t\sigma$. But a single point satisfying this condition will probably just be
\end{verbatim}
```
due to noise. To make a more robust estimate, this significance/condition has to hold for \texttt{numcontig} contiguous elements after \(a_i\). When this is satisfied, \(a_i\) is returned as the point where the distribution’s cumulative frequency plot becomes flat.

To get a good estimate of \(m\) and \(s\), it is thus recommended to set \texttt{numprev} as large as possible. However, be careful not to set it too high: the checks in the paragraph above are not done on the first \texttt{numprev} elements and this function assumes the flatness occurs after them. Also, be sure that the value to \texttt{numcontig} is much less than \texttt{numprev}, otherwise \(\sigma\)-clipping may not be able to remove the immediate outliers in \(D\), near the boundary of the flat region.

When \texttt{quiet)==0}, the basic measurements done on each element are printed on the command-line (good for finding the best parameters). When \texttt{inplace!=0}, the sorting and removal of blank elements is done on the input dataset, so the input may be altered after this function.

\subsection*{10.3.23 Binary datasets (binary.h)}

Binary datasets only have two (usable) values: 0 (also known as background) or 1 (also known as foreground). They are created after some binary classification is applied to the dataset. The most common is thresholding: for example in an image, pixels with a value above the threshold are given a value of 1 and those with a value less than the threshold are assigned a value of 0.

Since there is only two values, in the processing of binary images, you are usually concerned with the positioning of an element and its vicinity (neighbors). When a dataset has more than one dimension, multiple classes of immediate neighbors (that are touching the element) can be defined for each data-element. To separate these different classes of immediate neighbors, we define \emph{connectivity}.

The classification is done by the distance from element center to the neighbor’s center. The nearest immediate neighbors have a connectivity of 1, the second nearest class of neighbors have a connectivity of 2 and so on. In total, the largest possible connectivity for data with \texttt{ndim} dimensions is \texttt{ndim}. For example in a 2D dataset, 4-connected neighbors (that share an edge and have a distance of 1 pixel) have a connectivity of 1. The other 4 neighbors that only share a vertice (with a distance of \(\sqrt{2}\) pixels) have a connectivity of 2. Conventionally, the class of connectivity-2 neighbors also includes the connectivity 1 neighbors, so for example we call them 8-connected neighbors in 2D datasets.

Ideally, one bit is sufficient for each element of a binary dataset. However, CPUs are not designed to work on individual bits, the smallest unit of memory addresses is a byte (containing 8 bits on modern CPUs). Therefore, in Gnuastro, the type used for binary dataset is \texttt{uint8_t} (see Section 4.6 [Numeric data types], page 130). Although it does take 8-times more memory, this choice offers much better performance and the some extra (useful) features.

The advantage of using a full byte for each element of a binary dataset is that you can also have other values (that will be ignored in the processing). One such common “other” value in real datasets is a blank value (to mark regions that should not be processed because there is no data). The constant \texttt{GAL_BLANK_UINT8} value must be used in these cases (see Section 10.3.5 [Library blank values (blank.h)], page 396). Another is some temporary value(s) that can be given to a processed pixel to avoid having another copy of the dataset as in \texttt{GAL_BINARY_TMP_VALUE} that is described below.
GAL_BINARY_TMP_VALUE [Macro]
The functions described below work on a uint8_t type dataset with values of 1 or 0 (no other pixel will be touched). However, in some cases, it is necessary to put temporary values in each element during the processing of the functions. This temporary value has a special meaning for the operation and will be operated on. So if your input datasets have values other than 0 and 1 that you don’t want these functions to work on, be sure they are not equal to this macro’s value. Note that this value is also different from GAL_BLANK_UINT8, so your input datasets may also contain blank elements.

gal_data_t * [Function]
gal_binary_erode (gal_data_t *input, size_t num, int connectivity, int inplace)
Do num erosions on the connectivity-connected neighbors of input (see above for the definition of connectivity).

If inplace is non-zero and the input’s type is GAL_TYPE_UINT8, then the erosion will be done within the input dataset and the returned pointer will be input. Otherwise, input is copied (and converted if necessary) to GAL_TYPE_UINT8 and erosion will be done on this new dataset which will also be returned. This function will only work on the elements with a value of 1 or 0. It will leave all the rest unchanged.

Erosion (inverse of dilation) is an operation in mathematical morphology where each foreground pixel that is touching a background pixel is flipped (changed to background). The connectivity value determines the definition of “touching”. Erosion will thus decrease the area of the foreground regions by one layer of pixels.

gal_data_t * [Function]
gal_binary_dilate (gal_data_t *input, size_t num, int connectivity, int inplace)
Do num dilations on the connectivity-connected neighbors of input (see above for the definition of connectivity). For more on inplace and the output, see gal_binary_erode.

Dilation (inverse of erosion) is an operation in mathematical morphology where each background pixel that is touching a foreground pixel is flipped (changed to foreground). The connectivity value determines the definition of “touching”. Dilation will thus increase the area of the foreground regions by one layer of pixels.

gal_data_t * [Function]
gal_binary_open (gal_data_t *input, size_t num, int connectivity, int inplace)
Do num openings on the connectivity-connected neighbors of input (see above for the definition of connectivity). For more on inplace and the output, see gal_binary_erode.

Opening is an operation in mathematical morphology which is defined as erosion followed by dilation (see above for the definitions of erosion and dilation). Opening will thus remove the outer structure of the foreground. In this implementation, num erosions are going to be applied on the dataset, then num dilations.
size_t gal_binary_connected_components (gal_data_t *binary, gal_data_t **out, int connectivity)

Return the number of connected components in binary through the breadth first search algorithm (finding all pixels belonging to one component before going on to the next). Connection between two pixels is defined based on the value to connectivity. out is a dataset with the same size as binary with GAL_TYPE_INT32 type. Every pixel in out will have the label of the connected component it belongs to. The labeling of connected components starts from 1, so a label of zero is given to the input’s background pixels.

When *out!=NULL (its space is already allocated), it will be cleared (to zero) at the start of this function. Otherwise, when *out==NULL, the necessary dataset to keep the output will be allocated by this function.

binary must have a type of GAL_TYPE_UINT8, otherwise this function will abort with an error. Other than blank pixels (with a value of GAL_BLANK_UINT8 defined in Section 10.3.5 [Library blank values (blank.h), page 396], all other non-zero pixels in binary will be considered as foreground (and will be labeled). Blank pixels in the input will also be blank in the output.

gal_data_t * gal_binary_connected_indexs(gal_data_t *binary, int connectivity)

Build a gal_data_t linked list, where each node of the list contains an array with indexs of the connected regions. Therefore the arrays of each node can have a different size. Note that the indexs will only be calculated on the pixels with a value of 1 and internally, it will temporarily change the values to 2 (and return them back to 1 in the end).

gal_data_t * gal_binary_connected_adjacency_matrix (gal_data_t *adjacency, size_t *numconnected)

Find the number of connected labels and new labels based on an adjacency matrix, which must be a square binary array (type GAL_TYPE_UINT8). The returned dataset is a list of new labels for each old label. In other words, this function will find the objects that are connected (possibly through a third object) and in the output array, the respective elements for all input labels is going to have the same value. The total number of connected labels is put into the space that numconnected points to.

An adjacency matrix defines connection between two labels. For example, let’s assume we have 5 labels and we know that labels 1 and 5 are connected to label 3, but are not connected with each other. Also, labels 2 and 4 are not touching any other label. So in total we have 3 final labels: one combined object (merged from labels 1, 3, and 5) and the initial labels 2 and 4. The input adjacency matrix would look like this (note the extra row and column for a label 0 which is ignored):

<table>
<thead>
<tr>
<th>INPUT</th>
<th>OUTPUT</th>
</tr>
</thead>
<tbody>
<tr>
<td>in_lab</td>
<td>numconnected = 3</td>
</tr>
<tr>
<td>=====</td>
<td>======</td>
</tr>
<tr>
<td>1 2 3 4 5</td>
<td>0 0 0 0 0 0</td>
</tr>
</tbody>
</table>


Although the adjacency matrix as used here is symmetric, currently this function assumes that it is filled on both sides of the diagonal.

```c
[Function]
gal_data_t *
gal_binary_holes_label (gal_data_t *input, int connectivity, size_t *numholes)
```

Label all the holes in the foreground (non-zero elements in input) as independent regions. Holes are background regions (zero-valued in input) that are fully surrounded by the foreground, as defined by `connectivity`. The returned dataset has a 32-bit signed integer type with the size of the input. All holes in the input will have labels/counters greater or equal to 1. The rest of the background regions will still have a value of 0 and the initial foreground pixels will have a value of -1. The total number of holes will be written where `numholes` points to.

```c
void
gal_binary_holes_fill (gal_data_t *input, int connectivity, size_t maxsize)
```

Fill all the holes (0 valued pixels surrounded by 1 valued pixels) of the binary input dataset. The connectivity of the holes can be set with `connectivity`. Holes larger than `maxsize` are not filled. This function currently only works on a 2D dataset.

### 10.3.24 Labeled datasets (label.h)

A labeled dataset is one where each element/pixel has an integer label (or counter). The label identifies the group/class that the element belongs to. This form of labeling allows the higher-level study of all pixels within a certain class.

For example, to detect objects/targets in an image/dataset, you can apply a threshold to separate the noise from the signal (to detect diffuse signal, a threshold is useless and more advanced methods are necessary, for example Section 7.2 [NoiseChisel], page 269). But the output of detection is a binary dataset (which is just a very low-level labeling of 0 for noise and 1 for signal).

The raw detection map is therefore hardly useful for any kind of analysis on objects/targets in the image. One solution is to use a connected-components algorithm (see `gal_binary_connected_components` in Section 10.3.23 [Binary datasets (binary.h)], page 489). It is a simple and useful way to separate/label connected patches in the foreground. This higher-level (but still elementary) labeling therefore allows you to count how many connected patches of signal there are in the dataset and is a major improvement compared to the raw detection.

However, when your objects/targets are touching, the simple connected components algorithm is not enough and a still higher-level labeling mechanism is necessary. This brings us to the necessity of the functions in this part of Gnuastro’s library. The main inputs to the functions in this section are already labeled datasets (for example with the connected components algorithm above).
Each of the labeled regions are independent of each other (the labels specify different classes of targets). Therefore, especially in large datasets, it is often useful to process each label on independent CPU threads in parallel rather than in series. Therefore the functions of this section actually use an array of pixel/element indexes (belonging to each label/class) as the main identifier of a region. Using indexes will also allow processing of overlapping labels (for example in deblending problems). Just note that overlapping labels are not yet implemented, but planned. You can use \texttt{gal_label_indexs} to generate lists of indexes belonging to separate classes from the labeled input.

\begin{verbatim}
GAL_LABEL_INIT [Macro]
GAL_LABEL_RIVER [Macro]
GAL_LABEL_TMPCHECK [Macro]
\end{verbatim}

Special negative integer values used internally by some of the functions in this section. Recall that meaningful labels are considered to be positive integers ($\geq 1$). Zero is conventionally kept for regions with no labels, therefore negative integers can be used for any extra classification in the labeled datasets.

\begin{verbatim}
gal_data_t * gal_label_indexs (gal_data_t *labels, size_t numlabs, size_t minmapsize, int quietmmap)
\end{verbatim}

Return an array of \texttt{gal_data_t} containers, each containing the pixel indexes of the respective label (see Section 10.3.6.1 [Generic data container (\texttt{gal_data_t})], page 400). \texttt{labels} contains the label of each element and has to have an \texttt{GAL_TYPE_INT32} type (see Section 10.3.3 [Library data types (type.h)], page 390). Only positive (greater than zero) values in \texttt{labels} will be used/indexed, other elements will be ignored.

Meaningful labels start from 1 and not 0, therefore the output array of \texttt{gal_data_t} will contain \texttt{numlabs+1} elements. The first (zero-th) element of the output (\texttt{indexes[0]} in the example below) will be initialized to a dataset with zero elements. This will allow easy (non-confusing) access to the indexes of each (meaningful) label. \texttt{numlabs} is the number of labels in the dataset. If it is given a value of zero, then the maximum value in the input (largest label) will be found and used. Therefore if it is given, but smaller than the actual number of labels, this function may/will crash (it will write in unallocated space). \texttt{numlabs} is therefore useful in a highly optimized/check environment.

For example, if the returned array is called \texttt{indexes}, then \texttt{indexes[10].size} contains the number of elements that have a label of 10 in \texttt{labels} and \texttt{indexes[10].array} is an array (after casting to \texttt{size_t *}) containing the indexes of each one of those elements/pixels.

By \texttt{index} we mean the 1D position: the input number of dimensions is irrelevant (any dimensionality is supported). In other words, each element’s index is the number of elements/pixels between it and the dataset’s first element/pixel. Therefore it is always greater or equal to zero and stored in \texttt{size_t} type.
size_t gal_label_watershed(gal_data_t *values, gal_data_t *indexs, gal_data_t *label, size_t *topinds, int min0_max1)

Use the watershed algorithm\textsuperscript{24} to “over-segment” the pixels in the indexs dataset based on values in the values dataset. Internally, each local extrema (maximum or minimum, based on min0_max1) and its surrounding pixels will be given a unique label. For demonstration, see Figures 8 and 9 of Akhlaghi and Ichikawa [2015] (http://arxiv.org/abs/1505.01664). If topinds!NULL, it is assumed to point to an already allocated space to write the index of each clump’s local extrema, otherwise, it is ignored.

The values dataset must have a 32-bit floating point type (GAL_TYPE_FLOAT32, see Section 10.3.3 [Library data types (type.h)], page 390) and will only be read by this function. indexs must contain the indexes of the elements/pixels that will be over-segmented by this function and have a GAL_TYPE_SIZE_T type, see the description of gal_label_indexs, above. The final labels will be written in the respective positions of labels, which must have a GAL_TYPE_INT32 type and be the same size as values.

When indexs is already sorted, this function will ignore min0_max1. To judge if the dataset is sorted or not (by the values the indexes correspond to in values, not the actual indexes), this function will look into the bits of indexs\textasciitilde flag, for the respective bit flags, see Section 10.3.6.1 [Generic data container (gal_data_t)], page 400. If indexs is not already sorted, this function will sort it according to the values of the respective pixel in values. The increasing/decreasing order will be determined by min0_max1. Note that if this function is called on multiple threads and values points to a different array on each thread, this function will not return a reasonable result. In this case, please sort indexs prior to calling this function (see gal_qsort_index_multi_d in Section 10.3.18 [Qsort functions (qsort.h)], page 474).

When indexs is decreasing (increasing), or min0_max1 is 1 (0), local minima (maxima), are considered rivers (watersheds) and given a label of GAL_LABEL_RIVER (see above).

Note that rivers/watersheds will also be formed on the edges of the labeled regions or when the labeled pixels touch a blank pixel. Therefore this function will need to check for the presence of blank values. To be most efficient, it is thus recommended to use gal_blank_present (with updateflag=1) prior to calling this function (see Section 10.3.5 [Library blank values (blank.h)], page 396. Once the flag has been set, no other function (including this one) that needs special behavior for blank pixels will have to parse the dataset to see if it has blank values any more.

If you are sure your dataset doesn’t have blank values (by the design of your software), to avoid an extra parsing of the dataset and improve performance, you can set the two bits manually (see the description of flags in Section 10.3.6.1 [Generic data container (gal_data_t)], page 400):

\begin{verbatim}
input\rightarrow flag |= GAL_DATA_FLAG_BLANK_CH; /* Set bit to 1. */
input\rightarrow flag &~= ~GAL_DATA_FLAG_HASBLANK; /* Set bit to 0. */
\end{verbatim}

\textsuperscript{24} The watershed algorithm was initially introduced by Vincent and Soille (https://doi.org/10.1109/34.87344). It starts from the minima and puts the pixels in, one by one, to grow them until the touch (create a watershed). For more, also see the Wikipedia article: https://en.wikipedia.org/wiki/Watershed_%28image_processing%29.
void gal_label_clump_significance (gal_data_t *values, gal_data_t *std,  
gal_data_t *label, gal_data_t *indices, struct gal_tile_two_layer_params  
*t1, size_t numclumps, size_t minarea, int variance, int keepsmall,  
gal_data_t *sig, gal_data_t *sigind)

This function is usually called after gal_label_watershed, and is used as a measure  
to identify which over-segmented “clumps” are real and which are noise.

A measurement is done on each clump (using the values and std datasets, see below).
To help in multi-threaded environments, the operation is only done on pixels which  
are indexed in indices. It is expected for indices to be sorted by their values in  
values. If not sorted, the measurement may not be reliable. If sorted in a decreasing  
order, then clump building will start from their highest value and vice-versa. See the  
description of gal_label_watershed for more on indices.

Each “clump” (identified by a positive integer) is assumed to be surrounded by at  
least one river/watershed pixel (with a non-positive label). This function will parse  
the pixels identified in indices and make a measurement on each clump and over all  
the river/watershed pixels. The number of clumps (numclumps) must be given as an  
input argument and any clump that is smaller than minarea is ignored (because of  
scatter). If variance is non-zero, then the std dataset is interpreted as variance, not  
standard deviation.

The values and std datasets must have a float (32-bit floating point) type. Also,  
label and indices must respectively have int32 and size_t types. values and  
label must have the same size, but std can have three possible sizes: 1) a single  
element (which will be used for the whole dataset, 2) the same size as values (so a  
different error can be assigned to every pixel), 3) a single value for each tile, based  
on the t1 tessellation (see Section 10.3.15.2 [Tile grid], page 466). In the last case, a  
tile/value will be associated to each clump based on its flux-weighted (only positive  
values) center.

The main output is an internally allocated, 1-dimensional array with one value per  
label. The array information (length, type, etc) will be written into the sig generic  
data container. Therefore sig->array must be NULL when this function is called.
After this function, the details of the array (number of elements, type and size, etc)  
will be written in to the various components of sig, see the definition of gal_data_t  
in Section 10.3.6.1 [Generic data container (gal_data_t)], page 400. Therefore sig  
must already be allocated before calling this function.

Optionally (when sigind!=NULL, similar to sig) the clump labels of each measure-  
ment in sig will be written in sigind->array. If keepsmall zero, small clumps  
(where no measurement is made) will not be included in the output table.

This function is initially intended for a multi-threaded environment. In such cases,  
you will be writing arrays of clump measures from different regions in parallel into an  
array of gal_data_t. You can simply allocate (and initialize), such an array with the  
gal_data_array_calloc function in Section 10.3.6.3 [Arrays of datasets], page 406.  
For example if the gal_data_t array is called array, you can pass &array[i] as sig.

Along with some other functions in label.h, this function was initially written for  
Section 7.3 [Segment], page 284. The description of the parameter used to measure

```c
void gal_label_grow_indices (gal_data_t *labels, gal_data_t *indexes, int withrivers, int connectivity)
```

Grow the (positive) labels of `labels` over the pixels in `indexes` (see description of `gal_label_indices`). The pixels (position in `indexes`, values in `labels`) that must be “grown” must have a value of `GAL_LABEL_INIT` in `labels` before calling this function. For a demonstration see Columns 2 and 3 of Figure 10 in Akhlaghi and Ichikawa [2015] (http://arxiv.org/abs/1505.01664).

In many aspects, this function is very similar to over-segmentation (watershed algorithm, `gal_label_watershed`). The big difference is that in over-segmentation local maximums (that aren’t touching any already-labeled pixel) get a separate label. However, here the final number of labels will not change. All pixels that aren’t directly touching a labeled pixel just get pushed back to the start of the loop, and the loop iterates until its size doesn’t change any more. This is because in a generic scenario some of the indexed pixels might not be reachable through other indexed pixels.

The next major difference with over-segmentation is that when there is only one label in growth region(s), it is not mandatory for `indexes` to be sorted by values. If there are multiple labeled regions in growth region(s), then values are important and you can use `qsort` with `gal_qsort_index_single_d` to sort the `indexes` by values in a separate array (see Section 10.3.18 [Qsort functions (qsort.h)], page 474).

This function looks for positive-valued neighbors of each pixel in `indexes` and will label a pixel if it touches one. Therefore, it is very important that only pixels/labels that are intended for growth have positive values in `labels` before calling this function. Any non-positive (zero or negative) value will be ignored as a label by this function. Thus, it is recommended that while filling in the ‘indexes’ array values, you initialize all the pixels that are in `indexes` with `GAL_LABEL_INIT`, and set non-labeled pixels that you don’t want to grow to 0.

This function will write into both the input datasets. After this function, some of the non-positive `labels` pixels will have a new positive label and the number of useful elements in `indexes` will have decreased. The index of those pixels that couldn’t be labeled will remain inside `indexes`. If `withrivers` is non-zero, then pixels that are immediately touching more than one positive value will be given a `GAL_LABEL_RIVER` label.

Note that the `indexes->array` is not re-allocated to its new size at the end. But since `indexes->dsize[0]` and `indexes->size` have new values after this function is returned, the extra elements just won’t be used until they are ultimately freed by `gal_data_free`.

Connectivity is a value between 1 (fewest number of neighbors) and the number of dimensions in the input (most number of neighbors). For example in a 2D dataset, a connectivity of 1 and 2 corresponds to 4-connected and 8-connected neighbors.

---

Note that according to the GNU C Library, even a `realloc` to a smaller size can also cause a re-write of the whole array, which is not a cheap operation.
10.3.25 Convolution functions (convolve.h)

Convolution is a very common operation during data analysis and is thoroughly described as part of Gnuastro’s Section 6.3 [Convolve], page 216, program which is fully devoted to this job. Because of the complete introduction that was presented there, we will directly skip onto the currently available convolution functions in Gnuastro’s library.

As of this version, only spatial domain convolution is available in Gnuastro’s libraries. We haven’t had the time to liberate the frequency domain function convolution and de-convolution functions that are available in the Convolve program.

```c
gal_data_t *
gal_convolve_spatial (gal_data_t *tiles, gal_data_t *kernel, size_t numthreads, int edgecorrection, int convoverch)
```

Convolve the given `tiles` dataset (possibly a list of tiles, see Section 10.3.8.9 [List of `gal_data_t`], page 423, and Section 10.3.15 [Tessellation library (tile.h)], page 460) with `kernel` on `numthreads` threads. When `edgecorrection` is non-zero, it will correct for the edge dimming effects as discussed in Section 6.3.1.2 [Edges in the spatial domain], page 218.

tiles can be a single/complete dataset, but in that case the speed will be very slow. Therefore, for larger images, it is recommended to give a list of tiles covering a dataset. To create a tessellation that fully covers an input image, you may use `gal_tile_full`, or `gal_tile_full_two_layers` to also define channels over your input dataset. These functions are discussed in Section 10.3.15.2 [Tile grid], page 466. You may then pass the list of tiles to this function. This is the recommended way to call this function because spatial domain convolution is slow and breaking the job into many small tiles and working on simultaneously on several threads can greatly speed up the processing.

If the tiles are defined within a channel (a larger tile), by default convolution will be done within the channel, so pixels on the edge of a channel will not be affected by their neighbors that are in another channel. See Section 4.9 [Tessellation], page 141, for the necessity of channels in astronomical data analysis. This behavior may be disabled when `convoverch` is non-zero. In this case, it will ignore channel borders (if they exist) and mix all pixels that cover the kernel within the dataset.

```c
void

gal_convolve_spatial_correct_ch_edge (gal_data_t *tiles, gal_data_t *kernel, size_t numthreads, int edgecorrection, gal_data_t *tocorrect)
```

Correct the edges of channels in an already convolved image when it was initially convolved with `gal_convolve_spatial` and `convoverch==0`. In that case, strong boundaries might exist on the channel edges. So if you later need to remove those boundaries at later steps of your processing, you can call this function. It will only do convolution on the tiles that are near the edge and were effected by the channel borders. Other pixels in the image will not be touched. Hence, it is much faster.

---

26 Hence any help would be greatly appreciated.
10.3.26 Interpolation (interpolate.h)

During data analysis, it happens that parts of the data cannot be given a value, but one is necessary for the higher-level analysis. For example a very bright star saturated part of your image and you need to fill in the saturated pixels with some values. Another common usage case are masked sky-lines in 1D spectra that similarly need to be assigned a value for higher-level analysis. In other situations, you might want a value in an arbitrary point: between the elements/pixels where you have data. The functions described in this section are for such operations.

The parametric interpolations discussed below are wrappers around the interpolation functions of the GNU Scientific Library (or GSL, see Section 3.1.1.1 [GNU Scientific library], page 75). To identify the different GSL interpolation types, Gnuastro’s gnuastro/interpolate.h header file contains macros that are discussed below. The GSL wrappers provided here are not yet complete because we are too busy. If you need them, please consider helping us in adding them to Gnuastro’s library. Your would be very welcome and appreciated.

<table>
<thead>
<tr>
<th>Macro</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>GAL_INTERPOLATE_NEIGHBORS_METRIC_RADIAL</td>
<td>The metric used to find distance for nearest neighbor interpolation. A radial metric uses the simple Euclidean function to find the distance between two pixels. A manhattan metric will always be an integer and is like steps (but is also much faster to calculate than radial metric because it doesn’t need a square root calculation).</td>
</tr>
<tr>
<td>GAL_INTERPOLATE_NEIGHBORS_METRIC_MANHATTAN</td>
<td></td>
</tr>
<tr>
<td>GAL_INTERPOLATE_NEIGHBORS_METRIC_INVALID</td>
<td></td>
</tr>
<tr>
<td>GAL_INTERPOLATE_NEIGHBORS_FUNC_MIN</td>
<td>The various types of nearest-neighbor interpolation functions for gal_interpolate_neighbors. The names are descriptive for the operation they do, so we won’t go into much more detail here. The median operator will be one of the most used, but operators like the maximum are good to fill the center of saturated stars.</td>
</tr>
<tr>
<td>GAL_INTERPOLATE_NEIGHBORS_FUNC_MAX</td>
<td></td>
</tr>
<tr>
<td>GAL_INTERPOLATE_NEIGHBORS_FUNC_MEDIAN</td>
<td></td>
</tr>
<tr>
<td>GAL_INTERPOLATE_NEIGHBORS_FUNC_INVALID</td>
<td></td>
</tr>
</tbody>
</table>

```c
gal_data_t *
gal_interpolate_neighbors (gal_data_t *input, struct gal_tile_two_layer_params *tl, uint8_t metric, size_t numneighbors, size_t numthreads, int onlyblank, int aslinkedlist, int function)
```

Interpolate the values in the input dataset using a calculated statistics from the distribution of their numneighbors closest neighbors. The desired statistics is determined from the func argument, which takes any of the GAL_INTERPOLATE_NEIGHBORS_FUNC macros (see above). This function is non-parametric and thus agnostic to the input’s number of dimension or shape of the distribution.

Distance can be defined on different metrics that are identified through metric (taking values determined by the GAL_INTERPOLATE_NEIGHBORS_METRIC macros described above). If onlyblank is non-zero, then only blank elements will be interpolated and pixels that already have a value will be left untouched. This function is multi-threaded
and will run on `numthreads` threads (see `gal_threads_number` in Section 10.3.2 [Multithreaded programming (`threads.h`)], page 386).

tl is Gnuastro’s tessellation structure used to define tiles over an image and is fully described in Section 10.3.15.2 [Tile grid], page 466. When `tl!=NULL`, then it is assumed that the `input->array` contains one value per tile and interpolation will respect certain tessellation properties, for example to not interpolate over channel borders.

If several datasets have the same set of blank values, you don’t need to call this function multiple times. When `aslinkedlist` is non-zero, then `input` will be seen as a Section 10.3.8.9 [List of `gal_data_t`], page 423. In this case, the same neighbors will be used for all the datasets in the list. Of course, the values for each dataset will be different, so a different value will be written in the each dataset, but the neighbor checking that is the most CPU intensive part will only be done once.

This is a non-parametric and robust function for interpolation. The interpolated values are also always within the range of the non-blank values and strong outliers do not get created. However, this type of interpolation must be used with care when there are gradients. This is because it is non-parametric and if there aren’t enough neighbors, step-like features can be created.

**GAL_INTERPOLATE_1D_INVALID**  
This is just a place holder to manage errors.

**GAL_INTERPOLATE_1D_LINEAR**  
[From GSL:] Linear interpolation. This interpolation method does not require any additional memory.

**GAL_INTERPOLATE_1D_POLYNOMIAL**  
[From GSL:] Polynomial interpolation. This method should only be used for interpolating small numbers of points because polynomial interpolation introduces large oscillations, even for well-behaved datasets. The number of terms in the interpolating polynomial is equal to the number of points.

**GAL_INTERPOLATE_1D_CSPLINE**  
[From GSL:] Cubic spline with natural boundary conditions. The resulting curve is piecewise cubic on each interval, with matching first and second derivatives at the supplied data-points. The second derivative is chosen to be zero at the first point and last point.

**GAL_INTERPOLATE_1D_CSPLINE_PERIODIC**  
[From GSL:] Cubic spline with periodic boundary conditions. The resulting curve is piecewise cubic on each interval, with matching first and second derivatives at the supplied data-points. The derivatives at the first and last points are also matched. Note that the last point in the data must have the same y-value as the first point, otherwise the resulting periodic interpolation will have a discontinuity at the boundary.

**GAL_INTERPOLATE_1D_AKIMA**  
[From GSL:] Non-rounded Akima spline with natural boundary conditions. This method uses the non-rounded corner algorithm of Wodicka.
GAL_INTERPOLATE_1D_AKIMA_PERIODIC [Macro]
[From GSL:] Non-rounded Akima spline with periodic boundary conditions. This method uses the non-rounded corner algorithm of Wodicka.

GAL_INTERPOLATE_1D_STEFFEN [Macro]
[From GSL:] Steffen’s method\textsuperscript{27} guarantees the monotonicity of the interpolating function between the given data points. Therefore, minima and maxima can only occur exactly at the data points, and there can never be spurious oscillations between data points. The interpolated function is piecewise cubic in each interval. The resulting curve and its first derivative are guaranteed to be continuous, but the second derivative may be discontinuous.

gsl_spline *
gal_interpolate_1d_make_gsl_spline (gal_data_t *X, gal_data_t *Y, int type_1d)
Allocate and initialize a GNU Scientific Library (GSL) 1D gsl_spline structure using the non-blank elements of Y. type_1d identifies the interpolation scheme and must be one of the GAL_INTERPOLATE_1D_* macros defined above.

If X==NULL, the X-axis is assumed to be integers starting from zero (the index of each element in Y). Otherwise, the values in X will be used to initialize the interpolation structure. Note that when given, X must not contain any blank elements and it must be sorted (in increasing order).

Each interpolation scheme needs a minimum number of elements to successfully operate. If the number of non-blank values in Y is less than this number, this function will return a NULL pointer.

To be as generic and modular as possible, GSL’s tools are low-level. Therefore before doing the interpolation, many steps are necessary (like preparing your dataset, then allocating and initializing gsl_spline). The metadata available in Gnuastro’s Section 10.3.6.1 [Generic data container (gal_data_t)], page 400, make it easy to hide all those preparations within this function.

Once gsl_spline has been initialized by this function, the interpolation can be evaluated for any X value within the non-blank range of the input using gsl_spline_eval or gsl_spline_eval_e.

For example in the small program below, we read the first two columns of the table in table.txt and feed them to this function to later estimate the values in the second column for three selected points. You can use Section 10.2 [BuildProgram], page 380, to compile and run this function, see Section 10.4 [Library demo programs], page 507, for more.

```c
#include <stdio.h>
#include <stdlib.h>
#include <gnuastro/table.h>
#include <gnuastro/interpolate.h>

int
```

\textsuperscript{27} http://adsabs.harvard.edu/abs/1990A%26A...239..443S
main(void)
{
    size_t i;
    gal_data_t *X, *Y;
    gsl_spline *spline;
    gsl_interp_accel *acc;
    gal_list_str_t *cols=NULL;

    /* Change the values based on your input table. */
    double points[]={1.8, 2.5, 10.3};

    /* Read the first two columns from ‘tab.txt’.
       IMPORTANT: the list is first-in-first-out, so the output
       column order is the inverse of the input order. */
    gal_list_str_add(&cols, "1", 0);
    gal_list_str_add(&cols, "2", 0);
    Y=gal_table_read("table.txt", NULL, cols, GAL_TABLE_SEARCH_NAME,
                     0, -1, 1, NULL);
    X=Y->next;

    /* Allocate the GSL interpolation accelerator and make the
       ‘gsl_spline’ structure. */
    acc=gsl_interp_accel_alloc();
    spline=gal_interpolate_1d_make_gsl_spline(X, Y,
                                              GAL_INTERPOLATE_1D_STEFFEN);

    /* Calculate the respective value for all the given points,
       if ‘spline’ could be allocated. */
    if(spline)
        for(i=0; i<(sizeof points)/(sizeof *points); ++i)
            printf("%f: %f\n", points[i],
                    gsl_spline_eval(spline, points[i], acc));

    /* Clean up and return. */
    gal_data_free(X);
    gal_data_free(Y);
    gsl_spline_free(spline);
    gsl_interp_accel_free(acc);
    gal_list_str_free(cols, 0);
    return EXIT_SUCCESS;
}

 gall_interpolate_1d_blank (gal_data_t *in, int type_1d)
    Fill the blank elements of in using the rest of the elements and the given interpolation.
    The interpolation scheme can be set through type_1d, which accepts any of the
    GAL_INTERPOLATE_1D_* macros above. The interpolation is internally done in 64-bit
floating point type (**double**). However the evaluated/interpolated values (originally blank) will be written (in **in**) with its original numeric datatype, using C’s standard type conversion.

By definition, interpolation is only defined “between” valid points. Therefore, if any number of elements on the start or end of the 1D array are blank, those elements will not be interpolated and will remain blank. To see if any blank (non-interpolated) elements remain, you can use **gal_blank_present** on **in** after this function is finished.

### 10.3.27 Git wrappers (**git.h**)

Git is one of the most common tools for version control and it can often be useful during development, for example see COMMIT keyword in Section 4.11 [Output FITS files], page 143. At installation time, Gnuastro will also check for the existence of libgit2, and store the value in the **GAL_CONFIG_HAVE_LIBGIT2**, see Section 10.3.1 [Configuration information (**config.h**)], page 385, and Section 3.1.2 [Optional dependencies], page 77. **gnuastro/git.h** includes **gnuastro/config.h** internally, so you won’t have to include both for this macro.

**char **

**gal_git_describe** (** )

When libgit2 is present and the program is called within a directory that is version controlled, this function will return a string containing the commit description (similar to Gnuastro’s unofficial version number, see Section 1.5 [Version numbering], page 7). If there are uncommitted changes in the running directory, it will add a ‘-dirty’ prefix to the description. When there is no tagged point in the previous commit, this function will return a uniquely abbreviated commit object as fallback. This function is used for generating the value of the COMMIT keyword in Section 4.11 [Output FITS files], page 143. The output string is similar to the output of the following command:

```bash
$ git describe --dirty --always
```

Space for the output string is allocated within this function, so after using the value you have to **free** the output string. If libgit2 is not installed or the program calling this function is not within a version controlled directory, then the output will be the **NULL** pointer.

### 10.3.28 Unit conversion library (**units.h**)  

Datasets can contain values in various formats or units. The functions in this section are defined to facilitate the easy conversion between them and are declared in **units.h**. If there are certain conversions that are useful for your work, please get in touch.

**int**

**gal_units_extract_decimal** (**char **convert, **const char **delimeter, **double **args, **size_t n**)

Parse the input convert string with a certain delimiter (for example 01:23:45, where the delimiter is ":") as multiple numbers (for example 1,23,45) and write them as an array in the space that **args** is pointing to. The expected number of values in the string is specified by the **n** argument (3 in the example above).
If the function succeeds, it will return 1, otherwise it will return 0 and the values may not be fully written into args. If the number of values parsed in the string is different from n, this function will fail.

```
double gal_units_ra_to_degree (char *convert)
    Convert the input Right Ascension (RA) string (in the format of hours, minutes and seconds either as \_h\_m\_s or \_:\_:\_) to degrees (a single floating point number).
```

```
double gal_units_dec_to_degree (char *convert)
    Convert the input Declination (Dec) string (in the format of degrees, arc-minutes and arc-seconds either as \_d\_m\_s or \_:\_:\_) to degrees (a single floating point number).
```

```
char * gal_units_degree_to_ra (double decimal, int usecolon)
    Convert the input Right Ascension (RA) degree (a single floating point number) to old/standard notation (in the format of hours, minutes and seconds of \_h\_m\_s). If usecolon!=0, then the delimiters between the components will be colons: \_:\_:\_.
```

```
char * gal_units_degree_to_dec (double decimal, int usecolon)
    Convert the input Declination (Dec) degree (a single floating point number) to old/standard notation (in the format of degrees, arc-minutes and arc-seconds of \_d\_m\_s). If usecolon!=0, then the delimiters between the components will be colons: \_:\_:\_.
```

### 10.3.29 Spectral lines library (speclines.h)

gnustro’s library has the following macros and functions for dealing with spectral lines. All these functions are declared in gnuastro/spectra.h.

```
GAL_SPECLINES_INVALID               [Macro]
GAL_SPECLINES_SIIRED                [Macro]
GAL_SPECLINES_SII                   [Macro]
GAL_SPECLINES_SIIBLUE               [Macro]
GAL_SPECLINES_NIIIRED               [Macro]
GAL_SPECLINES_NII                   [Macro]
GAL_SPECLINES_HALPHA                [Macro]
GAL_SPECLINES_NIIBLUE               [Macro]
GAL_SPECLINES_OIIIIRED              [Macro]
GAL_SPECLINES_OIII                  [Macro]
GAL_SPECLINES_OIIIBLUE              [Macro]
GAL_SPECLINES_HBETA                 [Macro]
GAL_SPECLINES_HEIIRED               [Macro]
GAL_SPECLINES_HGAMMA                [Macro]
GAL_SPECLINES_HDELTALATE            [Macro]
GAL_SPECLINES_HEPSILON              [Macro]
GAL_SPECLINES_NEIII                 [Macro]
```
Internal values/identifiers for specific spectral lines as is clear from their names. Note the first and last one, they can be used when parsing the lines automatically: both don’t correspond to any line, but their integer values correspond to the two integers just before and after the first and last line identifier.

`GAL_SPECLINES_INVALID` has a value of zero, and allows you to have a fixed integer which never corresponds to a line. `GAL_SPECLINES_INVALID_MAX` is the total number of pre-defined lines, plus one. So you can parse all the known lines with a `for` loop like this:

```c
for(i=1;i<GAL_SPECLINES_INVALID_MAX;++i)
```

```c
GAL_SPECLINES_ANGSTROM_SIIREDSIIRED
GAL_SPECLINES_ANGSTROM_SII
GAL_SPECLINES_ANGSTROM_SIIBLUE
GAL_SPECLINES_ANGSTROM_NIIREDSIIRED
GAL_SPECLINES_ANGSTROM_NII
GAL_SPECLINES_ANGSTROM_HALPHA
GAL_SPECLINES_ANGSTROM_NIIBLUE
GAL_SPECLINES_ANGSTROM_OIIIREDSIIRED
GAL_SPECLINES_ANGSTROM_OII
GAL_SPECLINES_ANGSTROM_OIIBLUE
GAL_SPECLINES_ANGSTROM_BLIMIT
GAL_SPECLINES_ANGSTROM_MGIIRED
GAL_SPECLINES_ANGSTROM_MGII
GAL_SPECLINES_ANGSTROM_MGIBLUE
GAL_SPECLINES_ANGSTROM_NEIII
GAL_SPECLINES_ANGSTROM_OIII
GAL_SPECLINES_ANGSTROM_OIIIBLUE
GAL_SPECLINES_ANGSTROM_HBETA
GAL_SPECLINES_ANGSTROM_HEIIREDSIIRED
GAL_SPECLINES_ANGSTROM_HGAMMA
GAL_SPECLINES_ANGSTROM_HDELTA
GAL_SPECLINES_ANGSTROM_HEPSILON
GAL_SPECLINES_ANGSTROM_NEII
GAL_SPECLINES_ANGSTROM_OIIIREDSIIRED
GAL_SPECLINES_ANGSTROM_OII
GAL_SPECLINES_ANGSTROM_OIIIBLUE
GAL_SPECLINES_ANGSTROM_BLIMIT
GAL_SPECLINES_ANGSTROM_MGIIRED
GAL_SPECLINES_ANGSTROM_MGII
GAL_SPECLINES_ANGSTROM_MGIBLUE
```
Chapter 10: Library

/GAL_SPECLINES_ANGSTROM_CIIIRED [Macro]
/GAL_SPECLINES_ANGSTROM_CIIII [Macro]
/GAL_SPECLINES_ANGSTROM_CIIIBLUE [Macro]
/GAL_SPECLINES_ANGSTROM_HEIIBLUE [Macro]
/GAL_SPECLINES_ANGSTROM_LYALPHA [Macro]
/GAL_SPECLINES_ANGSTROM_LYLIMIT [Macro]

Wavelength (in Angstroms) of the named lines.

/GAL_SPECLINES_NAME_SIIRED [Macro]
/GAL_SPECLINES_NAME_SII [Macro]
/GAL_SPECLINES_NAME_SIIBLUE [Macro]
/GAL_SPECLINES_NAME_NIIRED [Macro]
/GAL_SPECLINES_NAME_NII [Macro]
/GAL_SPECLINES_NAME_HALPHA [Macro]
/GAL_SPECLINES_NAME_NIIBLUE [Macro]
/GAL_SPECLINES_NAME_OIIIRED [Macro]
/GAL_SPECLINES_NAME_OIII [Macro]
/GAL_SPECLINES_NAME_OIIIBLUE [Macro]
/GAL_SPECLINES_NAME_HBETA [Macro]
/GAL_SPECLINES_NAME_HEIIRED [Macro]
/GAL_SPECLINES_NAME_HGAMMA [Macro]
/GAL_SPECLINES_NAME_HDELTA [Macro]
/GAL_SPECLINES_NAME_HEPSILON [Macro]
/GAL_SPECLINES_NAME_NEIII [Macro]
/GAL_SPECLINES_NAME_OIIRED [Macro]
/GAL_SPECLINES_NAME_OII [Macro]
/GAL_SPECLINES_NAME_OIIBLUE [Macro]
/GAL_SPECLINES_NAME_BLIMIT [Macro]
/GAL_SPECLINES_NAME_MGIIRED [Macro]
/GAL_SPECLINES_NAME_MGII [Macro]
/GAL_SPECLINES_NAME_MGIIBLUE [Macro]
/GAL_SPECLINES_NAME_CIIIRED [Macro]
/GAL_SPECLINES_NAME_CIII [Macro]
/GAL_SPECLINES_NAME_CIIIBLUE [Macro]
/GAL_SPECLINES_NAME_HEIIBLUE [Macro]
/GAL_SPECLINES_NAME_LYALPHA [Macro]
/GAL_SPECLINES_NAME_LYLIMIT [Macro]

Names (as literal stings without any space, all in small-caps) that can be used to refer to the lines in your program and converted to and from line identifiers using the functions below.

char *

/gal_speclines_line_name (int linecode)

Return the literal string of the given spectral line identifier Macro (for example GAL_SPECLINES_HALPHA or GAL_SPECLINES_LYLIMIT).
int gal_speclines_line_code (char *name)
    Return the spectral line identifier of the given standard name (for example GAL_SPECLINES_NAME_HALPHA or GAL_SPECLINES_NAME_LYLIMIT).

double gal_speclines_line_angstrom (int linecode)
    Return the wavelength (in Angstroms) of the given line.

double gal_speclines_line_redshift (double obsline, double restline)
    Return the redshift where the observed wavelength (obsline) was emitted from (if its restframe wavelength was restline).

double gal_speclines_line_redshift_code (double obsline, int linecode)
    Return the redshift where the observed wavelength (obsline) was emitted from (assuming its a specific spectra line, identified with linecode).

10.3.30 Cosmology library (cosmology.h)

This library does the main cosmological calculations that are commonly necessary in extragalactic astronomical studies. The main variable in this context is the redshift (z). The cosmological input parameters in the functions below are H0, o_lambda_0, o_matter_0, o_radiation_0 which respectively represent the current (at redshift 0) expansion rate (Hubble constant in units of km/sec/Mpc), cosmological constant (Λ), matter and radiation densities.

All these functions are declared in gnuastro/cosmology.h. For a more extended introduction/discussion of the cosmological parameters, please see Section 9.1 [CosmicCalculator], page 359.

double gal_cosmology_age (double z, double H0, double o_lambda_0, double o_matter_0, double o_radiation_0)
    Returns the age of the universe at redshift z in units of Giga years.

double gal_cosmology_proper_distance (double z, double H0, double o_lambda_0, double o_matter_0, double o_radiation_0)
    Returns the proper distance to an object at redshift z in units of Mega parsecs.

double gal_cosmology_comoving_volume (double z, double H0, double o_lambda_0, double o_matter_0, double o_radiation_0)
    Returns the comoving volume over 4pi stradian to z in units of Mega parsecs cube.

double gal_cosmology_critical_density (double z, double H0, double o_lambda_0, double o_matter_0, double o_radiation_0)
    Returns the critical density at redshift z in units of g/cm^3.
double gal_cosmology_angular_distance (double z, double H0, double o_lambda_0, double o_matter_0, double o_radiation_0)
Return the angular diameter distance to an object at redshift z in units of Mega parsecs.

double gal_cosmology_luminosity_distance (double z, double H0, double o_lambda_0, double o_matter_0, double o_radiation_0)
Return the luminosity diameter distance to an object at redshift z in units of Mega parsecs.

double gal_cosmology_distance_modulus (double z, double H0, double o_lambda_0, double o_matter_0, double o_radiation_0)
Return the distance modulus at redshift z (with no units).

double gal_cosmology_to_absolute_mag (double z, double H0, double o_lambda_0, double o_matter_0, double o_radiation_0)
Return the conversion from apparent to absolute magnitude for an object at redshift z. This value has to be added to the apparent magnitude to give the absolute magnitude of an object at redshift z.

double gal_cosmology_velocity_from_z (double z)
Return the velocity (in km/s) corresponding to the given redshift (z).

double gal_cosmology_z_from_velocity (double v)
Return the redshift corresponding to the given velocity (v in km/s).

10.4 Library demo programs

In this final section of Chapter 10 [Library], page 372, we give some example Gnuastro programs to demonstrate various features in the library. All these programs have been tested and once Gnuastro is installed you can compile and run them with with Gnuastro’s Section 10.2 [BuildProgram], page 380, program that will take care of linking issues. If you don’t have any FITS file to experiment on, you can use those that are generated by Gnuastro after make check in the tests/ directory, see Section 1.1 [Quick start], page 1.

10.4.1 Library demo - reading a FITS image

The following simple program demonstrates how to read a FITS image into memory and use the void *array pointer in of Section 10.3.6.1 [Generic data container (gal_data_t)], page 400. For easy linking/compilation of this program along with a first run see Section 10.2 [BuildProgram], page 380. Before running, also change the filename and hdu variable values to specify an existing FITS file and/or extension/HDU.

This is just intended to demonstrate how to use the array pointer of gal_data_t. Hence it doesn’t do important sanity checks, for example in real datasets you may also have blank
pixels. In such cases, this program will return a NaN value (see Section 6.1.3 [Blank pixels], page 191). So for general statistical information of a dataset, it is much better to use Gnuastro's Section 7.1 [Statistics], page 248, program which can deal with blank pixels any many other issues in a generic dataset.

```c
#include <stdio.h>
#include <stdlib.h>
#include <gnuastro/fits.h> /* includes gnuastro's data.h and type.h */
#include <gnuastro/statistics.h>

int main(void)
{
    size_t i;
    float *farray;
    double sum=0.0f;
    gal_data_t *image;
    char *filename="img.fits", *hdu="1";

    /* Read 'img.fits' (HDU: 1) as a float32 array. */
    image=gal_fits_img_read_to_type(filename, hdu, GAL_TYPE_FLOAT32,
        -1, 1);

    /* Use the allocated space as a single precision floating
     * point array (recall that 'image->array' has 'void *'
     * type, so it is not directly usable. */
    farray=image->array;

    /* Calculate the sum of all the values. */
    for(i=0; i<image->size; ++i)
        sum += farray[i];

    /* Report the sum. */
    printf("Sum of values in %s (hdu %s) is: %f\n",
        filename, hdu, sum);

    /* Clean up and return. */
    gal_data_free(image);
    return EXIT_SUCCESS;
}
```
10.4.2 Library demo - inspecting neighbors

The following simple program shows how you can inspect the neighbors of a pixel using the `GAL_DIMENSION_NEIGHBOR_OP` function-like macro that was introduced in Section 10.3.7 [Dimensions (dimension.h)], page 408. For easy linking/compilation of this program along with a first run see Section 10.2 [BuildProgram], page 380. Before running, also change the file name and HDU (first and second arguments to `gal_fits_img_read_to_type`) to specify an existing FITS file and/or extension/HDU.

```c
#include <stdio.h>
#include <gnuastro/fits.h>
#include <gnuastro/dimension.h>

int main(void) {
    double sum;
    float *array;
    size_t i, num, *dinc;
    gal_data_t *input=gal_fits_img_read_to_type("input.fits", "1",
        GAL_TYPE_FLOAT32, -1, 1);

    /* To avoid the ‘void *’ pointer and have ‘dinc’. */
    array=input->array;
    dinc=gal_dimension_increment(input->ndim, input->dsize);

    /* Go over all the pixels. */
    for(i=0;i<input->size;++i) {
        num=0;
        sum=0.0f;
        GAL_DIMENSION_NEIGHBOR_OP( i, input->ndim, input->dsize,
            input->ndim, dinc,
            {++num; sum+=array[nind];} );
        printf("%zu: num: %zu, sum: %f\n", i, num, sum);
    }

    /* Clean up and return. */
    gal_data_free(input);
    return EXIT_SUCCESS;
}
```

10.4.3 Library demo - multi-threaded operation

The following simple program shows how to use Gnuastro to simplify spinning off threads and distributing different jobs between the threads. The relevant thread-related functions are defined in Section 10.3.2.2 [Gnuastro's thread related functions], page 388. For easy linking/compilation of this program, along with a first run, see Gnuastro's Section 10.2
Before running, also change the `filename` and `hdu` variable values to specify an existing FITS file and/or extension/HDU.

This is a very simple program to open a FITS image, distribute its pixels between different threads and print the value of each pixel and the thread it was assigned to. The actual operation is very simple (and would not usually be done with threads in a real-life program). It is intentionally chosen to put more focus on the important steps in spinning of threads and how the worker function (which is called by each thread) can identify the job-IDs it should work on.

For example, instead of an array of pixels, you can define an array of tiles or any other context-specific structures as separate targets. The important thing is that each action should have its own unique ID (counting from zero, as is done in an array in C). You can then follow the process below and use each thread to work on all the targets that are assigned to it. Recall that spinning-off threads is its self an expensive process and we don’t want to spin-off one thread for each target (see the description of `gal_threads_dist_in_threads` in Section 10.3.2.2 [Gnuastro’s thread related functions], page 388.

There are many (more complicated, real-world) examples of using `gal_threads_spin_off` in Gnuastro’s actual source code, you can see them by searching for the `gal_threads_spin_off` function from the top source (after unpacking the tarball) directory (for example with this command):

```
$ grep -r gal_threads_spin_off ./
```

The code of this demonstration program is shown below. This program was also built and run when you ran `make check` during the building of Gnuastro (`tests/lib/multithread.c`, so it is already tested for your system and you can safely use it as a guide.

```c
#include <stdio.h>
#include <stdlib.h>
#include <gnuastro/fits.h>
#include <gnuastro/threads.h>

/* This structure can keep all information you want to pass onto the
 * worker function on each thread. */
struct params
{
    gal_data_t *image;  /* Dataset to print values of. */
};

/* This is the main worker function which will be called by the
 * different threads. ‘gal_threads_params’ is defined in
 * ‘gnuastro/threads.h’ and contains the pointer to the parameter we
 * want. Note that the input argument and returned value of this
 * function always must have ‘void *’ type. */
```
void *
worker_on_thread(void *in_prm)
{
    /* Low-level definitions to be done first. */
    struct gal_threads_params *tprm=(struct gal_threads_params *)in_prm;
    struct params *p=(struct params *)tprm->params;

    /* Subsequent definitions. */
    float *array=p->image->array;
    size_t i, index, *dsize=p->image->dsize;

    /* Go over all the actions (pixels in this case) that were assigned
     * to this thread. */
    for(i=0; tprm->indexes[i] != GAL_BLANK_SIZE_T; ++i)
    {
        /* For easy reading. */
        index = tprm->indexes[i];

        /* Print the information. */
        printf("(%zu, %zu) on thread %zu: %g\n", index%dsize[1]+1,
               index/dsize[1]+1, tprm->id, array[index]);
    }

    /* Wait for all the other threads to finish, then return. */
    if(tprm->b) pthread_barrier_wait(tprm->b);
    return NULL;
}

/* High-level function (called by the operating system). */
int
main( void )
{
    struct params p;
    char *filename="input.fits", *hdu="1";
    size_t numthreads=gal_threads_number();

    /* Read the image into memory as a float32 data type. We are using
     * ‘-1’ for ‘minmapsize’ to ensure that the image is read into
     * memory and ‘1’ for ‘quietmmap’ (which can also be zero). */
Chapter 10: Library

10.4.4 Library demo - reading and writing table columns

Tables are some of the most common inputs to, and outputs of programs. This section contains a small program for reading and writing tables using the constructs described in Section 10.3.10 [Table input output (table.h)], page 426. For easy linking/compilation of this program, along with a first run, see Gnuastro's Section 10.2 [BuildProgram], page 380. Before running, also set the following file and column names in the first two lines of main.

This example program reads three columns from a table. The first two columns are selected by their name (NAME1 and NAME2) and the third is selected by its number: column 10 (counting from 1). Gnuastro's column selection is discussed in Section 4.8.3 [Selecting table columns], page 140. The first and second columns can be any type, but this program will convert them to int32_t and float for its internal usage respectively. However, the third column must be double for this program. So if it isn’t, the program will abort with an error. Having the columns in memory, it will print them out along with their sum (just a
simple application, you can do whatever you want at this stage). Reading the table finishes here.

The rest of the program is a demonstration of writing a table. While parsing the rows, this program will change the first column (to be counters) and multiply the second by 10 (so the output will be different). Then it will define the order of the output columns by setting the next element (to create a Section 10.3.8.9 [List of gal_data_t], page 423). Before writing, this function will also set names for the columns (units and comments can be defined in a similar manner). Writing the columns to a file is then done through a simple call to gal_table_write.

The operations that are shown in this example program are not necessary all the time. For example, in many cases, you know the numerical data type of the column before writing your program (see Section 4.6 [Numeric data types], page 130), so type checking and copying to a specific type won’t be necessary.

```c
#include <stdio.h>
#include <stdlib.h>
#include <gnuastro/table.h>

int
main(void)
{
    /* File names and column names (which may also be numbers). */
    char *c1_name="NAME1", *c2_name="NAME2", *c3_name="10";
    char *inname="input.fits", *hdu="1", *outname="out.fits";

    /* Internal parameters. */
    float *array2;
    double *array3;
    int32_t *array1;
    size_t i, counter=0;
    gal_data_t *c1, *c2;
    gal_data_t tmp, *col, *columns;
    gal_list_str_t *column_ids=NULL;

    /* Define the columns to read. */
    gal_list_str_add(&column_ids, c1_name, 0);
    gal_list_str_add(&column_ids, c2_name, 0);
    gal_list_str_add(&column_ids, c3_name, 0);

    /* The columns were added in reverse, so correct it. */
    gal_list_str_reverse(&column_ids);

    /* Read the desired columns. */
    columns = gal_table_read(inname, hdu, column_ids,
                             GAL_TABLE_SEARCH_NAME, 1, -1, 1, NULL);

    /* ... */
    /* End of example program. */
    return 0;
}
```

/* Go over the columns, we’ll assume that you don’t know their type * a-priori, so we’ll check */
counter=1;
for(col=columns; col!=NULL; col=col->next)
    switch(counter++)
    {
    case 1:  /* First column: we want it as int32_t. */
        c1=gal_data_copy_to_new_type(col, GAL_TYPE_INT32);
        array1 = c1->array;
        break;
    case 2:  /* Second column: we want it as float. */
        c2=gal_data_copy_to_new_type(col, GAL_TYPE_FLOAT32);
        array2 = c2->array;
        break;
    case 3:  /* Third column: it MUST be double. */
        if(col->type!=GAL_TYPE_FLOAT64)
        {
            fprintf(stderr, "Column %s must be float64 type, it is "
                        "%s", c3_name, gal_type_name(col->type, 1));
            exit(EXIT_FAILURE);
        }
        array3 = col->array;
        break;
    }

/* As an example application we’ll just print them out. In the * meantime (just for a simple demonstration), change the first * array value to the counter and multiply the second by 10. */
for(i=0;i<c1->size;++i)
    {
        printf("%zu: %d + %f + %f = %f\n", i+1, array1[i], array2[i],
               array3[i], array1[i]+array2[i]+array3[i]);
        array1[i] = i+1;
        array2[i] *= 10;
    }

/* Link the first two columns as a list. */
c1->next = c2;
c2->next = NULL;

/* Set names for the columns and write them out. */
c1->name = "COUNTER";
c2->name = "VALUE";
gal_table_write(c1, NULL, NULL, GAL_TABLE_FORMAT_BFITS, outname,
                "MY-COLUMNS", 0);
/* The names weren’t allocated, so to avoid cleaning-up problems, *
 * we’ll set them to NULL. */
c1->name = c2->name = NULL;

/* Clean up and return. */
gal_data_free(c1);
gal_data_free(c2);
gal_list_data_free(columns);
gal_list_str_free(column_ids, 0); /* strings weren’t allocated. */
return EXIT_SUCCESS;
11 Developing

The basic idea of GNU Astronomy Utilities is for an interested astronomer to be able to easily understand the code of any of the programs or libraries, be able to modify the code if s/he feels there is an improvement and finally, to be able to add new programs or libraries for their own benefit, and the larger community if they are willing to share it. In short, we hope that at least from the software point of view, the “obscurantist faith in the expert’s special skill and in his personal knowledge and authority” can be broken, see Section 1.2 [Science and its tools], page 2. With this aim in mind, Gnuastro was designed to have a very basic, simple, and easy to understand architecture for any interested inquirer.

This chapter starts with very general design choices, in particular Section 11.1 [Why C programming language?], page 516, and Section 11.2 [Program design philosophy], page 518. It will then get a little more technical about the Gnuastro code and file/directory structure in Section 11.3 [Coding conventions], page 519, and Section 11.4 [Program source], page 522. Section 11.4.2 [The TEMPLATE program], page 525, discusses a minimal (and working) template to help in creating new programs or easier learning of a program’s internal structure. Some other general issues about documentation, building and debugging are then discussed. This chapter concludes with how you can learn about the development and get involved in Section 11.9 [Gnuastro project webpage], page 530, Section 11.10 [Developing mailing lists], page 531, and Section 11.11 [Contributing to Gnuastro], page 532.

11.1 Why C programming language?

Currently the programming language that is most commonly used in scientific applications is C++\(^1\), Python\(^2\), and Julia\(^3\) (which is a newcomer but swiftly gaining ground). One of the main reasons behind this choice is their high-level abstractions. However, GNU Astronomy Utilities is fully written in the C programming language\(^4\). The reasons can be summarized with simplicity, portability and efficiency/speed. All three are very important in a scientific software and we will discuss them below.

Simplicity can best be demonstrated in a comparison of the main books of C++ and C. The “C programming language”\(^5\) book, written by the authors of C, is only 286 pages and covers a very good fraction of the language, it has also remained unchanged from 1988. C is the main programming language of nearly all operating systems and there is no plan of any significant update. On the other hand, the most recent “C++ programming language”\(^6\) book, also written by its author, has 1366 pages and its fourth edition came out in 2013! As discussed in Section 1.2 [Science and its tools], page 2, it is very important for other scientists to be able to readily read the code of a program at their will with minimum requirements.

In C++, inheriting objects in the object oriented programming paradigm and their internal functions make the code very easy to write for a programmer who is deeply invested in

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1 https://isocpp.org/
2 https://www.python.org/
3 https://julialang.org/
4 https://en.wikipedia.org/wiki/C_(programming_language)
Chapter 11: Developing

those objects and understands all their relations well. But it simultaneously makes reading
the program for a first time reader (a curious scientist who wants to know only how a small
step was done) extremely hard. Before understanding the methods, the scientist has to
invest a lot of time and energy in understanding those objects and their relations. But
in C, everything is done with basic language types for example ints or floats and their
pointers to define arrays. So when an outside reader is only interested in one part of the
program, that part is all they have to understand.

Recently it is also becoming common to write scientific software in Python, or a combi-
nation of it with C or C++. Python is a high level scripting language which doesn't need
compilation. It is very useful when you want to do something on the go and don't want to
be halted by the troubles of compiling, linking, memory checking, etc. When the datasets
are small and the job is temporary, this ability of Python is great and is highly encouraged.
A very good example might be plotting, in which Python is undoubtedly one of the best.

But as the data sets increase in size and the processing becomes more complicated, the
speed of Python scripts significantly decrease. So when the program doesn't change too
often and is widely used in a large community, mostly on large data sets (like astronomical
images), using Python will waste a lot of valuable research-hours. It is possible to wrap
C or C++ functions with Python to fix the speed issue. But this creates further complex-
ity, because the interested scientist has to master two programming languages and their
connection (which is not trivial).

Like C++, Python is object oriented, so as explained above, it needs a high level of
experience with that particular program to reasonably understand its inner workings. To
make things worse, since it is mainly for on-the-go programming\(^7\), it can undergo significant
changes. One recent example is how Python 2.x and Python 3.x are not compatible. Lots
of research teams that invested heavily in Python 2.x cannot benefit from Python 3.x or
future versions any more. Some converters are available, but since they are automatic, lots
of complications might arise in the conversion\(^8\).

If a research project begins using Python 3.x today, there is no telling how compatible
their investments will be when Python 4.x or 5.x will come out. This stems from the core
principles of Python, which are very useful when you look in the 'on the go' basis as described
before and not future usage. Reproducibility (ability to run the code in the future) is a core
principal of any scientific result, or the software that produced that result. Rebuilding all
the dependencies of a software in an obsolete language is not easy. Future-proof code (as
long as current operating systems will be used) is written in C.

The portability of C is best demonstrated by the fact that both C++ and Python are
part of the C-family of programming languages which also include Julia, Java, Perl, and
many other languages. C libraries can be immediately included in C++, and it is easy to
write wrappers for them in all C-family programming languages. This will allow other
scientists to benefit from C libraries using any C-family language that they prefer. As a
result, Gnuastro's library is already usable in C and C++, and wrappers will be\(^9\) added for
higher-level languages like Python, Julia and Java.

\(^7\) Note that Python is good for fast programming, not fast programs.
\(^8\) For example see Jenness (2017) (https://arxiv.org/abs/1712.00461) which describes how LSST is
managing the transition.
\(^9\) http://savannah.gnu.org/task/?13786
Chapter 11: Developing

The final reason was speed. This is another very important aspect of C which is not independent of simplicity (first reason discussed above). The abstractions provided by the higher-level languages (which also makes learning them harder for a newcomer) comes at the cost of speed. Since C is a low-level language\(^\text{10}\) (closer to the hardware), it is much less complex for both the human reader and the computer. The benefits of simplicity for a human were discussed above. Simplicity for the computer translates into more efficient (faster) programs. This creates a much closer relation between the scientist/programmer (or their program) and the actual data and processing. The GNU coding standards\(^\text{11}\) also encourage the use of C over all other languages when generality of usage and “high speed” is desired.

11.2 Program design philosophy

The core processing functions of each program (and all libraries) are written mostly with the basic ISO C90 standard. We do make lots of use of the GNU additions to the C language in the GNU C library\(^\text{12}\), but these functions are mainly used in the user interface functions (reading your inputs and preparing them prior to or after the analysis). The actual algorithms, which most scientists would be more interested in, are much more closer to ISO C90. For this reason, program source files that deal with user interface issues and those doing the actual processing are clearly separated, see Section 11.4 [Program source], page 522. If anything particular to the GNU C library is used in the processing functions, it is explained in the comments in between the code.

All the Gnuastro programs provide very low level and modular operations (modeled on GNU Coreutils). Almost all the basic command-line programs like `ls`, `cp` or `rm` on GNU/Linux operating systems are part of GNU Coreutils. This enables you to use shell scripting languages (for example GNU Bash) to operate on a large number of files or do very complex things through the creative combinations of these tools that the authors had never dreamed of. We have put a few simple examples in Chapter 2 [Tutorials], page 16.

For example all the analysis output can be saved as ASCII tables which can be fed into your favorite plotting program to inspect visually. Python’s Matplotlib is very useful for fast plotting of the tables to immediately check your results. If you want to include the plots in a document, you can use the PGFplots package within \LaTeX, no attempt is made to include such operations in Gnuastro. In short, Bash can act as a glue to connect the inputs and outputs of all these various Gnuastro programs (and other programs) in any fashion. Of course, Gnuastro’s programs are just front-ends to the main workhorse (Section 10.3 [Gnuastro library], page 384), allowing a user to create their own programs (for example with Section 10.2 [BuildProgram], page 380). So once the functions within programs become mature enough, they will be moved within the libraries for even more general applications.

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\(^{10}\) Low-level languages are those that directly operate the hardware like assembly languages. So C is actually a high-level language, but it can be considered one of the lowest-level languages among all high-level languages.

\(^{11}\) http://www.gnu.org/prep/standards/

\(^{12}\) Gnuastro uses many GNU additions to the C library. However, thanks to the GNU Portability library (Gnulib) which is included in the Gnuastro tarball, users of non-GNU/Linux operating systems can also benefit from all these features when using Gnuastro.
The advantage of this architecture is that the programs become small and transparent: the starting and finishing point of every program is clearly demarcated. For nearly all operations on a modern computer (fast file input-output) with a modest level of complexity, the read/write speed is insignificant compared to the actual processing a program does. Therefore the complexity which arises from sharing memory in a large application is simply not worth the speed gain. Gnuastro’s design is heavily influenced from Eric Raymond’s “The Art of Unix Programming”\textsuperscript{13} which beautifully describes the design philosophy and practice which lead to the success of Unix-based operating systems\textsuperscript{14}.

### 11.3 Coding conventions

In Gnuastro, we try our best to follow the GNU coding standards. Added to those, Gnuastro defines the following conventions. It is very important for readability that the whole package follows the same convention.

- The code must be easy to read by eye. So when the order of several lines within a function does not matter (for example when defining variables at the start of a function). You should put the lines in the order of increasing length and group the variables with similar types such that this half-pyramid of declarations becomes most visible. If the reader is interested, a simple search will show them the variable they are interested in. However, this visual aid greatly helps in general inspections of the code and help the reader get a grip of the function’s processing.

- A function that cannot be fully displayed (vertically) in your monitor is probably too long and may be more useful if it is broken up into multiple functions. 40 lines is usually a good reference. When the start and end of a function are clearly visible in one glance, the function is much more easier to understand. This is most important for low-level functions (which usually define a lot of variables). Low-level functions do most of the processing, they will also be the most interesting part of a program for an inquiring astronomer. This convention is less important for higher level functions that don’t define too many variables and whose only purpose is to run the lower-level functions in a specific order and with checks.

In general you can be very liberal in breaking up the functions into smaller parts, the GNU Compiler Collection (GCC) will automatically compile the functions as inline functions when the optimizations are turned on. So you don’t have to worry about decreasing the speed. By default Gnuastro will compile with the -O3 optimization flag.

- All Gnuastro hand-written text files (C source code, Texinfo documentation source, and version control commit messages) should not exceed 75 characters per line. Monitors today are certainly much wider, but with this limit, reading the functions becomes much more easier. Also for the developers, it allows multiple files (or multiple views of one file) to be displayed beside each other on wide monitors. Emacs’s buffers are excellent for this capability, setting a buffer width of 80 with ‘C-u 80 C-x 3’ will allow you to view and work on several files or different parts of one file using the wide monitors common today. Emacs buffers can also be used as a shell prompt and compile the program (with M-x compile), and 80 characters is the default.

---


\textsuperscript{14} KISS principle: Keep It Simple, Stupid!
width in most terminal emulators. If you use Emacs, Gnuastro sets the 75 character
\texttt{fill-column} variable automatically for you, see cartouche below.

For long comments you can use press $\texttt{Alt-q}$ in Emacs to separate them into separate
lines automatically. For long literal strings, you can use the fact that in C, two strings
immediately after each other are concatenated, for example "\texttt{The first part, }" "\texttt{and}
\texttt{the second part}.	exttt{"}. Note the space character in the end of the first part. Since they
are now separated, you can easily break a long literal string into several lines and adhere
to the maximum 75 character line length policy.

- The headers required by each source file (ending with .c) should be defined inside
  of it. All the headers a complete program needs should \textit{not} be stacked in another
  header to include in all source files (for example \texttt{main.h}). Although most ‘professional’
  programmers choose this single header method, Gnuastro is primarily written for pro-
  fessional/inquisitive astronomers (who are generally amateur programmers). The list
  of header files included provides valuable general information and helps the reader.
  \texttt{main.h} may only include the header file(s) that define types that the main program
  structure needs, see \texttt{main.h} in Section 11.4 [Program source], page 522. Those partic-
  ular header files that are included in \texttt{main.h} can of course be ignored (not included)
in separate source files.

- The headers should be classified (by an empty line) into separate groups:
  1. $\texttt{#include \langle config.h\rangle}$: This must be the first code line (not commented or blank)
in each source file \textit{within Gnuastro}. It sets macros that the GNU Portability
  Library (Gnulib) will use for a unified environment (GNU C Library), even when
  the user is building on a system that doesn’t use the GNU C library.
  2. The C library header files, for example \texttt{stdio.h}, \texttt{stdlib.h}, or \texttt{math.h}.
  3. Installed library header files, including Gnuastro’s installed headers (for example
  \texttt{cfitsio.h} or \texttt{gsl/gsl_rng.h}, or \texttt{gnuastro/fits.h}).
  4. Gnuastro’s internal headers (that are not installed), for example
  \texttt{gnuastro-internal/options.h}.
  5. For programs, the \texttt{main.h} file (which is needed by the next group of headers).
  6. That particular program’s header files, for example \texttt{mkprof.h}, or \texttt{noisechisel.h}.

As much as order does not matter when you include the header of each group, sort
them by length, as described above.

- All function names, variables, etc should be in lower case. Macros and constant global
  \texttt{enums} should be in upper case.

- For the naming of exported header files, functions, variables, macros, and library
  functions, we adopt similar conventions to those used by the GNU Scientific Library
  (GSL)\textsuperscript{15}. In particular, in order to avoid clashes with the names of functions and vari-
  ables coming from other libraries the name-space ‘gal\_’ is prefixed to them. GAL
  stands for GNU Astronomy Library.

- All installed header files should be in the \texttt{lib/gnuastro} directory (under the
top Gnuastro source directory). After installation, they will be put in the
\texttt{$prefix/include/gnuastro} directory (see Section 3.3.1.2 [Installation directory],

\textsuperscript{15} https://www.gnu.org/software/gsl/design/gsl-design.html#SEC15
Therefore with this convention Gnuastro’s headers can be included in internal (to Gnuastro) and external (a library user) source files with the same line

```c
#include <gnuastro/headername.h>
```

Note that the GSL convention for header file names is `gsl_specialname.h`, so your include directive for a GSL header must be something like `#include <gsl/gsl_specialname.h>`. Gnuastro doesn’t follow this GSL guideline because of the repeated `gsl` in the include directive. It can be confusing and cause bugs for beginners. All Gnuastro (and GSL) headers must be located within a unique directory and will not be mixed with other headers. Therefore the `gsl_` prefix to the header file names is redundant.\(^{16}\)

- All installed functions and variables should also include the base-name of the file in which they are defined as prefix, using underscores to separate words.\(^ {17}\) The same applies to exported macros, but in upper case. For example in Gnuastro’s top source directory, the prototype of function `gal_box_border_from_center` is in `lib/gnuastro/box.h`, and the macro `GAL_POLYGON_MAX_CORNERS` is defined in `lib/gnuastro/polygon.h`.

This is necessary to give any user (who is not familiar with the library structure) the ability to follow the code. This convention makes the function names longer (a little harder to write), but the extra documentation it provides plays an important role in Gnuastro and is worth the cost.

- There should be no trailing white space in a line. To do this automatically every time you save a file in Emacs, add the following line to your `~/.emacs` file.

```emacs
(add-hook 'before-save-hook 'delete-trailing-whitespace)
```

- There should be no tabs in the indentation.\(^ {18}\)

- Individual, contextually similar, functions in a source file are separated by 5 blank lines to be easily seen to be related in a group when parsing the source code by eye. In Emacs you can use `CTRL-u 5 CTRL-o`.

- One group of contextually similar functions in a source file is separated from another with 20 blank lines. In Emacs you can use `CTRL-u 20 CTRL-o`. Each group of functions has short descriptive title of the functions in that group. This title is surrounded by asterisks (*) to make it clearly distinguishable. Such contextual grouping and clear title are very important for easily understanding the code.

- Always read the comments before the patch of code under it. Similarly, try to add as many comments as you can regarding every patch of code. Effectively, we want someone to get a good feeling of the steps, without having to read the C code and only by reading the comments. This follows similar principles as Literate programming (https://en.wikipedia.org/wiki/Literate_programming).

---

\(^{16}\) For GSL, this prefix has an internal technical application: GSL’s architecture mixes installed and not-installed headers in the same directory. This prefix is used to identify their installation status. Therefore this filename prefix in GSL is a technical internal issue (for developers, not users).

\(^{17}\) The convention to use underscores to separate words, called “snake case” (or “snake_case”). This is also recommended by the GNU coding standards.

\(^{18}\) If you use Emacs, Gnuastro’s `.dir-locals.el` file will automatically never use tabs for indentation. To make this a default in all your Emacs sessions, you can add the following line to your `~/.emacs` file:

```emacs
(setq-default indent-tabs-mode nil)
```
The last two conventions are not common and might benefit from a short discussion here. With a good experience in advanced text editor operations, the last two are redundant for a professional developer. However, recall that Gnuastro aspires to be friendly to unfamiliar, and inexperienced (in programming) eyes. In other words, as discussed in Section 1.2 [Science and its tools], page 2, we want the code to appear welcoming to someone who is completely new to coding (and text editors) and only has a scientific curiosity.

Newcomers to coding and development, who are curious enough to venture into the code, will probably not be using (or have any knowledge of) advanced text editors. They will see the raw code in the webpage or on a simple text editor (like Gedit) as plain text. Trying to learn and understand a file with dense functions that are all spaced with one or two blank lines can be very daunting for a newcomer. But when they scroll through the file and see clear titles and meaningful spaces for similar functions, we are helping them find and focus on the part they are most interested in sooner and easier.

**GNU Emacs, the recommended text editor:** GNU Emacs is an extensible and easily customizable text editor which many programmers rely on for developing due to its countless features. Among them, it allows specification of certain settings that are applied to a single file or to all files in a directory and its sub-directories. In order to harmonize code coming from different contributors, Gnuastro comes with a `dir-locals.el` file which automatically configures Emacs to satisfy most of the coding conventions above when you are using it within Gnuastro's directories. Thus, Emacs users can readily start hacking into Gnuastro. If you are new to developing, we strongly recommend this editor. Emacs was the first project released by GNU and is still one of its flagship projects. Some resources can be found at:

Official manual
At [https://www.gnu.org/software/emacs/manual/emacs.html](https://www.gnu.org/software/emacs/manual/emacs.html). This is a great and very complete manual which is being improved for over 30 years and is the best starting point to learn it. It just requires a little patience and practice, but rest assured that you will be rewarded. If you install Emacs, you also have access to this manual on the command-line with the following command (see Section 4.3.4 [Info], page 125).

```
$ info emacs
```

A guided tour of emacs

Unofficial mini-manual

### 11.4 Program source

Besides the fact that all the programs share some functions that were explained in Chapter 10 [Library], page 372, everything else about each program is completely independent. Recall that Gnuastro is written for an active astronomer/scientist (not a
Chapter 11: Developing

passive one who just uses a software). It must thus be easily navigable. Hence there are
fixed source files (that contain fixed operations) that must be present in all programs, these
are discussed fully in Section 11.4.1 [Mandatory source code files], page 523. To easily
understand the explanations in this section you can use Section 11.4.2 [The TEMPLATE
program], page 525, which contains the bare minimum code for one working program. This
template can also be used to easily add new utilities: just copy and paste the directory
and change TEMPLATE with your program’s name.

11.4.1 Mandatory source code files

Some programs might need lots of source files and if there is no fixed convention, navigating
them can become very hard for a new inquirer into the code. The following source files
exist in every program’s source directory (which is located in bin/progname). For small
programs, these files are enough. Larger programs will need more files and developers are
encouraged to define any number of new files. It is just important that the following list
of files exist and do what is described here. When creating other source files, please choose
filenames that are a complete single word: don’t abbreviate (abbreviations are cryptic). For
a minimal program containing all these files, see Section 11.4.2 [The TEMPLATE program],
page 525.

main.c  Each executable has a main function, which is located in main.c. Therefore this
file is the starting point when reading any program’s source code. No actual
processing functions must be defined in this file, the function(s) in this file are
only meant to connect the most high level steps of each program. Generally,
main will first call the top user interface function to read user input and make
all the preparations. Then it will pass control to the top processing function
for that program. The functions to do both these jobs must be defined in other
source files.

main.h  All the major parameters which will be used in the program must be stored
in a structure which is defined in main.h. The name of this structure is usu-
ally progrnameparams, for example cropparams or noisechiselparams. So
#include "main.h" will be a staple in all the source codes of the program. It
is also regularly the first (and only) argument most of the program’s functions
which greatly helps in readability.

Keeping all the major parameters of a program in this structure has the major
benefit that most functions will only need one argument: a pointer to this struc-
ture. This will significantly facilitate the job of the programmer, the inquirer
and the computer. All the programs in Gnuastro are designed to be low-level,
small and independent parts, so this structure should not get too large.

The main root structure of all programs contains at least one instance of the
gal_options_common_params structure. This structure will keep the values
to all common options in Gnuastro’s programs (see Section 4.1.2 [Common
options], page 109). This top root structure is conveniently called p (short
for parameters) by all the functions in the programs and the common options
parameters within it are called cp. With this convention any reader can im-
mediately understand where to look for the definition of one parameter. For
example you know that p->cp->output is in the common parameters while
p->threshold is in the program’s parameters.
With this basic root structure, source code of functions can potentially become full of structure de-reference operators (\(-\rightarrow\)) which can make the code very unreadable. In order to avoid this, whenever a structure element is used more than a couple of times in a function, a variable of the same type and with the same name (so it can be searched) as the desired structure element should be defined with the value of the root structure inside of it in definition time. Here is an example.

```c
char *hdu=p->cp.hdu;
float threshold=p->threshold;
```

**args.h** The options particular to each program are defined in this file. Each option is defined by a block of parameters in *program_options*. These blocks are all you should modify in this file, leave the bottom group of definitions untouched. These are fed directly into the GNU C library’s Argp facilities and it is recommended to have a look at that for better understand what is going on, although this is not required here.

Each element of the block defining an option is described under *argp_option* in *bootstrapped/lib/argp.h* (from Gnuastro’s top source file). Note that the last few elements of this structure are Gnuastro additions (not documented in the standard Argp manual). The values to these last elements are defined in *lib/gnuastro/type.h* and *lib/gnuastro-internal/options.h* (from Gnuastro’s top source directory).

**ui.h** Besides declaring the exported functions of *ui.c*, this header also keeps the “key”s to every program-specific option. The first class of keys for the options that have a short-option version (single letter, see Section 4.1.1.2 [Options], page 107). The character that is defined here is the option’s short option name. The list of available alphabet characters can be seen in the comments. Recall that some common options also take some characters, for those, see *lib/gnuastro-internal/options.h*.

The second group of options are those that don’t have a short option alternative. Only the first in this group needs a value (1000), the rest will be given a value by C’s *enum* definition, so the actual value is irrelevant and must never be used, always use the name.

**ui.c** Everything related to reading the user input arguments and options, checking the configuration files and checking the consistency of the input parameters before the actual processing is run should be done in this file. Since most functions are the same, with only the internal checks and structure parameters differing. We recommend going through the *ui.c* of Section 11.4.2 [The TEMPLATE program], page 525, or several other programs for a better understanding.

The most high-level function in *ui.c* is named *ui_read_check_inputs_setup*. It accepts the raw command-line inputs and a pointer to the root structure for that program (see the explanation for *main.h*). This is the function that *main* calls. The basic idea of the functions in this file is that the processing functions should need a minimum number of such checks. With this convention an inquirer who only wants to understand only one part (mostly the processing part and not user input details and sanity checks) of the code can easily do so
in the later files. It also makes all the errors related to input appear before the processing begins which is more convenient for the user.

**proname.c, proname.h**

The high-level processing functions in each program are in a file named **proname.c**, for example `crop.c` or `noisechisel.c`. The function within these files which `main` calls is also named after the program, for example

```c
void
crop(struct cropparams *p)
```
or

```c
void
noisechisel(struct noisechiselparams *p)
```

In this manner, if an inquirer is interested the processing steps, they can immediately come and check this file for the first processing step without having to go through `main.c` and `ui.c` first. In most situations, any failure in any step of the programs will result in an informative error message and an immediate abort in the program. So there is usually no need for return values. Under more complicated situations where a return value might be necessary, `void` will be replaced with an `int` in the examples above. This value must be directly returned by `main`, so it has to be an `int`.

**authors-cite.h**

This header file keeps the global variable for the program authors and its BibTeX record for citation. They are used in the outputs of the common options `--version` and `--cite`, see Section 4.1.2.3 [Operating mode options], page 114.

### 11.4.2 The TEMPLATE program

The extra creativity offered by libraries comes at a cost: you have to actually write your `main` function and get your hands dirty in managing user inputs: are all the necessary parameters given a value? is the input in the correct format? do the options and the inputs correspond? and many other similar checks. So when an operation has well-defined inputs and outputs and is commonly needed, it is much more worthwhile to simply do use all the great features that Gnuastro has already defined for such operations.

To make it easier to learn/apply the internal program infra-structure discussed in Section 11.4.1 [Mandatory source code files], page 523, in the Section 3.2.2 [Version controlled source], page 85, Gnuastro ships with a template program. This template program is not available in the Gnaastro tarball so it doesn’t confuse people using the tarball. The `bin/TEMPLATE` directory in Gnuastro’s Git repository contains the bare-minimum files necessary to define a new program and all the basic/necessary files/functions are pre-defined there.

Below you can see a list of initial steps to take for customizing this template. We just assume that after cloning Gnuastro’s history, you have already bootstrapped Gnuastro, if not, please see Section 3.2.2.1 [Bootstrapping], page 86.

1. Select a name for your new program (for example `myprog`).
2. Copy the `TEMPLATE` directory to a directory with your program’s name:

   ```
   $ cp -R bin/TEMPLATE bin/myprog
   ```
3. As with all source files in Gnuastro, all the files in template also have a copyright notice at their top. Open all the files and correct these notices: 1) The first line contains a single-line description of the program. 2) In the second line only the name or your program needs to be fixed and 3) Add your name and email as a “Contributing author”. As your program grows, you will need to add new files, don’t forget to add this notice in those new files too, just put your name and email under “Original author” and correct the copyright years.

4. Open configure.ac in the top Gnuastro source. This file manages the operations that are done when a user runs ./configure. Going down the file, you will notice repetitive parts for each program. You will notice that the program names follow an alphabetic ordering in each part. There is also a commented line/patch for the TEMPLATE program in each part. You can copy one line/patch (from the program above or below your desired name for example) and paste it in the proper place for your new program. Then correct the names of the copied program to your new program name. There are multiple places where this has to be done, so be patient and go down to the bottom of the file. Ultimately add bin/myprog/Makefile to AC_CONFIG_FILES, only here the ordering depends on the length of the name (it isn’t alphabetical).

5. Open Makefile.am in the top Gnuastro source. Similar to the previous step, add your new program similar to all the other programs. Here there are only two places: 1) at the top where we define the conditionals (three lines per program), and 2) immediately under it as part of the value for SUBDIRS.

6. Open doc/Makefile.am and similar to Makefile.am (above), add the proper entries for the man-page of your program to be created (here, the variable that keeps all the man-pages to be created is dist_man_MANS). Then scroll down and add a rule to build the man-page similar to the other existing rules (in alphabetical order). Don’t forget to add a short one-line description here, it will be displayed on top of the man-page.

7. Change TEMPLATE.c and TEMPLATE.h to myprog.c and myprog.h in the file names:

```bash
$ cd bin/myprog
$ mv TEMPLATE.c myprog.c
$ mv TEMPLATE.h myprog.h
```

8. Correct all occurrences of TEMPLATE in the input files to myprog (in short or long format). You can get a list of all occurrences with the following command. If you use Emacs, it will be able to parse the Grep output and open the proper file and line automatically. So this step can be very easy.

```bash
$ grep --color -nHi -e template *
```

9. Run the following commands to re-build the configuration and build system, and then to configure and build Gnuastro (which now includes your exciting new program).

```bash
$ autoreconf -f
$ .configure
$ make
```

10. You are done! You can now start customizing your new program to do your special processing. When its complete, just don’t forget to add checks also, so it can be tested at least once on a user’s system with make check, see Section 11.7 [Test scripts], page 529. Finally, if you would like to share it with all Gnuastro users, inform us so we merge it into Gnuastro’s main history.
11.5 Documentation

Documentation (this book) is an integral part of Gnuastro (see Section 1.2 [Science and its tools], page 2). Documentation is not considered a separate project and must be written by its developers. Users can make edits/corrections, but the initial writing must be by the developer. So, no change is considered valid for implementation unless the respective parts of the book have also been updated. The following procedure can be a good suggestion to take when you have a new idea and are about to start implementing it.

The steps below are not a requirement, the important thing is that when you send your work to be included in Gnuastro, the book and the code have to both be fully up-to-date and compatible, with the purpose of the update very clearly explained. You can follow any strategy you like, the following strategy was what we have found to be most useful until now.

1. Edit the book and fully explain your desired change, such that your idea is completely embedded in the general context of the book with no sense of discontinuity for a first time reader. This will allow you to plan the idea much more accurately and in the general context of Gnuastro (a particular program or library). Later on, when you are coding, this general context will significantly help you as a road-map.

A very important part of this process is the program/library introduction. These first few paragraphs explain the purposes of the program or library and are fundamental to Gnuastro. Before actually starting to code, explain your idea’s purpose thoroughly in the start of the respective/new section you wish to work on. While actually writing its purpose for a new reader, you will probably get some valuable and interesting ideas that you hadn’t thought of before. This has occurred several times during the creation of Gnuastro.

If an introduction already exists, embed or blend your idea’s purpose with the existing introduction. We emphasize that doing this is equally useful for you (as the programmer) as it is useful for the user (reader). Recall that the purpose of a program is very important, see Section 11.2 [Program design philosophy], page 518.

As you have already noticed for every program/library, it is very important that the basics of the science and technique be explained in separate subsections prior to the ‘Invoking Programname’ subsection. If you are writing a new program or your addition to an existing program involves a new concept, also include such subsections and explain the concepts so a person completely unfamiliar with the concepts can get a general initial understanding. You don’t have to go deep into the details, just enough to get an interested person (with absolutely no background) started with some good pointers/links to where they can continue studying if they are more interested. If you feel you can’t do that, then you have probably not understood the concept yourself. If you feel you don’t have the time, then think about yourself as the reader in one year: you will forget almost all the details, so now that you have done all the theoretical preparations, add a few more hours and document it. Therefore in one year, when you find a bug or want to add a new feature, you don’t have to prepare as much. Have in mind that your only limitation in length is the fatigue of the reader after reading a long text, nothing else. So as long as you keep it relevant/interesting for the reader, there is no page number limit/cost.
Chapter 11: Developing

It might also help if you start discussing the usage of your idea in the ‘Invoking Pro-
gramName’ subsection (explaining the options and arguments you have in mind) at
this stage too. Actually starting to write it here will really help you later when you are
coding.

2. After you have finished adding your initial intended plan to the book, then start coding
your change or new program within the Gnuastro source files. While you are coding,
you will notice that somethings should be different from what you wrote in the book
(your initial plan). So correct them as you are actually coding, but don’t worry too
much about missing a few things (see the next step).

3. After your work has been fully implemented, read the section documentation from the
start and see if you didn’t miss any change in the coding and to see if the context
is fairly continuous for a first time reader (who hasn’t seen the book or had known
Gnuastro before you made your change).

4. If the change is notable, also update the NEWS file.

11.6 Building and debugging

To build the various programs and libraries in Gnuastro, the GNU build system is used
which defines the steps in Section 1.1 [Quick start], page 1. It consists of GNU Autoconf,
GNU Automake and GNU Libtool which are collectively known as GNU Autotools. They
provide a very portable system to check the hosts environment and compile Gnuastro based
on that. They also make installing everything in their standard places very easy for the
programmer. Most of the small caps files that you see in the top source directory of
the tarball are created by these three tools (see Section 3.2.2 [Version controlled source],
page 85). To facilitate the building and testing of your work during development, Gnuastro
comes with two useful scripts:

developer-build
This is more fully described in Section 3.3.1.4 [Configure and build in RAM],
page 98. During development, you will usually run this command only once (at
the start of your work).

tests/during-dev.sh
This script is designed to be run each time you make a change and want to test
your work (with some possible input and output). The script itself is heavily
commented and thoroughly describes the best way to use it, so we won’t repeat
it here.

As a short summary: you specify the build directory, an output directory (for
the built program to be run in, and also contains the inputs), the program’s
short name and the arguments and options that it should be run with. This
script will then build Gnuastro, go to the output directory and run the built
executable from there. One option for the output directory might be your
desktop, so you can easily see the output files and delete them when you are
finished. The main purpose of these scripts is to keep your source directory
clean and facilitate your development.

By default all the programs are compiled with optimization flags for increased speed. A
side effect of optimization is that valuable debugging information is lost. All the libraries
are also linked as shared libraries by default. Shared libraries further complicate the debugging process and significantly slow down the compilation (the `make` command). So during development it is recommended to configure Gnuastro as follows:

```
$ ./configure --enable-debug
```

In `developer-build` you can ask for this behavior through the `--debug` option, see Section 3.3.2 [Separate build and source directories], page 98.

In order to understand the building process, you can go through the Autoconf, Automake and Libtool manuals, like all GNU manuals they provide both a great tutorial and technical documentation. The “A small Hello World” section in Automake’s manual (in chapter 2) can be a good starting guide after you have read the separate introductions.

### 11.7 Test scripts

As explained in Section 3.3.3 [Tests], page 101, for every program some simple tests are written to check the various independent features of the program. All the tests are placed in the `tests/` directory. The `tests/prepconf.sh` script is the first ‘test’ that will be run. It will copy all the configuration files from the various directories to a `tests/.gnuastro` directory (which it will make) so the various tests can set the default values. This script will also make sure the programs don’t go searching for user and system wide configuration files to avoid the mixing of values with different Gnuastro version on the system.

For each program, the tests are placed inside directories with the program name. Each test is written as a shell script. The last line of this script is the test which runs the program with certain parameters. The return value of this script determines the fate of the test, see the “Support for test suites” chapter of the Automake manual for a very nice and complete explanation. In every script, two variables are defined at first: `prog` and `execname`. The first specifies the program name and the second the location of the executable.

The most important thing to have in mind about all the test scripts is that they are run from inside the `tests/` directory in the “build tree”. Which can be different from the directory they are stored in (known as the “source tree”)\(^\text{19}\). This distinction is made by GNU Autoconf and Automake (which configure, build and install Gnuastro) so that you can install the program even if you don’t have write access to the directory keeping the source files. See the “Parallel build trees (a.k.a VPATH builds)” in the Automake manual for a nice explanation.

Because of this, any necessary inputs that are distributed in the tarball\(^\text{20}\), for example the catalogs necessary for checks in MakeProfiles and Crop, must be identified with the `$topsrc` prefix instead of `./` (for the top source directory that is unpacked). This `$topsrc` variable points to the source tree where the script can find the source data (it is defined in `tests/Makefile.am`). The executables and other test products were built in the build tree (where they are being run), so they don’t need to be prefixed with that variable. This is also true for images or files that were produced by other tests.

\(^{19}\) The `developer-build` script also uses this feature to keep the source and build directories separate (see Section 3.3.2 [Separate build and source directories], page 98).

\(^{20}\) In many cases, the inputs of a test are outputs of previous tests, this doesn’t apply to this class of inputs. Because all outputs of previous tests are in the “build tree”.

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11.8 Developer’s checklist

This is a checklist of things to do after applying your changes/additions in Gnuastro:

1. If the change is non-trivial, write test(s) in the `tests/progname/` directory to test the change(s)/addition(s) you have made. Then add their file names to `tests/Makefile.am`.

2. Run `$ make check` to make sure everything is working correctly.

3. Make sure the documentation (this book) is completely up to date with your changes, see Section 11.5 [Documentation], page 527.

4. Commit the change to your issue branch (see Section 11.11.3 [Production workflow], page 535, and Section 11.11.4 [Forking tutorial], page 536). Afterwards, run Autoreconf to generate the appropriate version number:

   ```
   $ autoreconf -f
   ```

5. Finally, to make sure everything will be built, installed and checked correctly run the following command (after re-configuring, and re-building). To greatly speed up the process, use multiple threads (8 in the example below, change it appropriately)

   ```
   $ make distcheck -j8
   ```

   This command will create a distribution file (ending with `.tar.gz`) and try to compile it in the most general cases, then it will run the tests on what it has built in its own mini-environment. If `$ make distcheck` finishes successfully, then you are safe to send your changes to us to implement or for your own purposes. See Section 11.11.3 [Production workflow], page 535, and Section 11.11.4 [Forking tutorial], page 536.

11.9 Gnuastro project webpage

Gnuastro’s central management hub ([https://savannah.gnu.org/projects/gnuastro/](https://savannah.gnu.org/projects/gnuastro/))\(^{21}\) is located on GNU Savannah ([https://savannah.gnu.org/](https://savannah.gnu.org/))\(^{22}\). Savannah is the central software development management system for many GNU projects. Through this central hub, you can view the list of activities that the developers are engaged in, their activity on the version controlled source, and other things. Each defined activity in the development cycle is known as an ‘issue’ (or ‘item’). An issue can be a bug (see Section 1.7 [Report a bug], page 11), or a suggested feature (see Section 1.8 [Suggest new feature], page 12) or an enhancement or generally any one job that is to be done. In Savannah, issues are classified into three categories or ‘tracker’s:

Support    This tracker is a way that (possibly anonymous) users can get in touch with the Gnuastro developers. It is a complement to the bug-gnuastro mailing list (see Section 1.7 [Report a bug], page 11). Anyone can post an issue to this tracker. The developers will not submit an issue to this list. They will only reassign the issues in this list to the other two trackers if they are valid\(^{23}\). Ideally (when the developers have time to put on Gnuastro, please don’t forget that Gnuastro is a volunteer effort), there should be no open items in this tracker.

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\(^{21}\) [https://savannah.gnu.org/projects/gnuastro/](https://savannah.gnu.org/projects/gnuastro/)

\(^{22}\) [https://savannah.gnu.org/](https://savannah.gnu.org/)

\(^{23}\) Some of the issues registered here might be due to a mistake on the user’s side, not an actual bug in the program.
Chapter 11: Developing

Bugs
This tracker contains all the known bugs in Gnuastro (problems with the existing tools).

Tasks
The items in this tracker contain the future plans (or new features/capabilities) that are to be added to Gnuastro.

All the trackers can be browsed by a (possibly anonymous) visitor, but to edit and comment on the Bugs and Tasks trackers, you have to be a registered on Savannah. When posting an issue to a tracker, it is very important to choose the ‘Category’ and ‘Item Group’ options accurately. The first contains a list of all Gnuastro’s programs along with ‘Installation’, ‘New program’ and ‘Webpage’. The “Item Group” contains the nature of the issue, for example if it is a ‘Crash’ in the software (a bug), or a problem in the documentation (also a bug) or a feature request or an enhancement.

The set of horizontal links on the top of the page (Starting with ‘Main’ and ‘Homepage’ and finishing with ‘News’) are the easiest way to access these trackers (and other major aspects of the project) from any part of the project webpage. Hovering your mouse over them will open a drop down menu that will link you to the different things you can do on each tracker (for example, ‘Submit new’ or ‘Browse’). When you browse each tracker, you can use the “Display Criteria” link above the list to limit the displayed issues to what you are interested in. The ‘Category’ and ‘Group Item’ (explained above) are a good starting point.

Any new issue that is submitted to any of the trackers, or any comments that are posted for an issue, is directly forwarded to the gnuastro-devel mailing list (https://lists.gnu.org/mailman/listinfo/gnuastro-devel, see Section 11.10 [Developing mailing lists], page 531, for more). This will allow anyone interested to be up to date on the overall development activity in Gnuastro and will also provide an alternative (to Savannah) archiving for the development discussions. Therefore, it is not recommended to directly post an email to this mailing list, but do all the activities (for example add new issues, or comment on existing ones) on Savannah.

Do I need to be a member in Savannah to contribute to Gnuastro? No.

The full version controlled history of Gnuastro is available for anonymous download or cloning. See Section 11.11.3 [Production workflow], page 535, for a description of Gnuastro’s Integration-Manager Workflow. In short, you can either send in patches, or make your own fork. If you choose the latter, you can push your changes to your own fork and inform us. We will then pull your changes and merge them into the main project. Please see Section 11.11.4 [Forking tutorial], page 536, for a tutorial.

11.10 Developing mailing lists

To keep the developers and interested users up to date with the activity and discussions within Gnuastro, there are two mailing lists which you can subscribe to:

gnuastro-devel@gnu.org
(at https://lists.gnu.org/mailman/listinfo/gnuastro-devel)

All the posts made in the support, bugs and tasks discussions of Section 11.9 [Gnuastro project webpage], page 530, are also sent to this mailing address and
archived. By subscribing to this list you can stay up to date with the discussions that are going on between the developers before, during and (possibly) after working on an issue. All discussions are either in the context of bugs or tasks which are done on Savannah and circulated to all interested people through this mailing list. Therefore it is not recommended to post anything directly to this mailing list. Any mail that is sent to it from Savannah to this list has a link under the title “Reply to this item at:”. That link will take you directly to the issue discussion page, where you can read the discussion history or join it.

While you are posting comments on the Savannah issues, be sure to update the meta-data. For example if the task/bug is not assigned to anyone and you would like to take it, change the “Assigned to” box, or if you want to report that it has been applied, change the status and so on. All these changes will also be circulated with the email very clearly.

gnuastro-commits@gnu.org
(at https://lists.gnu.org/mailman/listinfo/gnuastro-commits)

This mailing list is defined to circulate all commits that are done in Gnuastro’s version controlled source, see Section 3.2.2 [Version controlled source], page 85. If you have any ideas, or suggestions on the commits, please use the bug and task trackers on Savannah to followup the discussion, do not post to this list. All the commits that are made for an already defined issue or task will state the respective ID so you can find it easily.

11.11 Contributing to Gnuastro

You have this great idea or have found a good fix to a problem which you would like to implement in Gnuastro. You have also become familiar with the general design of Gnuastro in the previous sections of this chapter (see Chapter 11 [Developing], page 516) and want to start working on and sharing your new addition/change with the whole community as part of the official release. This is great and your contribution is most welcome. This section and the next (see Section 11.8 [Developer’s checklist], page 530) are written in the hope of making it as easy as possible for you to share your great idea with the community.

In this section we discuss the final steps you have to take: legal and technical. From the legal perspective, the copyright of any work you do on Gnuastro has to be assigned to the Free Software Foundation (FSF) and the GNU operating system, or you have to sign a disclaimer. We do this to ensure that Gnuastro can remain free in the future, see Section 11.11.1 [Copyright assignment], page 533. From the technical point of view, in this section we also discuss commit guidelines (Section 11.11.2 [Commit guidelines], page 534) and the general version control workflow of Gnuastro in Section 11.11.3 [Production workflow], page 535, along with a tutorial in Section 11.11.4 [Forking tutorial], page 536.

Recall that before starting the work on your idea, be sure to checkout the bugs and tasks trackers in Section 11.9 [Gnuastro project webpage], page 530, and announce your work there so you don’t end up spending time on something others have already worked on, and also to attract similarly interested developers to help you.
11.11.1 Copyright assignment

Gnuastro's copyright is owned by the FSF. Professor Eben Moglen, of the Columbia University Law School has given a nice summary of the reasons for this at https://www.gnu.org/licenses/why-assign. Below we are copying it verbatim for self consistency (in case you are offline or reading in print).

Under US copyright law, which is the law under which most free software programs have historically been first published, there are very substantial procedural advantages to registration of copyright. And despite the broad right of distribution conveyed by the GPL, enforcement of copyright is generally not possible for distributors: only the copyright holder or someone having assignment of the copyright can enforce the license. If there are multiple authors of a copyrighted work, successful enforcement depends on having the cooperation of all authors.

In order to make sure that all of our copyrights can meet the record keeping and other requirements of registration, and in order to be able to enforce the GPL most effectively, FSF requires that each author of code incorporated in FSF projects provide a copyright assignment, and, where appropriate, a disclaimer of any work-for-hire ownership claims by the programmer's employer. That way we can be sure that all the code in FSF projects is free code, whose freedom we can most effectively protect, and therefore on which other developers can completely rely.

Please get in touch with the Gnuastro maintainer (currently Mohammad Akhlaghi, mohammad -at- akhlaghi -dot- org) to follow the procedures. It is possible to do this for each change (good for for a single contribution), and also more generally for all the changes/additions you do in the future within Gnuastro. So if you have already assigned the copyright of your work on another GNU software to the FSF, it should be done again for Gnuastro. The FSF has staff working on these legal issues and the maintainer will get you in touch with them to do the paperwork. The maintainer will just be informed in the end so your contributions can be merged within the Gnuastro source code.

Gnuastro will gratefully acknowledge (see Section 1.11 [Acknowledgments], page 14) all the people who have assigned their copyright to the FSF and have thus helped to guarantee the freedom and reliability of Gnuastro. The Free Software Foundation will also acknowledge your copyright contributions in the Free Software Supporter: https://www.fsf.org/free-software-supporter which will circulate to a very large community (104,444 people in April 2016). See the archives for some examples and subscribe to receive interesting updates. The very active code contributors (or developers) will also be recognized as project members on the Gnuastro project webpage (see Section 11.9 [Gnuastro project webpage], page 530) and can be given a gnu.org email address. So your very valuable contribution and copyright assignment will not be forgotten and is highly appreciated by a very large community. If you are reluctant to sign an assignment, a disclaimer is also acceptable.
Do I need a disclaimer from my university or employer? It depends on the contract with your university or employer. From the FSF’s /gd/gnuorg/conditions.text: “If you are employed to do programming, or have made an agreement with your employer that says it owns programs you write, we need a signed piece of paper from your employer disclaiming rights to” Gnuastro. The FSF’s copyright clerk will kindly help you decide, please consult the following email address: “assign -at- gnu -dot- org”.

11.11.2 Commit guidelines

To be able to cleanly integrate your work with the other developers, **never commit on the master branch** (see Section 11.11.3 [Production workflow], page 535, for a complete discussion and Section 11.11.4 [Forking tutorial], page 536, for a cookbook example). In short, leave master only for changes you fetch, or pull from the official repository (see Section 3.2.2.2 [Synchronizing], page 88).

In the Gnuastro commit messages, we strive to follow these standards. Note that in the early phases of Gnuastro’s development, we are experimenting and so if you notice earlier commits don’t satisfy some of the guidelines below, it is because they predate that guideline.

**Commit title**

The commits have to start with one short descriptive title. The title is separated from the body with one blank line. Run `git log` to see some of the most recent commit messages as an example. In general, the title should satisfy the following conditions:

- It is best for the title to be short, about 60 (or even 50) characters. Most emulated command-line terminals are about 80 characters wide. However, we should also allow for the commit hashes which are printed in `git log --oneline`, and also branch names or the graph structure outputs of `git log` which are also commonly used.
- The title should not finish with any full-stops or periods (‘.’).

**Commit body**

The body of the commit message is separated from the title by one empty line. Recall that anyone who has subscribed to `gnuastro-commits` mailing list will get the commit in their email after it has been pushed to `master`. People will also read them when they synchronize with the main Gnuastro repository (see Section 3.2.2.2 [Synchronizing], page 88). Finally, the commit messages will later be used to update the NEWS file on each release. Therefore the commit message body plays a very important role in the development of Gnuastro, so please adhere to the following guidelines.

- The body should be very descriptive. Start the commit message body by explaining what changes your commit makes from a user’s perspective (added, changed, or removed options, or arguments to programs or libraries, or modified algorithms, or new installation step, etc).
- Try to explain the committed contents as best as you can. Recall that the readers of your commit message do not necessarily have your current background. After some time you will also forget the context, so this request is not just for others. Therefore be very descriptive and explain

---

as much as possible: what the bug/task was, justify the way you fixed it and discuss other possible solutions that you might not have included.
For the last item, it is best to discuss them thoroughly as comments in the appropriate section of the code, but only give a short summary in the commit message. Note that all added and removed source code lines will also be circulated in the gnuastro-commits mailing list.

- Like all other Gnuastro's text files, the lines in the commit body should not be longer than 75 characters, see Section 11.3 [Coding conventions], page 519. This is to ensure that on standard terminal emulators (with 80 character width), the git log output can be cleanly displayed (note that the commit message is indented in the output of git log). If you use Emacs, Gnuastro's .dir-locals.el file will ensure that your commits satisfy this condition (using M-q).

- When the commit is related to a task or a bug, please include the respective ID (in the format of bug/task #ID, note the space) in the commit message (from Section 11.9 [Gnuastro project webpage], page 530) for interested people to be able to followup the discussion that took place there. If the commit fixes a bug or finishes a task, the recommended way is to add a line after the body with 'This fixes bug #ID.', or 'This finishes task #ID.'. Don’t assume that the reader has internet access to check the bug’s full description when reading the commit message, so give a short introduction too.

11.11.3 Production workflow

Fortunately ‘Pro Git’ has done a wonderful job in explaining the different workflows in Chapter 5\(^{25}\) and in particular the “Integration-Manager Workflow” explained there. The implementation of this workflow is nicely explained in Section 5.2\(^ {26}\) under “Forked-Public-Project”. We have also prepared a short tutorial in Section 11.11.4 [Forking tutorial], page 536. Anything on the master branch should always be tested and ready to be built and used. As described in ‘Pro Git’, there are two methods for you to contribute to Gnuastro in the Integration-Manager Workflow:

1. You can send commit patches by email as fully explained in ‘Pro Git’. This is good for your first few contributions. Just note that raw patches (containing only the diff) do not have any meta-data (author name, date, etc). Therefore they will not allow us to fully acknowledge your contributions as an author in Gnuastro: in the AUTHORS file and at the start of the PDF book. These author lists are created automatically from the version controlled source.

To receive full acknowledgment when submitting a patch, is thus advised to use Git’s format-patch tool. See Pro Git’s Public project over email (https://git-scm.com/book/en/v2/Distributed-Git-Contributing-to-a-Project#Public-Project-over-Email) section for a nice explanation. If you would like to get more heavily involved in Gnuastro’s development, then you can try the next solution.

2. You can have your own forked copy of Gnuastro on any hosting site you like (GitHub, GitLab, BitBucket, etc) and inform us when your changes are ready so we merge them in Gnuastro. This is more suited for people who commonly contribute to the code (see Section 11.11.4 [Forking tutorial], page 536).

In both cases, your commits (with your name and information) will be preserved and your contributions will thus be fully recorded in the history of Gnuastro and in the AUTHORS file and this book (second page in the PDF format) once they have been incorporated into the official repository. Needless to say that in such cases, be sure to follow the bug or task trackers (or subscribe to the gnuastro-devel mailing list) and contact us before hand so you don’t do something that someone else is already working on. In that case, you can get in touch with them and help the job go on faster, see Section 11.9 [Gnuastro project webpage], page 530. This workflow is currently mostly borrowed from the general recommendations of Git and GitHub. But since Gnuastro is currently under heavy development, these might change and evolve to better suit our needs.

11.11.4 Forking tutorial

This is a tutorial on the second suggested method (commonly known as forking) that you can submit your modifications in Gnuastro (see Section 11.11.3 [Production workflow], page 535).

To start, please create an empty repository on your hosting service webpage (we recommend GitLab). If this is your first hosted repository on the webpage, you also have to upload your public SSH key for the git push command below to work. Here we’ll assume you use the name janedoe to refer to yourself everywhere and that you choose gnuastro-janedoe as the name of your Gnuastro fork. Any online hosting service will give you an address (similar to the ‘git@gitlab.com:...’ below) of the empty repository you have created using their webpage, use that address in the third line below.

```bash
$ git clone git://git.sv.gnu.org/gnuastro.git
$ cd gnuastro
$ git remote add janedoe git@gitlab.com:janedoe/gnuastro-janedoe.git
$ git push janedoe master
```

The full Gnuastro history is now pushed onto your hosting service and the janedoe remote is now also following your master branch. If you run git remote show REMOTENAME for the origin and janedoe remotes, you will see their difference: the first has pull access and the second doesn’t. This nicely summarizes the main idea behind this workflow: you push to your remote repository, we pull from it and merge it into master, then you finalize it by pulling from the main repository.

To test (compile) your changes during your work, you will need to bootstrap the version controlled source, see Section 3.2.2.1 [Bootstrapping], page 86, for a full description. The cloning process above is only necessary for your first time setup, you don’t need to repeat

---

27 https://github.com/git/git/blob/master/Documentation/SubmittingPatches

28 See https://www.gnu.org/software/repo-criteria-evaluation.html for an evaluation of the major existing repositories. Gnuastro uses GNU Savannah (which also has the highest ranking in the evaluation), but for starters, GitLab may be easier.

29 For example see this explanation provided by GitLab: http://docs.gitlab.com/ce/ssh/README.html.
it. However, please repeat the steps below for each independent issue you intend to work on.

Let’s assume you have found a bug in lib/statistics.c’s median calculating function. Before actually doing anything, please announce it (see Section 1.7 [Report a bug], page 11) so everyone knows you are working on it or to find out others aren’t already working on it. With the commands below, you make a branch, checkout to it, correct the bug, check if it is indeed fixed, add it to the staging area, commit it to the new branch and push it to your hosting service. But before all of them, make sure that you are on the master branch and that your master branch is up to date with the main Gnuastro repository with the first two commands.

```
$ git checkout master
$ git pull
$ git checkout -b bug-median-stats    # Choose a descriptive name
$ emacs lib/statistics.c
$                           # do your checks here
$ git add lib/statistics.c
$ git commit
$ git push janedoe bug-median-stats
```

Your new branch is now on your hosted repository. Through the respective tracker on Savannah (see Section 11.9 [Gnuastro project webpage], page 530) you can then let the other developers know that your bug-median-stats branch is ready. They will pull your work, test it themselves and if it is ready to be merged into the main Gnuastro history, they will merge it into the master branch. After that is done, you can simply checkout your local master branch and pull all the changes from the main repository. After the pull you can run ‘git log’ as shown below, to see how bug-median-stats is merged with master. To finalize, you can push all the changes to your hosted repository and delete the branch:

```
$ git checkout master
$ git pull
$ git log --oneline --graph --decorate --all
$ git push janedoe master
$ git branch -d bug-median-stats       # delete local branch
$ git push janedoe --delete bug-median-stats   # delete remote branch
```

Just as a reminder, always keep your work on each issue in a separate local and remote branch so work can progress on them independently. After you make your announcement, other people might contribute to the branch before merging it in to master, so this is very important. As a final reminder: before starting each issue branch from master, be sure to run git pull in master as shown above. This will enable you to start your branch (work) from the most recent commit and thus simplify the final merging of your work.
Appendix A  Gnuastro programs list

GNU Astronomy Utilities 0.13.35-644c, contains the following programs. They are sorted in alphabetical order and a short description is provided for each program. The description starts with the executable names in this font followed by a pointer to the respective section in parenthesis. Throughout this book, they are ordered based on their context, please see the top-level contents for contextual ordering (based on what they do).

Arithmetic
(astarithmetic, see Section 6.2 [Arithmetic], page 199) For arithmetic operations on multiple (theoretically unlimited) number of datasets (images). It has a large and growing set of arithmetic, mathematical, and even statistical operators (for example +, -, *, /, sqrt, log, min, average, median).

BuildProgram
(astbuildprog, see Section 10.2 [BuildProgram], page 380) Compile, link and run programs that depend on the Gnuastro library (see Section 10.3 [Gnuastro library], page 384). This program will automatically link with the libraries that Gnuastro depends on, so there is no need to explicitly mention them every time you are compiling a Gnuastro library dependent program.

ConvertType
(astconvertt, see Section 5.3 [ConvertType], page 162) Convert astronomical data files (FITS or IMH) to and from several other standard image and data formats, for example TXT, JPEG, EPS or PDF.

Convolve (astconvolve, see Section 6.3 [Convolve], page 216) Convolve (blur or smooth) data with a given kernel in spatial and frequency domain on multiple threads. Convolve can also do de-convolution to find the appropriate kernel to PSF-match two images.

CosmicCalculator
(astcosmiccal, see Section 9.1 [CosmicCalculator], page 359) Do cosmological calculations, for example the luminosity distance, distance modulus, comoving volume and many more.

Crop
(astcrop, see Section 6.1 [Crop], page 188) Crop region(s) from an image and stitch several images if necessary. Inputs can be in pixel coordinates or world coordinates.

Fits
(astfits, see Section 5.1 [Fits], page 146) View and manipulate FITS file extensions and header keywords.

MakeCatalog
(astmkcatalog, see Section 7.4 [MakeCatalog], page 295) Make catalog of labeled image (output of NoiseChisel). The catalogs are highly customizable and adding new calculations/columns is very straightforward.

MakeNoise
(astmknoise, see Section 8.2 [MakeNoise], page 352) Make (add) noise to an image, with a large set of random number generators and any seed.
Appendix A: Gnuastro programs list

MakeProfiles

(\texttt{astmkprof}, see Section 8.1 [MakeProfiles], page 332\texttt{astmkprof}) Make mock 2D profiles in an image. The central regions of radial profiles are made with a configurable 2D Monte Carlo integration. It can also build the profiles on an over-sampled image.

Match

(\texttt{astmatch}, see Section 7.5 [Match], page 326) Given two input catalogs, find the rows that match with each other within a given aperture (may be an ellipse).

NoiseChisel

(\texttt{astnoisechisel}, see Section 7.2 [NoiseChisel], page 269) Detect signal in noise. It uses a technique to detect very faint and diffuse, irregularly shaped signal in noise (galaxies in the sky), using thresholds that are below the Sky value, see arXiv:1505.01664 (\url{http://arxiv.org/abs/1505.01664}).

Query

(\texttt{astquery}, see Section 5.5 [Query], page 183) High-level interface to query pre-defined remote, or external databases, and directly download the required sub-tables on the command-line.

Segment

(\texttt{astsegment}, see Section 7.3 [Segment], page 284) Segment detected regions based on the structure of signal and the input dataset’s noise properties.

Statistics

(\texttt{aststatistics}, see Section 7.1 [Statistics], page 248) Statistical calculations on the input dataset (column in a table, image or datacube).

Table

(\texttt{asttable}, Section 5.4 [Table], page 171) Convert FITS binary and ASCII tables into other such tables, print them on the command-line, save them in a plain text file, or get the FITS table information.

Warp

(\texttt{astwarp}, see Section 6.4 [Warp], page 238) Warp image to new pixel grid. Any projective transformation or Homography can be applied to the input images.

The programs listed above are designed to be highly modular and generic. Hence, they are naturally for lower-level operations. In Gnuastro, higher-level operations (combining multiple programs, or running a program in a special way), are done with installed Bash scripts (all prefixed with \texttt{astscript-}). They can be run just like a program and behave very similarly (with minor differences, see Section 4.4 [Installed scripts], page 126).

\texttt{astscript-sort-by-night}

(See Section 5.2 [Sort FITS files by night], page 158) Given a list of FITS files, and a HDU and keyword name (for a date), this script separates the files in the same night (possibly over two calendar days).
Appendix B Other useful software

In this appendix the installation of programs and libraries that are not direct Gnuastro dependencies are discussed. However they can be useful for working with Gnuastro.

B.1 SAO ds9

SAO ds9\(^1\) is not a requirement of Gnuastro, it is a FITS image viewer. So to check your inputs and outputs, it is one of the best options. Like the other packages, it might already be available in your distribution’s repositories. It is already pre-compiled in the download section of its webpage. Once you download it you can unpack and install (move it to a system recognized directory) with the following commands (x.x.x is the version number):

\[
\begin{align*}
$\text{tar xf ds9.linux64.x.x.x.tar.gz} \\
$\text{sudo mv ds9 /usr/local/bin}
\end{align*}
\]

Once you run it, there might be a complaint about the Xss library, which you can find in your distribution package management system. You might also get an XPA related error. In this case, you have to add the following line to your "/.bashrc and "/.profile file (you will have to log out and back in again for the latter):

\[
\begin{align*}
\text{export XPA\_METHOD=local}
\end{align*}
\]

B.1.1 Viewing multiextension FITS images

The FITS definition allows for multiple extensions inside one FITS file, each extension can have a completely independent dataset inside of it. If you just double click on a multi-extension FITS file or run $\text{ds9 foo.fits}$, SAO ds9 will only show you the first extension. If you have a multi-extension file containing 2D images, one way to load and switch between the each 2D extension is to take the following steps in the SAO ds9 window: “File”→”Open Other”→”Open Multi Ext Cube” and then choose the Multi extension FITS file in your computer’s file structure.

The method above is a little tedious to do every time you want view a multi-extension FITS file. A different series of steps is also necessary if you the extensions are 3D data cubes. Fortunately SAO ds9 also provides command-line options that you can use to specify a particular behavior. One of those options is -mecube which opens a FITS image as a multi-extension data cube (treating each 2D extension as a slice in a 3D cube). This allows you to flip through the extensions easily while keeping all the settings similar.

Try running $\text{ds9 -mecube foo.fits}$ to see the effect (for example on the output of Section 7.2 [NoiseChisel], page 269). If the file has multiple extensions, a small window will also be opened along with the main ds9 window. This small window allows you to slide through the image extensions of foo.fits. If foo.fits only consists of one extension, then SAO ds9 will open as usual. Just to avoid confusion, note that SAO ds9 does not follow the GNU style of separating long and short options as explained in Section 4.1.1 [Arguments and options], page 106. In the GNU style, this ‘long’ (multi-character) option should have been called like --mecube, but SAO ds9 follows its own conventions.

Recall the -mecube opens each 2D input extension as a slice in 3D. Therefore, when you want to inspect a multi-extension FITS file containing a 3D dataset, the -mecube option is

\(^1\) http://ds9.si.edu/
Appendix B: Other useful software

no good any more (it only opens the first slice of the 3D cube in each extension). In that case, we have to use SAO ds9’s \texttt{-multiframe} option to open each extension as a separate frame. Since the input is a 3D dataset, we get the same small window as the 2D case above for scrolling through the 3D slices. We then have to also ask ds9 to match the frames and lock the slices, so for example zooming in one, will also zoom the others.

We can use a script to automatize this process and make work much easier (and save a lot of time) when opening any generic 2D or 3D dataset. After taking the following steps, when you click on a FITS file in your graphic user interface, ds9 will open in the respective 2D or 3D mode when double clicking a FITS file on the graphic user interface, and an executable will also be available to open ds9 similarly on the command-line. Note that the following solution assumes you already have Gnuastro installed (and in particular the Section 5.1 [Fits], page 146, program).

Let’s assume that you want to store this script in \texttt{BINDIR} (that is in your \texttt{PATH} environment variable, see Section 3.3.1.2 [Installation directory], page 92). [Tip: a good place would be \texttt{~/.local/bin}, just don’t forget to make sure it is in your \texttt{PATH}]. Using your favorite text editor, put the following script into a file called \texttt{BINDIR/ds9-multi-ext}. You can change the size of the opened ds9 window by changing the 1800x3000 part of the script below.

```bash
#!/bin/bash

# To allow generic usage, if no input file is given (the ‘if’ below is # true), then just open an empty ds9.
if [ "x$1" == "x" ]; then
d9
else
  # Make sure we are dealing with a FITS file. We are using shell # redirection here to make sure that nothing is printed in the # terminal (to standard output when we have a FITS file, or to # standard error when we don’t). Since we’ve used redirection, # we’ll also have to echo the return value of ‘astfits’.
  check=$(astfits $1 -h0 > /dev/null 2>&1; echo $?)
  if [ "$check" == "0" ]; then
    # Read the number of dimensions.
    n0=$(astfits $1 -h0 | awk '$1=="NAXIS"{print $3}')
    # Find the number of dimensions.
    if [ "$n0" == "0" ]; then
      ndim=$(astfits $1 -h1 | awk '$1=="NAXIS"{print $3}')
    else
      ndim=$n0
    fi;
    # Open DS9 based on the number of dimension.
  fi
```

if [ "$ndim" = "2" ]; then
    # 2D multi-extension file: use the "Cube" window to
    # flip/slide through the extensions.
    ds9 -zscale -geometry 1800x3000 -mecube $1 \
    -zoom to fit -wcs degrees
else
    # 3D multi-extension file: The "Cube" window will slide
    # between the slices of a single extension. To flip
    # through the extensions (not the slices), press the top
    # row "frame" button and from the last four buttons of the
    # bottom row ("first", "previous", "next" and "last") can
    # be used to switch through the extensions (while keeping
    # the same slice).
    ds9 -zscale -geometry 1800x3000 -wcs degrees \ 
    -multiframe $1 -match frame image \ 
    -lock slice image -lock frame image -single \ 
    -zoom to fit
fi
else
    if [ -f $1 ]; then
        echo "'$1' isn't a FITS file."
    else
        echo "'$1' doesn't exist."
    fi
fi

As described above (also in the comments of the script), if you have opened a multi-
extension 2D dataset (image), the “Cube” window can be used to slide/flip through each
extension. But when the input is a 3D data cube, the “Cube” window will slide/flip through
the slices in each extension (a separate 3D dataset). To flip through the extensions (while
keeping the slice fixed), click the “frame” button on the top row of buttons, then use the last
four buttons of the bottom row ("first", "previous", "next" and "last") to change between
the extensions.

To run this script, you have to activate its executable flag with this command:

   $ chmod +x BINDIR/ds9-multi-ext

If BINDIR is within your system’s PATH environment variable (see Section 3.3.1.2 [Instal-
lation directory], page 92), you can now open ds9 conditionally using the script above with
this command:

   $ ds9-multi-ext foo.fits

For the graphic user interface, we’ll assume you are using GNOME (the most popu-
lar graphic user interface for GNU/Linux systems), version 3. For GNOME 2, see below.
You can customize GNOME to open specific files with .desktop files. For each user,
they are stored in "/.local/share/applications/". In case you don’t have the direc-
tory, make it your self (with mkdir). Using your favorite text editor, you can now create "/.local/share/applications/saods9.desktop with the following contents. Just don’t
forget to correct BINDIR. If you would also like to have ds9’s logo/icon in GNOME, download it, uncomment the Icon line, and write its address in the value.

```
[Desktop Entry]
Type=Application
Version=1.0
Name=SAO DS9
Comment=View FITS images
Terminal=false
Categories=Graphics;RasterGraphics;2DGraphics;3DGraphics
#Icon=/PATH/TO/DS9/ICON/ds9.png
Exec=BINDIR/ds9-multi-ext %f
```

The steps above will add SAO ds9 as one of your applications. To make it default, take the following steps (just once is enough). Right click on a FITS file and select Open with other application → View all applications → SAO ds9.

In case you are using GNOME 2 you can take the following steps: right click on a FITS file and choose Properties → Open With → Add button. A list of applications will show up, ds9 might already be present in the list, but don’t choose it because it will run with no options. Below the list is an option “Use a custom command”. Click on it and write the following command: `BINDIR/ds9-multi-ext` in the box and click “Add”. Then finally choose the command you just added as the default and click the “Close” button.

### B.2 PGPLOT

PGPLOT is a package for making plots in C. It is not directly needed by Gnuastro, but can be used by WCSLIB, see Section 3.1.1.3 [WCSLIB], page 76. As explained in Section 3.1.1.3 [WCSLIB], page 76, you can install WCSLIB without it too. It is very old (the most recent version was released early 2001!), but remains one of the main packages for plotting directly in C. WCSLIB uses this package to make plots if you want it to make plots. If you are interested you can also use it for your own purposes.

If you want your plotting codes in between your C program, PGPLOT is currently one of your best options. The recommended alternative to this method is to get the raw data for the plots in text files and input them into any of the various more modern and capable plotting tools separately, for example the Matplotlib library in Python or PGFplots in \LaTeX. This will also significantly help code readability. Let’s get back to PGPLOT for the sake of WCSLIB. Installing it is a little tricky (mainly because it is so old!).

You can download the most recent version from the FTP link in its webpage\(^2\). You can unpack it with the `tar xf` command. Let’s assume the directory you have unpacked it to is PGPLOT, most probably it is: `~/Downloads/pgplot/`. open the `drivers.list` file:

```
$ gedit drivers.list
```

Remove the ! for the following lines and save the file in the end:

```
PSDRIV 1 /PS
PSDRIV 2 /VPS
PSDRIV 3 /CPS
```

PSDRIV 4 /VCPS
XWDRIV 1 /XWINDOW
XWDRIV 2 /XSERVE

Don’t choose GIF or VGIF, there is a problem in their codes.

Open the PGPLOT/sys_linux/g77_gcc.conf file:

```
$ gedit PGPLOT/sys_linux/g77_gcc.conf
```

change the line saying: FCOMPL="g77" to FCOMPL="gfortran", and save it. This is a very important step during the compilation of the code if you are in GNU/Linux. You now have to create a folder in /usr/local, don’t forget to replace PGPLOT with your unpacked address:

```
$ su
# mkdir /usr/local/pgplot
# cd /usr/local/pgplot
# cp PGPLOT/drivers.list ./
```

To make the Makefile, type the following command:

```
# PGPLOT/makemake PGPLOT linux g77_gcc
```

It should finish by saying: Determining object file dependencies. You have done the hard part! The rest is easy: run these three commands in order:

```
# make
# make clean
# make cpg
```

Finally you have to place the position of this directory you just made into the LD_LIBRARY_PATH environment variable and define the environment variable PGPLOT_DIR. To do that, you have to edit your .bashrc file:

```
$ cd ~
$ gedit .bashrc
```

Copy these lines into the text editor and save it:

```
PGPLOT_DIR="/usr/local/pgplot/"; export PGPLOT_DIR
LD_LIBRARY_PATH=$LD_LIBRARY_PATH:/usr/local/pgplot/
export LD_LIBRARY_PATH
```

You need to log out and log back in again so these definitions take effect. After you logged back in, you want to see the result of all this labor, right? Tim Pearson has done that for you, create a temporary folder in your home directory and copy all the demonstration files in it:

```
$ cd ~
$ mkdir temp
$ cd temp
$ cp /usr/local/pgplot/pgdemo* ./
$ ls
```

You will see a lot of pgdemoXX files, where XX is a number. In order to execute them type the following command and drink your coffee while looking at all the beautiful plots! You are now ready to create your own.

```
$ ./pgdemoXX
```
Appendix C GNU Free Doc. License

Version 1.3, 3 November 2008


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0. PREAMBLE

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Index: Macros, structures and functions

All Gnuastro library’s exported macros start with GAL_, and its exported structures and functions start with gal_. This abbreviation stands for GNU Astronomy Library. The next element in the name is the name of the header which declares or defines them, so to use the gal_array_fset_const function, you have to #include <gnuastro/array.h>. See Section 10.3 [Gnuastro library], page 384, for more. The pthread_barrier constructs are our implementation and are only available on systems that don’t have them, see Section 10.3.2.1 [Implementation of pthread_barrier], page 387.

G

<table>
<thead>
<tr>
<th>Function</th>
<th>Page</th>
</tr>
</thead>
<tbody>
<tr>
<td>gal_arithmetic</td>
<td>450</td>
</tr>
<tr>
<td>gal_arithmetic_operator_string</td>
<td>459</td>
</tr>
<tr>
<td>gal_arithmetic_set_operator</td>
<td>459</td>
</tr>
<tr>
<td>gal_array_name_recognized</td>
<td>424</td>
</tr>
<tr>
<td>gal_array_name_recognized_multiext</td>
<td>425</td>
</tr>
<tr>
<td>gal_array_read</td>
<td>425</td>
</tr>
<tr>
<td>gal_array_read_one_ch</td>
<td>425</td>
</tr>
<tr>
<td>gal_array_read_one_ch_to_type</td>
<td>426</td>
</tr>
<tr>
<td>gal_array_read_to_type</td>
<td>426</td>
</tr>
<tr>
<td>gal_binary_connected_adjacency_matrix</td>
<td>491</td>
</tr>
<tr>
<td>gal_binary_connected_components</td>
<td>491</td>
</tr>
<tr>
<td>gal_binary_connected_indices(gal_data_t)</td>
<td>491</td>
</tr>
<tr>
<td>gal_binary_dilate</td>
<td>490</td>
</tr>
<tr>
<td>gal_binary_erode</td>
<td>490</td>
</tr>
<tr>
<td>gal_binary_holes_fill</td>
<td>492</td>
</tr>
<tr>
<td>gal_binary_holes_label</td>
<td>492</td>
</tr>
<tr>
<td>gal_binary_init</td>
<td>490</td>
</tr>
<tr>
<td>gal_blank_alloc_write</td>
<td>397</td>
</tr>
<tr>
<td>gal_blank_as_string</td>
<td>398</td>
</tr>
<tr>
<td>gal_blank_flag</td>
<td>398</td>
</tr>
<tr>
<td>gal_blank_flag_apply</td>
<td>399</td>
</tr>
<tr>
<td>gal_blank_flag_remove</td>
<td>399</td>
</tr>
<tr>
<td>gal_blank_init</td>
<td>397</td>
</tr>
<tr>
<td>gal_blank_init_array</td>
<td>398</td>
</tr>
<tr>
<td>gal_blank_is</td>
<td>398</td>
</tr>
<tr>
<td>gal_blank_number</td>
<td>398</td>
</tr>
<tr>
<td>gal_blank_present</td>
<td>398</td>
</tr>
<tr>
<td>gal_blank_remove</td>
<td>399</td>
</tr>
<tr>
<td>gal_blank_remove_realloc</td>
<td>399</td>
</tr>
<tr>
<td>gal_blank_remove_rows</td>
<td>399</td>
</tr>
<tr>
<td>gal_blank_write</td>
<td>397</td>
</tr>
<tr>
<td>gal_box_border_from_center</td>
<td>471</td>
</tr>
<tr>
<td>gal_box_bound_ellipse</td>
<td>470</td>
</tr>
<tr>
<td>gal_box_bound_ellipse_extent</td>
<td>470</td>
</tr>
<tr>
<td>gal_box_bound_ellipsoid</td>
<td>471</td>
</tr>
<tr>
<td>gal_box_bound_ellipsoid_extent</td>
<td>470</td>
</tr>
<tr>
<td>gal_box_overlap</td>
<td>471</td>
</tr>
<tr>
<td>gal_convolve_spatial</td>
<td>497</td>
</tr>
<tr>
<td>gal_convolve_spatial_correct_ch_edge</td>
<td>497</td>
</tr>
<tr>
<td>gal_cosmology_age</td>
<td>506</td>
</tr>
<tr>
<td>gal_cosmology_angular_distance</td>
<td>507</td>
</tr>
<tr>
<td>gal_cosmology_comoving_volume</td>
<td>506</td>
</tr>
<tr>
<td>gal_cosmology_critical_density</td>
<td>506</td>
</tr>
<tr>
<td>gal_cosmology_distance_modulus</td>
<td>507</td>
</tr>
<tr>
<td>gal_cosmology_luminosity_distance</td>
<td>507</td>
</tr>
<tr>
<td>gal_cosmology_proper_distance</td>
<td>506</td>
</tr>
<tr>
<td>gal_cosmology_to_absolute_mag</td>
<td>507</td>
</tr>
<tr>
<td>gal_cosmology_velocity_from_z</td>
<td>507</td>
</tr>
<tr>
<td>gal_cosmology_z_from_velocity</td>
<td>507</td>
</tr>
<tr>
<td>gal_data_alloc</td>
<td>405</td>
</tr>
<tr>
<td>gal_data_array_alloc</td>
<td>406</td>
</tr>
<tr>
<td>gal_data_array_free</td>
<td>406</td>
</tr>
<tr>
<td>gal_data_array_ptr_alloc</td>
<td>406</td>
</tr>
<tr>
<td>gal_data_array_ptr_free</td>
<td>407</td>
</tr>
<tr>
<td>gal_data_copy</td>
<td>407</td>
</tr>
<tr>
<td>gal_data_copy_string_to_number</td>
<td>408</td>
</tr>
<tr>
<td>gal_data_copy_to_allocated</td>
<td>407</td>
</tr>
<tr>
<td>gal_data_copy_to_new_type</td>
<td>407</td>
</tr>
<tr>
<td>gal_data_copy_to_new_type_free</td>
<td>407</td>
</tr>
<tr>
<td>gal_data_free</td>
<td>406</td>
</tr>
<tr>
<td>gal_data_free_contents</td>
<td>406</td>
</tr>
<tr>
<td>gal_data_init</td>
<td>405</td>
</tr>
<tr>
<td>gal_dimension_add_coords</td>
<td>409</td>
</tr>
<tr>
<td>gal_dimension_added</td>
<td>410</td>
</tr>
<tr>
<td>gal_dimension_collapsed_mean</td>
<td>410</td>
</tr>
<tr>
<td>gal_dimension_collapsed_minmax</td>
<td>410</td>
</tr>
<tr>
<td>gal_dimension_collapsed_number</td>
<td>410</td>
</tr>
<tr>
<td>gal_dimension_collapsed_sum</td>
<td>409</td>
</tr>
<tr>
<td>gal_dimension_coord_to_index</td>
<td>409</td>
</tr>
<tr>
<td>gal_dimension_distance_manhattan</td>
<td>409</td>
</tr>
<tr>
<td>gal_dimension_distance_radial</td>
<td>409</td>
</tr>
<tr>
<td>gal_dimension_increment</td>
<td>408</td>
</tr>
<tr>
<td>gal_dimension_index_to_coord</td>
<td>409</td>
</tr>
<tr>
<td>gal_dimension_is_different</td>
<td>408</td>
</tr>
<tr>
<td>gal_dimension_num_neighbors</td>
<td>409</td>
</tr>
<tr>
<td>gal_dimension_remove_extra</td>
<td>410</td>
</tr>
<tr>
<td>gal_dimension_total_size</td>
<td>408</td>
</tr>
<tr>
<td>gal_eps_name_is_eps</td>
<td>447</td>
</tr>
<tr>
<td>gal_eps_suffix_is_eps</td>
<td>447</td>
</tr>
<tr>
<td>gal_eps_to_pt</td>
<td>447</td>
</tr>
<tr>
<td>gal_eps_write</td>
<td>448</td>
</tr>
<tr>
<td>gal_fts_bitpix_to_type</td>
<td>431</td>
</tr>
<tr>
<td>gal_fts_datatype_to_type</td>
<td>431</td>
</tr>
<tr>
<td>gal_fts_hdu_format</td>
<td>432</td>
</tr>
<tr>
<td>gal_fts_hdu_num</td>
<td>432</td>
</tr>
<tr>
<td>gal_fts_hdu_open</td>
<td>432</td>
</tr>
<tr>
<td>gal_fts_hdu_open_format</td>
<td>432</td>
</tr>
<tr>
<td>gal_fts_info</td>
<td>439</td>
</tr>
<tr>
<td>gal_fts_img_info</td>
<td>439</td>
</tr>
<tr>
<td>gal_fts_img_info_dim</td>
<td>439</td>
</tr>
<tr>
<td>gal_fts_img_read</td>
<td>439</td>
</tr>
</tbody>
</table>
Index: Macros, structures and functions

gal_fits_img_read_kernel ...................... 440
gal_fits_img_read_to_type ..................... 439
gal_fits_img_write ............................. 440
gal_fits_img_write_corr_wcs_str .............. 440
gal_fits_img_write_to_ptr ..................... 440
gal_fits_img_write_to_type .................... 440
gal_fits_io_error .............................. 430
gal_fits_key_clean_str_value ................. 433
gal_fits_key_date_to_seconds ................ 434
gal_fits_key_date_to_struct_tm ............... 434
gal_fits_key_img_blank ...................... 433
gal_fits_key_list_add ........................ 436
gal_fits_key_list_add_end ..................... 436
gal_fits_key_list_reverse .................... 437
gal_fits_key_list_title_add .................. 436
gal_fits_key_list_title_add_end ............... 436
gal_fits_key_read ............................. 436
gal_fits_key_read_from_ptr ................... 434
gal_fits_key_write ............................. 437
gal_fits_key_write_config .................... 438
gal_fits_key_write_filename .................. 437
gal_fits_key_write_in_ptr .................... 438
gal_fits_key_write_title_in_ptr ............... 437
gal_fits_key_write_version ................... 438
gal_fits_key_write_version_in_ptr ............. 438
gal_fits_key_write_wcsstr .................... 437
gal_fits_name_is_fits ......................... 430
gal_fits_name_save_as_string ................ 430
gal_fits_open_to_write ....................... 432
gal_fits_suffix_is_fits ....................... 430
gal_fits_tab_format .......................... 441
gal_fits_tab_info ............................. 441
gal_fits_tab_read ............................. 441
gal_fits_tab_size ............................. 441
gal_fits_tab_write ............................. 442
gal_fits_type_to_bin_tform ................... 431
gal_fits_type_to_bitpix ....................... 431
gal_fits_type_to_datatype .................... 431
gal_get_describe .............................. 502
gal_interpolate_1d_blank ..................... 501
gal_interpolate_1d_make_gsl_spline .......... 500
gal_interpolate_neighbours .................... 498
gal_jpeg_name_is_jpeg ....................... 446
gal_jpeg_read ................................. 447
gal_jpeg_suffix_is_jpeg ...................... 446
gal_jpeg_write ................................. 447
gal_kdtree_create ............................. 477
gal_kdtree_nearest_neighbour ............... 478
gal_label_clump_significance ................ 495
gal_label_grow_indices ....................... 496
gal_label_indices .............................. 493
gal_label_watershed ........................... 494
gal_list_data_add ............................. 423
gal_list_data_add_alloc ....................... 424
gal_list_data_free ............................ 424
gal_list_data_last ............................. 424
gal_list_data_number ......................... 424
gal_list_data_pop ............................. 424
gal_list_data_reverse ....................... 424
gal_list_data_to_array_ptr .................. 424
gal_list_data_to_sizet ....................... 422
gal_list_dosizet_add ......................... 423
gal_list_dosizet_free ......................... 423
gal_list_dosizet_pop_smallest ............... 423
gal_list_dosizet_pop ......................... 423
gal_list_dosizet_reverse .................... 423
gal_list_dosizet_to_sizet ................... 423
gal_list_f32_add ............................. 417
gal_list_f32_free ............................ 418
gal_list_f32_last ............................. 418
gal_list_f32_number .......................... 418
gal_list_f32_pop ............................. 417
gal_list_f32_reverse ......................... 418
gal_list_f32_to_array ....................... 418
gal_list_f64_add ............................. 419
gal_list_f64_free ............................ 420
gal_list_f64_last ............................. 419
gal_list_f64_number ........................... 419
gal_list_f64_pop ............................. 419
gal_list_f64_print ............................ 419
gal_list_f64_reverse ......................... 419
gal_list_f64_to_array ....................... 420
gal_list_i32_add ............................. 414
gal_list_i32_free ............................ 415
gal_list_i32_last ............................. 415
gal_list_i32_number ........................... 414
gal_list_i32_pop ............................. 414
gal_list_i32_reverse ......................... 415
gal_list_i32_to_array ....................... 415
gal_list_osizet_add ......................... 421
gal_list_osizet_pop ......................... 421
gal_list_osizet_to_sizet_free ............... 422
gal_list_sizet_add ........................... 416
gal_list_sizet_free ........................... 417
gal_list_sizet_last ........................... 416
gal_list_sizet_number ........................ 416
gal_list_sizet_pop ........................... 416
gal_list_sizet_print ......................... 416
gal_list_sizet_reverse ....................... 417
gal_list_sizet_to_array ..................... 417
gal_list_sizet_to_sizet ...................... 416
gal_list_str_add ............................. 413
gal_list_str_free ............................. 414
gal_list_str_last ............................. 413
gal_list_str_number .......................... 413
gal_list_str_pop ............................. 413
gal_list_str_reverse ......................... 414
gal_list_void_add ............................. 420
gal_list_void_free ............................ 421
gal_list_void_last ............................ 421
gal_list_void_number .......................... 421
gal_list_void_pop ............................. 420
gal_list_void_reverse ......................... 421
gal_match_coordinates ....................... 480
gal_pdf_name_is_pdf .......................... 448
gal_pdf_suffix_is_pdf ......................... 448
<table>
<thead>
<tr>
<th>Function</th>
<th>Page</th>
</tr>
</thead>
<tbody>
<tr>
<td>gal_pdf_write</td>
<td>448</td>
</tr>
<tr>
<td>gal_permutation_apply</td>
<td>480</td>
</tr>
<tr>
<td>gal_permutation_apply_inverse</td>
<td>480</td>
</tr>
<tr>
<td>gal_permutation_check</td>
<td>480</td>
</tr>
<tr>
<td>gal_pointer_allocate</td>
<td>395</td>
</tr>
<tr>
<td>gal_pointer_allocate_mmap</td>
<td>395</td>
</tr>
<tr>
<td>gal_pointer_increment</td>
<td>395</td>
</tr>
<tr>
<td>gal_pointer_num_between</td>
<td>395</td>
</tr>
<tr>
<td>gal_polygon_area</td>
<td>473</td>
</tr>
<tr>
<td>gal_polygon_clip</td>
<td>474</td>
</tr>
<tr>
<td>gal_polygon_is_convex</td>
<td>473</td>
</tr>
<tr>
<td>gal_polygon_is_counterclockwise</td>
<td>473</td>
</tr>
<tr>
<td>gal_polygon_is_inside</td>
<td>473</td>
</tr>
<tr>
<td>gal_polygon_is_inside_convex</td>
<td>473</td>
</tr>
<tr>
<td>gal_polygon_propen</td>
<td>473</td>
</tr>
<tr>
<td>gal_polygon_to_counterclockwise</td>
<td>473</td>
</tr>
<tr>
<td>gal_polygon_vertices_sort</td>
<td>474</td>
</tr>
<tr>
<td>gal_polygon_vertices_sort_convex</td>
<td>472</td>
</tr>
<tr>
<td>gal_qsort_index_multi_d</td>
<td>476</td>
</tr>
<tr>
<td>gal_qsort_index_multi_i</td>
<td>476</td>
</tr>
<tr>
<td>gal_qsort_index_single</td>
<td>475</td>
</tr>
<tr>
<td>gal_qsort_index_single_TYPE_d</td>
<td>475</td>
</tr>
<tr>
<td>gal_qsort_index_single_TYPE_i</td>
<td>476</td>
</tr>
<tr>
<td>gal_qsort_TYPE_d</td>
<td>475</td>
</tr>
<tr>
<td>gal_qsort_TYPE_i</td>
<td>475</td>
</tr>
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<td>gal_speclines_line_angstrom</td>
<td>506</td>
</tr>
<tr>
<td>gal_speclines_line_code</td>
<td>506</td>
</tr>
<tr>
<td>gal_speclines_line_name</td>
<td>505</td>
</tr>
<tr>
<td>gal_speclines_line_redshift</td>
<td>506</td>
</tr>
<tr>
<td>gal_speclines_line_redshift_code</td>
<td>506</td>
</tr>
<tr>
<td>gal_statistics_cfp</td>
<td>486</td>
</tr>
<tr>
<td>gal_statistics_histogram</td>
<td>486</td>
</tr>
<tr>
<td>gal_statistics_is_sorted</td>
<td>484</td>
</tr>
<tr>
<td>gal_statistics_maximum</td>
<td>482</td>
</tr>
<tr>
<td>gal_statistics_mean</td>
<td>482</td>
</tr>
<tr>
<td>gal_statistics_mean_std</td>
<td>483</td>
</tr>
<tr>
<td>gal_statistics_median</td>
<td>483</td>
</tr>
<tr>
<td>gal_statistics_minimum</td>
<td>482</td>
</tr>
<tr>
<td>gal_statistics_mode</td>
<td>484</td>
</tr>
<tr>
<td>gal_statistics_mode_mirror_plots</td>
<td>484</td>
</tr>
<tr>
<td>gal_statistics_no_blank_sorted</td>
<td>485</td>
</tr>
<tr>
<td>gal_statistics_number</td>
<td>482</td>
</tr>
<tr>
<td>gal_statistics_outlier_bydistance</td>
<td>487</td>
</tr>
<tr>
<td>gal_statistics_outlier_flat_cfp</td>
<td>488</td>
</tr>
<tr>
<td>gal_statistics_quantile</td>
<td>483</td>
</tr>
<tr>
<td>gal_statistics_quantile_function</td>
<td>483</td>
</tr>
<tr>
<td>gal_statistics_quantile_function_index</td>
<td>483</td>
</tr>
<tr>
<td>gal_statistics_quantile_index</td>
<td>483</td>
</tr>
<tr>
<td>gal_statistics_regular_bins</td>
<td>486</td>
</tr>
<tr>
<td>gal_statistics_sigma_clip</td>
<td>487</td>
</tr>
<tr>
<td>gal_statistics_sort_decreasing</td>
<td>485</td>
</tr>
<tr>
<td>gal_statistics_sort_increasing</td>
<td>485</td>
</tr>
<tr>
<td>gal_statistics_std</td>
<td>483</td>
</tr>
<tr>
<td>gal_statistics_sum</td>
<td>482</td>
</tr>
<tr>
<td>gal_statistics_unique</td>
<td>484</td>
</tr>
<tr>
<td>gal_table_comments_add_intro</td>
<td>429</td>
</tr>
<tr>
<td>gal_table_info</td>
<td>427</td>
</tr>
<tr>
<td>gal_table_list_of_indexes</td>
<td>428</td>
</tr>
<tr>
<td>gal_table_print_info</td>
<td>428</td>
</tr>
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<td>gal_table_read</td>
<td>428</td>
</tr>
<tr>
<td>gal_table_write</td>
<td>429</td>
</tr>
<tr>
<td>gal_table_write_log</td>
<td>429</td>
</tr>
<tr>
<td>gal_threads_attr_barrier_init</td>
<td>389</td>
</tr>
<tr>
<td>gal_threads_dist_in_threads</td>
<td>389</td>
</tr>
<tr>
<td>gal_threads_number</td>
<td>389</td>
</tr>
<tr>
<td>gal_threads_spin_off</td>
<td>389</td>
</tr>
<tr>
<td>gal_tiff_dir_string_read</td>
<td>446</td>
</tr>
<tr>
<td>gal_tiff_name_is_tiff</td>
<td>446</td>
</tr>
<tr>
<td>gal_tiff_read</td>
<td>446</td>
</tr>
<tr>
<td>gal_tiff_suffix_is_tiff</td>
<td>446</td>
</tr>
<tr>
<td>gal_tile_block</td>
<td>462</td>
</tr>
<tr>
<td>gal_tile_block_blank_flag</td>
<td>463</td>
</tr>
<tr>
<td>gal_tile_block_check_tiles</td>
<td>463</td>
</tr>
<tr>
<td>gal_tile_block_increment</td>
<td>462</td>
</tr>
<tr>
<td>gal_tile_block_relative_to_other</td>
<td>463</td>
</tr>
<tr>
<td>gal_tile_block_write_const_value</td>
<td>462</td>
</tr>
<tr>
<td>gal_tile_full</td>
<td>467</td>
</tr>
<tr>
<td>gal_tile_full_free_contents</td>
<td>470</td>
</tr>
<tr>
<td>gal_tile_full_id_from_coord</td>
<td>470</td>
</tr>
<tr>
<td>gal_tile_full_permutation</td>
<td>468</td>
</tr>
<tr>
<td>gal_tile_full Sanity_check</td>
<td>468</td>
</tr>
<tr>
<td>gal_tile_full_two_layers</td>
<td>468</td>
</tr>
<tr>
<td>gal_tile_full_values_smooth</td>
<td>469</td>
</tr>
<tr>
<td>gal_tile_full_values_write</td>
<td>469</td>
</tr>
<tr>
<td>gal_tile_series_from_minmax</td>
<td>462</td>
</tr>
<tr>
<td>gal_tile_start_coord</td>
<td>461</td>
</tr>
<tr>
<td>gal_tile_start_end_coord</td>
<td>461</td>
</tr>
<tr>
<td>gal_tile_start_end_ind_inclusive</td>
<td>461</td>
</tr>
<tr>
<td>gal_txt_image_read</td>
<td>444</td>
</tr>
<tr>
<td>gal_txt_line_stat</td>
<td>443</td>
</tr>
<tr>
<td>gal_txt_stdin_read</td>
<td>444</td>
</tr>
<tr>
<td>gal_txt_table_info</td>
<td>443</td>
</tr>
<tr>
<td>gal_txt_table_read</td>
<td>443</td>
</tr>
<tr>
<td>gal_txt_trim_space</td>
<td>443</td>
</tr>
<tr>
<td>gal_txt_write</td>
<td>445</td>
</tr>
<tr>
<td>gal_type_bit_string</td>
<td>393</td>
</tr>
<tr>
<td>gal_type_from_name</td>
<td>392</td>
</tr>
<tr>
<td>gal_type_from_string</td>
<td>394</td>
</tr>
<tr>
<td>gal_type_is_int</td>
<td>393</td>
</tr>
<tr>
<td>gal_type_is_list</td>
<td>393</td>
</tr>
<tr>
<td>gal_type_max</td>
<td>392</td>
</tr>
<tr>
<td>gal_type_min</td>
<td>392</td>
</tr>
<tr>
<td>gal_type_name</td>
<td>392</td>
</tr>
<tr>
<td>gal_type_out</td>
<td>393</td>
</tr>
<tr>
<td>gal_type_sizeof</td>
<td>392</td>
</tr>
<tr>
<td>gal_type_string_to_number</td>
<td>394</td>
</tr>
<tr>
<td>gal_type_to_string</td>
<td>393</td>
</tr>
<tr>
<td>gal_units_dec_to_degree</td>
<td>503</td>
</tr>
<tr>
<td>gal_units_degree_to_dec</td>
<td>503</td>
</tr>
<tr>
<td>gal_units_degree_to_ra</td>
<td>503</td>
</tr>
<tr>
<td>gal_units_extract_decimal</td>
<td>502</td>
</tr>
<tr>
<td>gal_units_ra_to_degree</td>
<td>503</td>
</tr>
<tr>
<td>gal_wcs_angular_distance_deg</td>
<td>453</td>
</tr>
<tr>
<td>gal_wcs_clean_small_errors</td>
<td>451</td>
</tr>
<tr>
<td>gal_wcs_copy</td>
<td>451</td>
</tr>
<tr>
<td>gal_wcs_coverage</td>
<td>453</td>
</tr>
<tr>
<td>Function</td>
<td>Description</td>
</tr>
<tr>
<td>----------</td>
<td>-------------</td>
</tr>
<tr>
<td>gal_wcs_decompose_pc_cdelt</td>
<td>Decomposes position coordinate system</td>
</tr>
<tr>
<td>gal_wcs_dimension_name</td>
<td>Returns the name of a dimension</td>
</tr>
<tr>
<td>gal_wcs_distortion_convert(struct)</td>
<td>Converts distortion to another coordinate system</td>
</tr>
<tr>
<td>gal_wcs_distortion_from_string</td>
<td>Parses distortion string to struct</td>
</tr>
<tr>
<td>gal_wcs_distortion_identify</td>
<td>Identifies distortion type</td>
</tr>
<tr>
<td>gal_wcs_distortion_to_string</td>
<td>Converts distortion struct to string</td>
</tr>
<tr>
<td>gal_wcs_on_tile</td>
<td>Returns true if pixel is on current tile</td>
</tr>
<tr>
<td>gal_wcs_pixel_area_arcsec2</td>
<td>Calculates pixel area in arcsec^2</td>
</tr>
<tr>
<td>gal_wcs_pixel_scale</td>
<td>Returns pixel scale</td>
</tr>
<tr>
<td>gal_wcs_read</td>
<td>Reads WCS file</td>
</tr>
<tr>
<td>gal_wcs_remove_dimension</td>
<td>Removes dimension from WCS</td>
</tr>
<tr>
<td>gal_wcs_warp_matrix</td>
<td>Calculates warp matrix</td>
</tr>
<tr>
<td>gal_wcs_world_to_img</td>
<td>Calculates image coordinates from world coordinates</td>
</tr>
<tr>
<td>gal_wcs_write</td>
<td>Writes WCS file</td>
</tr>
<tr>
<td>gal_wcs_write_in_fitsptr(fits_file)</td>
<td>Writes WCS file to FITS file</td>
</tr>
<tr>
<td>gal_wcs_world_to_img</td>
<td>Converts world to image coordinates</td>
</tr>
<tr>
<td>gal_wcs_distortion_identify</td>
<td>Identifies distortion type</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_OR</td>
<td>Or arithmetic operation</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_NUMBERVAL</td>
<td>Returns number value</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_MINVAL</td>
<td>Returns minimum value</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_MAXVAL</td>
<td>Returns maximum value</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_ADM</td>
<td>Arithmetic operation for mixing</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_MAKENEW</td>
<td>Makes new arithmetic operation</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_FLAGS_ALL</td>
<td>All arithmetic flags</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_INPLACE</td>
<td>In-place arithmetic operation</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_SECONDS_TO_TIME</td>
<td>Converts seconds to time</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_SECONDS_TO_TIME</td>
<td>Converts time to seconds</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_MIN</td>
<td>Returns minimum value</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_MAX</td>
<td>Returns maximum value</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_DIR</td>
<td>Directional arithmetic operation</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OPERAND</td>
<td>Arithmetic operation operand</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_WHERE</td>
<td>Returns where value</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_TO_UINT8</td>
<td>Converts to uint8</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_TO_UINT64</td>
<td>Converts to uint64</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_TO_UINT32</td>
<td>Converts to uint32</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_TO_UINT</td>
<td>Converts to uint</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_TO_FLOAT64</td>
<td>Converts to float64</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_TO_FLOAT32</td>
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<td>GAL_ARITHMETIC_OP_TO_INT8</td>
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<td>GAL_ARITHMETIC_OP_TO_INT32</td>
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</tr>
<tr>
<td>GAL_ARITHMETIC_OP_TO_INT</td>
<td>Converts to int</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_STD</td>
<td>Standard deviation</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_SIGCLIP_STD</td>
<td>Sigma clip standard deviation</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_SIGCLIP_MEDIAN</td>
<td>Sigma clip median</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_SIGCLIP_MEAN</td>
<td>Sigma clip mean</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_RA_TO_DEGREE</td>
<td>Converts RA to degrees</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_DEGREE_TO_RA</td>
<td>Converts degrees to RA</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_DEC_TO_DEGREE</td>
<td>Converts DEC to degrees</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_DEC_TO_RA</td>
<td>Converts DE to RA</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_MAX</td>
<td>Returns maximum value</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_MAXVAL</td>
<td>Returns maximum value</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_MEAN</td>
<td>Returns mean value</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_MEANVAL</td>
<td>Returns mean value</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_MIN</td>
<td>Returns minimum value</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_MINVAL</td>
<td>Returns minimum value</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_MAKENEW</td>
<td>Makes new arithmetic operation</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_FLAGS_ALL</td>
<td>All arithmetic flags</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_INPLACE</td>
<td>In-place arithmetic operation</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_SECONDS_TO_TIME</td>
<td>Converts seconds to time</td>
</tr>
<tr>
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<td>Converts time to seconds</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_MIN</td>
<td>Returns minimum value</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_MAX</td>
<td>Returns maximum value</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_DIR</td>
<td>Directional arithmetic operation</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OPERAND</td>
<td>Arithmetic operation operand</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_WHERE</td>
<td>Returns where value</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_TO_UINT8</td>
<td>Converts to uint8</td>
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<td>GAL_ARITHMETIC_OP_TO_UINT64</td>
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<td>Converts to uint</td>
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<tr>
<td>GAL_ARITHMETIC_OP_STD</td>
<td>Standard deviation</td>
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<tr>
<td>GAL_ARITHMETIC_OP_SIGCLIP_STD</td>
<td>Sigma clip standard deviation</td>
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<tr>
<td>GAL_ARITHMETIC_OP_SIGCLIP_MEDIAN</td>
<td>Sigma clip median</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_SIGCLIP_MEAN</td>
<td>Sigma clip mean</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_RA_TO_DEGREE</td>
<td>Converts RA to degrees</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_DEGREE_TO_RA</td>
<td>Converts DE to RA</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_MIN</td>
<td>Returns minimum value</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_MAX</td>
<td>Returns maximum value</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_DIR</td>
<td>Directional arithmetic operation</td>
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<td>Arithmetic operation operand</td>
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</tr>
<tr>
<td>GAL_ARITHMETIC_OP_TO_INT</td>
<td>Converts to int</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_STD</td>
<td>Standard deviation</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_SIGCLIP_STD</td>
<td>Sigma clip standard deviation</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_SIGCLIP_MEDIAN</td>
<td>Sigma clip median</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_SIGCLIP_MEAN</td>
<td>Sigma clip mean</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_RA_TO_DEGREE</td>
<td>Converts RA to degrees</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_DEGREE_TO_RA</td>
<td>Converts DE to RA</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_MIN</td>
<td>Returns minimum value</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_MAX</td>
<td>Returns maximum value</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_DIR</td>
<td>Directional arithmetic operation</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OPERAND</td>
<td>Arithmetic operation operand</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_WHERE</td>
<td>Returns where value</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_TO_UINT8</td>
<td>Converts to uint8</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_TO_UINT64</td>
<td>Converts to uint64</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_TO_UINT32</td>
<td>Converts to uint32</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_TO_UINT</td>
<td>Converts to uint</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_TO_FLOAT64</td>
<td>Converts to float64</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_TO_FLOAT32</td>
<td>Converts to float32</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_TO_INT8</td>
<td>Converts to int8</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_TO_INT64</td>
<td>Converts to int64</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_TO_INT32</td>
<td>Converts to int32</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_TO_INT</td>
<td>Converts to int</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_STD</td>
<td>Standard deviation</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_SIGCLIP_STD</td>
<td>Sigma clip standard deviation</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_SIGCLIP_MEDIAN</td>
<td>Sigma clip median</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_SIGCLIP_MEAN</td>
<td>Sigma clip mean</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_RA_TO_DEGREE</td>
<td>Converts RA to degrees</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_DEGREE_TO_RA</td>
<td>Converts DE to RA</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_MIN</td>
<td>Returns minimum value</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_MAX</td>
<td>Returns maximum value</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_DIR</td>
<td>Directional arithmetic operation</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OPERAND</td>
<td>Arithmetic operation operand</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_WHERE</td>
<td>Returns where value</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_TO_UINT8</td>
<td>Converts to uint8</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_TO_UINT64</td>
<td>Converts to uint64</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_TO_UINT32</td>
<td>Converts to uint32</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_TO_UINT</td>
<td>Converts to uint</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_TO_FLOAT64</td>
<td>Converts to float64</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_TO_FLOAT32</td>
<td>Converts to float32</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_TO_INT8</td>
<td>Converts to int8</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_TO_INT64</td>
<td>Converts to int64</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_TO_INT32</td>
<td>Converts to int32</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_TO_INT</td>
<td>Converts to int</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_STD</td>
<td>Standard deviation</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_SIGCLIP_STD</td>
<td>Sigma clip standard deviation</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_SIGCLIP_MEDIAN</td>
<td>Sigma clip median</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_SIGCLIP_MEAN</td>
<td>Sigma clip mean</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_RA_TO_DEGREE</td>
<td>Converts RA to degrees</td>
</tr>
<tr>
<td>GAL_ARITHMETIC_OP_DEGREE_TO_RA</td>
<td>Converts DE to RA</td>
</tr>
</tbody>
</table>
Index: Macros, structures and functions

GAL_TABLE_DEF_PRECISION_INT .......................... 426
GAL_TABLE_DEF_WIDTH_DBL ............................... 426
GAL_TABLE_DEF_WIDTH_FLT ............................... 426
GAL_TABLE_DEF_WIDTH_INT ............................... 426
GAL_TABLE_DEF_WIDTH_LINT .............................. 426
GAL_TABLE_DEF_WIDTH_STR ............................... 426
GAL_TABLE_DISPLAY_FMT_DECIMAL ........................ 426
GAL_TABLE_DISPLAY_FMT_EXP ............................. 426
GAL_TABLE_DISPLAY_FMT_FLOAT ........................... 426
GAL_TABLE_DISPLAY_FMT_GENERAL ........................ 426
GAL_TABLE_DISPLAY_FMT_HEX ............................. 426
GAL_TABLE_DISPLAY_FMT_OCTAL .......................... 426
GAL_TABLE_DISPLAY_FMT_STRING .......................... 426
GAL_TABLE_DISPLAY_FMT_UDECIMAL ........................ 426
GAL_TABLE_FORMAT_AFITS ................................. 427
GAL_TABLE_FORMAT_BFITS ................................. 427
GAL_TABLE_FORMAT_INVALID .............................. 427
GAL_TABLE_FORMAT_TXT ................................. 427
GAL_TABLE_SEARCH_COMMENT .............................. 427
GAL_TABLE_SEARCH_INVALID .............................. 427
GAL_TABLE_SEARCH_NAME ................................. 427
GAL_TABLE_SEARCH_UNIT ................................. 427
GAL_TILE_PARSE_OPERATE ................................. 463
GAL_TXT_LINESTAT_BLANK .................................. 442
GAL_TXT_LINESTAT_COMMENT ............................. 442
GAL_TXT_LINESTAT_DATAROW .............................. 442
GAL_TXT_LINESTAT_INVALID .............................. 442
GAL_TYPE_BIT ............................................ 390
GAL_TYPE_COMPLEX32 ..................................... 391
GAL_TYPE_COMPLEX64 ..................................... 391
GAL_TYPE_FLOAT32 ....................................... 391
GAL_TYPE_FLOAT64 ....................................... 391
GAL_TYPE_INT ............................................ 391
GAL_TYPE_INT16 .......................................... 391
GAL_TYPE_INT32 .......................................... 391
GAL_TYPE_INT64 .......................................... 391
GAL_TYPE_INVALID ........................................ 390
GAL_TYPE_LONG .......................................... 391
GAL_TYPE_SIZE_T ........................................ 391
GAL_TYPE_STRING ........................................ 392
GAL_TYPE_STRLL .......................................... 392
GAL_TYPE_UINT .......................................... 391
GAL_TYPE_UINT16 ......................................... 390
GAL_TYPE_UINT32 ......................................... 391
GAL_TYPE_UINT64 ......................................... 391
GAL_TYPE_UINT8 .......................................... 390
GAL_TYPE_ULONG ......................................... 391
GAL_WCS_DISTORTION_DSS ................................ 449
GAL_WCS_DISTORTION_INVALID ........................... 449
GAL_WCS_DISTORTION_SIP ................................ 449
GAL_WCS_DISTORTION_TPD ................................ 449
GAL_WCS_DISTORTION_TPV ................................ 449
GAL_WCS_DISTORTION_WAT ................................ 449
GAL_WCS_FLTERROR ........................................ 449

P

pthread_barrier_destroy ......................... 388
pthread_barrier_init ......................... 387
pthread_barrier_t ....................... 387
pthread_barrier_wait ...................... 388
pthread_barrierattr_t .................. 387
Anonymous bug submission ........................................ 12
Ancombe F. J. ........................................ 2
Ancombe’s quartet ........................................ 3
ANSI C ........................................ 516
Aperture blurring ........................................ 251
apt-get ........................................ 82
Arch Linux ........................................ 83
Area, ellipse ........................................ 321
Argp argument parser ................................. 124, 524
ARGP_HELP_FMT ........................................ 124
args.h ........................................ 524
Arguments to programs .................................. 106
Aristarchus of Samos ................................ 221
Array ........................................ 411
ASCII plot ........................................ 259
ASCII table, FITS .................................. 136
ASCII85 encoding .................................... 168, 488
astprogsname ........................................ 7
Astronomical data format .................................. 162
Astronomical data suffixes ............................. 107
Astronomical Magnitude system .......................... 339
Asynchronous thread allocation .......................... 193
Atmosphere ........................................ 217
Atmosphere blurring .................................... 251
authors-cite.h ........................................ 525
Auto-complete in the shell ................................ 97
Automatic configuration file writing ..................... 120
Automatic output file names ............................. 142
Automatically created build files ....................... 86
Available number of threads ............................ 127
Average ........................................ 482
Average, weighted ..................................... 216
AWK .... 71, 119, 171, 178, 216, 260, 428
Axis ratio ........................................ 332
Azophi ........................................ 17

B

Background flux ........................................ 253, 353
Background pixels ..................................... 276
Backup ........................................ 98
Balmer limit ........................................ 367, 503
Best use of CPU threads ................................ 128
Bi-linear interpolation .................................. 242
Bias current ........................................ 141
Bicubic interpolation .................................. 242
Bin width, histogram .................................. 248
Binary datasets ....................................... 489
Binary image ........................................ 163, 276
Binary table, FITS .................................... 136
Bit ........................................ 130
bit-32 ........................................ 386
bit-64 ........................................ 386
Bitwise Or ........................................ 454
Black and white image ................................ 163
blank color channel .................................. 164
Blank data ........................................ 403
Blank pixel ........................................ 191, 208
Blur image ........................................ 217, 334
Blurring ........................................ 251
Book formats ........................................ 123
Bootstrapping ........................................ 86
Border on an image .................................... 168
Brahe, Tycho ........................................ 4
Breadth first search .................................... 333, 491
brew ........................................ 83
Brightness ........................................ 336, 338, 340
Buffers (Emacs) .................................... 519
Bug ........................................ 11, 530
Bug reporting ......................................... 11
Bug tracker ........................................ 12
bug-gnuastro@gnu.org ................................ 12
Build ........................................ 1
Build individual profiles ................................ 350
Build tree ........................................ 529
Building from source ................................... 81
Byte ........................................ 130
Bzip2 ........................................ 62

C

C compiler ........................................ 382
C Pre-Processor ....................................... 382
C programming language ................................ 516
C++ programming language ................................ 516
C, plotting ........................................ 543
C: restrict ........................................ 401
C99 ........................................ 395
Cache, system ....................................... 128
Calendar ........................................ 158
Camera ........................................ 242
CANDLES survey ..................................... 193, 299
Caspar Wessel ....................................... 221
Catalog, Gaia ....................................... 185
CC ........................................ 384
CCD ........................................ 141, 239
CDELT ........................................ 29
Celestial sphere ....................................... 339
CentOS ........................................ 82
Central management ................................... 530
CFITSIO ........................................ 75, 155, 385, 430
CFITSIO version on outputs ............................. 143
Change converted pixel values .......................... 169
Channel ........................................ 142, 425
Channel, color ....................................... 165
Charge-coupled device ................................ 239
Check ........................................ 1
Check center of crop ................................ 197
Checking detection algorithms .......................... 332
Checking tests ....................................... 101
CHECKSUM: FITS keyword ............................ 155
CII doublet ........................................ 367, 503
Citation information ................................... 525
CIV doublet ........................................ 367
Claudius Ptolemy ..................................... 17
CLI: command-line user interface .......................... 9
Convex polygons ........................................ 196, 471
Convolution ........................................... 216, 218, 334
Convolution kernel ..................................... 440
Cookbook .................................................. 16
Coordinate scales ....................................... 29
Coordinate transformation ............................... 239
Coordinates, homogeneous ............................... 240
Copyright ................................................... 6
Correlated noise ........................................... 302
Correlation ................................................ 218
Cosmic ray removal ...................................... 253
Cosmic rays .................................................. 217, 239, 251, 253, 256
COSMOS survey ............................................. 188
Cotes, Roger ................................................ 221
Counting error ............................................. 353
Counting from zero ....................................... 109
Counts .................................................................. 383, 354
Coverage of image over sky ................................ 150
CPPFLAGS ................................................. 103, 375, 384
CPU threads .................................................. 127
CPU threads, number ...................................... 120
CPU threads, set number ................................... 118
CPU, using all threads ...................................... 127
CRLF line terminator ....................................... 442
Crop (astcrop) ............................................... 188
Crop a given section of image ............................ 191
Crop part of image ......................................... 188
Crop section format ........................................ 191
Cubes (3D data) ............................................. 205, 323
Cumulative Frequency Plot ............................... 248
cURL (downloading tool) ................................... 79
Customize --help output ................................... 124
Customize executable names ............................. 97
Customizing installation ................................... 90

Data ........................................................ 255
Data cubes .................................................. 205
Data format conversion ..................................... 162
Data structures .............................................. 374
Data type ..................................................... 401
Data’s depth .................................................. 298
Dataset: binary ............................................. 489
DATASUM: FITS keyword .................................. 151, 155
Date: FITS format ............................................ 434
de Moivre, Abraham ....................................... 221, 353
de Vaucouleur profile ....................................... 336
Debian .......................................................... 82
Debug .......................................................... 99, 116, 383
Debugging ...................................................... 90, 528
Declination .................................................... 175, 456, 503
Default executable search directory .................... 93
Default library search directory ........................ 95
Default option values ..................................... 108, 120
Define section to crop .................................... 191
Dependencies, Gnuastro .................................. 75
Install with no super-user access .......... 92
Installation .................................. 74
Installation, customizing ..................... 90
Installed help methods ......................... 123
Instrumental noise .............................. 354
Integer, Signed ................................ 130
Integral Field Unit .............................. 320
Integral field unit (IFU) ....................... 205, 232
Integration over pixel ......................... 336
Integration to infinity .......................... 340
Internal default value ......................... 120
Internally stored option value .............. 127
Interpolation .................................. 242, 498
Interpolation, bi-linear ....................... 242
Interpolation, bicubic ......................... 242
Interpolation: Akima spline ................... 499
Interpolation: monotonic ...................... 500
Interpolation: Polynomial..................... 499
Interpolation: Spline .......................... 499
Interpolation: Steffen ......................... 500
Intervals, histogram ........................... 248
INT ........................................... 108
IRAF ......................................... 162
ISO C90 ........................................ 516
Issue .......................................... 530

J
Jaynes E. T. ........................................... 6
JPEG compression quality ..................... 168, 447
JPEG format .................................... 78, 92, 162, 446

K
K-d tree ............................................. 476
Ken Thomson ....................................... 5
Kernel, convolution ............................ 216, 440
Kernel, Linux .................................... 134
Kernighan, Brian ................................. 516

L
Labeling ............................................ 269
Large astronomical images .................... 188
last-in-first-out ................................ 412, 433
IMpkX ........................................... 80, 163, 518
Lawrence Livermore National Laboratory ... 386
LD_LIBRARY_PATH ............................... 95, 103, 544
LD_FLAGS ........................................... 103, 384
Learning GNU Info ............................... 125
Lensing simulations ............................ 332
Leonhard Euler ................................... 221
less .............................................. 124
libgit2 .......................................... 78, 92, 502
libjpeg .......................................... 78, 92
Library search directory ...................... 95
Library: shared .................................. 376
libtiff .......................................... 78, 92
Limit, object/clump magnitude .................. 298
Line terminator, CRLF .......................... 442
Linear spatial filtering ........................ 217
Linked list ...................................... 411, 433
Linking .......................................... 376
Linking: dynamic ................................ 376
Linking: Dynamic ................................ 376
Linking: Static .................................. 376
Linux ............................................. 9
Linux kernel ..................................... 98, 134
Linux Mint ....................................... 82
Long option abbreviation ..................... 108
Long outputs .................................... 124
Lord Kelvin ....................................... 5
Low level programming .......................... 517
Luminosity ....................................... 338
Lyman limit ..................................... 367, 503
Lyman-alpha ...................................... 367, 503
Lyman-beta ...................................... 367
Lyman-delta ...................................... 367
Lyman-epsilon ................................... 367
Lyman-gamma ..................................... 367
Lzip .............................................. 1, 85

M
M51 .................................................. 61
macOS ............................................. 83
MacPorts .......................................... 83
Macro ............................................ 374
Magnitude zero point ........................... 339
Magnitude, object/clump detection limit ..... 298
Magnitude, upper limit ........................ 302
Magnitudes from flux ........................... 339
Mailing list archives ........................... 12, 126
Mailing list: bug-gnuastro ..................... 12, 530
Mailing list: gnuastro-commits ............... 532, 534, 535
Mailing list: gnuastro-devel ................... 531
Mailing list: help-gnuastro ................... 126
Mailing list: info-gnuastro .................... 7, 13, 88
main function .................................. 523
Main parameters C structure ................... 523
main.c ........................................... 523
main.h ........................................... 523
Major version number ........................... 7
Make .............................................. 129
make check ........................................ 101
MakeProfiles (astmkprof) ....................... 332
Making a distribution package ................. 530
Making profiles pixel by pixel ................ 333
Man pages ....................................... 125
Management hub ................................ 530
Mandatory arguments ........................... 106, 123
Manhattan metric ................................ 114
ManPATH .......................................... 95
Mathematical morphology ...................... 490
Matplotlib, Python .............................. 518, 543
<table>
<thead>
<tr>
<th>Noise simulation</th>
<th>354</th>
</tr>
</thead>
<tbody>
<tr>
<td>Noise, instrumental</td>
<td>354</td>
</tr>
<tr>
<td>Non-commutative operations</td>
<td>241</td>
</tr>
<tr>
<td>Non-volatile memory</td>
<td>132</td>
</tr>
<tr>
<td>Normalizing histogram</td>
<td>248</td>
</tr>
<tr>
<td>nproc</td>
<td>127</td>
</tr>
<tr>
<td>Number</td>
<td>482</td>
</tr>
<tr>
<td>Number of CPU threads to use</td>
<td>118, 120</td>
</tr>
<tr>
<td>Number of threads available</td>
<td>127</td>
</tr>
<tr>
<td>Number, version</td>
<td>7</td>
</tr>
<tr>
<td>Numbers, complex</td>
<td>237</td>
</tr>
<tr>
<td>Numbers, pseudo-random</td>
<td>355</td>
</tr>
<tr>
<td>Numbers, random</td>
<td>355</td>
</tr>
</tbody>
</table>

**O**

- Object magnitude limit | 298 |
- Object oriented programming | 516 |
- OII doublet | 367, 503 |
- OIII doublet | 503 |
- OIII doublet in UV | 367 |
- OIII doublet in visible | 366 |
- On/Off options | 107 |
- Online help | 123 |
- Opening | 68 |
- Opening (Mathematical morphology) | 490 |
- Opening multiextension FITS | 540 |
- OpenMP | 387 |
- openSUSE | 83 |
- Operations on files | 146 |
- Operations, non-commutative | 241 |
- Operator, structure de-reference | 523 |
- Optical distortion | 230 |
- Optimization | 383, 528 |
- Optimization flag | 519 |
- Option values | 108 |
- Optional and mandatory tokens | 123 |
- Options | 216 |
- Options common to all programs | 109 |
- Options to programs | 106 |
- Options, abbreviation | 108 |
- Options, GNU style | 107 |
- Options, on/off | 107 |
| Options, repeated | 108 |
- Options, short (–) and long (--) | 107 |
- Order in search directory | 96 |
- Outlier | 262 |
- Outliers | 256 |
- Output file names, automatic | 142 |
- Output FITS headers | 143 |
- Output, wrong | 11 |
- Oversample | 20 |
- Oversampling | 337 |

**N**

- Names of executables | 97 |
- Names, customize | 97 |
- Names, programs | 7 |
- NaN... 138, 201, 246, 266, 276, 396, 397, 440, 474 |
- Narrow-band image | 205 |
- Navigating source files | 522 |
- Necessary parameters | 120 |
- Neighborhood | 216 |
- Neighbors, immediate | 489 |
- NGC5195 | 61 |
- NII doublet | 366, 503 |
- No access to super-user install | 92 |
- Noise | 255, 352 |
Sampling ........................................... 242, 336
SAO DS9 .................................. 39, 54, 70, 169, 195, 293, 540
Saturated stars .................................. 498
Save output to file .................................. 124
Saving binary image ................................. 163
Scales, coordinate .................................. 29
Scaling ............................................. 239
Scientific Linux .................................. 82
Scientist, puzzle solver .............................. 5
Script, shell ........................................ 55
Scripts, startup ..................................... 94
Scroll command-line ................................ 124
SDSS, Sloan Digital Sky Survey .................. 61
Search directory for executables .................. 93
Search directory order ............................... 96
Searching text ....................................... 124
Second moment ...................................... 303
Section of an image ................................ 188
Secure shell ........................................ 10
SED, stream editor ................................ 97
Seed, Random number generator ............... 313, 337, 345, 355, 356, 358
Segmentation ....................................... 269, 270
sequent WCS distortion .............................. 449
Sérsic index ........................................ 336
Sérsic profile ....................................... 321, 336
Sérsic, J. L. ........................................ 336
Setting output file names automatically ..... 142
Setting PATH ........................................ 93
Sexagesimal ......................................... 175, 456
Shared library ....................................... 376
Shared library versioning ........................... 378
Shear ................................................. 240
Shebang .............................................. 56
Shell ................................................ 9, 106
Shell alias .......................................... 342
Shell auto-complete ................................ 97
Shell history ........................................ 55
Shell redirection .................................... 55
Shell script ......................................... 8, 55
Shell startup ......................................... 342
Shell variables ....................................... 93
Shift + PageUP and Shift + PageDown .......... 124
SI (International System of Units) ............... 339
Sigma-clipping ...................................... 255, 488
Signal ................................................. 255
Signal to noise ratio ................................ 238, 242
Signed integer ....................................... 130
SII doublet .......................................... 366, 503
SiII doublet ......................................... 367
Simulating noise ..................................... 354
Simultaneous multithreading ...................... 127
Single channel CMYK .............................. 166
SIP WCS distortion ................................. 158, 449, 452
size_t .............................................. 421, 422
Skewed Poisson distribution ....................... 353
Skewness ............................................. 319
Sky .................................................. 252
Sky line ............................................. 498
Sky value ............................................ 253, 353
Sloan Digital Sky Survey, SDSS .................. 61
SLS Color ........................................... 169
Software bug ......................................... 11
Source code building ................................ 81
Source code compilation ............................ 81
Source file navigation .............................. 522
Source tree .......................................... 529
Source, uncompress .................................. 1
Spectrum (of astronomical source) .............. 323
Spectrum, Fourier ................................... 237
Spline (Akima) interpolation ........................ 499
Spline (cubic) interpolation ........................ 499
Spread of a point source ........................... 334
SSD .................................................. 98
SSH ................................................. 10
Standard deviation .................................. 303, 483
Standard input ..................................... 109, 118, 142, 166, 258, 444
Standard output .................................... 179
Standard output stream ............................ 118
Standard, FITS ..................................... 401
Stars, modeling ..................................... 336
StartUp scripts ..................................... 94, 356
Startup, shell ....................................... 342
Static document description format ............ 163
Static linking ....................................... 376
Statistical analysis ................................... 3
Steffen interpolation ................................ 500
Steradian ............................................ 339
Stitch multiple images .............................. 188
Stream editor, SED .................................. 97
Stream: standard input ................................ 118
Stream: standard output ............................ 118
Stroustrup, Bjarne .................................. 5, 516
Structure de-reference operator .................. 523
Structures .......................................... 374
STR ................................................. 108
Subaru Telescope .................................... 141
Submit new tracker item ............................ 12
Suffixes, astronomical data ...................... 107
Suffixes, EPS format ................................ 163
Suffixes, JPEG images ............................. 162
<table>
<thead>
<tr>
<th>Page</th>
<th>Index</th>
</tr>
</thead>
<tbody>
<tr>
<td>164</td>
<td>Suffixes, PDF format</td>
</tr>
<tr>
<td>164</td>
<td>Suffixes, plain text</td>
</tr>
<tr>
<td>17</td>
<td>Sufi, Abd al-rahman</td>
</tr>
<tr>
<td>482</td>
<td>Sum</td>
</tr>
<tr>
<td>340</td>
<td>Sum for total flux</td>
</tr>
<tr>
<td>92</td>
<td>Superuser, not possible</td>
</tr>
<tr>
<td>12</td>
<td>Support request manager</td>
</tr>
<tr>
<td>69, 298, 339</td>
<td>Surface brightness</td>
</tr>
<tr>
<td>83</td>
<td>SUSE Linux Enterprise Server</td>
</tr>
<tr>
<td>97</td>
<td>Symbolic link</td>
</tr>
<tr>
<td>128</td>
<td>System Cache</td>
</tr>
<tr>
<td>122</td>
<td>System wide configuration files</td>
</tr>
</tbody>
</table>

**T**

<table>
<thead>
<tr>
<th>Page</th>
<th>Index</th>
</tr>
</thead>
<tbody>
<tr>
<td>136</td>
<td>Tables FITS</td>
</tr>
<tr>
<td>521</td>
<td>Tabs are evil</td>
</tr>
<tr>
<td>12</td>
<td>Task tracker</td>
</tr>
<tr>
<td>114</td>
<td>Taxicab metric</td>
</tr>
<tr>
<td>1</td>
<td>Test</td>
</tr>
<tr>
<td>529</td>
<td>Test scripts</td>
</tr>
<tr>
<td>103</td>
<td>Tests, only one passes</td>
</tr>
<tr>
<td>101</td>
<td>Tests, running</td>
</tr>
<tr>
<td>528</td>
<td>tests/during-dev.sh</td>
</tr>
<tr>
<td>103, 163</td>
<td>TEx Live</td>
</tr>
<tr>
<td>80</td>
<td>Thread-safety</td>
</tr>
<tr>
<td>475</td>
<td>Thresholding</td>
</tr>
<tr>
<td>78, 92, 162, 445</td>
<td>TIFF format</td>
</tr>
<tr>
<td>109</td>
<td>Tilde expansion as option values</td>
</tr>
<tr>
<td>161</td>
<td>Time zone</td>
</tr>
<tr>
<td>157, 158</td>
<td>Time, Unix epoch</td>
</tr>
<tr>
<td>109</td>
<td>Timeout</td>
</tr>
<tr>
<td>98</td>
<td>tmpfs file system</td>
</tr>
<tr>
<td>525</td>
<td>Top processing source file</td>
</tr>
<tr>
<td>523</td>
<td>Top root structure</td>
</tr>
<tr>
<td>449</td>
<td>TPD WCS distortion</td>
</tr>
<tr>
<td>158, 449, 452</td>
<td>TPV WCS distortion</td>
</tr>
<tr>
<td>12, 530</td>
<td>Tracker</td>
</tr>
<tr>
<td>521</td>
<td>Trailing space</td>
</tr>
<tr>
<td>332</td>
<td>Transform image</td>
</tr>
<tr>
<td>241</td>
<td>Transformation, affine</td>
</tr>
<tr>
<td>241</td>
<td>Transformation, projective</td>
</tr>
<tr>
<td>340</td>
<td>Truncation radius</td>
</tr>
<tr>
<td>16</td>
<td>Tutorial</td>
</tr>
<tr>
<td>130</td>
<td>Type</td>
</tr>
</tbody>
</table>

**U**

<table>
<thead>
<tr>
<th>Page</th>
<th>Index</th>
</tr>
</thead>
<tbody>
<tr>
<td>82</td>
<td>Ubuntu</td>
</tr>
<tr>
<td>524</td>
<td>ui.c</td>
</tr>
<tr>
<td>524</td>
<td>ui.h</td>
</tr>
<tr>
<td>1</td>
<td>Uncompress source</td>
</tr>
<tr>
<td>353</td>
<td>Undetected objects</td>
</tr>
<tr>
<td>161</td>
<td>Universal time coordinate (UTC)</td>
</tr>
<tr>
<td>157, 158, 434</td>
<td>Unix epoch time</td>
</tr>
<tr>
<td>130</td>
<td>Unsigned integer</td>
</tr>
<tr>
<td>302</td>
<td>Upper limit magnitude</td>
</tr>
<tr>
<td>102</td>
<td>US letter paper size</td>
</tr>
<tr>
<td>123</td>
<td>Usage pattern</td>
</tr>
<tr>
<td>524</td>
<td>User interface functions</td>
</tr>
<tr>
<td>127</td>
<td>Using CPU threads</td>
</tr>
<tr>
<td>127</td>
<td>Using multiple CPU cores</td>
</tr>
<tr>
<td>128</td>
<td>Using multiple threads</td>
</tr>
<tr>
<td>161</td>
<td>UTC (Universal time coordinate)</td>
</tr>
</tbody>
</table>

**V**

<table>
<thead>
<tr>
<th>Page</th>
<th>Index</th>
</tr>
</thead>
<tbody>
<tr>
<td>90, 100</td>
<td>Valgrind</td>
</tr>
<tr>
<td>108</td>
<td>Values to options</td>
</tr>
<tr>
<td>303</td>
<td>Variance</td>
</tr>
<tr>
<td>146</td>
<td>Vatican library</td>
</tr>
<tr>
<td>163</td>
<td>Vector graphics</td>
</tr>
<tr>
<td>11, 85</td>
<td>Version control</td>
</tr>
<tr>
<td>78, 92</td>
<td>Version control systems</td>
</tr>
<tr>
<td>7</td>
<td>Version number</td>
</tr>
<tr>
<td>378</td>
<td>Versioning: Shared library</td>
</tr>
<tr>
<td>12</td>
<td>Viewing trackers</td>
</tr>
<tr>
<td>169</td>
<td>Viridis: Colormap</td>
</tr>
<tr>
<td>165</td>
<td>Virtual console</td>
</tr>
<tr>
<td>401</td>
<td>Visualization</td>
</tr>
<tr>
<td>132</td>
<td>Volatile memory</td>
</tr>
</tbody>
</table>

**W**

<table>
<thead>
<tr>
<th>Page</th>
<th>Index</th>
</tr>
</thead>
<tbody>
<tr>
<td>128</td>
<td>Wall-clock time</td>
</tr>
<tr>
<td>221</td>
<td>Wassel, Caspar</td>
</tr>
<tr>
<td>449</td>
<td>WAT WCS distortion</td>
</tr>
<tr>
<td>285, 494</td>
<td>Watershed algorithm</td>
</tr>
<tr>
<td>366</td>
<td>Wavelength, rest-frame</td>
</tr>
<tr>
<td>76</td>
<td>WCS</td>
</tr>
<tr>
<td>158, 449, 452</td>
<td>WCS distortion</td>
</tr>
<tr>
<td>173</td>
<td>WCS: World Coordinate System</td>
</tr>
<tr>
<td>76, 247</td>
<td>WCSLIB</td>
</tr>
<tr>
<td>216</td>
<td>Weighted average</td>
</tr>
<tr>
<td>239</td>
<td>WFC3</td>
</tr>
<tr>
<td>120</td>
<td>White space character</td>
</tr>
<tr>
<td>239, 240</td>
<td>Wide Field Camera 3</td>
</tr>
<tr>
<td>5</td>
<td>William Thomson</td>
</tr>
<tr>
<td>76, 247</td>
<td>World Coordinate System</td>
</tr>
<tr>
<td>173, 205</td>
<td>World Coordinate System (WCS)</td>
</tr>
<tr>
<td>120</td>
<td>Writing configuration files</td>
</tr>
<tr>
<td>11</td>
<td>Wrong output</td>
</tr>
<tr>
<td>11</td>
<td>Wrong results</td>
</tr>
</tbody>
</table>

**X**

<table>
<thead>
<tr>
<th>Page</th>
<th>Index</th>
</tr>
</thead>
<tbody>
<tr>
<td>25, 299</td>
<td>XDF survey</td>
</tr>
</tbody>
</table>

**Y**

<table>
<thead>
<tr>
<th>Page</th>
<th>Index</th>
</tr>
</thead>
<tbody>
<tr>
<td>82</td>
<td>yum</td>
</tr>
</tbody>
</table>
Z

Zero point magnitude ...................... 339
zypper, OpenSUSE package manager ........ 83